

74HC73

Dual JK flip-flop with reset; negative-edge trigger

Rev. 03 — 12 November 2004

Product data sheet

1. General description

The 74HC73 is a high-speed Si-gate CMOS device and is pin compatible with low-power Schottky TTL (LSTTL). The 74HC73 is specified in compliance with JEDEC standard no. 7A.

The 74HC is a dual negative-edge triggered JK flip-flop featuring individual J, K, clock (\overline{nCP}) and reset (\overline{nR}) inputs; also complementary nQ and $n\overline{Q}$ outputs.

The J and K inputs must be stable one set-up time prior to the HIGH-to-LOW clock transition for predictable operation.

The reset (\overline{nR}) is an asynchronous active LOW input. When LOW, it overrides the clock and data inputs, forcing the nQ output LOW and the $n\overline{Q}$ output HIGH.

Schmitt-trigger action in the clock input makes the circuit highly tolerant to slower clock rise and fall times.

2. Features

- Low-power dissipation
- Complies with JEDEC standard no. 7A
- ESD protection:
 - ◆ HBM EIA/JESD22-A114-B exceeds 2000 V
 - ◆ MM EIA/JESD22-A115-A exceeds 200 V.
- Multiple package options
- Specified from $-40\text{ }^{\circ}\text{C}$ to $+80\text{ }^{\circ}\text{C}$ and from $-40\text{ }^{\circ}\text{C}$ to $+125\text{ }^{\circ}\text{C}$.

PHILIPS

3. Quick reference data

Table 1: Quick reference data

$GND = 0\text{ V}$; $T_{amb} = 25\text{ °C}$; $t_r = t_f = 6\text{ ns}$.

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit | |
|-----------------------|---|--|-----|-----|-----|------|----|
| t_{PHL} , t_{PLH} | propagation delay | $C_L = 15\text{ pF}$; $V_{CC} = 5\text{ V}$ | - | | - | | |
| | $n\overline{CP}$ to nQ | | - | 16 | - | ns | |
| | $n\overline{CP}$ to $n\overline{Q}$ | | - | 16 | - | ns | |
| | $n\overline{R}$ to nQ , $n\overline{Q}$ | | - | 15 | - | ns | |
| f_{max} | maximum clock frequency | $C_L = 15\text{ pF}$; $V_{CC} = 5\text{ V}$ | - | 77 | - | MHz | |
| C_I | input capacitance | | - | 3.5 | - | pF | |
| C_{PD} | power dissipation capacitance per flip-flop | $V_I = GND$ to V_{CC} | [1] | - | 30 | - | pF |

[1] C_{PD} is used to determine the dynamic power dissipation (P_D in μW).

$$P_D = C_{PD} \times V_{CC}^2 \times f_i \times N + \sum(C_L \times V_{CC}^2 \times f_o) \text{ where:}$$

f_i = input frequency in MHz;

f_o = output frequency in MHz;

C_L = output load capacitance in pF;

V_{CC} = supply voltage in V;

N = number of inputs switching;

$\sum(C_L \times V_{CC}^2 \times f_o)$ = sum of outputs.

4. Ordering information

Table 2: Ordering information

| Type number | Package | | | |
|-------------|-------------------|---------|--|----------|
| | Temperature range | Name | Description | Version |
| 74HC73N | -40 °C to +125 °C | DIP14 | plastic dual in-line package; 14 leads (300 mil) | SOT27-1 |
| 74HC73D | -40 °C to +125 °C | SO14 | plastic small outline package; 14 leads; body width 3.9 mm | SOT108-1 |
| 74HC73DB | -40 °C to +125 °C | SSOP14 | plastic shrink small outline package; 14 leads; body width 5.3 mm | SOT337-1 |
| 74HC73PW | -40 °C to +125 °C | TSSOP14 | plastic thin shrink small outline package; 14 leads; body width 4.4 mm | SOT402-1 |

5. Functional diagram

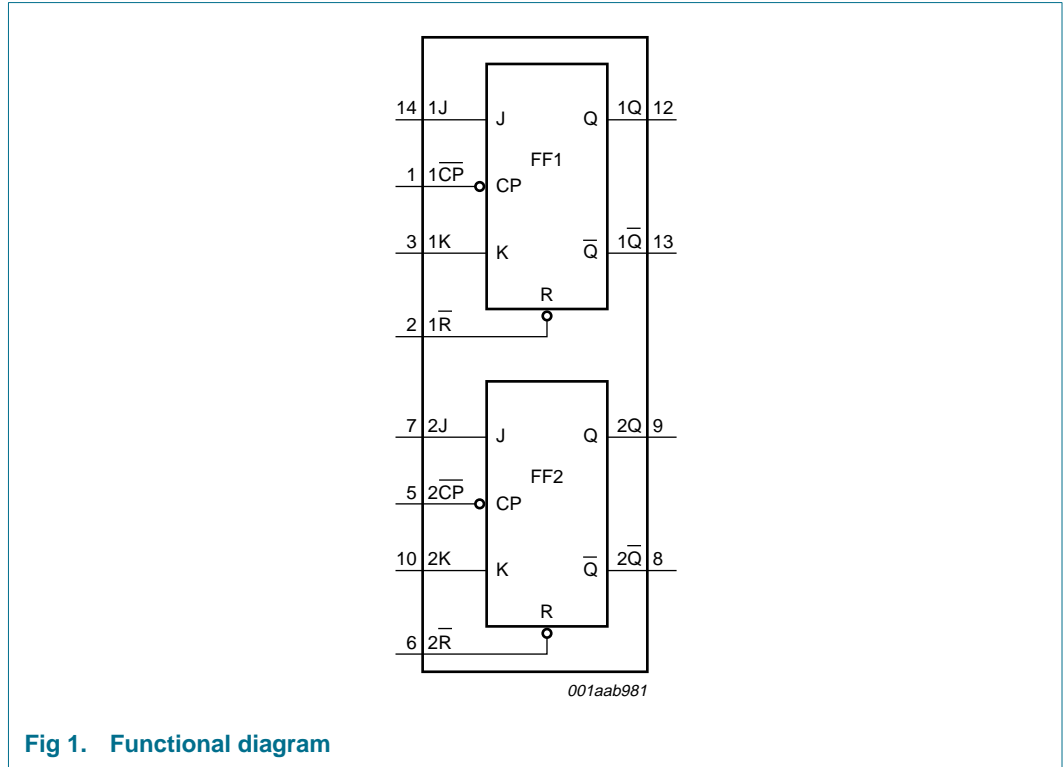


Fig 1. Functional diagram

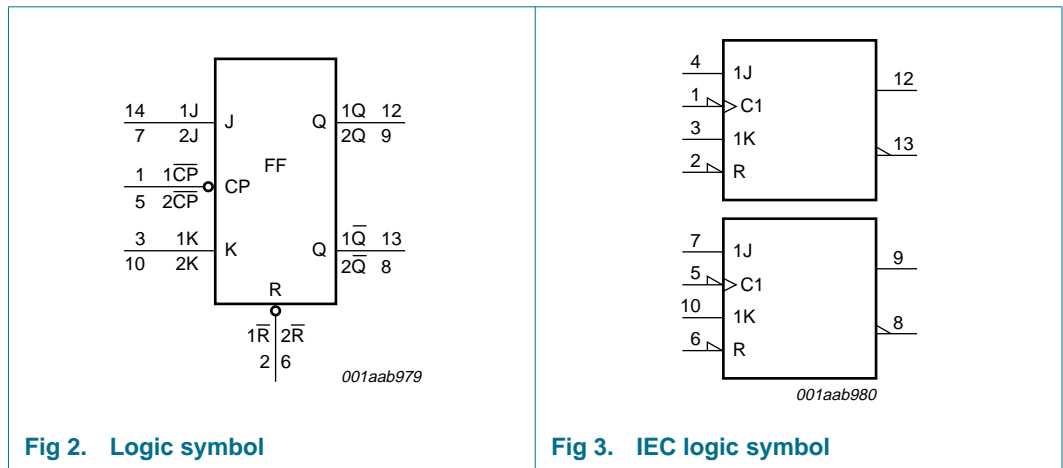
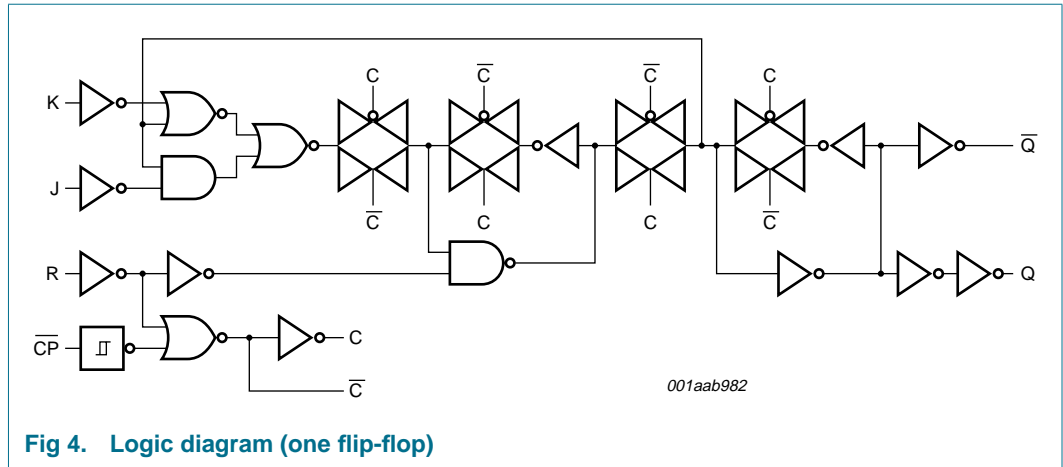


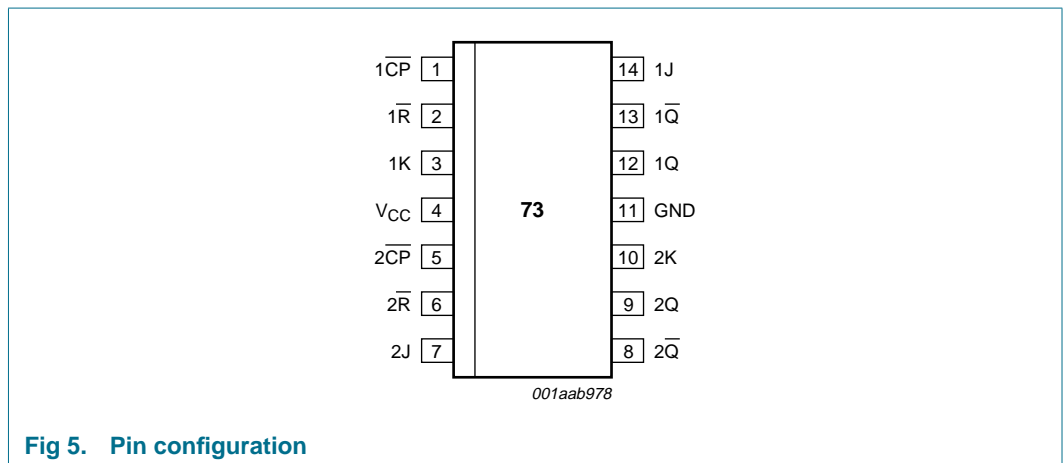
Fig 2. Logic symbol

Fig 3. IEC logic symbol



6. Pinning information

6.1 Pinning



6.2 Pin description

Table 3: Pin description

| Symbol | Pin | Description |
|------------------|-----|---|
| $1\overline{CP}$ | 1 | clock input for flip-flop 1 (HIGH-to-LOW, edge-triggered) |
| $1\overline{R}$ | 2 | asynchronous reset input for flip-flop 1 (active LOW) |
| 1K | 3 | synchronous K input for flip-flop 1 |
| V_{CC} | 4 | positive supply voltage |
| $2\overline{CP}$ | 5 | clock input for flip-flop 2 (HIGH-to-LOW, edge-triggered) |
| $2\overline{R}$ | 6 | asynchronous reset input for flip-flop 2 (active LOW) |
| 2J | 7 | synchronous J input for flip-flop 2 |
| $2\overline{Q}$ | 8 | complement flip-flop 2 output |
| 2Q | 9 | true flip-flop 2 output |
| 2K | 10 | synchronous K input for flip-flop 2 |

Table 3: Pin description ...continued

| Symbol | Pin | Description |
|-------------|-----|-------------------------------------|
| GND | 11 | ground (0 V) |
| 1Q | 12 | true flip-flop 1 output |
| 1 \bar{Q} | 13 | complement flip-flop 1 output |
| 1J | 14 | synchronous J input for flip-flop 1 |

7. Functional description

7.1 Function table

Table 4: Function table [1]

| Input | | | | Output | | Operating mode |
|-------------|--------------|----|----|-----------|-------------|--------------------|
| n \bar{R} | n \bar{CP} | nJ | nK | nQ | n \bar{Q} | |
| L | X | X | X | L | H | asynchronous reset |
| H | ↓ | h | h | \bar{q} | q | toggle |
| | | l | h | L | H | load 0 (reset) |
| | | h | l | H | L | load 1 (set) |
| | | l | l | q | \bar{q} | hold (no change) |

- [1] H = HIGH voltage level;
h = HIGH voltage level one set-up time prior to the HIGH-to-LOW CP transition;
L = LOW voltage level;
l = LOW voltage level one set-up time prior to the HIGH-to-LOW CP transition;
q = state of referenced output one set-up time prior to the HIGH-to-LOW CP transition;
X = don't care;
↓ = HIGH-to-LOW CP transition.

8. Limiting values

Table 5: Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to GND (ground = 0 V).

| Symbol | Parameter | Conditions | Min | Max | Unit |
|-------------------|-----------------------------------|--|------|------|--------|
| V_{CC} | supply voltage | | -0.5 | +7 | V |
| I_{IK} | input diode current | $V_I < -0.5$ V or $V_I > V_{CC} + 0.5$ V | - | ±20 | mA |
| I_{OK} | output diode current | $V_O < -0.5$ V or $V_O > V_{CC} + 0.5$ V | - | ±20 | mA |
| I_O | output source or sink current | $V_O = -0.5$ V to $V_{CC} + 0.5$ V | - | ±25 | mA |
| I_{CC}, I_{GND} | V_{CC} or GND current | | - | ±50 | mA |
| T_{stg} | storage temperature | | -65 | +150 | °C |
| P_{tot} | power dissipation | | | | |
| | DIP14 package | | [1] | - | 750 mW |
| | SO14, SSOP14 and TSSOP14 packages | | [2] | - | 500 mW |

[1] Above 70 °C: P_{tot} derates linearly with 12 mW/K.

[2] Above 70 °C: P_{tot} derates linearly with 8 mW/K.

9. Recommended operating conditions

Table 6: Recommended operating conditions

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|------------|--|-------------------------|-----|-----|----------|------|
| V_{CC} | supply voltage | | 2.0 | 5.0 | 6.0 | V |
| V_I | input voltage | | 0 | - | V_{CC} | V |
| V_O | output voltage | | 0 | - | V_{CC} | V |
| t_r, t_f | input rise and fall times except for nCP | $V_{CC} = 2.0\text{ V}$ | - | - | 1000 | ns |
| | | $V_{CC} = 4.5\text{ V}$ | - | 6.0 | 500 | ns |
| | | $V_{CC} = 6.0\text{ V}$ | - | - | 400 | ns |
| T_{amb} | ambient temperature | | -40 | - | +125 | °C |

10. Static characteristics

Table 7: Static characteristics

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|--|--|--|------|------|-----------|---------------|
| $T_{amb} = 25\text{ °C}$ | | | | | | |
| V_{IH} | HIGH-level input voltage | $V_{CC} = 2.0\text{ V}$ | 1.5 | 1.2 | - | V |
| | | $V_{CC} = 4.5\text{ V}$ | 3.15 | 2.4 | - | V |
| | | $V_{CC} = 6.0\text{ V}$ | 4.2 | 3.2 | - | V |
| V_{IL} | LOW-level input voltage | $V_{CC} = 2.0\text{ V}$ | - | 0.8 | 0.5 | V |
| | | $V_{CC} = 4.5\text{ V}$ | - | 2.1 | 1.35 | V |
| | | $V_{CC} = 6.0\text{ V}$ | - | 2.8 | 1.8 | V |
| V_{OH} | HIGH-level output voltage | $V_I = V_{IH}$ or V_{IL} | | | | |
| | | $I_O = -20\text{ }\mu\text{A}; V_{CC} = 2.0\text{ V}$ | 1.9 | 2.0 | - | V |
| | | $I_O = -20\text{ }\mu\text{A}; V_{CC} = 4.5\text{ V}$ | 4.4 | 4.5 | - | V |
| | | $I_O = -20\text{ }\mu\text{A}; V_{CC} = 6.0\text{ V}$ | 5.9 | 6.0 | - | V |
| | | $I_O = -4\text{ mA}; V_{CC} = 4.5\text{ V}$ | 3.98 | 4.32 | - | V |
| V_{OL} | LOW-level output voltage | $V_I = V_{IH}$ or V_{IL} | | | | |
| | | $I_O = 20\text{ }\mu\text{A}; V_{CC} = 2.0\text{ V}$ | - | 0 | 0.1 | V |
| | | $I_O = 20\text{ }\mu\text{A}; V_{CC} = 4.5\text{ V}$ | - | 0 | 0.1 | V |
| | | $I_O = 20\text{ }\mu\text{A}; V_{CC} = 6.0\text{ V}$ | - | 0 | 0.1 | V |
| | | $I_O = 4\text{ mA}; V_{CC} = 4.5\text{ V}$ | - | 0.15 | 0.26 | V |
| | $I_O = 5.2\text{ mA}; V_{CC} = 6.0\text{ V}$ | - | 0.16 | 0.26 | V | |
| I_{LI} | input leakage current | $V_I = V_{CC}$ or GND; $V_{CC} = 6.0\text{ V}$ | - | - | ± 0.1 | μA |
| I_{CC} | quiescent supply current | $V_I = V_{CC}$ or GND; $I_O = 0\text{ A}; V_{CC} = 6.0\text{ V}$ | - | - | 4.0 | μA |
| C_I | input capacitance | | - | 3.5 | - | pF |

Table 7: Static characteristics ...continued

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|--|---------------------------|--|------|-----|-----------|---------------|
| $T_{amb} = -40\text{ °C to }+85\text{ °C}$ | | | | | | |
| V_{IH} | HIGH-level input voltage | $V_{CC} = 2.0\text{ V}$ | 1.5 | - | - | V |
| | | $V_{CC} = 4.5\text{ V}$ | 3.15 | - | - | V |
| | | $V_{CC} = 6.0\text{ V}$ | 4.2 | - | - | V |
| V_{IL} | LOW-level input voltage | $V_{CC} = 2.0\text{ V}$ | - | - | 0.5 | V |
| | | $V_{CC} = 4.5\text{ V}$ | - | - | 1.35 | V |
| | | $V_{CC} = 6.0\text{ V}$ | - | - | 1.8 | V |
| V_{OH} | HIGH-level output voltage | $V_I = V_{IH}$ or V_{IL} | | | | |
| | | $I_O = -20\text{ }\mu\text{A}; V_{CC} = 2.0\text{ V}$ | 1.9 | - | - | V |
| | | $I_O = -20\text{ }\mu\text{A}; V_{CC} = 4.5\text{ V}$ | 4.4 | - | - | V |
| | | $I_O = -20\text{ }\mu\text{A}; V_{CC} = 6.0\text{ V}$ | 5.9 | - | - | V |
| | | $I_O = -4\text{ mA}; V_{CC} = 4.5\text{ V}$ | 3.84 | - | - | V |
| | | $I_O = -5.2\text{ mA}; V_{CC} = 6.0\text{ V}$ | 5.34 | - | - | V |
| V_{OL} | LOW-level output voltage | $V_I = V_{IH}$ or V_{IL} | | | | |
| | | $I_O = 20\text{ }\mu\text{A}; V_{CC} = 2.0\text{ V}$ | - | - | 0.1 | V |
| | | $I_O = 20\text{ }\mu\text{A}; V_{CC} = 4.5\text{ V}$ | - | - | 0.1 | V |
| | | $I_O = 20\text{ }\mu\text{A}; V_{CC} = 6.0\text{ V}$ | - | - | 0.1 | V |
| | | $I_O = 4\text{ mA}; V_{CC} = 4.5\text{ V}$ | - | - | 0.33 | V |
| | | $I_O = 5.2\text{ mA}; V_{CC} = 6.0\text{ V}$ | - | - | 0.33 | V |
| I_{LI} | input leakage current | $V_I = V_{CC}$ or GND; $V_{CC} = 6.0\text{ V}$ | - | - | ± 1.0 | μA |
| I_{CC} | quiescent supply current | $V_I = V_{CC}$ or GND; $I_O = 0\text{ A}; V_{CC} = 6.0\text{ V}$ | - | - | 40.0 | μA |

Table 7: Static characteristics ...continued

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|---|---------------------------|--|------|-----|-----------|---------------|
| $T_{amb} = -40\text{ °C to }+125\text{ °C}$ | | | | | | |
| V_{IH} | HIGH-level input voltage | $V_{CC} = 2.0\text{ V}$ | 1.5 | - | - | V |
| | | $V_{CC} = 4.5\text{ V}$ | 3.15 | - | - | V |
| | | $V_{CC} = 6.0\text{ V}$ | 4.2 | - | - | V |
| V_{IL} | LOW-level input voltage | $V_{CC} = 2.0\text{ V}$ | - | - | 0.5 | V |
| | | $V_{CC} = 4.5\text{ V}$ | - | - | 1.35 | V |
| | | $V_{CC} = 6.0\text{ V}$ | - | - | 1.8 | V |
| V_{OH} | HIGH-level output voltage | $V_I = V_{IH}$ or V_{IL} | | | | |
| | | $I_O = -20\text{ }\mu\text{A}; V_{CC} = 2.0\text{ V}$ | 1.9 | - | - | V |
| | | $I_O = -20\text{ }\mu\text{A}; V_{CC} = 4.5\text{ V}$ | 4.4 | - | - | V |
| | | $I_O = -20\text{ }\mu\text{A}; V_{CC} = 6.0\text{ V}$ | 5.9 | - | - | V |
| | | $I_O = -4\text{ mA}; V_{CC} = 4.5\text{ V}$ | 3.7 | - | - | V |
| V_{OL} | LOW-level output voltage | $V_I = V_{IH}$ or V_{IL} | | | | |
| | | $I_O = 20\text{ }\mu\text{A}; V_{CC} = 2.0\text{ V}$ | - | - | 0.1 | V |
| | | $I_O = 20\text{ }\mu\text{A}; V_{CC} = 4.5\text{ V}$ | - | - | 0.1 | V |
| | | $I_O = 20\text{ }\mu\text{A}; V_{CC} = 6.0\text{ V}$ | - | - | 0.1 | V |
| | | $I_O = 4\text{ mA}; V_{CC} = 4.5\text{ V}$ | - | - | 0.4 | V |
| I_{LI} | input leakage current | $V_I = V_{CC}$ or GND; $V_{CC} = 6.0\text{ V}$ | - | - | ± 1.0 | μA |
| | | $V_I = V_{CC}$ or GND; $I_O = 0\text{ A}; V_{CC} = 6.0\text{ V}$ | - | - | 80.0 | μA |

11. Dynamic characteristics

Table 8: Dynamic characteristics

$GND = 0\text{ V}$; $t_r = t_f = 6\text{ ns}$; $C_L = 50\text{ pF}$; see [Figure 8](#).

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit | |
|--|--|--|------------------------------|-----|-----|------|----|
| $T_{amb} = 25\text{ °C}$ | | | | | | | |
| t_{PHL}, t_{PLH} | propagation delay \overline{nCP} to nQ | see Figure 6 | | | | | |
| | | $V_{CC} = 2.0\text{ V}$ | - | 52 | 160 | ns | |
| | | $V_{CC} = 4.5\text{ V}$ | - | 19 | 32 | ns | |
| | | $V_{CC} = 6.0\text{ V}$ | - | 15 | 27 | ns | |
| | | $V_{CC} = 5.0\text{ V}; C_L = 15\text{ pF}$ | - | 16 | - | ns | |
| | propagation delay \overline{nCP} to $n\overline{Q}$ | see Figure 6 | | | | | |
| | | $V_{CC} = 2.0\text{ V}$ | - | 52 | 160 | ns | |
| | | $V_{CC} = 4.5\text{ V}$ | - | 19 | 32 | ns | |
| | | $V_{CC} = 6.0\text{ V}$ | - | 15 | 27 | ns | |
| | | $V_{CC} = 5.0\text{ V}; C_L = 15\text{ pF}$ | - | 16 | - | ns | |
| | propagation delay $n\overline{R}$ to $nQ, n\overline{Q}$ | see Figure 7 | | | | | |
| | | $V_{CC} = 2.0\text{ V}$ | - | 50 | 145 | ns | |
| $V_{CC} = 4.5\text{ V}$ | | - | 18 | 29 | ns | | |
| $V_{CC} = 6.0\text{ V}$ | | - | 14 | 25 | ns | | |
| | $V_{CC} = 5.0\text{ V}; C_L = 15\text{ pF}$ | - | 15 | - | ns | | |
| t_{THL}, t_{TLH} | output transition time | see Figure 6 | | | | | |
| | | $V_{CC} = 2.0\text{ V}$ | - | 19 | 75 | ns | |
| | | $V_{CC} = 4.5\text{ V}$ | - | 7 | 15 | ns | |
| | | $V_{CC} = 6.0\text{ V}$ | - | 6 | 13 | ns | |
| t_W | \overline{nCP} clock pulse width HIGH or LOW | see Figure 6 | | | | | |
| | | $V_{CC} = 2.0\text{ V}$ | 80 | 22 | - | ns | |
| | | $V_{CC} = 4.5\text{ V}$ | 16 | 8 | - | ns | |
| | | $V_{CC} = 6.0\text{ V}$ | 14 | 6 | - | ns | |
| | $n\overline{R}$ reset pulse width HIGH or LOW | see Figure 7 | | | | | |
| | | $V_{CC} = 2.0\text{ V}$ | 80 | 22 | - | ns | |
| | | $V_{CC} = 4.5\text{ V}$ | 16 | 8 | - | ns | |
| | | $V_{CC} = 6.0\text{ V}$ | 14 | 6 | - | ns | |
| | t_{rem} | removal time $n\overline{R}$ to \overline{nCP} | see Figure 7 | | | | |
| | | | $V_{CC} = 2.0\text{ V}$ | 80 | 22 | - | ns |
| $V_{CC} = 4.5\text{ V}$ | | | 16 | 8 | - | ns | |
| | $V_{CC} = 6.0\text{ V}$ | 14 | 6 | - | ns | | |
| t_{su} | set-up time nJ, nK to \overline{nCP} | see Figure 6 | | | | | |
| | | $V_{CC} = 2.0\text{ V}$ | 80 | 22 | - | ns | |
| | | $V_{CC} = 4.5\text{ V}$ | 16 | 8 | - | ns | |
| | $V_{CC} = 6.0\text{ V}$ | 14 | 6 | - | ns | | |

Table 8: Dynamic characteristics ...continued
 $GND = 0\text{ V}$; $t_r = t_f = 6\text{ ns}$; $C_L = 50\text{ pF}$; see [Figure 8](#).

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit | |
|--|---|--|------------------------------|------------------------------|-----|------|----|
| t_h | hold time nJ, nK to nCP | see Figure 6 | | | | | |
| | | $V_{CC} = 2.0\text{ V}$ | 3 | -8 | - | ns | |
| | | $V_{CC} = 4.5\text{ V}$ | 3 | -3 | - | ns | |
| | | $V_{CC} = 6.0\text{ V}$ | 3 | -2 | - | ns | |
| f_{max} | maximum clock frequency | see Figure 6 | | | | | |
| | | $V_{CC} = 2.0\text{ V}$ | 6.0 | 23 | - | MHz | |
| | | $V_{CC} = 4.5\text{ V}$ | 30 | 70 | - | MHz | |
| | | $V_{CC} = 6.0\text{ V}$ | 35 | 83 | - | MHz | |
| | | $V_{CC} = 5.0\text{ V}$; $C_L = 15\text{ pF}$ | - | 77 | - | MHz | |
| C_{PD} | power dissipation capacitance per flip-flop | $V_I = GND$ to V_{CC} | [1] - | 30 | - | pF | |
| $T_{amb} = -40\text{ °C to }+85\text{ °C}$ | | | | | | | |
| t_{PHL}, t_{PLH} | propagation delay nCP to nQ | see Figure 6 | | | | | |
| | | $V_{CC} = 2.0\text{ V}$ | - | - | 200 | ns | |
| | | $V_{CC} = 4.5\text{ V}$ | - | - | 40 | ns | |
| | propagation delay nCP to nQ | $V_{CC} = 6.0\text{ V}$ | - | - | 34 | ns | |
| | | see Figure 6 | | | | | |
| | | $V_{CC} = 2.0\text{ V}$ | - | - | 200 | ns | |
| | propagation delay nCP to nQ | $V_{CC} = 4.5\text{ V}$ | - | - | 40 | ns | |
| | | $V_{CC} = 6.0\text{ V}$ | - | - | 34 | ns | |
| | | propagation delay nR to nQ, nQ | see Figure 7 | | | | |
| | $V_{CC} = 2.0\text{ V}$ | | - | - | 180 | ns | |
| | $V_{CC} = 4.5\text{ V}$ | | - | - | 36 | ns | |
| | propagation delay nR to nQ, nQ | $V_{CC} = 6.0\text{ V}$ | - | - | 31 | ns | |
| t_{THL}, t_{TLH} | | output transition time | see Figure 6 | | | | |
| | | | $V_{CC} = 2.0\text{ V}$ | - | - | 95 | ns |
| | $V_{CC} = 4.5\text{ V}$ | | - | - | 19 | ns | |
| | $V_{CC} = 6.0\text{ V}$ | | - | - | 16 | ns | |
| t_w | nCP clock pulse width HIGH or LOW | see Figure 6 | | | | | |
| | | $V_{CC} = 2.0\text{ V}$ | 100 | - | - | ns | |
| | | $V_{CC} = 4.5\text{ V}$ | 20 | - | - | ns | |
| | nR reset pulse width HIGH or LOW | $V_{CC} = 6.0\text{ V}$ | 17 | - | - | ns | |
| | | see Figure 7 | | | | | |
| | | $V_{CC} = 2.0\text{ V}$ | 100 | - | - | ns | |
| | nR reset pulse width HIGH or LOW | $V_{CC} = 4.5\text{ V}$ | 20 | - | - | ns | |
| | | $V_{CC} = 6.0\text{ V}$ | 17 | - | - | ns | |
| | | t_{rem} | removal time nR to nCP | see Figure 7 | | | |
| | $V_{CC} = 2.0\text{ V}$ | | | 100 | - | - | ns |
| | $V_{CC} = 4.5\text{ V}$ | | | 20 | - | - | ns |
| | $V_{CC} = 6.0\text{ V}$ | | | 17 | - | - | ns |

Table 8: Dynamic characteristics ...continued
 $GND = 0\text{ V}$; $t_r = t_f = 6\text{ ns}$; $C_L = 50\text{ pF}$; see [Figure 8](#).

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit | |
|---|--|------------------------------|------------------------------|-----|-----|------|----|
| t_{su} | set-up time nJ, nK to \overline{nCP} | see Figure 6 | | | | | |
| | | $V_{CC} = 2.0\text{ V}$ | 100 | - | - | ns | |
| | | $V_{CC} = 4.5\text{ V}$ | 20 | - | - | ns | |
| | | $V_{CC} = 6.0\text{ V}$ | 17 | - | - | ns | |
| t_h | hold time nJ, nK to \overline{nCP} | see Figure 6 | | | | | |
| | | $V_{CC} = 2.0\text{ V}$ | 3 | - | - | ns | |
| | | $V_{CC} = 4.5\text{ V}$ | 3 | - | - | ns | |
| | | $V_{CC} = 6.0\text{ V}$ | 3 | - | - | ns | |
| f_{max} | maximum clock frequency | see Figure 6 | | | | | |
| | | $V_{CC} = 2.0\text{ V}$ | 4.8 | - | - | MHz | |
| | | $V_{CC} = 4.5\text{ V}$ | 24 | - | - | MHz | |
| | | $V_{CC} = 6.0\text{ V}$ | 28 | - | - | MHz | |
| $T_{amb} = -40\text{ °C to }+125\text{ °C}$ | | | | | | | |
| t_{PHL}, t_{PLH} | propagation delay \overline{nCP} to nQ | see Figure 6 | | | | | |
| | | $V_{CC} = 2.0\text{ V}$ | - | - | 240 | ns | |
| | | $V_{CC} = 4.5\text{ V}$ | - | - | 48 | ns | |
| | propagation delay \overline{nCP} to \overline{nQ} | see Figure 6 | | | | | |
| | | $V_{CC} = 2.0\text{ V}$ | - | - | 240 | ns | |
| | | $V_{CC} = 4.5\text{ V}$ | - | - | 48 | ns | |
| | propagation delay \overline{nR} to nQ, \overline{nQ} | see Figure 7 | | | | | |
| | | $V_{CC} = 2.0\text{ V}$ | - | - | 220 | ns | |
| | | $V_{CC} = 4.5\text{ V}$ | - | - | 44 | ns | |
| | t_{THL}, t_{TLH} | output transition time | see Figure 6 | | | | |
| | | | $V_{CC} = 2.0\text{ V}$ | - | - | 110 | ns |
| | | | $V_{CC} = 4.5\text{ V}$ | - | - | 22 | ns |
| t_w | \overline{nCP} clock pulse width HIGH or LOW | see Figure 6 | | | | | |
| | | $V_{CC} = 2.0\text{ V}$ | 120 | - | - | ns | |
| | | $V_{CC} = 4.5\text{ V}$ | 24 | - | - | ns | |
| | \overline{nR} reset pulse width HIGH or LOW | see Figure 7 | | | | | |
| | | $V_{CC} = 2.0\text{ V}$ | 120 | - | - | ns | |
| | | $V_{CC} = 4.5\text{ V}$ | 24 | - | - | ns | |
| | $V_{CC} = 6.0\text{ V}$ | 20 | - | - | ns | | |

Table 8: Dynamic characteristics ...continued
GND = 0 V; $t_r = t_f = 6$ ns; $C_L = 50$ pF; see [Figure 8](#).

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|-----------|--|------------------------------|-----|-----|-----|------|
| t_{rem} | removal time $n\bar{R}$ to $n\bar{CP}$ | see Figure 7 | | | | |
| | | $V_{CC} = 2.0$ V | 120 | - | - | ns |
| | | $V_{CC} = 4.5$ V | 24 | - | - | ns |
| | | $V_{CC} = 6.0$ V | 20 | - | - | ns |
| t_{su} | set-up time nJ, nK to $n\bar{CP}$ | see Figure 6 | | | | |
| | | $V_{CC} = 2.0$ V | 120 | - | - | ns |
| | | $V_{CC} = 4.5$ V | 24 | - | - | ns |
| | | $V_{CC} = 6.0$ V | 20 | - | - | ns |
| t_h | hold time nJ, nK to $n\bar{CP}$ | see Figure 6 | | | | |
| | | $V_{CC} = 2.0$ V | 3 | - | - | ns |
| | | $V_{CC} = 4.5$ V | 3 | - | - | ns |
| | | $V_{CC} = 6.0$ V | 3 | - | - | ns |
| f_{max} | maximum clock frequency | see Figure 6 | | | | |
| | | $V_{CC} = 2.0$ V | 4.0 | - | - | MHz |
| | | $V_{CC} = 4.5$ V | 20 | - | - | MHz |
| | | $V_{CC} = 6.0$ V | 24 | - | - | MHz |

[1] C_{PD} is used to determine the dynamic power dissipation (P_D in μ W).

$$P_D = C_{PD} \times V_{CC}^2 \times f_i \times N + \sum(C_L \times V_{CC}^2 \times f_o) \text{ where:}$$

f_i = input frequency in MHz;

f_o = output frequency in MHz;

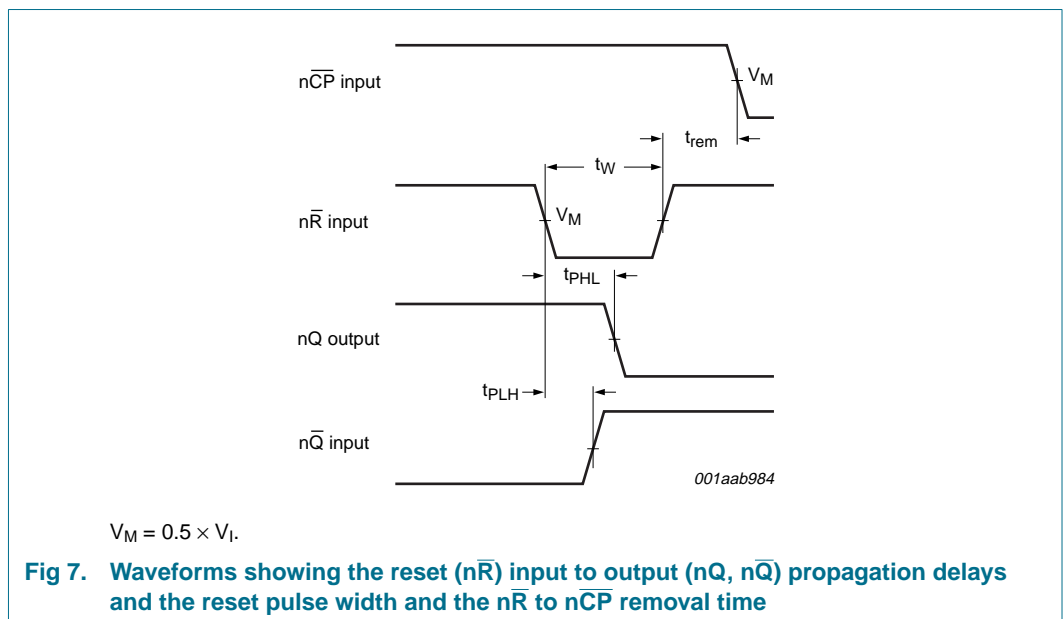
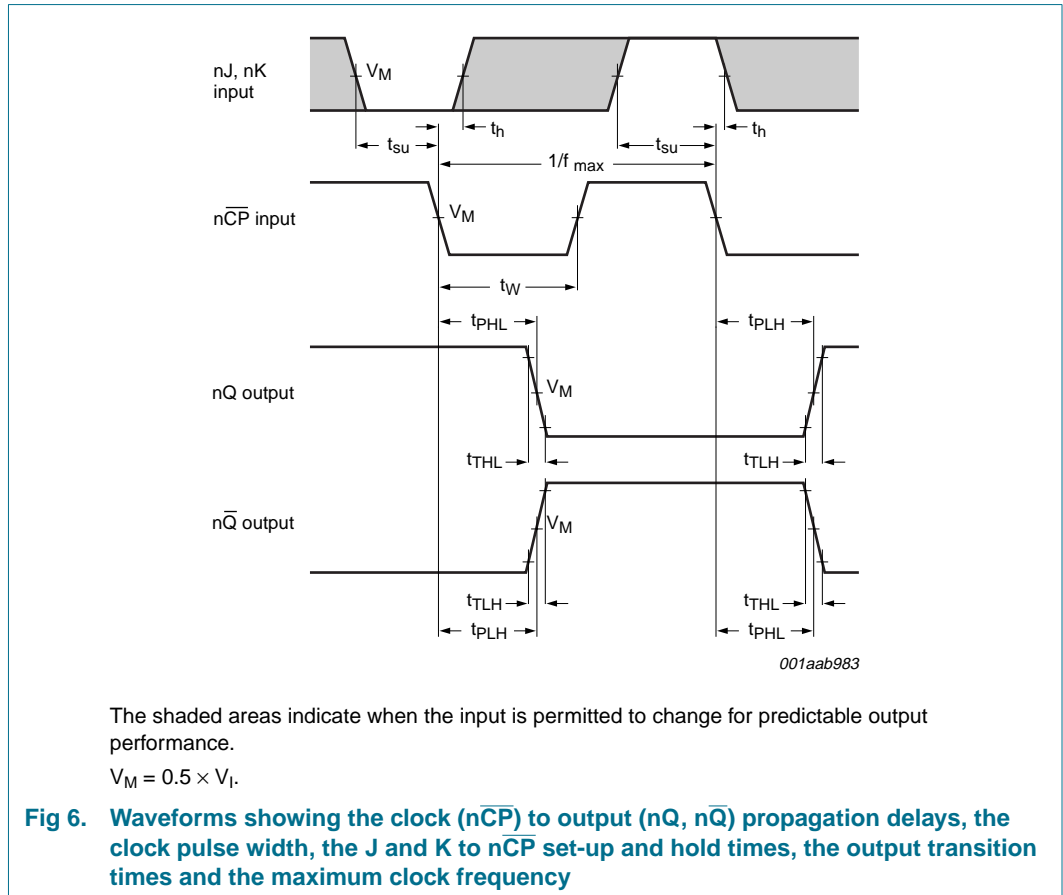
C_L = output load capacitance in pF;

V_{CC} = supply voltage in V;

N = number of inputs switching;

$\sum(C_L \times V_{CC}^2 \times f_o)$ = sum of outputs.

12. Waveforms



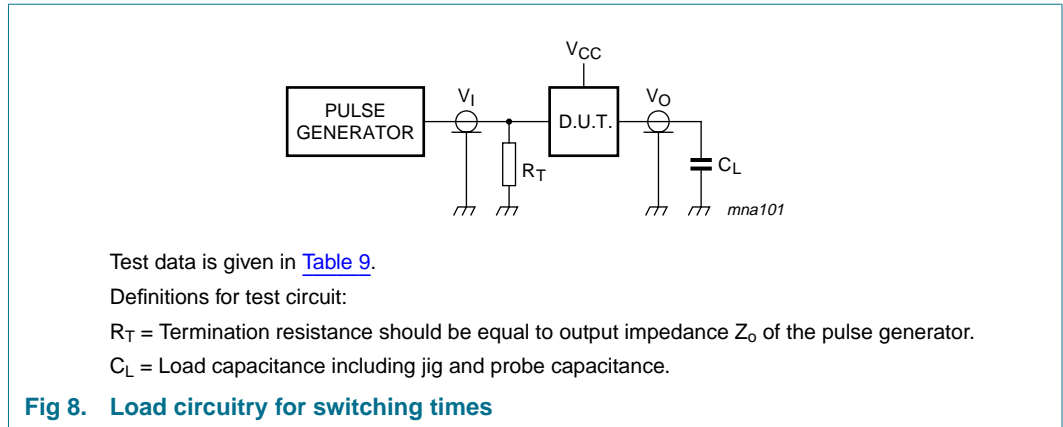


Table 9: Test data

| Supply | Input | | Load |
|----------|----------|------------|-------|
| V_{CC} | V_I | t_r, t_f | C_L |
| 2.0 V | V_{CC} | 6 ns | 50 pF |
| 4.5 V | V_{CC} | 6 ns | 50 pF |
| 6.0 V | V_{CC} | 6 ns | 50 pF |
| 5.0 V | V_{CC} | 6 ns | 15 pF |

13. Package outline

DIP14: plastic dual in-line package; 14 leads (300 mil)

SOT27-1

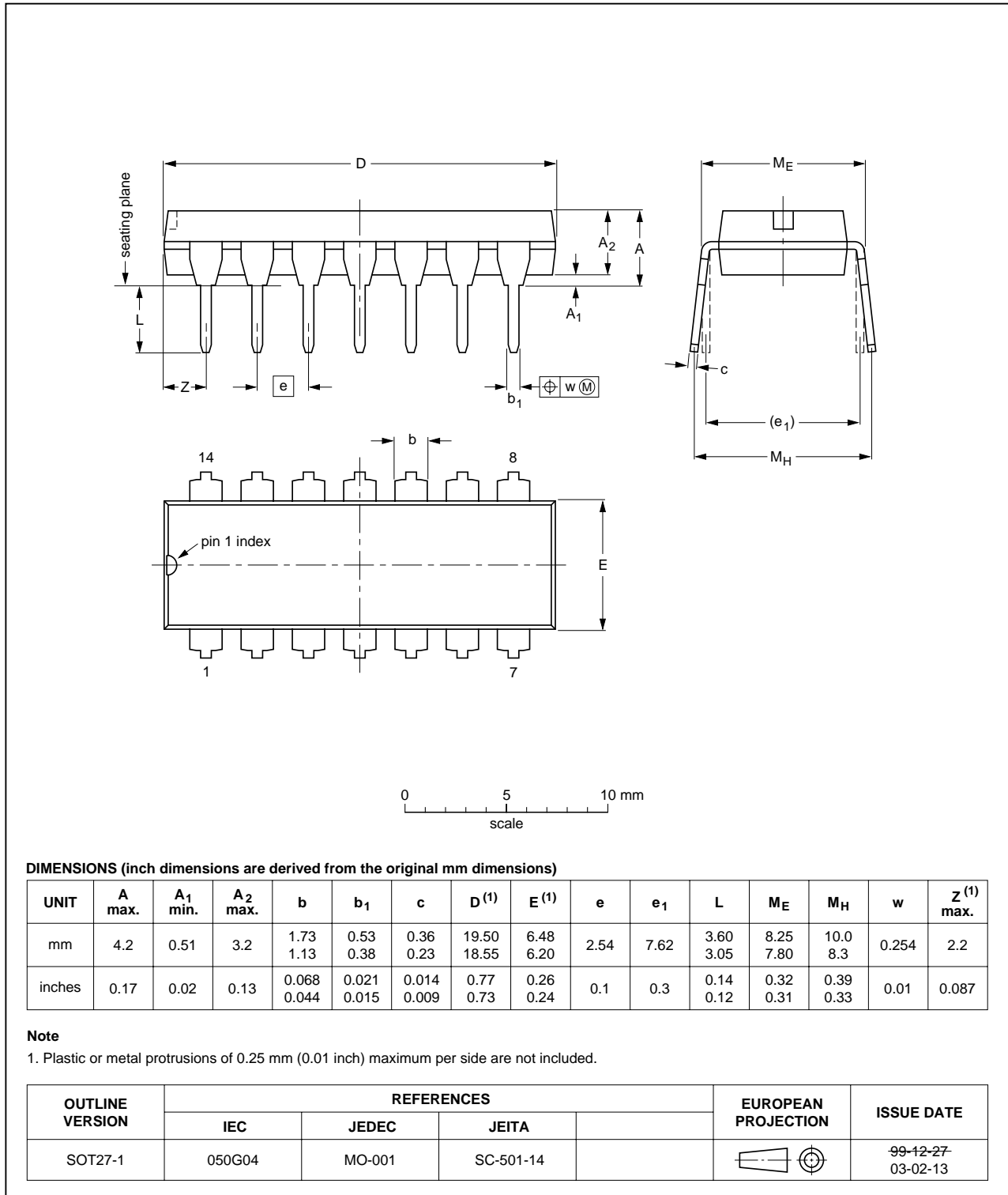


Fig 9. Package outline SOT27-1 (DIP14)

SO14: plastic small outline package; 14 leads; body width 3.9 mm

SOT108-1

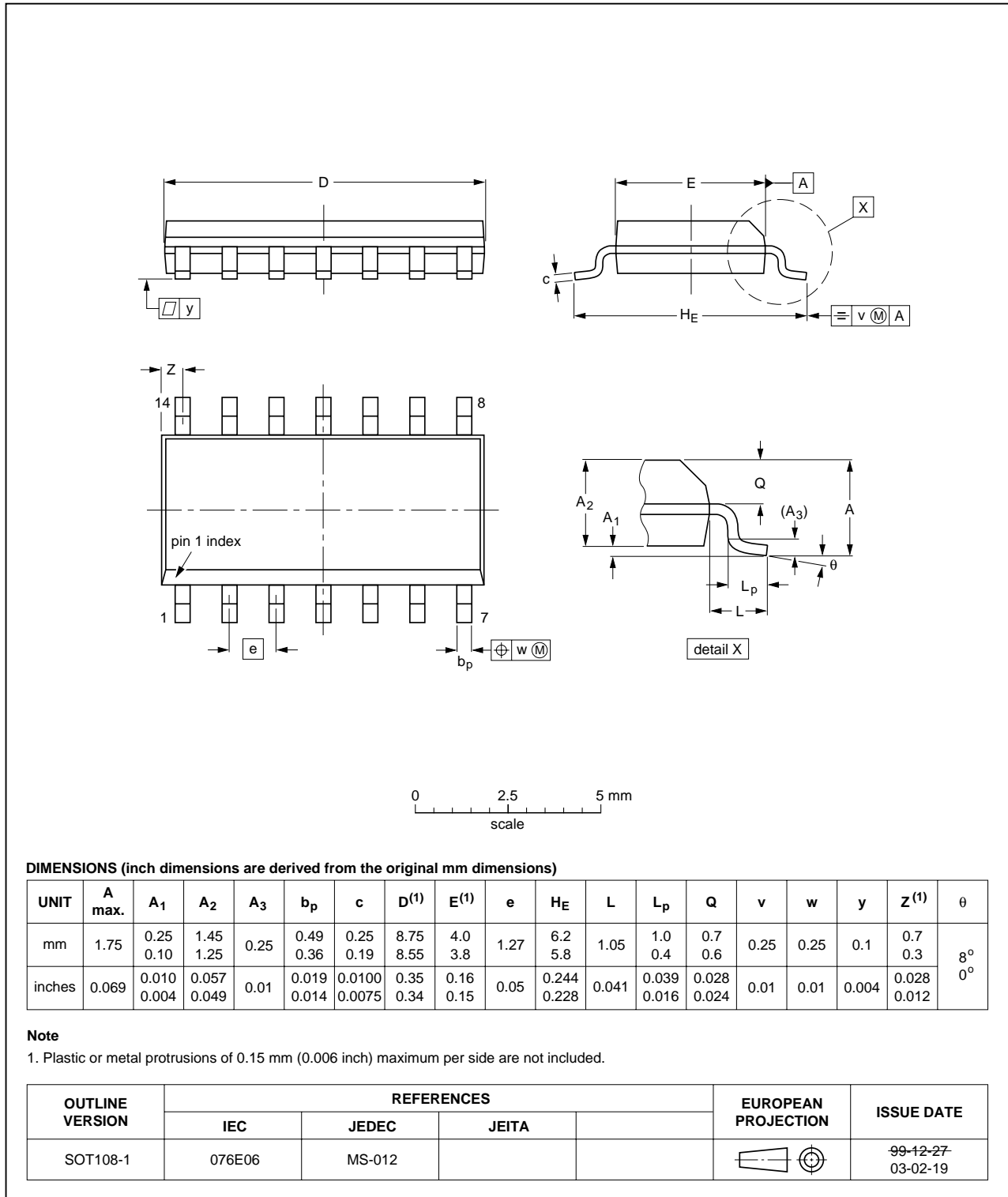


Fig 10. Package outline SOT108-1 (SO14)

SSOP14: plastic shrink small outline package; 14 leads; body width 5.3 mm

SOT337-1

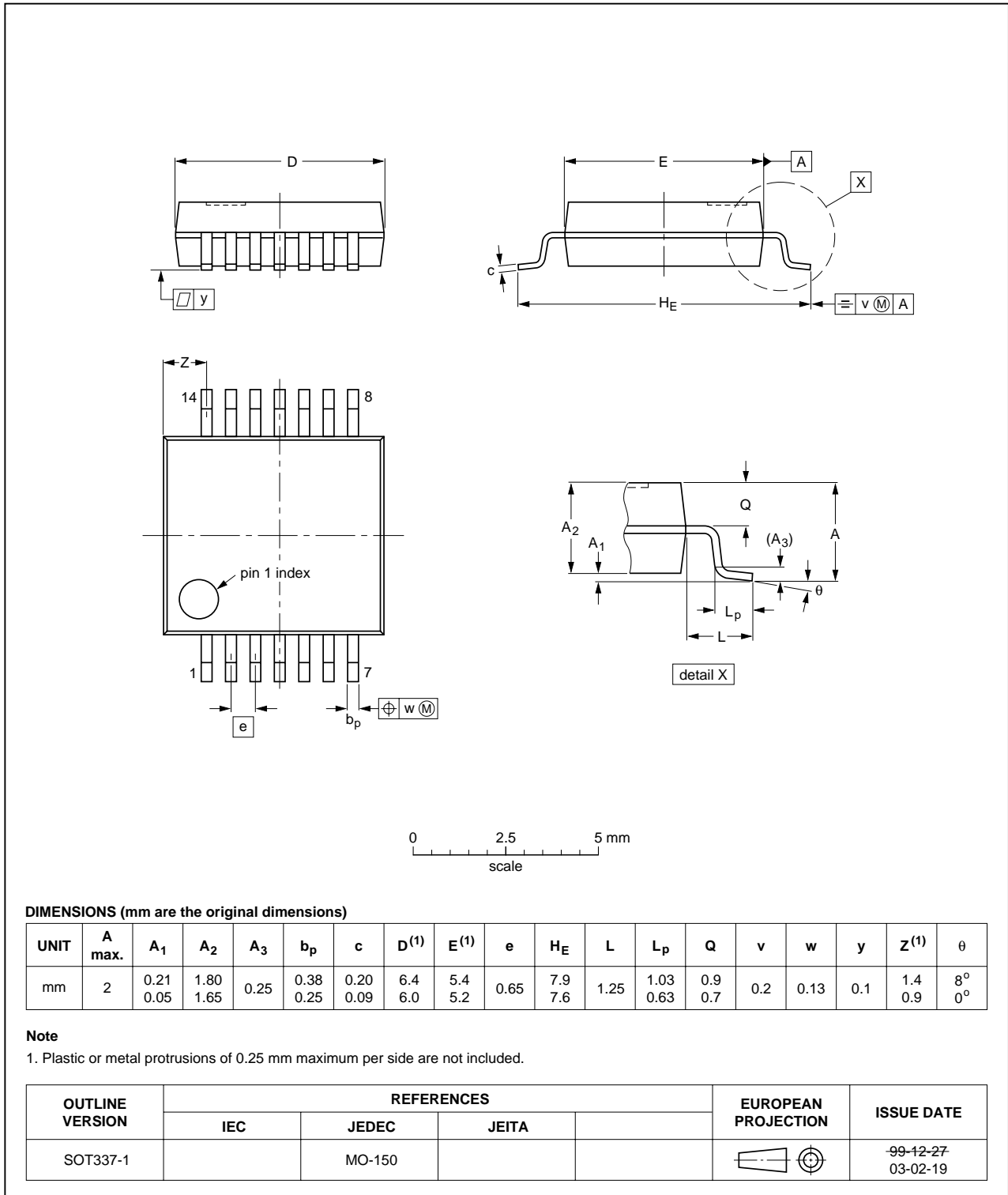


Fig 11. Package outline SOT337-1 (SSOP14)

TSSOP14: plastic thin shrink small outline package; 14 leads; body width 4.4 mm

SOT402-1

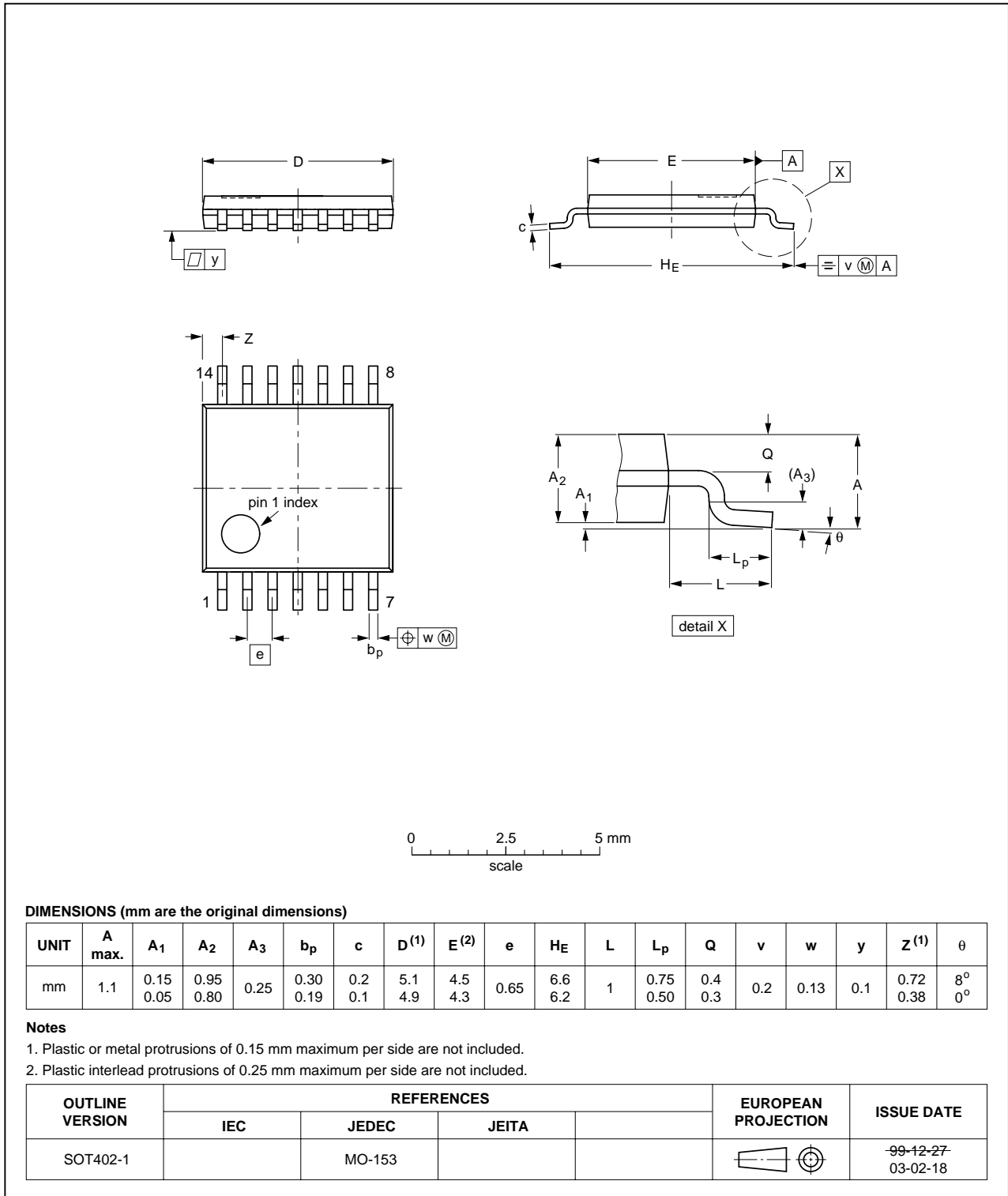


Fig 12. Package outline SOT402-1 (TSSOP14)

14. Revision history

Table 10: Revision history

| Document ID | Release date | Data sheet status | Change notice | Doc. number | Supersedes |
|------------------|--------------|-----------------------|---------------|----------------|---|
| 74HC73_3 | 20041112 | Product data sheet | - | 9397 750 13815 | 74HC_HCT73_CNV_2 |
| Modifications: | | | | | |
| | | | | | <ul style="list-style-type: none">• The format of this data sheet has been redesigned to comply with the current presentation and information standard of Philips Semiconductors.• Removed type number 74HCT73.• Inserted family specification. |
| 74HC_HCT73_CNV_2 | 19970911 | Product specification | - | - | 74HC_HCT73_1 |
| 74HC_HCT73_1 | 19901201 | Product specification | - | - | - |

15. Data sheet status

| Level | Data sheet status ^[1] | Product status ^[2] ^[3] | Definition |
|-------|----------------------------------|--|--|
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[1] Please consult the most recently issued data sheet before initiating or completing a design.

[2] The product status of the device(s) described in this data sheet may have changed since this data sheet was published. The latest information is available on the Internet at URL <http://www.semiconductors.philips.com>.

[3] For data sheets describing multiple type numbers, the highest-level product status determines the data sheet status.

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Limiting values definition — Limiting values given are in accordance with the Absolute Maximum Rating System (IEC 60134). Stress above one or more of the limiting values may cause permanent damage to the device. These are stress ratings only and operation of the device at these or at any other conditions above those given in the Characteristics sections of the specification is not implied. Exposure to limiting values for extended periods may affect device reliability.

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18. Contact information

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For sales office addresses, send an email to: sales.addresses@www.semiconductors.philips.com

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