

# STV9325

### Vertical Deflection Booster for 2.5-A<sub>PP</sub>TV/Monitor Applications with 70-V Flyback Generator

### **Main Features**

- Power Amplifier
- Flyback Generator
- Stand-by Control
- Output Current up to 2.5 App
- Thermal Protection

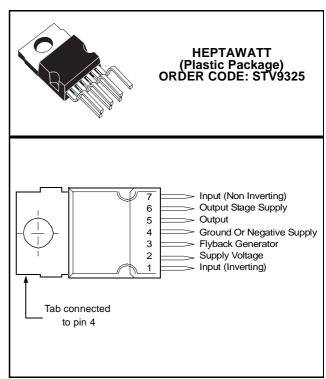
### Description

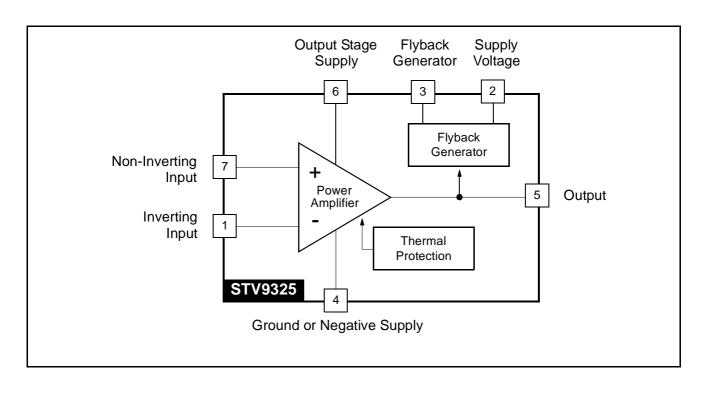
The STV9325 is a vertical deflection booster designed for TV and monitor applications.

This device, supplied with up to 35 V, provides up to 2.5 App output current to drive the vertical deflection yoke.

The internal flyback generator delivers flyback voltages up to 75 V.

In double-supply applications, a stand-by state will be reached by stopping the (+) supply alone.





# 1 Absolute Maximum Ratings

Symbol	Parameter	Value	Unit
Voltage			
V <sub>S</sub>	Supply Voltage (pin 2) - Note 1 and Note 2	40	V
V <sub>5</sub> , V <sub>6</sub>	Flyback Peak Voltage - Note 2	75	V
V <sub>3</sub>	Voltage at Pin 3 - Note 2, Note 3 and Note 6	-0.4 to (V <sub>S</sub> + 3)	V
V <sub>1</sub> , V <sub>7</sub>	Amplifier Input Voltage - Note 2, Note 6 and Note 7	- 0.4 to (V <sub>S</sub> + 2) or +40	V
Current			
I <sub>0</sub> (1)	Output Peak Current at f = 50 to 200 Hz, t $\leq$ 10µs - Note 4	±5	А
I <sub>0</sub> (2)	Output Peak Current non-repetitive - Note 5	±2	Α
I <sub>3</sub> Sink	Sink Current, t<1ms - Note 3	2	А
I <sub>3</sub> Source	Source Current, t < 1ms	2	А
l <sub>3</sub>	Flyback pulse current at f=50 to 200 Hz, t≤10µs - Note 4	±5	Α
ESD Susceptibil	ity		
ESD1	Human body model (100 pF discharged through 1.5 k $\Omega$ )	2	kV
ESD2	EIAJ Standard (200 pF discharged through 0 $\Omega$ )	300	V
Temperature		· · ·	
Τ <sub>s</sub>	Storage Temperature	-40 to 150	°C
Т <sub>і</sub>	Junction Temperature	+150	°C

Note:1. Usually the flyback voltage is slightly more than 2 x  $V_S$ . This must be taken into consideration when setting  $V_{S}$ .

- 2. Versus pin 4
- 3. V3 is higher than  $V_S$  during the first half of the flyback pulse.
- 4. Such repetitive output peak currents are usually observed just before and after the flyback pulse.
- 5. This non-repetitive output peak current can be observed, for example, during the Switch-On/Switch-Off phases. This peak current is acceptable providing the SOA is respected (Figure 8 and Figure 9).
- 6. All pins have a reverse diode towards pin 4, these diodes should never be forward-biased.
- 7. Input voltages must not exceed the lower value of either  $V_S$  + 2 or 40 volts.

# 2 Thermal Data

Symbol	Parameter	Value	Unit
R <sub>thJC</sub>	Junction-to-Case Thermal Resistance	3	°C/W
T <sub>T</sub>	Temperature for Thermal Shutdown	150	°C
TJ	Recommended Max. Junction Temperature	120	°C



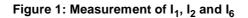
## **3** Electrical Characteristics

(V<sub>S</sub> = 34 V,  $T_{AMB}$  = 25°C, unless otherwise specified)

Symbol	Parameter	Test Conditions	Min.	Тур.	Max.	Unit	Fig.
Supply							
VS	Operating Supply Voltage Range (V <sub>2</sub> -V <sub>4</sub> )	Note 8	10		35	V	
I <sub>2</sub>	Pin 2 Quiescent Current	$I_3 = 0, I_5 = 0$		5	20	mA	1
I <sub>6</sub>	Pin 6 Quiescent Current	I <sub>3</sub> = 0, I <sub>5</sub> = 0, V <sub>6</sub> =35v 8		19	50	mA	1
Input							
I <sub>1</sub>	Input Bias Current	V <sub>1</sub> = 1 V, V <sub>7</sub> = 2.2 V		- 0.6	-1.5	μA	1
I <sub>7</sub>	Input Bias Current	V <sub>1</sub> = 2.2 V, V <sub>7</sub> = 1 V		- 0.6	-1.5	μA	
V <sub>IR</sub>	Operating Input Voltage Range		0		V <sub>S</sub> - 2	V	
V <sub>I0</sub>	Offset Voltage			2		mV	
$\Delta V_{I0}/dt$	Offset Drift versus Temperature			10		µV/°C	
Output		L					
I <sub>0</sub>	Operating Peak Output Current	0° <tcase<125°c< td=""><td></td><td></td><td>±1.25</td><td>А</td><td></td></tcase<125°c<>			±1.25	А	
V <sub>5L</sub>	Output Saturation Voltage to pin 4	I <sub>5</sub> = 1.25 A		0.9	1.6	V	3
V <sub>5H</sub>	Output Saturation Voltage to pin 6	I <sub>5</sub> = -1.25 A		1.5	2.2	V	2
Stand-by							
V <sub>5STBY</sub>	Output Voltage in Stand-by	$V_1 = V_7 = V_S = 0$ See Note 9	V <sub>S</sub> - 2			V	
Miscellan	eous		1				
G	Voltage Gain		80			dB	
$V_{D5-6}$	Diode Forward Voltage Between pins 5-6	I <sub>5</sub> = 1.25 A		1.5	2.1	V	
V <sub>D3-2</sub>	Diode Forward Voltage between pins 3-2	I <sub>3</sub> = 1.25 A		1.5	2.1	V	
V <sub>3SL</sub>	Saturation Voltage on pin 3	I <sub>3</sub> = 20 mA		0.4	1	V	3
V <sub>3SH</sub>	Saturation Voltage to pin 2 (2nd part of flyback)	I <sub>3</sub> = -1.25 A		1.8	2.6	V	

- 8. In normal applications, the peak flyback voltage is slightly greater than 2 x ( $V_S V_4$ ). Therefore, ( $V_S V_4$ ) = 35 V is not allowed without special circuitry.
- 9. Refer to Figure 4, Stand-by condition.

57



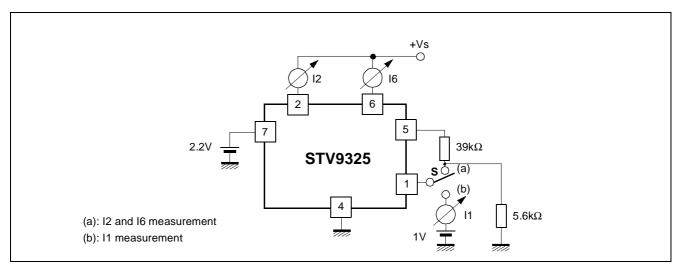


Figure 2: Measurement of V<sub>5H</sub>

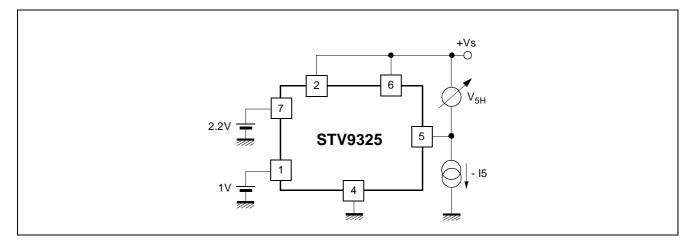
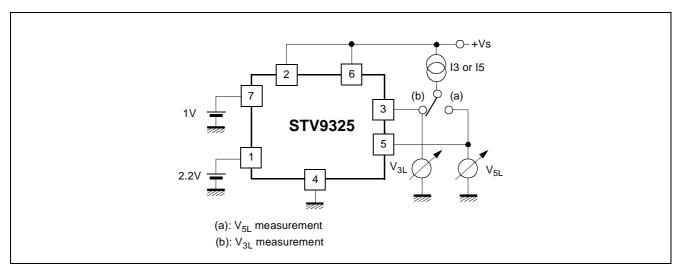


Figure 3: Measurement of  $V_{3L}$  and  $V_{5L}$ 



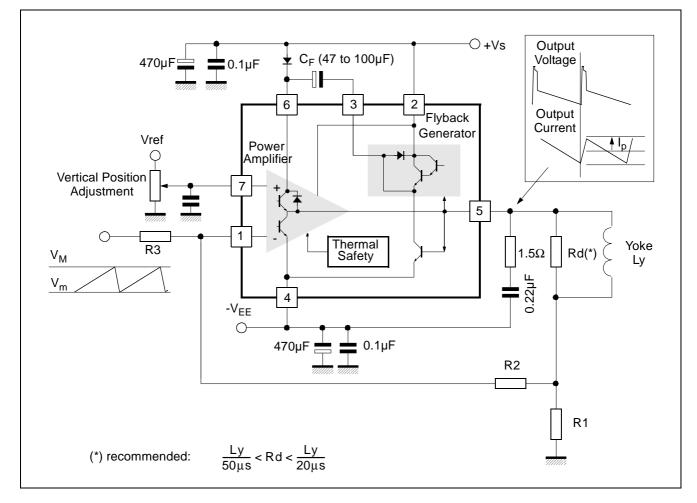
### 4 Application Hints

The yoke can be coupled either in AC or DC.

### 4.1 DC-coupled Application

When DC coupled (see Figure 4), the display vertical position can be adjusted with input bias. On the other hand, 2 supply sources (V<sub>S</sub> and -V<sub>EE</sub>) are required.

A Stand-by state will be reached by switching OFF the positive supply alone. In this state, where both inputs are the same voltage as pin 2 or higher, the output will sink negligible current from the deviation coil.



#### Figure 4: DC-coupled Application

#### 4.1.1 Application Hints

For calculations, treat the IC as an op-amp, where the feedback loop maintains  $V_1 = V_7$ .

**ل\_م/** 

#### 4.1.1.1 Centering

Display will be centered (null mean current in yoke) when voltage on pin 7 is (R1 is negligible):

$$V_7 = \frac{V_M + V_m}{2} \times \left(\frac{R_2}{R_2 + R_3}\right)$$

#### 4.1.1.2 Peak Current

$$I_{\mathsf{P}} = \frac{(\mathsf{V}_{\mathsf{M}} - \mathsf{V}_{\mathsf{m}})}{2} \times \frac{\mathsf{R}_2}{\mathsf{R}_1 \mathsf{x} \mathsf{R}_3}$$

Example: for V<sub>m</sub> = 2 V, V<sub>M</sub> = 5 V and I<sub>P</sub> = 1 A

Choose  $R_1$  in the 1  $\Omega$  range, for instance  $R_1=1 \Omega$ 

From equation of peak current:  $\frac{R_2}{R_3} = \frac{2 \times I_P \times R_1}{V_M - V_m} = \frac{2}{3}$ 

Then choose  $R_2$  or  $R_3$ . For instance, if  $R_2 = 10 \text{ k}\Omega$ , then  $R_3 = 15 \text{ k}\Omega$ 

Finally, the bias voltage on pin 7 should be:

$$V_7 = \frac{V_M + V_m}{2} \times \frac{1}{1 + \frac{R_3}{R_2}} = \frac{7}{2} \times \frac{1}{2.5} = 1.4V$$

#### 4.1.2 Ripple Rejection

When both ramp signal and bias are provided by the same driver IC, you can gain natural rejection of any ripple caused by a voltage drop in the ground (see Figure 5), if you manage to apply the same fraction of ripple voltage to both booster inputs. For that purpose, arrange an intermediate point in the bias resistor bridge, such that  $(R_8 / R_7) = (R_3 / R_2)$ , and connect the bias filtering capacitor between the intermediate point and the local driver ground. Of course,  $R_7$  should be connected to the booster reference point, which is the ground side of  $R_1$ .

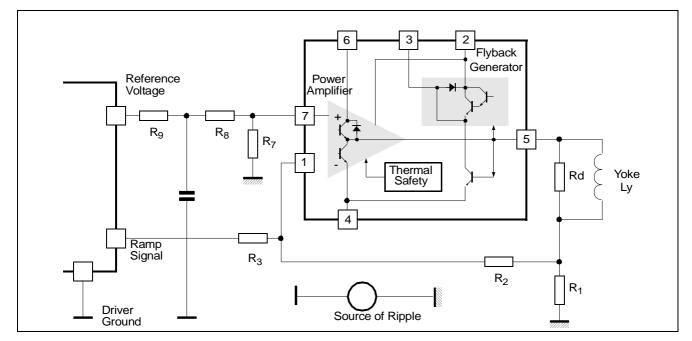


Figure 5: Ripple Rejection

### 4.2 AC-Coupled Applications

In AC-coupled applications (See Figure 6), only one supply ( $V_S$ ) is needed. The vertical position of the scanning cannot be adjusted with input bias (for that purpose, usually some current is injected or sunk with a resistor in the low side of the yoke).

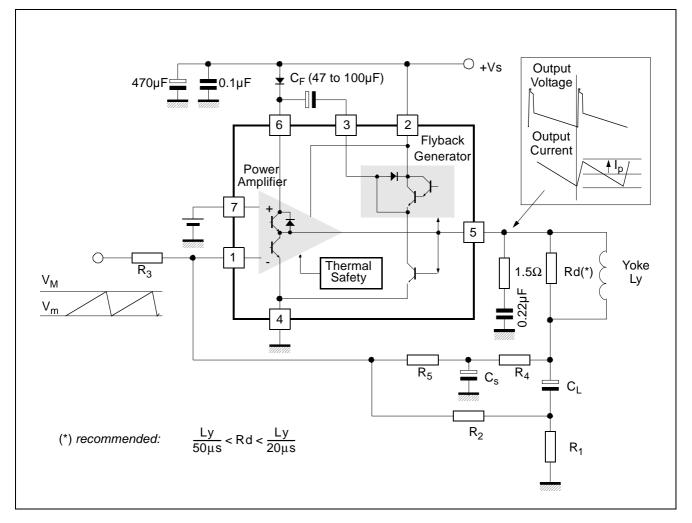


Figure 6: AC-coupled Application

#### 4.2.1 Application Hints

Gain is defined as in the previous case:

$$I_{p} = \frac{V_{M} - V_{m}}{2} \times \frac{R_{2}}{R_{1} \times R_{3}}$$

Choose  $R_1$  then either  $R_2$  or  $R_3$ . For good output centering,  $V_7$  must fulfill the following equation:

$$\frac{V_{S}}{\frac{2}{R_{4}} + R_{5}} = \frac{V_{7} - \frac{V_{M} + V_{m}}{2}}{R_{3}} + \frac{V_{7}}{R_{2}}$$

or

$$V_7 \times \left(\frac{1}{R_3} + \frac{1}{R_2} + \frac{1}{R_4 + R_5}\right) = \left(\frac{V_S}{2(R_4 + R_5)} + \frac{V_M + V_m}{2 \times R_3}\right)$$

57

**A7** 

 $C_S$  performs an integration of the parabolic signal on  $C_L$ , therefore the amount of S correction is set by the combination of  $C_L$  and  $C_s$ .

### 4.3 Application with Differential-output Drivers

Certain driver ICs provide the ramp signal in differential form, as two current sources  $i_{+}$  and  $i_{-}$  with opposite variations.

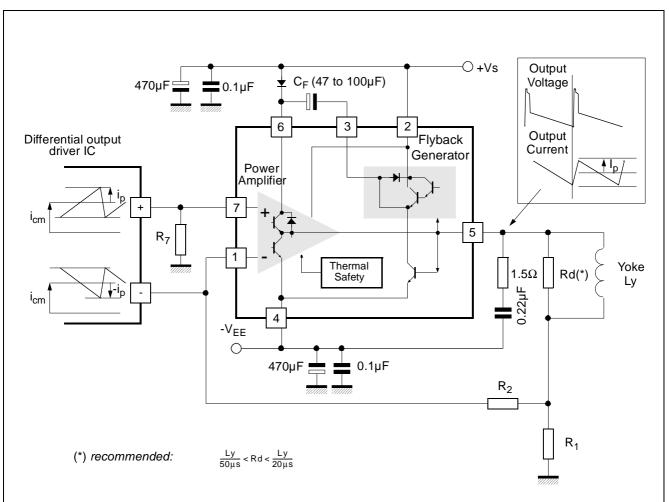


Figure 7: Using a Differential-output Driver

Let us set some definitions:

- $i_{cm}$  is the common-mode current:  $i_{cm} = \frac{1}{2}(i_+ + i_-)$
- at peak of signal,  $i_+ = i_{cm} + i_p$  and  $i_- = i_{cm} i_p$ , therefore the peak differential signal is  $i_p (-i_p) = 2 i_p$ , and the peak-peak differential signal,  $4i_p$ .

The application is described in Figure 7 with DC yoke coupling. The calculations still rely on the fact that  $V_1$  remains equal to  $V_7$ .

### 4.3.1 Centring

When idle, both driver outputs provide  $i_{cm}$  and the yoke current should be null (R<sub>1</sub> is negligible), hence:

 $i_{cm} \cdot R_7 = i_{cm} \cdot R_2$  therefore  $R_7 = R_2$ 

#### 4.3.2 Peak Current

Scanning current should be IP when positive and negative driver outputs provide respectively

 $i_{cm}$  -  $i_{p}$  and  $i_{cm}$  +  $i_{p},$  therefore

 $(i_{cm}-i) \cdot R_7 = I_p \cdot R_1 + (i_{cm}+i) \cdot R_2$  and since  $R_7 = R_2$ :  $\frac{I_p}{i} = -\frac{2R_7}{R_1}$ 

Choose  $R_1$  in the 1 $\Omega$  range, the value of  $R_2 = R_7$  follows. Remember that i is one-quarter of driver peak-peak differential signal! Also check that the voltages on the driver outputs remain inside allowed range.

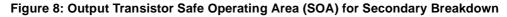
Example: for i<sub>cm</sub> = 0.4mA, i = 0.2mA (corresponding to 0.8mA of peak-peak differential current), I<sub>n</sub> = 1A

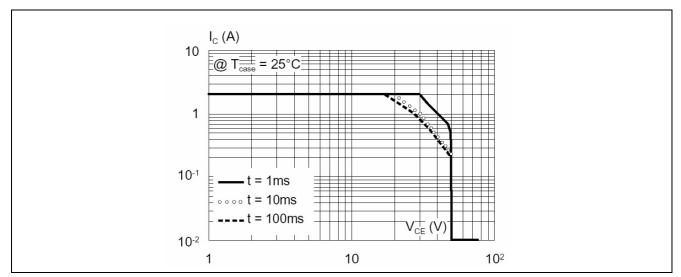
Choose  $R_1 = 0.75\Omega$ , it follows  $R_2 = R_7 = 1.875k\Omega$ .

#### 4.3.3 Ripple Rejection

Make sure to connect R7 directly to the ground side of R1.

#### 4.3.4 Secondary Breakdown Diagrams





The diagram has been arbitrarily limited to max I0 (2 A).

**لرك**ا

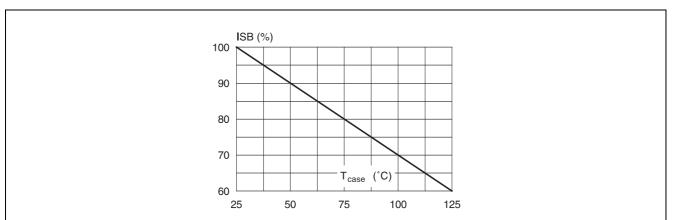
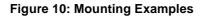


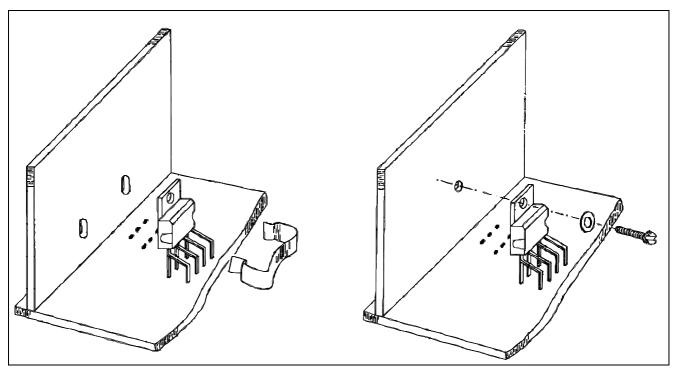
Figure 9: Secondary Breakdown Temperature Derating Curve (ISB = Secondary Breakdown Current)

# 5 Mounting Instructions

The power dissipated in the circuit is removed by adding an external heatsink. With the HEPTAWATT<sup>™</sup> package, the heatsink is simply attached with a screw or a compression spring (clip).

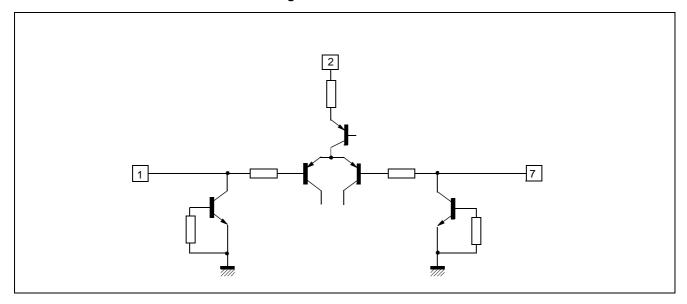
A layer of silicon grease inserted between heatsink and package optimizes thermal contact. In DCcoupled applications we recommend to use a silicone tape between the device tab and the heatsink to electrically isolate the tab.



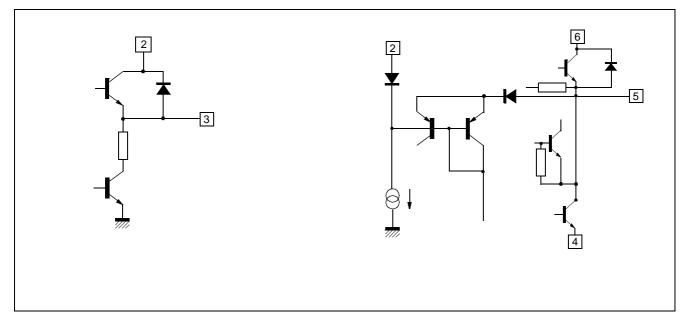


# 6 Pin Configuration

Figure 11: Pins 1 and 7



### Figure 12: Pin 3 & Pins 5 and 6



# 7 Package Mechanical Data

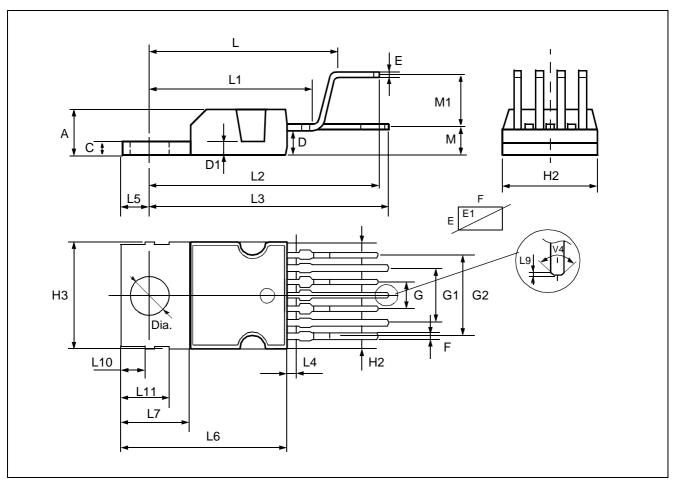


Figure 13: 7-pin Heptawatt Package

#### Table 1: Heptawatt Package

Dim.		mm		inches		
Dini.	Min.	Тур.	Max.	Min.	Тур.	Max.
Α			4.8			0.189
С			1.37			0.054
D	2.40		2.80	0.094		0.110
D1	1.20		1.35	0.047		0.053
E	0.35		0.55	0.014		0.022
E1	0.70		0.97	0.028		0.038
F	0.60		0.80	0.024		0.031
G	2.34	2.54	2.74	0.095	0.100	0.105
G1	4.88	5.08	5.28	0.193	0.200	0.205
G2	7.42	7.62	7.82	0.295	0.300	0.307
H2			10.40			0.409
H3	10.05		10.40	0.396		0.409
L	16.70	16.90	17.10	0.657	0.668	0.673



Dim.		mm		inches		
Dini.	Min.	Тур.	Max.	Min.	Тур.	Max.
L1		14.92			0.587	
L2	21.24	21.54	21.84	0.386	0.848	0.860
L3	22.27	22.52	22.77	0.877	0.891	0.896
L4			1.29			0.051
L5	2.60	2.80	3.00	0.102	0.110	0.118
L6	15.10	15.50	15.80	0.594	0.610	0.622
L7	6.00	6.35	6.60	0.0236	0.250	0.260
L9		0.20			0.008	
L10	2.10		2.70	0.082		0.106
L11	4.30		4.80	0.169		0.190
М	2.55	2.80	3.05	0.100	0.110	0.120
M1	4.83	5.08	5.33	0.190	0.200	0.210
V4		40 (Тур.)				
Dia.	3.65		3.85	0.144		0.152

#### Table 1: Heptawatt Package (Continued)

# 8 Revision History

Version	Date Description		
1.0	April 2003	First Issue.	
1.1	April 2003	Correction to Section 4.1.1.2: Peak Current. Creation of new title, Section 4.3.4: Secondary Breakdown Diagrams.	
1.2	November 2003	Datasheet status changed to preliminary data.	
1.3 December 2003 Modification to Figure 11.		Modification to Figure 11.	
1.4	April 2004	April 2004 Flyback voltage value changed on page 1.	
1.5	June 2004	Datasheet status changed to datasheet.	

#### **Table 2: Summary of Modifications**

Information furnished is believed to be accurate and reliable. However, STMicroelectronics assumes no responsibility for the consequences of use of such information nor for any infringement of patents or other rights of third parties which may result from its use. No license is granted by implication or otherwise under any patent or patent rights of STMicroelectronics. Specifications mentioned in this publication are subject to change without notice. This publication supersedes and replaces all information previously supplied. STMicroelectronics products are not authorized for use as critical components in life support devices or systems without express written approval of STMicroelectronics.

The ST logo is a registered trademark of STMicroelectronics

All other names are the property of their respective owners

© 2004 STMicroelectronics - All rights reserved

STMicroelectronics GROUP OF COMPANIES

Australia - Belgium - Brazil - Canada - China - Czech Republic - Finland - France - Germany - Hong Kong - India - Israel - Italy - Japan - Malaysia - Malta - Morocco - Singapore - Spain - Sweden - Switzerland - United Kingdom - United States

www.st.com