

LM2900/LM3900/LM3301 Quad Amplifiers

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| If Military/Aerospace specified devices are requ Distributors for availability and specifications. | uired, please contact the National Sem | iconductor Sales Office/ | | | |
|---|--|--|--|--|--|
| Supply Voltage | LM2900/LM3900 32 V _{DC} ±16 V _{DC} | LM3301 28 V _{DC} ± 14 V _{DC} | | | |
| Power Dissipation (T _A = 25°C) (Note 1) Molded DIP S.O. Package | 1080 mW 765 mW | 1080 mW | | | |
| Input Currents, I_{IN}^+ or I_{IN}^- | 20 mA _{DC} | 20 mA _{DC} | | | |
| Output Short-Circuit Duration—One Amplifier $T_A = 25^{\circ}C$ (See Application Hints) | Continuous | Continuous | | | |
| Operating Temperature Range LM2900 LM3900 | -40°C to +85°C 0°C to +70°C | -40°C to +85°C | | | |
| Storage Temperature Range | -65°C to +150°C | -65°C to +150°C | | | |
| Lead Temperature (Soldering, 10 sec.) | 260°C | 260°C | | | |
| Soldering Information Dual-In-Line Package | | | | | |
| Soldering (10 sec.) Small Outline Package | 260°C | 260°C | | | |
| Vapor Phase (60 sec.) | 215°C | 215°C | | | |
| Infrared (15 sec.) | 220°C | 220°C | | | |

2000V

devices. ESD tolerance (Note 7)

2000V

Electrical Characteristics $T_{A} = 25^{\circ}C, V^{+} = 15 V_{DC}$, unless otherwise stated

| - | | Conditions | | LM2900 | | | LM3900 | | | LM3301 | | | | |
|-----------------------------------|-----------------------|---|---|--------|-----------|-----|--------|-----------|-----|--------|-----------|-------|------------------|--|
| F | Parameter Conditions | | Min | Тур | Max | Min | Тур | Мах | Min | Тур | Max | Units | | |
| Open | Voltage Gain | Over Temp. | | | | | | | | | | | | |
| Loop | Voltage Gain | $\Delta V_{O} = 10 V_{DC}$ | | 1.2 | 2.8 | | 1.2 | 2.8 | | 1.2 | 2.8 | | V/mV | |
| Input Resistance | | Inverting Input | | | 1 | | | 1 | | | 1 | | MΩ | |
| | Output Resistance | | | | 8 | | | 8 | | | 9 | | kΩ | |
| Unity Gain Bandwidth Inverting Ir | | Inverting Input | ting Input | | 2.5 | | | 2.5 | | | 2.5 | | MHz | |
| Input Bias Current | | Inverting Input, $V^+ = 5 V_{DC}$ Inverting Input | | | 30 | 200 | | 30 | 200 | | 30 | 300 | nA | |
| Slew Rate | | Positive Output Swing Negative Output Swing | | | 0.5 20 | | | 0.5 20 | | | 0.5 20 | | V/µs | |
| Supply Current | | $R_L = \infty$ On All Amplifiers | | | 6.2 | 10 | | 6.2 | 10 | | 6.2 | 10 | mA _{DC} | |
| Output Voltage Swing | V _{OUT} High | $\begin{array}{l} R_{L} = 2k, \\ V^+ = 15.0 \ V_{DC} \end{array}$ | $I_{IN}^{-} = 0,$ $I_{IN}^{+} = 0$ | 13.5 | | | 13.5 | | | 13.5 | | | | |
| | V _{OUT} Low | | $I_{\text{IN}}^{-} = 10 \ \mu\text{A},$ $I_{\text{IN}}^{+} = 0$ | | 0.09 | 0.2 | | 0.09 | 0.2 | | 0.09 | 0.2 | V _{DC} | |
| | V _{OUT} High | V ⁺ = Absolute Maximum Ratings | | 29.5 | | | 29.5 | | | 26.0 | | | | |
| Output Current Capability | Source | | | 6 | 18 | | 6 | 10 | | 5 | 18 | | | |
| | Sink | (Note 2) $V_{OL} = 1V, I_{IN}^{-} = 5 \mu A$ | | 0.5 | 1.3 | | 0.5 | 1.3 | | 0.5 | 1.3 | | mA _{DC} | |
| | I _{SINK} | | | | 5 | | | 5 | | | 5 | | | |

| Parameter | Conditions | LM2900 | | | LM3900 | | | LM3301 | | | |
|------------------------|---------------------------------------|--------------|------------|------------|--------------|------------|------------|--------------|--------|--------------|------------------|
| | | Min | Тур | Мах | Min | Тур | Max | Min | Тур | Max | Units |
| Power Supply Rejection | T _A = 25°C, f = 100 Hz | | 70 | | | 70 | | | 70 | | dB |
| Mirror Gain | @ 20 μA (Note 3) @ 200 μA (Note 3) | 0.90 0.90 | 1.0 1.0 | 1.1 1.1 | 0.90 0.90 | 1.0 1.0 | 1.1 1.1 | 0.90 0.90 | 1 1 | 1.10 1.10 | μΑ/μΑ |
| ∆Mirror Gain | @ 20 μA to 200 μA (Note 3) | | 2 | 5 | | 2 | 5 | | 2 | 5 | % |
| Mirror Current | (Note 4) | | 10 | 500 | | 10 | 500 | | 10 | 500 | μA_{DC} |
| Negative Input Current | T _A = 25°C (Note 5) | | 1.0 | | | 1.0 | | | 1.0 | | mA _{DC} |
| Input Bias Current | Inverting Input | | 300 | | | 300 | | | | | nA |

Note 1: For operating at high temperatures, the device must be derated based on a 125°C maximum junction temperature and a thermal resistance of 92°C/W which applies for the device soldered in a printed circuit board, operating in a still air ambient. Thermal resistance for the S.O. package is 131°C/W. Note 2: The output current sink capability can be increased for large signal conditions by overdriving the inverting input. This is shown in the section on Typical

Note 2: The output current sink capability can be increased for large signal conditions by overdriving the inverting input. This is shown in the section on Typical Characteristics.

Note 3: This spec indicates the current gain of the current mirror which is used as the non-inverting input.

Note 4: Input V_{BE} match between the non-inverting and the inverting inputs occurs for a mirror current (non-inverting input current) of approximately 10 µA. This is therefore a typical design center for many of the application circuits.

Note 5: Clamp transistors are included on the IC to prevent the input voltages from swinging below ground more than approximately $-0.3 V_{DC}$. The negative input currents which may result from large signal overdrive with capacitance input coupling need to be externally limited to values of approximately 1 mA. Negative input currents in excess of 4 mA will cause the output voltage to drop to a low voltage. This maximum current applies to any one of the input terminals. If more than one of the input terminals are simultaneously driven negative smaller maximum currents are allowed. Common-mode current biasing can be used to prevent negative input voltages; see for example, the "Differentiator Circuit" in the applications section.

Note 6: These specs apply for $-40^\circ C \le T_A \le +85^\circ C$, unless otherwise stated.

Note 7: Human body model, 1.5 k Ω in series with 100 pF.

Application Hints

When driving either input from a low-impedance source, a limiting resistor should be placed in series with the input lead to limit the peak input current. Currents as large as 20 mA will not damage the device, but the current mirror on the non-inverting input will saturate and cause a loss of mirror gain at mA current levels—especially at high operating temperatures.

Precautions should be taken to insure that the power supply for the integrated circuit never becomes reversed in polarity or that the unit is not inadvertently installed backwards in a test socket as an unlimited current surge through the resulting forward diode within the IC could cause fusing of the internal conductors and result in a destroyed unit.

Output short circuits either to ground or to the positive power supply should be of short time duration. Units can be destroyed, not as a result of the short circuit current causing metal fusing, but rather due to the large increase in IC chip dissipation which will cause eventual failure due to excessive junction temperatures. For example, when operating from a well-regulated +5 V_{DC} power supply at $T_{A}\,=\,25^{\circ}C$ with a 100 k Ω shunt-feedback resistor (from the output to the inverting input) a short directly to the power supply will not cause catastrophic failure but the current magnitude will be approximately 50 mA and the junction temperature will be above T I max. Larger feedback resistors will reduce the current, 11 $\text{M}\Omega$ provides approximately 30 mA, an open circuit provides 1.3 mA, and a direct connection from the output to the non-inverting input will result in catastrophic failure when the output is shorted to V^+ as this then places the base-emitter junction of the input transistor directly across the power supply. Short-circuits to ground will have magnitudes of approximately 30 mA and will not cause catastrophic failure at $T_A = 25^{\circ}C$.

Unintentional signal coupling from the output to the non-inverting input can cause oscillations. This is likely only in breadboard hook-ups with long component leads and can be prevented by a more careful lead dress or by locating the non-inverting input biasing resistor close to the IC. A quick check of this condition is to bypass the non-inverting input to ground with a capacitor. High impedance biasing resistors used in the non-inverting input circuit make this input lead highly susceptible to unintentional AC signal pickup.

Operation of this amplifier can be best understood by noticing that input currents are differenced at the inverting-input terminal and this difference current then flows through the external feedback resistor to produce the output voltage. Common-mode current biasing is generally useful to allow operating with signal levels near ground or even negative as this maintains the inputs biased at +VBE. Internal clamp transistors (see note 5) catch-negative input voltages at approximately -0.3 V_{DC} but the magnitude of current flow has to be limited by the external input network. For operation at high temperature, this limit should be approximately 100 µA. This new "Norton" current-differencing amplifier can be used in most of the applications of a standard IC op amp. Performance as a DC amplifier using only a single supply is not as precise as a standard IC op amp operating with split supplies but is adequate in many less critical applications. New functions are made possible with this amplifier which are useful in single power supply systems. For example, biasing can be designed separately from the AC gain as was shown in the "inverting amplifier," the "difference integrator" allows controlling the charging and the discharging of the integrating capacitor with positive voltages, and the "frequency doubling tachometer" provides a simple circuit which reduces the ripple voltage on a tachometer output DC voltage.







































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