General Description

The MAX1282 evaluation system (EV system) is a complete four-channel data-acquisition system consisting of a MAX1282 evaluation kit (EV kit) and a Maxim 68HC16MODULE-DIP microcontroller (μ C) module. The MAX1282 is a high-speed, 12-bit data-acquisition system. Windows[®] 95/98 software provides a handy user interface to exercise the MAX1282's features.

Order the complete EV system (MAX1282EVC16) for comprehensive evaluation of the MAX1282 using a PC. Order the EV kit (MAX1282EVKIT) if the 68HC16MOD-ULE-DIP module has already been purchased with a previous Maxim EV system, or for custom use in other μ C-based systems.

MAX1282EVC16 System

PART	QTY	DESCRIPTION
MAX1282EVKIT	1	MAX1282 EV kit
68HC16MODULE-DIP	1	$68HC16 \mu C$ module

MAX1282EVKIT Component List

DESIGNATION	QTY	DESCRIPTION
C1–C4, C10	5	0.01µF ceramic capacitors
C9	1	$4.7 \mu F$ tantalum capacitor
C11, C13	2	0.1µF ceramic capacitors
C12, C14	2	10µF, 10V tantalum capacitors
J1	1	2x20 right-angle socket
JU1	1	2-pin header
JU2	1	3-pin header
R1–R4	4	$300\Omega \pm 5\%$ resistors
R9, R10	2	$10\Omega \pm 1\%$ resistors
TP1	1	8-pin header
U1	1	Maxim MAX1282BCUE (16-pin TSSOP)
None	1	PC board, MAX1282 EV kit
None	1	3-1/2in software disk, MAX1282
None	1	MAX1282 EV kit data sheet
None	1	MAX1282 data sheet

Windows 95/98 is a registered trademark of Microsoft Corp.

Features

- Proven PC Board Layout
- Convenient On-Board Test Points
- Data-Logging Software
- Fully Assembled and Tested

Ordering Information

PART	TEMP. RANGE	INTERFACE
MAX1282EVKIT	0°C to +70°C	User supplied
MAX1282EVC16	0°C to +70°C	Windows software

Note: MAX1282 software is designed for use with the complete EV system, MAX1282EVC16 (includes 68HC16MODULE-DIP module and MAX1282EVKIT). If the MAX1282 evaluation software will not be used, the MAX1282EVKIT board can be purchased by itself, without the μ C.

MAX1282EVKIT Files

	FILE	DESCRIPTION	
IN	NSTALL.EXE	Installs the EV kit files on your computer	
Μ	IAX1282.EXE	Application program	
K	IT1282.C16	Software loaded into 68HC16 μC	

Recommended Equipment

- Maxim MAX1282EVC16 (contains MAX1282EVKIT board and 68HC16MODULE-DIP)
- A small DC power supply, such as a 12VDC 0.25A plug-in transformer or a 9V battery
- An IBM PC-compatible computer running Windows
 95/98
- A spare serial communications port, preferably a 9pin plug
- A serial cable to connect the computer's serial port to the 68HC16MODULE-DIP

Quick Start

 Carefully connect the boards by aligning the 40-pin header of the MAX1282 EV kit with the 40-pin connector of the 68HC16MODULE-DIP module. Gently press them together. The two boards should be flush against one another.

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- 2) Ensure that JU1 is closed and JU2 is in the 1-2 position (Table 1).
- Connect a 7VDC to 20VDC power source to the μC module at the terminal block located next to the on/off switch, along the top edge of the μC module. Observe the polarity marked on the board.
- 4) Connect a cable from the computer's serial port to the μC module. If using a 9-pin serial port, use a straight-through, 9-pin female-to-male cable. If the only available serial port uses a 25-pin connector, a standard 25-pin to 9-pin adapter will be required. The EV kit software checks the modem status lines (CTS, DSR, DCD) to confirm that the correct port has been selected.
- 5) Install the MAX1282 EV kit software on your computer by running the INSTALL.EXE program on the floppy disk. The program files are copied and icons are created for them in the Windows Start menu.
- 6) Start the MAX1282 program by opening its icon in the Start menu.
- 7) The program will prompt you to connect the μC module and turn its power on. Slide SW1 to the ON position. Select the correct serial port, and press OK. The program will automatically download KIT1282.C16 to the module.
- 8) Apply input signal between CH0 and COM. Observe the readout on the screen.

_Detailed Description

MAX1282 Stand-Alone EV Kit

The MAX1282EVKIT provides a proven PC board layout to evaluate the MAX1282. It must be interfaced to appropriate timing signals for proper operation. Connect +5V to VDD, and connect ground return to GND (Figure 1). Refer to the MAX1282 data sheet for timing requirements.

MAX1282 EV System

The MAX1282EVC16 EV system operates from a usersupplied 7VDC to 20VDC power supply. Windows 95/98 software running on an IBM PC interfaces to the EV system board through the computer's serial communications port. See the *Quick Start* section for set-up and operating instructions.

Description of Software

The evaluation software's main window controls the serial clock speed and sample rate. It displays the voltage and output code, as well as some input signal statistics. A separate graph window shows the data changing in real time. The update rate is limited to about 10 samples per second, due to COM port bandwidth limitations.

Controls

The control word is divided into several fields. To change the active control word, drop down the appropriate field's combo box and select the desired option. If the QSPI[™] clock is set to STOP, then configuration data will not be sent until the READ button is pressed.

Statistics

The Minimum and Maximum fields show the highest and lowest readings acquired. The Average field shows a running mean. The Clear button resets the statistics. To remove offset errors, first apply 0V to the active input channel, clear statistics, acquire some samples, and then check Tare. This average offset voltage will now be subtracted from all subsequent measurements.

Sampling

Choose the desired sampling rate (QSPI clock), sampling size (Sample! menu item), and press Begin Sampling! (in Sample! pop-up window). Sample size is restricted to a power of two to permit FFT processing once the data is saved to a file. After the samples have been collected, the data is automatically uploaded to the host and is graphed. Once displayed, the data can optionally be saved to a file.

Saving Graphs to Disk

Data in the real-time graph and in sampled data graphs may be saved to a file. Only the raw output codes are saved, but voltages may be inferred, based on the reference voltage and the maximum code value.

Scanning All Channels Input Signal

To scan through all channels, select SCAN from the Input menu.

Table 1. Jumper Functions

JUMPER	POSITION	FUNCTION
	Closed*	COM tied to GND
JU1	Open	COM must be connected to analog common
JU2	1-2*	Operate
	2-3	Shutdown

*Default configuration

QSPI is a trademark of Motorola, Inc.



Evaluating Shutdown

The evaluation software configures the 68HC16's QSPI submodule to continuously read data from the MAX1282 into the 68HC16. The sample rate is controlled by the QSPI clock. To evaluate power-saving modes, these automatic updates must be stopped. First, set the QSPI clock control to STOP. This reconfigures the 68HC16's QSPI submodule to stop driving the serial clock. Second, in the evaluation software's main window, uncheck the Read Every...msec check-box. Next, choose the desired software power-down control word, and press the Read button to send the new configuration to the MAX1282. If evaluating the hardware shutdown, move jumper JU2 to the 2-3 position.

Reference Voltage

The evaluation software assumes a 2.5V reference voltage, unless otherwise specified. Refer to the MAX1282 data sheet for more information. To override this value, type the new reference voltage into the V_{REF} edit box and press the Set V_{REF} button. Note: This new V_{REF} value is used only by the evaluation software and does not physically change the reference voltage.

Detailed Hardware Description

U1, the MAX1282, is a high-speed, multichannel, 12-bit data-acquisition system. Resistors R1–R4 and capacitors C1–C4 form single-pole, lowpass anti-aliasing filters with a nominal 3µs time constant and a corner frequency of approximately 50kHz. C9 and C10 bypass the ADC's voltage reference and reference buffer. When plugged into the 68HC16MODULE, the VDD circuit is powered by +5V. (See Figure 1 and refer to the MAX1282 data sheet.)

Troubleshooting

Problem: No output measurement. System seems to report zero voltage or fails to make a measurement.

Check the VDD supply voltage. Check the reference voltage using a digital voltmeter (DVM). Use an oscilloscope to verify that the conversion-start signal is being strobed. Verify that SHDN is being driven high.

Problem: Measurements are erratic, unstable; poor accuracy.

Check the reference voltage using a DVM. Use an oscilloscope to check for noise. When probing for noise, keep the oscilloscope ground return lead as short as possible, preferably less than 1/2in (10mm).

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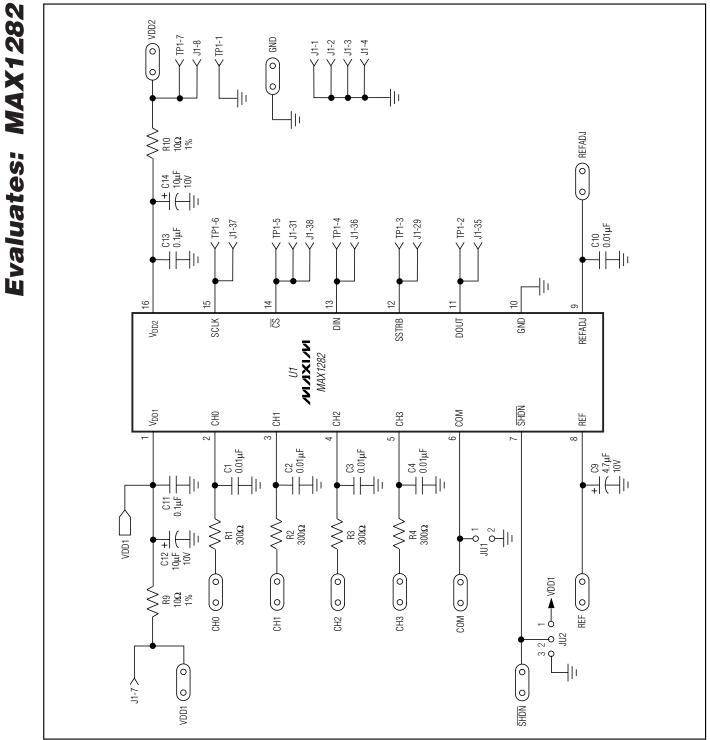


Figure 1. MAX1282 EV Kit Schematic

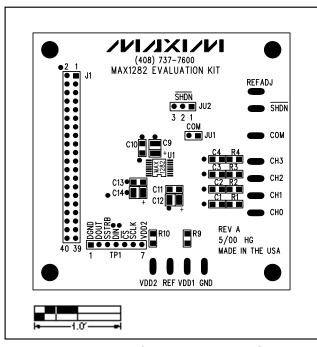


Figure 2. MAX1282 EV Kit Component Placement Guide— Component Side

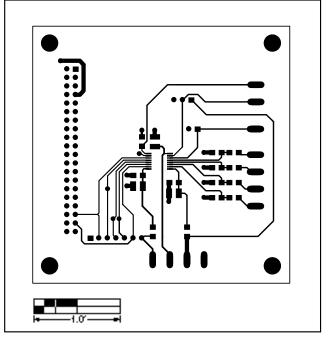


Figure 3. MAX1282 EV Kit PC Board Layout—Component Side

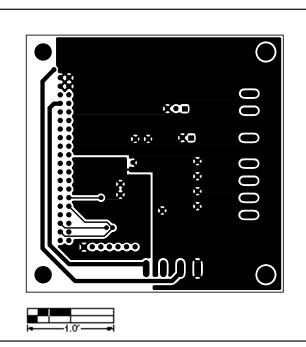


Figure 4. MAX1282 EV Kit PC Board Layout—Solder Side

Evaluates: MAX1282

NOTES

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