

TC35096P 8 BIT 4-CH SERIAL I/O ANALOG TO DIGITAL CONVERTER

GENERAL DESCRIPTION

The TC35096P is a monolithic CMOS 8 bit successive approximation A/D converter with serial I/O and 4 channel multiplex inputs.

Conversion start when CS is set low and start bit ("L" level) and channel select bit (two bits) are given to serial input DI.

In case that SE is high, as soon as the conversion starts a start bit ("L" level) appears at serial output DO and 8 bit conversion data (MSB first) and a stop bit ("H" level) follow continuously.

In case that SE is low, after the conversion is completed a start bit, 8 bit conversion data (LSB first) and a stop bit appear at DO.

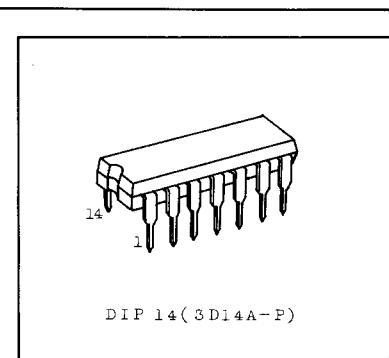
The TC35096P has features of high speed, high accuracy and microprocessor compatible I/O which make the device well suited to a broad application field such as process and machine control and automotive equipment.

FEATURES

- High accuracy $\pm \frac{3}{4}$ LSB MAX
- High speed conversion 32.5 μ s MAX @ $f_{CP} = 400$ kHz
- Single power supply 5V $\pm 10\%$
- Low power consumption 5 mW MAX @ $T_a = 25^\circ C$
- Serial I/O
- 4 channel analog multiplex input
- Easy interface to all microprocessors
- 3-state output
- Zero or full scale adjustment free

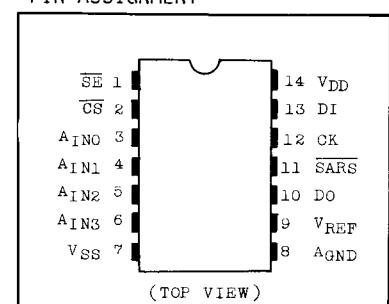
ABSOLUTE MAXIMUM RATINGS

PARAMETER	SYMBOL	VALUE	UNIT
Supply Voltage Range	V _{DD}	V _{SS} -0.5 ~ V _{SS} +7	V
DC Input Voltage	V _{IN}	V _{SS} -0.5 ~ V _{DD} +0.5	V
DC Output Voltage	V _{OUT}	V _{SS} -0.5 ~ V _{DD} +0.5	V
Reference Voltage	V _{REF}	V _{SS} -0.5 ~ V _{DD} +0.5	V
Analog Ground Voltage	A _{GND}	V _{SS} -0.5 ~ V _{DD} +0.5	V
DC Input Current	I _{IN}	± 10	mA
Power Dissipation	P _D	300	mA
Storage Temperature	T _{STG}	-65 ~ 150	°C
Lead Temperature 10 sec.	T _L	300	°C



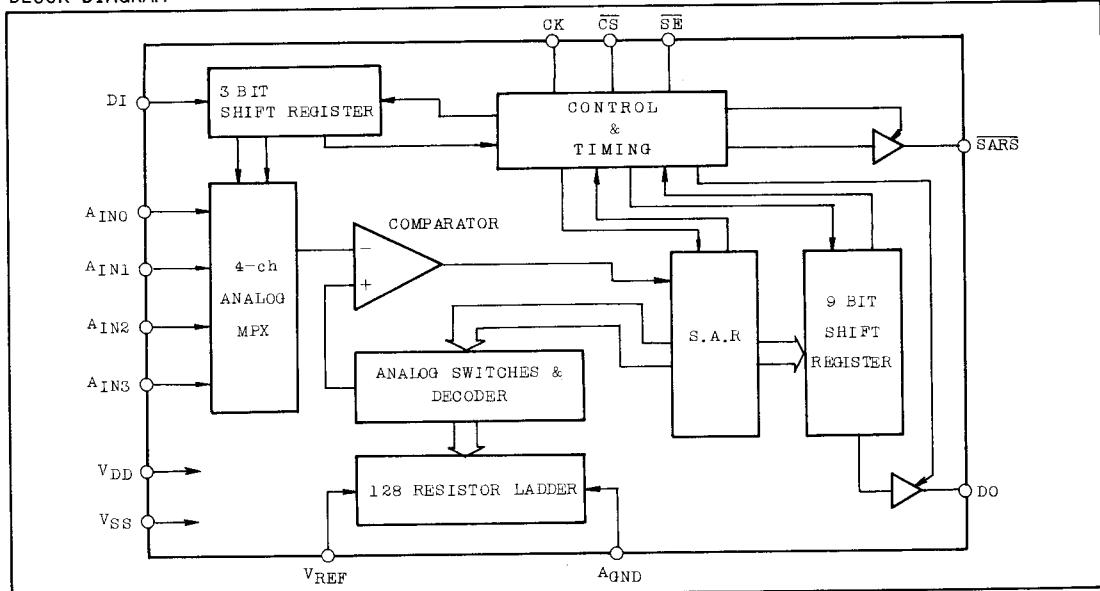
DIP 14(3D14A-P)

PIN ASSIGNMENT

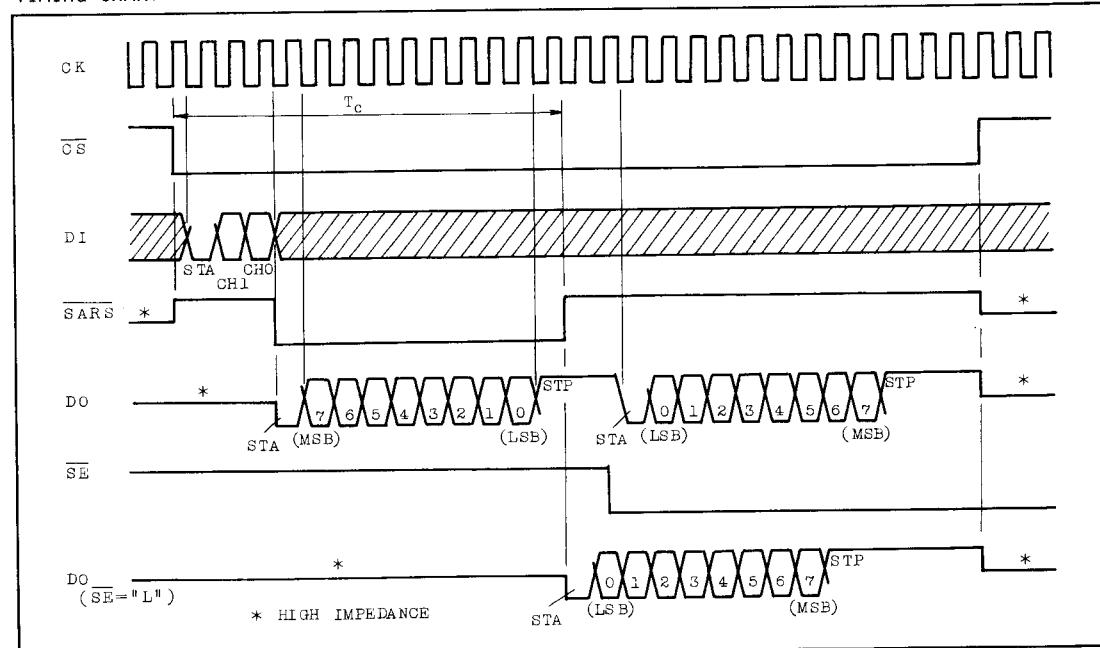


TC35096P

BLOCK DIAGRAM



TIMING CHART



PIN & FUNCTION

PIN NO.	SYMBOL	PIN NAME & FUNCTION	PIN NO.	SYMBOL	PIN NAME & FUNCTION
1	\overline{SE}	[SELECT] \overline{SE} determines the order of output data. $\overline{SE} = "L"$ LSB first $\overline{SE} = "H"$ MSB first	8	A_{GND}	[ANALOG GROUND] A_{GND} defines the zero level of A_{IN} .
2	\overline{CS}	[CHIP SELECT] At the falling edge of \overline{CS} , the device is set stand-by for conversion. When \overline{CS} is "H" the device is reset and all outputs become high impedance.	9	V_{REF}	[REFERENCE VOLTAGE] V_{REF} defines the full scale of A_{IN} .
3	A_{IN0}	[ANALOG INPUT] One of $A_{IN0} \sim A_{IN3}$ is selected according to the serial channel select bit applied on DI input. Full range of input signal is to be from A_{GND} to V_{REF} .	10	DO	[DATA OUTPUT] Output data is sent out in series.
4	A_{IN1}		11	$SARS$	[SAR STATUS] When a start bit ("L" level) is detected at DI input, \overline{SARS} is set "L" level and conversion starts. When conversion is completed \overline{SARS} returns to "H" level.
5	A_{IN2}		12	CK	[CLOCK INPUT] Basic system clock. Duty cycle is to be 50%.
6	A_{IN3}		13	DI	[DATA INPUT] For starting conversion, a start bit ("L" level) and channel select bit (from CH1 to CH0 in order) are to be applied.
7	V_{SS}	[DIGITAL GROUND]	14	V_{DD}	[POWER SUPPLY] $5V \pm 10\%$

RECOMMENDED OPERATING CONDITIONS ($V_{SS}=0V$)

PARAMETER	SYMBOL	CONDITION	MIN.	TYP.	MAX.	UNIT
Supply Voltage	V_{DD}		4.5	5.0	5.5	V
Input Voltage	V_{IN}		0	-	V_{DD}	V
Reference Voltage	V_{REE}	$V_{DD}=5V, A_{GND}=0V$	2.0	V_{DD}	V_{DD}	V
Analog Ground Voltage	A_{GND}	$V_{DD}=5V, V_{REE}=5V$	0.0	0.0	3.0	V
Voltage Between V_{REF} and A_{GND}		$V_{DD}=5V \pm 10\%$	2.0	V_{DD}	V_{DD}	V
Clock Frequency	f_{CP}	$V_{DD}=5V \pm 10\%$	-	-	400	kHz
Clock Pulse Width	$t_w(H)$ $t_w(L)$	$V_{DD}=5V \pm 10\%$	0.63	1.25	-	μs
Operating Temperature	t_{opr}		-40	-	+85	$^{\circ}C$

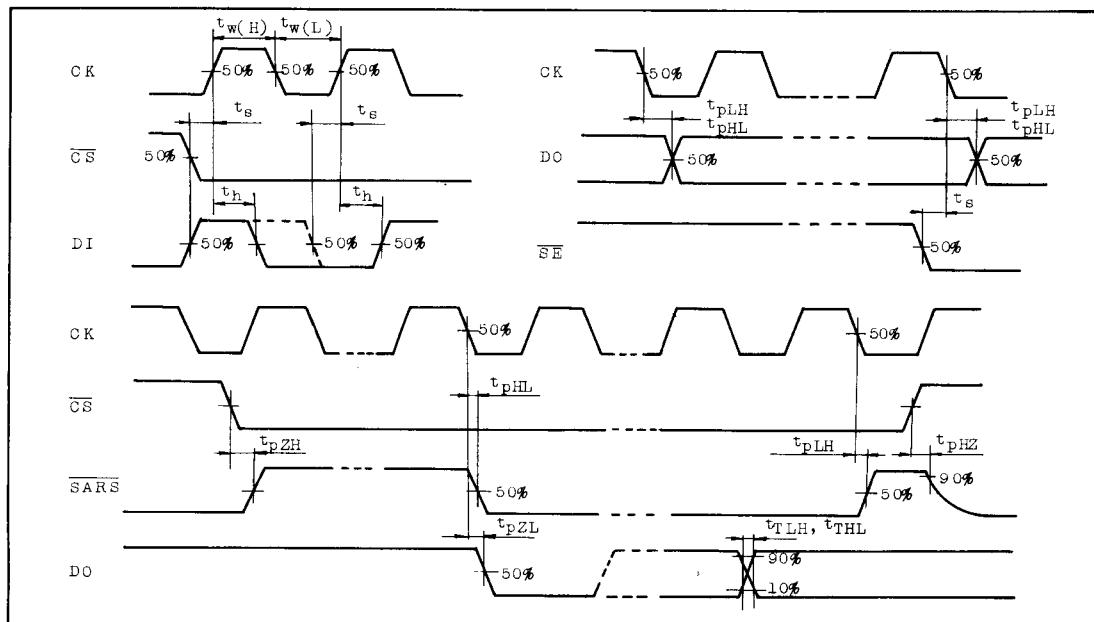
DC ELECTRICAL CHARACTERISTICS ($V_{DD}=5V \pm 10\%, V_{SS}=0V$)

PARAMETER	SYMBOL	TEST CONDITION	25°C		-40 85°C			
High Level Output Voltage	V_{OH}	$ I_{OUT} < 1\mu A$ $V_{IN}=V_{SS}, V_{DD}$	$V_{DD}-0.05$	V_{DD}	-	$V_{DD}-0.05$	-	V
Low Level Output Voltage	V_{OL}	$ I_{OUT} < 1\mu A$ $V_{IN}=V_{SS}, V_{DD}$	-	0.00	0.05	-	0.05	V
High Level Output Current	I_{OH}	$V_{OH}=V_{DD}-0.4V$ $V_{IN}=V_{SS}, V_{DD}$	-0.44	-	-	-0.36	-	mA
Low Level Output Current	I_{OL}	$V_{OL}=0.4V$ $V_{IN}=V_{SS}, V_{DD}$	2.0	-	-	1.6	-	mA
High Level Input Voltage	V_{IH}	$ I_{OUT} < 1\mu A$ $V_{OUT}=0.5V, V_{DD}-0.5V$	$0.7 \times V_{DD}$	-	-	$0.7 \times V_{DD}$	-	V
Low Level Input Voltage	V_{IL}	$ I_{OUT} < 1\mu A$ $V_{OUT}=0.5V, V_{DD}-0.5V$	-	-	$0.3 \times V_{DD}$	-	$0.3 \times V_{DD}$	V
3-State Output Disable Current	I_{DH} I_{DL}	$V_{OH}=V_{DD}$ or $V_{OL}=0.0V$	-	± 0.5	-	± 1	μA	
Digital Input Current	I_{IH} I_{IL}	$V_{IH}=V_{DD}$ or $V_{IL}=0.0V$	-	± 0.3	-	± 1	μA	
ON Channel Input Current	I_{ON}	$V_{IH}=V_{REF}$ or $V_{IL}=0.0V$ $f_{CP}=400kHz$	-	-	± 2	-	± 5	μA
OFF Channel Input Current	I_{OFF}	$V_{IH}=V_{DD}$ or $V_{IL}=0.0V$	-	-	± 0.2	-	± 1	μA
Operating Current	I_{DD}	$f_{CP}=400kHz$	-	-	1.1	-	1.4	mA
Reference Resistance	R_{REF}		1.4	2.6	3.8	1.2	4.2	$k\Omega$

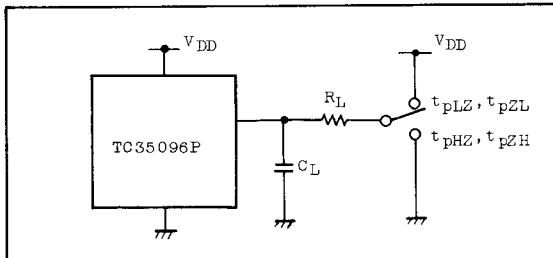
SWITCHING CHARACTERISTICS ($V_{DD}=5V\pm10\%$, $V_{SS}=0V$, $T_a=25^\circ C$)

PARAMETER	SYMBOL	TEST CONDITION	MIN.	TYP.	MAX.	UNIT
Output Transition Time	t_{TLH} t_{THL}	$C_L=50pF$	-		100	nS
Propagation Delay Time (CK-Data)	t_{pLH} t_{pHL}	$C_L=50pF$	-		250	
Propagation Delay Time (CK- \overline{SARS})	t_{pLH} t_{pHL}	$C_L=50pF$	-		250	
3-State Output Enable Time (\overline{CS} - \overline{SARS} , $SARS$ -Data)	t_{pZH} t_{pZL}	$C_L=50pF$ $R_L=1k\Omega$	-		200	
3-State Output Disable Time (\overline{CS} - \overline{SARS} , Data)	t_{pHZ} t_{pLZ}		-		200	
Minimum Pulse Width (\overline{CS})	$t_w(H)$	$C_L=50pF$	-		100	
Minimum Set-up Time (\overline{CS} , \overline{SE} , DI)	t_s	$C_L=50pF$	-		150	
Minimum Hold Time (DI)	t_h	$C_L=50pF$	-		50	
Input Capacitance	C_{IN1}	Digital Input	-	5	-	pF
Input Capacitance	C_{IN2}	Analog In(ON)	-	5	-	
Input Capacitance	C_{IN3}	Analog In(OFF)	-	5	-	
Output Capacitance	C_{OUT}	3-State Out	-	10	-	

SWITCHING CHARACTERISTICS TEST WAVEFORM



3-STATE OUTPUT TEST CIRCUIT



SYSTEM CHARACTERISTICS ($T_a = -40 \sim 85^\circ\text{C}$)

PARAMETER	SYMBOL	TEST CONDITION	MIN.	TYP.	MAX.	UNIT
Zero Point Error	EZR	$V_{DD} = 5.0V$ $V_{REF} = 5.000V$ $f_{cp} = 400\text{kHz}$ Duty = 50%	-	$\pm 1/4$	$\pm 1/2$	LSB
Full Scale Error	EFS		-	$\pm 1/4$	$\pm 1/2$	
Nonlinearity Error	ELI		-	$\pm 1/4$	-	
Total Error	E _T		-	$\pm 1/4$	$\pm 3/4$	
Conversion Time	TC	$f_{cp} = 400\text{kHz}$	-	32.5	34	μs

APPLICATION CIRCUIT (EXAMPLE)

$$T_c = \frac{13 + \alpha}{f_{cp}} \quad 0 < \alpha < \frac{1}{2f_{cp}}$$

