

Pin 1: Vcc Pin 2: Gnd Pin 3: Output Pin 4: Ip+ Pin 5: Ip-

#### **ABSOLUTE MAXIMUM RATINGS**

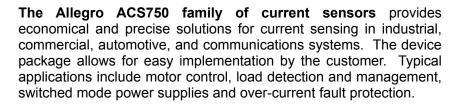
#### **Operating Temperature**

'S'2	0 to +85°C
'L'40	to +150°C
Supply Voltage, Vcc	16V
Output Voltage	16V
Output Current Source	3mA
Output Current Sink	10mA
Maximum Storage Temperature	170°C
Maximum Junction Temperature	165°C
Thermal Resistance, R <sub>⊝JA</sub>	TBD °C/W

#### Always order by complete part number:

ACS750SCA-075 or ACS750LCA-075





The sensor consists of a precision linear Hall IC optimized to an internal magnetic circuit to increase device sensitivity. The combination of a precisely controlled self-aligning assembly process (patents pending) and the factory programmed precision of the linear Hall sensor result in high level performance and product uniformity.

The primary conductor used for current sensing (terminals 4 and 5) is designed for extremely low power loss. The power terminals are also electrically isolated from the sensor leads (pins 1-3). This allows the ACS750 family of sensors to be used in applications requiring electrical isolation without the use of opto-isolators or other costly isolation techniques.

The output of the device has a positive slope (>Vcc/2) when an increasing current flows from terminal 4 to terminal 5.

#### **Features and Benefits**

- Monolithic Hall IC for High Reliability
- Single +5V Supply
- High Isolation Voltage
- Lead-free
- Automotive Temperature Range
- End-of-line Factory Trimmed for Gain and Offset
- Ultra-low Power Loss: Low Resistance of Primary Conductor
- Ratiometric Output from Supply Voltage
- Low Thermal Drift of Offset Voltage
- On-chip Transient Protection
- Small Package Size with Easy Mounting Capability

#### **Applications**

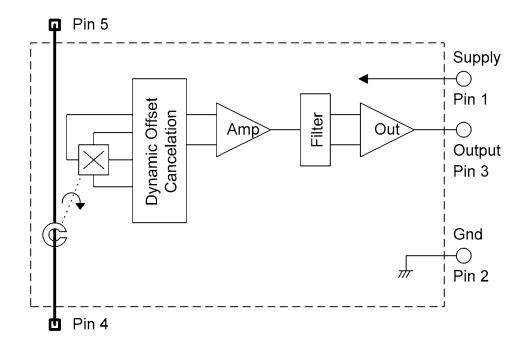
- Automotive Systems
- Industrial Systems
- Motor Control
- Servo Systems
- Power Conversion
- Battery Monitors



$\begin{array}{c} \textbf{Symbol} \\ \textbf{ISTICS, over} \\ \textbf{I}_{P} \\ \textbf{V}_{CC} \\ \textbf{I}_{CC} \\ \textbf{R}_{OUT} \\ \\ \textbf{R}_{PRIMARY} \end{array}$	temperature unless otherwise stated $V_{cc} = 5.0V, \text{ output open}$ $lout = 1.2 \text{ mA}$	Min. -75 4.5	Тур.	<b>Max.</b> 75	Units A	
I <sub>P</sub> V <sub>CC</sub> I <sub>CC</sub> R <sub>OUT</sub>	V <sub>cc</sub> = 5.0V, output open			75	Δ	
I <sub>CC</sub> R <sub>OUT</sub>		4.5	<b>-</b> ^		~	
R <sub>OUT</sub>			5.0	5.5	V	
	lout = 1.0 mA		7	10	mA	
RDDIMADY	10ut = 1.2 mA		1	2	Ω	
IXIIVIAIXI	$I_P = \pm 100A; +25^{\circ}C$ 130			$\mu\Omega$		
$V_{ISO}$	Pins 1-3 and 4-5, 60 Hz, 1 minute		2.5		kV	
PERFORMANCE CHARACTERISTICS, -20 °C to +85 °C, Vcc = 5V unless otherwise specified						
	· ·		4			
			27		μS	
	. , , , , , , , , , , , , , , , , , , ,		26			
f	` ,				kHz	
_		18.75		20.75	mV/A	
Sens	1 /				mV/A	
V <sub>NOISE</sub>	Peak-to-Peak; T = +25°C External Filter BW = 24kHz		7		mV	
EL	± <b>Ι</b> Ρ			+/- 5	%	
	±  <sub>P</sub>	97	100	103	%	
		-40	Vcc/2	+40	mV	
Electrical Offset Voltage (Magnetic error not included)	•	-50		+50	mV	
V <sub>OM</sub>	•			+/- 0.8	Α	
Total Accuracy (Including all offsets) X <sub>Ip</sub>				+/- 13	- %	
PERFORMANCE CHARACTERISTICS, -40 °C to +150 °C, Vcc = 5V unless otherwise specified						
	•		-			
					μS	
	, , , , , , , , , , , , , , , , , , , ,				kHz	
-		18.75		20.75	mV/A	
Sensitivity Sens					mV/A	
V <sub>NOISE</sub>	Peak to Peak; T = +25°C	10.0	7		mV	
Eı				+/- 5	%	
	•	97	100		%	
Floatrical Offset Voltage	·				mV	
$V_{OE}$	· · · · · · · · · · · · · · · · · · ·			-	mV	
Vora	•	- 55			A	
				7, 0.0	- %	
X <sub>Ip</sub>	. ,			+/- 15		
	V <sub>ISO</sub> ERISTICS, -7  t <sub>PROP</sub> t <sub>RESPONSE</sub> t <sub>r</sub> f  Sens  V <sub>NOISE</sub> E <sub>L</sub> E <sub>S</sub> V <sub>OM</sub> X <sub>Ip</sub> ERISTICS, -7  t <sub>PROP</sub> t <sub>RESPONSE</sub> t <sub>r</sub> f  Sens	$V_{ISO} = \begin{array}{c} \text{Pins 1-3 and 4-5,} \\ 60 \text{ Hz, 1 minute} \\ \text{ERISTICS, -20 °C to +85 °C, Vcc = 5V unless of} \\ t_{PROP} = \begin{array}{c} I_P = \pm 50 \text{A} (\pm 75 \text{A TBD}) \\ I_P = \pm 50 \text{A} (\pm 75 \text{A TBD}) \\ t_{RESPONSE} = \begin{array}{c} I_P = \pm 50 \text{A} (\pm 75 \text{A TBD}) \\ I_P = \pm 50 \text{A} (\pm 75 \text{A TBD}) \\ t_T = -3 \text{dB} \\ \text{Sens} = \begin{array}{c} \pm I_P = \pm 50 \text{A} (\pm 75 \text{A TBD}) \\ \pm I_P, \text{ T = +25 °C} \\ \hline \pm I_P, \text{ Over Temperature} \\ \text{Peak-to-Peak; T = +25 °C} \\ \text{External Filter BW = 24kHz} \\ \hline E_L = \pm I_P \\ \hline E_S = \pm I_P \\ \hline V_{OE} = \begin{array}{c} I = 0 \text{A, T = +25 °C} \\ I = 0 \text{A, Over Temperature} \\ \hline V_{OM} = 1 = 0 \text{A, after excursion of 100A} \\ \hline X_{IP} = \pm 0 \text{A, after excursion of 100A} \\ \hline X_{IP} = \pm 0 \text{A, after excursion of 100A} \\ \hline X_{IP} = \pm 50 \text{A} (\pm 75 \text{A TBD}) \\ \hline t_{RESPONSE} = \begin{array}{c} I_P = \pm 50 \text{A} (\pm 75 \text{A TBD}) \\ I_P = \pm 50 \text{A} (\pm 75 \text{A TBD}) \\ \hline t_T = -25 \text{C} \\ \hline \pm I_P, \text{ Over Temperature} \\ \hline V_{NOISE} = \begin{array}{c} I_P = \pm 50 \text{A} (\pm 75 \text{A TBD}) \\ \hline t_P, \text{ Over Temperature} \\ \hline V_{NOISE} = \begin{array}{c} I_P = \pm 50 \text{A} (\pm 75 \text{A TBD}) \\ \hline t_P, \text{ Over Temperature} \\ \hline V_{OE} = 1 = 0 \text{A, T = +25 °C} \\ \hline I = 0 \text{A, Over Temperature} \\ \hline V_{OE} = 1 = 0 \text{A, Over Temperature} \\ \hline I = 0 \text{A, Over Temperature} \\ \hline V_{OE} = 1 = 0 \text{A, over Temperature} \\ \hline I = 0 \text{A, Over Temperature} \\ \hline V_{OM} = 1 = 0 \text{A, after excursion of 100A} \\ \hline + I_D = 1 = 25 \text{C} \\ \hline I = 0 \text{A, over Temperature} \\ \hline V_{OM} = 1 = 0 \text{A, after excursion of 100A} \\ \hline + I_D = 1 = 25 \text{C} \\ \hline \end{array}$	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	Viso   Pins 1-3 and 4-5,	

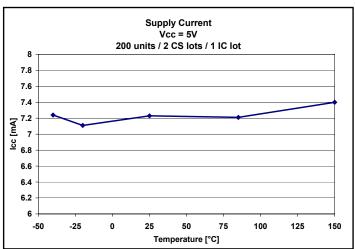


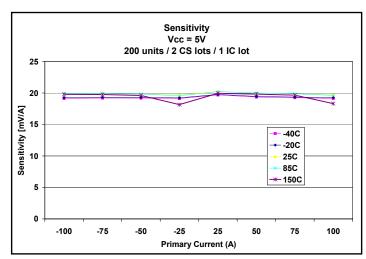
### **Functional Block Diagram**

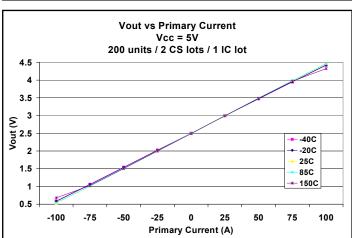


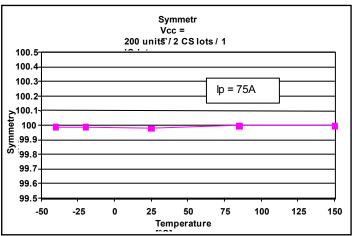


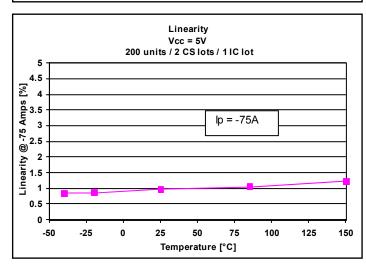
### **Typical Performance Characteristics**

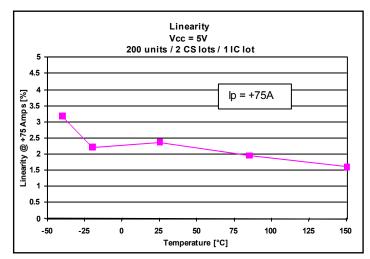






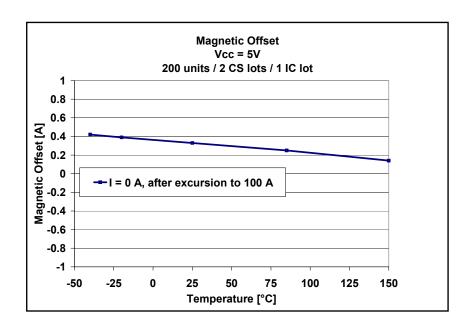


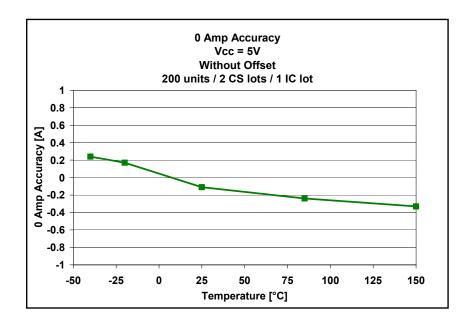






**Typical Performance Characteristics (continued)** 







#### **Definitions of Accuracy Characteristics**

**Sensitivity:** The sensitivity is the change in sensor output to 1A change through the primary conductor. The sensitivity is the product of the magnetic circuit sensitivity (G/A) and the linear IC amplifier gain (mV/G). The linear IC amplifier gain is trimmed at the factory to optimize the sensitivity (mV/A) for the full-scale current of the device.

**Noise:** The noise is the product of the linear IC amplifier gain (mV/G) and the noise floor for the Allegro Hall effect linear IC (~1Gauss). The noise floor is derived from the thermal and shot noise observed in Hall elements. Dividing the noise (mV) by the sensitivity (mV/A) provides the smallest current that the device is able to resolve.

**Linearity:** The linearity is the degree to which the voltage output from the sensor varies in direct proportion to the primary current through its full-scale amplitude. Linearity reveals the maximum deviation from the ideal transfer curve for this transducer. Non-linearity in the output can be attributed to the gain variation across temperature and saturation of the flux concentrator approaching the full scale current. The following equation is used to derive the linearity:

$$[1-[(Vout full-scale Amps - Vout 0A)/(2*(Vout 1/2 full-scale Amps - Vout 0A))]]*100$$

**Symmetry:** Symmetry is the degree to which the absolute voltage output from the sensor varies in proportion to either a positive or negative full-scale primary current. The following equation is used to derive symmetry:

$$[(Vout\_full\text{-scale Amps} - Vout\_oA)/(Vout\_oA - Vout\_-full\text{-scale Amps})]*100$$

**Electrical offset voltage:** The quiescent output voltage ( $V_{OE}$ ) is the output of the sensor when the primary current is zero. For a unipolar supply voltage,  $V_{OE}$  nominally sits at  $V_{CC}/2$ .  $V_{CC} = 5V$  translates into  $V_{OE} = 2.5V$ . Variation in  $V_{OE}$  can be attributed to the resolution of the Allegro linear IC quiescent voltage trim, magnetic hysteresis, and thermal drift.

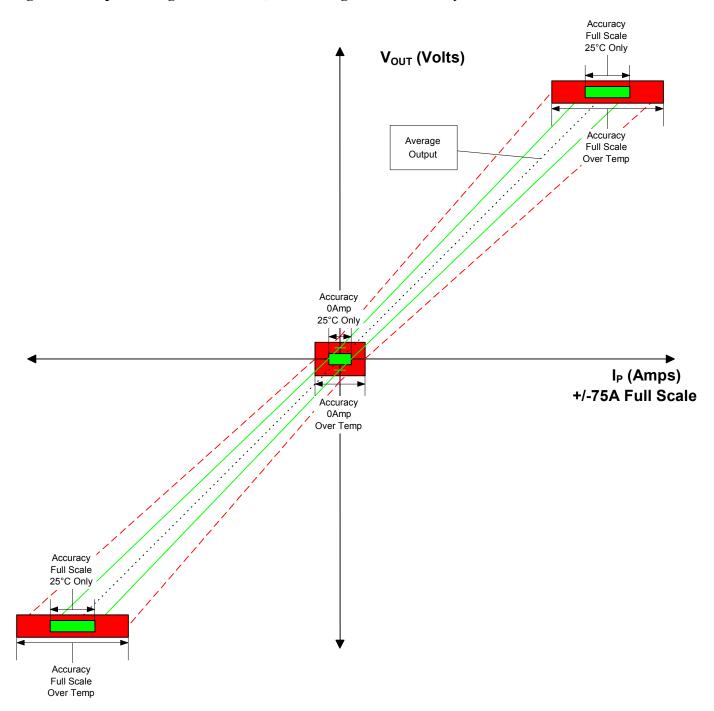
**Magnetic offset error:** The magnetic offset is due to the residual magnetism (remnant field) of the core material. The magnetic offset error is highest when the magnetic circuit has been saturated, usually when the device has been subjected to a full scale or high current overload condition. The magnetic offset is largely dependent on the material used as a flux concentrator. The largest magnetic offset is observed at the lowest operating temperature.

**Accuracy:** The accuracy represents the maximum deviation of the actual output from its ideal value. This is also known as the total error. The accuracy is illustrated graphically in Figure #1. The accuracy is divided into four areas as defined below:

- 0 A @ 25°C: Accuracy of sensing zero current flow at 25°C, without the effects of temperature.
- **0** A over temperature: Accuracy of sensing zero current flow including temperature effects.
- Full-scale current @ 25°C: Accuracy of sensing the full-scale current at 25°C, without the effects of temperature.
- Full-scale current over temperature: Accuracy of sensing full-scale current flow including temperature effects.



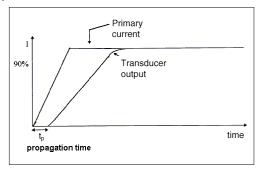
Figure 1: Output Voltage vs. Current, illustrating sensor accuracy at 0A and full-scale current



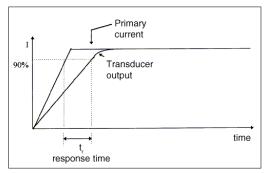


#### **Definitions of Dynamic Response Characteristics**

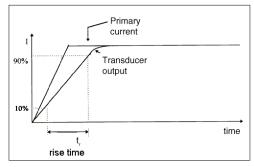
**Propagation delay:** Propagation delay is the time that it takes for the sensor output to reflect a change in the primary current signal. Propagation delay is attributed to inductive loading within the linear IC package as well as the inductive loop formed by the primacy conductor geometry. Propagation delay can be considered as a fixed time offset and may be compensated.



**Response time:** Response time is the time between when the primary current signal reaches 90% of its final value and when the sensor reaches 90% of its output corresponding to the applied current.



**Rise time:** Rise time is the time between the sensor's output reaching 10 and 90% of its full scale value. The rise time to a step response is used to derive the bandwidth of the current sensor, in which f(-3dB) = 0.35/tr. Both rise time and response time are detrimentally affected by eddy current losses observed in the conductive IC ground plane and, to varying degrees, in the ferrous flux concentrator within the current sensor package.

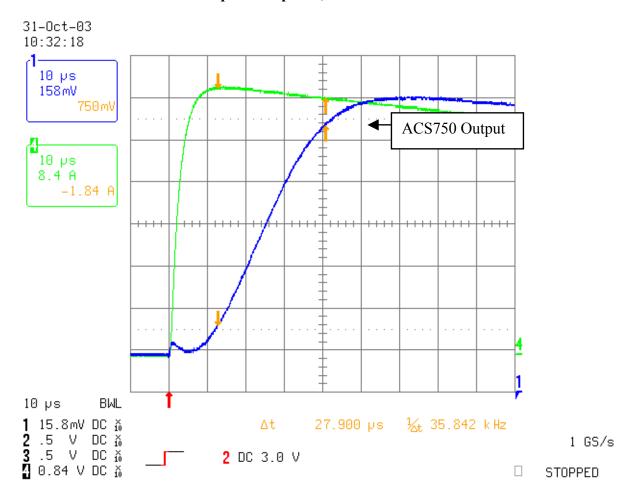




### Peak to Peak Noise, applying low-pass filter to ACS750 output

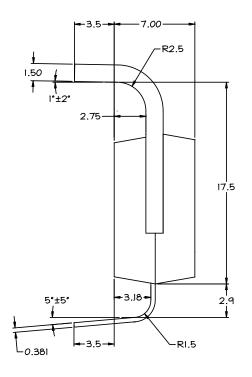
Low Pass Filter Break Frequency	Typical Peak to Peak Noise
Unfiltered	22.7 mV
1.4MHz	21 mV
400kHz	TBD
160kHz	TBD
80kHz	TBD
24kHz	7.1 mV

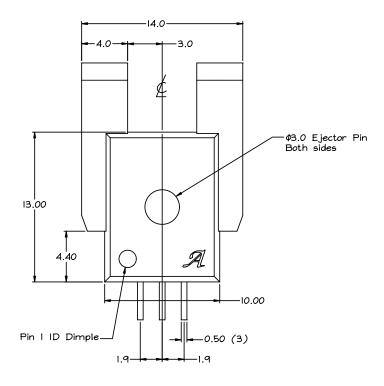
### Step Resonsponse, $I_{PRIMARY} = 0$ to 50A





#### PACKAGE DRAWING





#### Notes:

- 1. This drawing is only a preliminary issue and no tolerances are implied to any dimensions.
- Draft angle is 10° unless otherwise specified.
- 3. There is no plating in areas that are trimmed.
- 4. SIP lead flash along the edge or sides for 3mm from the package due to resin bleeding.



The products described herein are manufactured under one or more of the following U.S. patents: 5,045,920; 5,264,783; 5,442,283; 5,389,889; 5,581,179; 5,517,112; 5,619,137; 5,621,319; 5,650,719; 5,686,894; 5,694,038; 5,729,130; 5,917,320; and other patents pending.

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