

GaAs HBT PROGRAMMABLE 5-BIT COUNTER, DC - 2.2 GHz

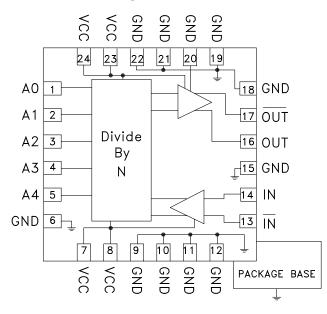
Typical Applications

Programmable divider for offset synthesizer and variable divide by N applications:

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- Satellite Communication Systems
- Pt-Pt and Pt-MPt Radios
- LMDS
- SONET

Functional Diagram



Features

SSB Phase Noise: -153 dBc/Hz @ 100 kHz Selectable Division from 2 to 32 Parallel 5-Bit Control Wide Input Power Range: -20 to +10 dBm 4mm x 4mm Leadless SMT Package

General Description

The HMC394LP4 is a low noise GaAs HBT programmable 5-bit counter in a 4mm x 4mm leadless surface mount package. This device allows continuous division from N= 2 to 32 at input frequencies up to 2.2 GHz. The output voltage swing is 800 mV with a duty cycle inversely proportional to N. The low additive SSB phase noise of -153 dBc/Hz at 100 KHz offset makes this counter an excellent choice for low noise synthesizer applications.

Electrical Specifications, $T_A = +25^{\circ}$ *C, 50 Ohm System, Vcc= 5V*

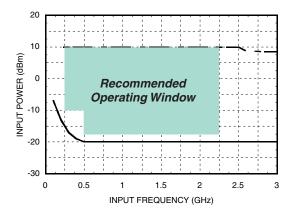
Parameter	Conditions	Min.	Тур.	Max.	Units
Maximum Input Frequency	2.				GHz
Minimum Input Frequency	Sine Wave Input [1]	Sine Wave Input [1]		0.1	GHz
Input Power Range	Fin = 0.1 to 2.2 GHz	-15	>-20	+10	dBm
Output Power	Divide-by-2		4		dBm
SSB Phase Noise	Fin = 1 GHz, N = 4		-153		dBc/Hz
Output Transition Time			100		ps
Supply Current (Icc)			194		mA

1. Divider will operate down to DC for square-wave input signal.

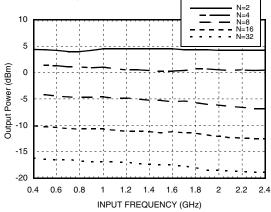


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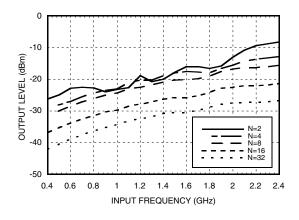
Input Sensitivity Window, 5 major Divide Ratio States, T= 25 °C



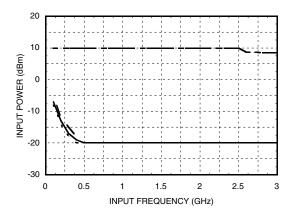
Output Power, 5 Major Divide Ratio States, T= 25 °C



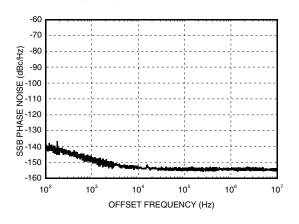
Fundamental Feedthru Power, Pin= 0 dBm, T= 25 °C



Input Sensitivity Window vs. Temperature, N= 16, T= -40 °C to +85 °C



SSB Phase Noise Performance, Fin= 1 GHz, N= 4, T= 25 °C



Typical Supply Current vs. Vcc

Vcc (V)	Icc (mA)
4.75	176
5.0	194
5.25	210

Note: Divider will operate over full voltage range shown above.

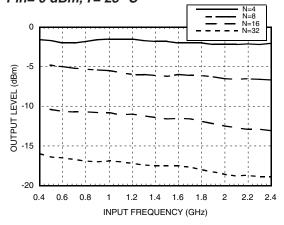


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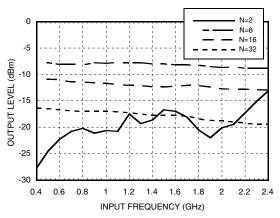
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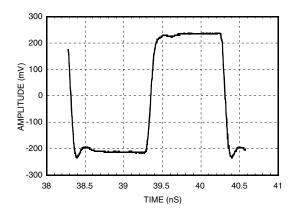
2nd Harmonic, Pin= 0 dBm, T= 25 °C

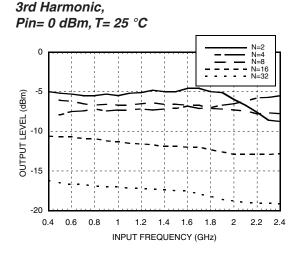


4th Harmonic, Pin= 0 dBm, T= 25 °C

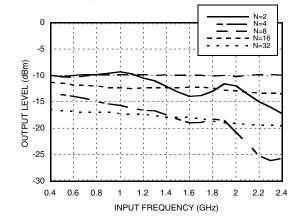


Output Voltage Wavform, Fin= 1 GHz, N= 2, Pin= 0 dBm, T= 25 °C

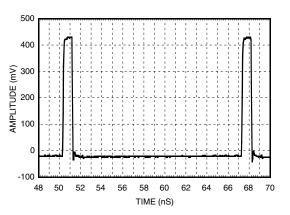




5th Harmonic, Pin= 0 dBm, T= 25 °C



Output Voltage Wavform, Fin= 1 GHz, N= 17, Pin= 0 dBm, T= 25 °C



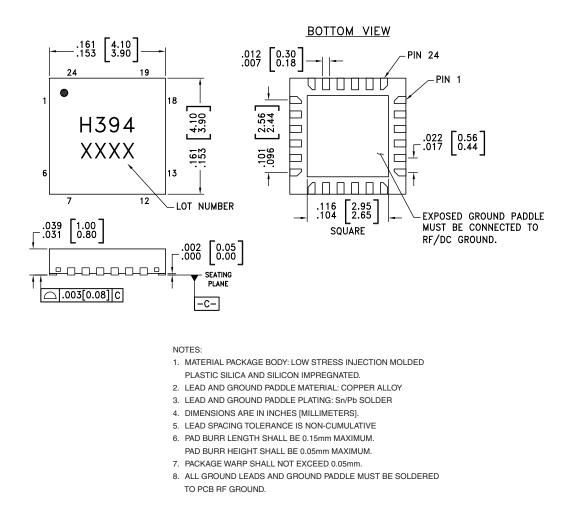


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Absolute Maximum Ratings

RF Input (Vcc = +5V)	+13 dBm	
Vcc	+5.5V	
VLogic	-1.6 to -1.2 Vcc	
Maximum Channel Temperature	135 °C	
Continuous Pdiss (T = 85 °C) (derate 55 mW/°C above 85 °C)	1.155 W	
Storage Temperature	-65 to +150 °C	
Operating Temperature	-55 to +85 °C	

Outline Drawing





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Pin Description

Pin Number	Function	Description	Interface Schematic
1 - 5	AO - A4	CMOS compatible control input bit 0 (LSB) - 4.	
6, 9, 10, 11, 12, 15, 18, 19, 20, 21, 22	GND	Ground: Backside of package has exposed metal ground slug which must be connected to ground.	
7, 8, 23, 24	VCC	Supply voltage 5V \pm 0.25V must be applied to all four pins.	Vcc 58pF
13	ĪN	RF input 180° out of phase with pin 14 must be AC ground.	
14	IN	RF input must be DC blocked.	BIAS EIAS
16	OUT	Divided output pulse.	
17	OUT	Divided output pulse 180° out of phase with pin 16.	

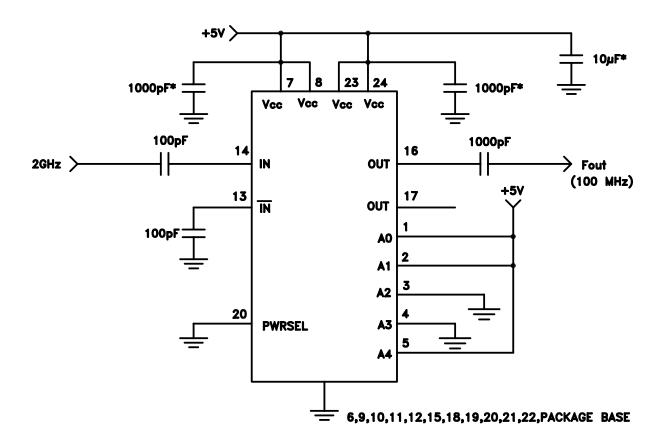


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HMC394LP4 Programming Truth Table

Function	(LSB) A0	A1	A2	A3	A4
Output Low	0	0	0	0	0
/2	1	0	0	0	0
/ 3	0	1	0	0	0
/ 4	1	1	0	0	0
-	-	-	-	-	-
/ 32	1	1	1	1	1
Note: A0 through A4 are CMOS compatible logic control inputs.					

Application Circuit, (2 GHz - Divide-by-20)



* Note: Mount bypass capacitors as close to pins as possible.

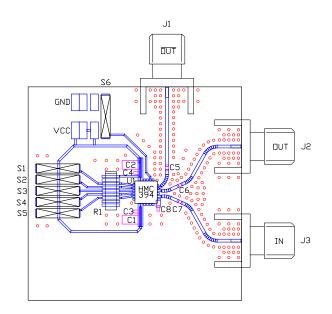


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Evaluation PCB



The circuit board used in the final application should use RF circuit design techniques. Signal lines should have 50 ohm impedance while the package ground leads and backside ground slug should be connected directly to the ground plane similar to that shown. A sufficient number of via holes should be used to connect the top and bottom ground planes. The evaluation circuit board shown is available from Hittite upon request.

Note: C1 and C3 bypass capacitors are not necessary if power supply trace is short.

HMC394LP4 Evaluation PCB Truth Table

Note: The evaluation PCB for the HMC394LP4 contains 10K Ohm pull up resistors for each of the five control inputs A0 through A4. Programming the 31 distinct division ratios consists of installing or removing jumpers S1 through S5, as shown below.

Function	S1	S2	S3	S4	S5
Output Low	0	0	0	0	0
/2	1	0	0	0	0
/ 3	0	1	0	0	0
/ 4	1	1	0	0	0
/32 1 1 1 1 1					
Note: 0 = Jumper Installed. 1 = Jumper Not Installed. Install jumper S6 for high power mode.					

Evaluation Circuit Board Layout Design Details

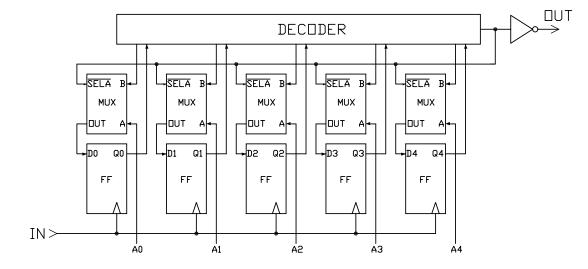
Item	Description
J1 - J3	PC Mount SMA RF Connector
C1 - C2*	1.0 µF Tantalum Capacitor
C3 - C4*	.01 µF Capacitor, 0603 Pkg.
C5 - C8	1000 pF Capacitor, 0603 Pkg.
R1*	Resistor SIP 10 K ohm
S1 - S6	Jumper (shunt) 2mm
U1	HMC394LP4 5-Bit Counter
РСВ	104435 Eval Board
* Optional components.	



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Applications Information

Simplified Block Diagram



Asynchronous Programming

The 5-Bit programmable counter counts-down from the programmed value of the data bits to zero and issues an output pulse at the end of each cycle. Settling time of the programmable 5-Bit counter is defined as the maximum time required for the counter to change the division ratio N to a new value after the data bits have settled. The worst case settling time occurs if the data bits A0 thru A4 are changing during the load cycle. Under this condition, the data bits may potentially be erroneous when they are clocked in and in the worst case could be all 1's, requiring 32 clock cycles until the correct data is re-loaded into the flip flops. The worst case asynchronous settling time can be calculated as follows:

T_{SETTLING MAX} = 32/f_{IN} (For Asynchronous Programming)

As an example, if the input frequency is 1 GHz, the maximum settling time is 32 nS



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Synchronous Programming

For applications which can not tolerate a momentary undefined division ratio, which normally occurs while changing the data bits (A0-A4) at random, synchronous programming can be used. Data is loaded into the counter on every rising edge of the clock which occurs while the output (OUT) is "HIGH". The typical minimum setup and hold times are shown in the table below as a function of frequency. For precision applications, the rising edge of the complementary output may be used to latch the new data bits (A0-A4), so that all bits are settled before the next load cycle.

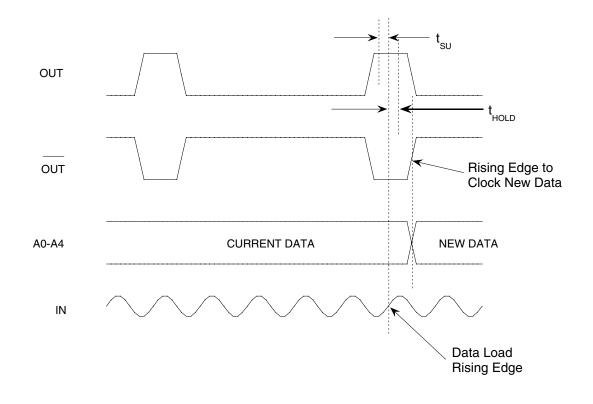
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T_{SETTLING MAX} = N/f_{IN} (For Synchronous Programming)

Where N is the desired division ratio, and $f_{IN} =$ Input Frequency (Hz)

Parameter	0.5 GHz	1 GHz	2 GHz
t _{setup}	200 ps	200 ps	200 ps
t _{HOLD}	700 ps	300 ps	120 ps

Programmable Divider Timing Requirements for Synchronous Programming



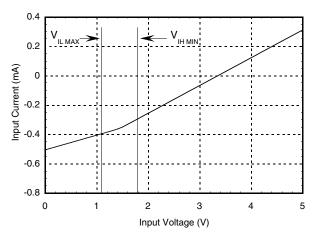
For price, delivery, and to place orders, please contact Hittite Microwave Corporation: 12 Elizabeth Drive, Chelmsford, MA 01824 Phone: 978-250-3343 Fax: 978-250-3373 Order Online at www.hittite.com



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CMOS/TTL Input Characteristics

Maximum Input Logic "0" Voltage ($V_{IL MAXIMUM}$) = 1.1V @ 10 uA. Minimum Input Logic "1" Voltage ($V_{IH MINIMUM}$) = 1.8V @ 500 uA. Input IV characteristics for the logic inputs (A0-A4) are shown below:



FREQ. DIVIDERS & DETECTORS - SMT