

SP8902 (MP)

5GHZ ÷2 Fixed Modulus Divider

Preliminary Information

DS4375 Issue 1.4 September 1999

The SP8902 is one of a range of very high speed low power prescalers for professional applications. The dividing elements are static D type flip flops and therefore allow operation down to DC if the drive signal is a pulse waveform with fast risetime. The output stage has a differential current output and provides a direct drive into a 50 ohm load.

Features

- Very High Operating Speed
- Operation down to DC with Square Wave Input
- Silicon Technology for Low Phase Noise (Typically better than -140dBc/Hz at 1KHz)
- 5V Single Supply Operation
- Low Power Dissipation: 335mW (Typ.)
- Surface Mount Plastic Package

Ordering Information

SP8902/KG/MP1S (tubes) SP8902/KG/MP1T (tape and reel)

Absolute Maximum Ratings

Supply voltage, V _{CC}	6·5V
Storage temperature	−65°C to +150°C
Maximum junction temperatu	re +150°C
Prescaler input voltage	2·5Vp-p
Operating temperature	KG-40°C to +85°C T_{CASE}

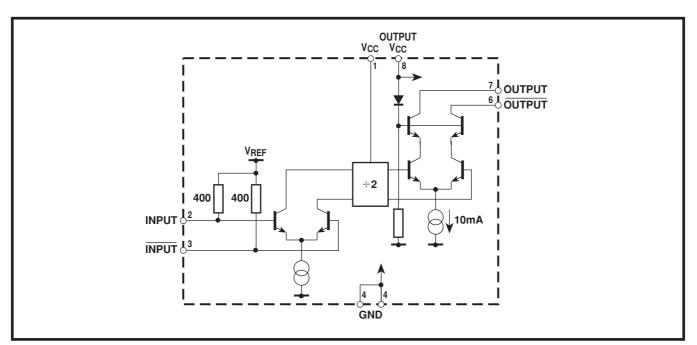


Figure 1 block diagram

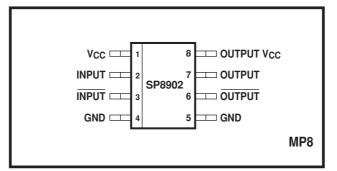


Figure 2 Pin connections - top view

Electrical Characteristics

These characteristics are guaranteed by either production test or design over the following range of operating conditions unless otherwise stated: $T_{AMB} = -40^{\circ}C$ to $+85^{\circ}C$, $V_{CC} = 4.75V$ to 5.25V

		Value					
Characteristic	Pin	Min.	Тур.	Max.	Units	Conditions	
Supply current	1, 8	-	67	92	mA		
Input frequency	2, 3	1.0	-	5∙0	GHz	RMS sinewave	
Input sensitivity	2, 3	-	-	180	mVrms	$f_{IN} = 1GHz$ and 4.2GHz	
Input sensitivity	2, 3	-	-	570	mVrms	f _{IN} = 5GHz	
Input overload	2, 3	440	-	-	mVrms	f _{IN} = 1GHz and 3GHz	
Input overload	2, 3	700	-	-	mVrms	$f_{IN} = 5.0GHz$ and 3.8GHz	
Output voltage	6, 7	-	0.2	-	Vp-р	Into 50 Ω pullup resistor	
Output power	6, 7	<i>−</i> 15·0	+12	+2.0	dBm	$f_{IN} = 1GHz$ and 5GHz (see note 1)	

NOTE

1. Measured into 50Ω measuring instrument in parallel with 50Ω pullup resistor. See Figure 5.

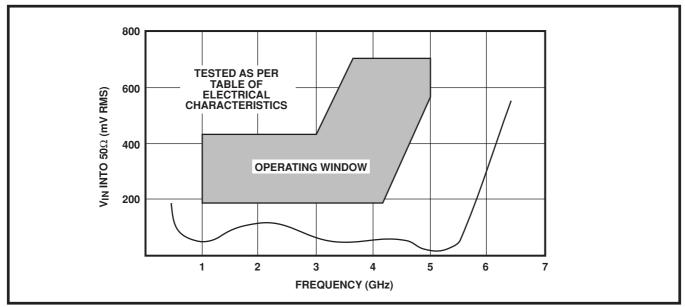


Figure3 Typical input sensitiviy (sinewave drive)

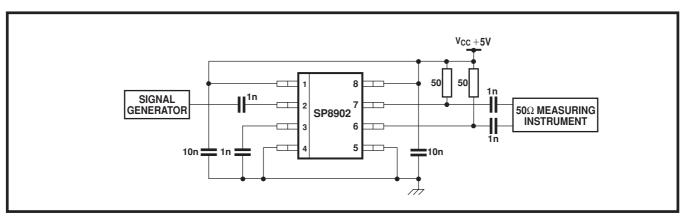


Figure 4 Typical application and test circuit

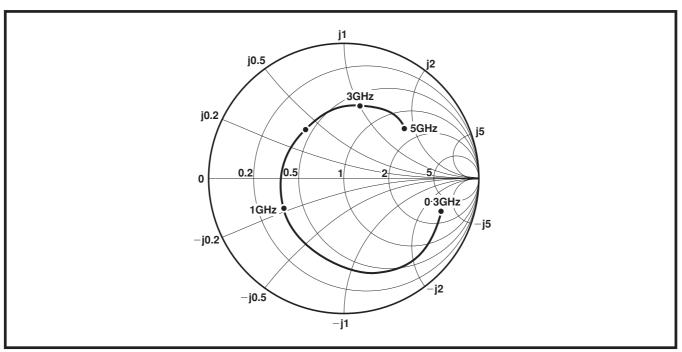


Figure 5 Typical input impedance

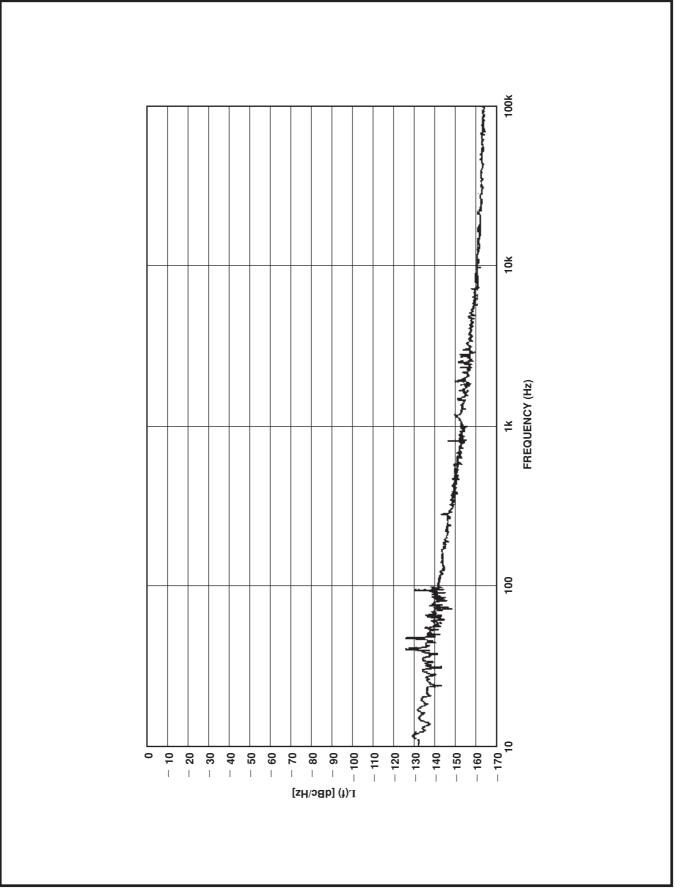
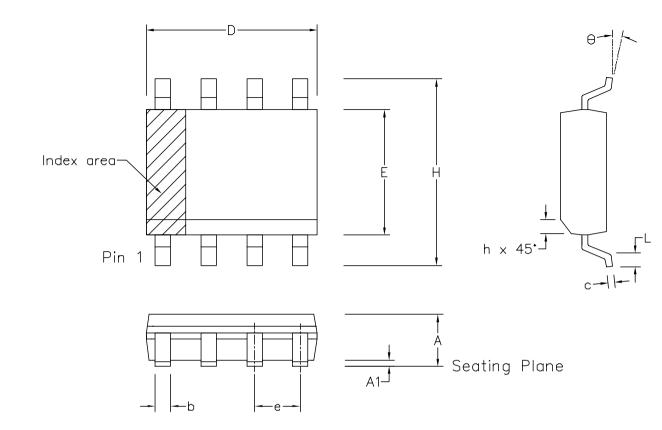


Figure 6 Typical phase noise, input frequency = 3GHz



	Min	Max	Min	Max	
	mm	mm	inch	inch	
A	1.35	1.75	0.053	0.069	
A1	0.10	0.25	0.004	0.010	
D	4.80	5.00	0.189	0.197	
Н	5.80	6.20	0.228	0.244	
E	3.80	4.00	0.150	0.157	
L	0.40	1.27	0.016	0.050	
е	1.27	BSC	0.050_BSC		
b	0.33	0.51	0.013	0.020	
С	0.19	0.25	0.008	0.010	
0	٥	8°	0°	8°	
			0 04 0		
<u>h</u>	0.25	0.50	0.010	0.020	
h	0.25		<u>0.010</u> eatures	0.020	
h N			atures	3	

Notes:

- 1. The chamfer on the body is optional. If it not present, a visual index feature, e.g. a dot, must be located within the cross-hatched area.
- 2. Controlling dimension are in inches.
- Dimension D do not include mould flash, protusion or gate burrs. These shall not exceed 0.006" per side.
 Dimension E1 do not include inter-lead flash or protusion. These shall not exceed 0.010" per side.
 Dimension b does not include dambar protusion/intrusion. Allowable dambar protusion shall be 0.004"
- total in excess of b dimension.

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DATE	5APR95	27FEB97	12JUN97	9DEC97				Drawing Number
APPROVED								GPD00010



http://www.mitelsemi.com

World Headquarters - Canada

Tel: +1 (613) 592 2122 Fax: +1 (613) 592 6909

North America

Tel: +1 (770) 486 0194 Fax: +1 (770) 631 8213

Asia/Pacific

Tel: +65 333 6193 Fax: +65 333 6192

Europe, Middle East, and Africa (EMEA) Tel: +44 (0) 1793 518528 Fax: +44 (0) 1793 518581

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