

AN8473SA

Spindle motor driver IC for optical disk

Overview

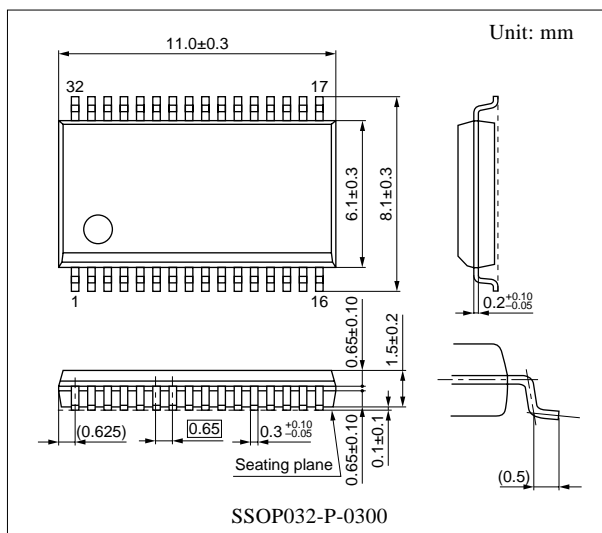
The AN8473SA is an optical disk driver IC, featuring direct PWM drive, DMOS power drive, low ON resistance of output power MOS and 120° of duty-factor.

Features

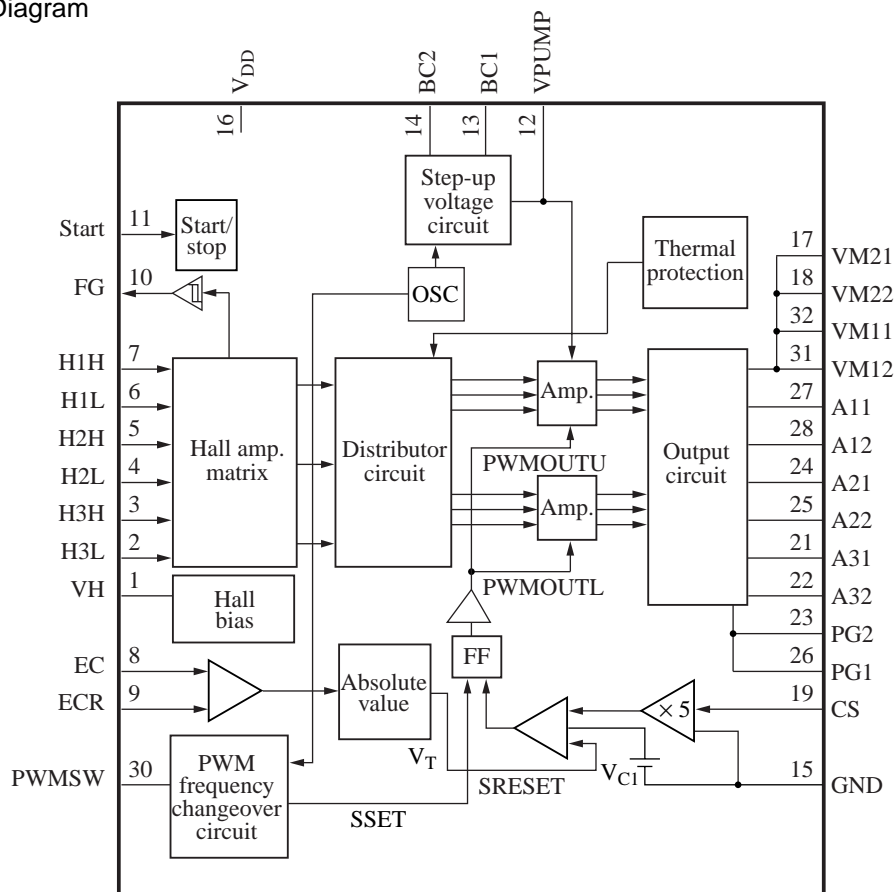
- $R_{ON} = 0.5 \Omega$ (for both upper and lower)
- 5 V single power source
- Circuit current 7 mA (including step-up circuit current)

Applications

- Optical disk



Block Diagram



■ Pin Descriptions

| Pin No. | Symbol | Description | Pin No. | Symbol | Description |
|---------|-----------------|------------------------------------|---------|--------|------------------------------|
| 1 | VH | Hall bias pin | 17 | VM21 | Motor supply voltage pin 2 |
| 2 | H3L | Hall element-3 negative input pin | 18 | VM22 | Motor supply voltage pin 2 |
| 3 | H3H | Hall element-3 positive input pin | 19 | CS | Current det. pin |
| 4 | H2L | Hall element-2 negative input pin | 20 | N.C. | N.C. |
| 5 | H2H | Hall element-2 positive input pin | 21 | A31 | Drive output 3 |
| 6 | H1L | Hall element-1 negative input pin | 22 | A32 | Drive output 3 |
| 7 | H1H | Hall element-1 positive input pin | 23 | PG2 | Power current det. pin 2 |
| 8 | EC | Torque command input pin | 24 | A21 | Drive output 2 |
| 9 | ECR | Torque command reference input pin | 25 | A22 | Drive output 2 |
| 10 | FG | FG signal output pin | 26 | PG1 | Power current det. pin 1 |
| 11 | Start | Start/stop changeover pin | 27 | A11 | Drive output 1 |
| 12 | VPUMP | Booster pin | 28 | A12 | Drive output 1 |
| 13 | BC1 | Booster capacitor connection pin 1 | 29 | N.C. | N.C. |
| 14 | BC2 | Booster capacitor connection pin 2 | 30 | PWMSW | PWM frequency changeover pin |
| 15 | GND | Ground pin | 31 | VM12 | Motor supply voltage pin 1 |
| 16 | V _{DD} | Supply voltage pin | 32 | VM11 | Motor supply voltage pin 1 |

■ Absolute Maximum Ratings

| Parameter | Symbol | Rating | Unit |
|---|----------------------|----------------------|------|
| Supply voltage ^{*2} | V _{DD} | 6.5 | V |
| | V _{M11, 12} | | |
| | V _{M21, 22} | | |
| Drive output voltage ^{*5} | V _(m) | 15 | V |
| Control signal input voltage ^{*6} | V _(n) | 0 to V _{DD} | V |
| Supply current | I _{DD} | 30 | mA |
| Drive output current ^{*4} | I _(o) | ±1 200 | mA |
| Hall bias current ^{*7} | I _{HB(n)} | 30 | mA |
| Power dissipation ^{*3} | P _D | 293 | mW |
| Operating ambient temperature ^{*1} | T _{opr} | −30 to +85 | °C |
| Storage temperature ^{*1} | T _{stg} | −55 to +150 | °C |

Note) Do not apply external currents or voltages to any pins not specifically mentioned.

For circuit currents, '+' denotes current flowing into the IC, and '-' denotes current flowing out of the IC.

*1: Except for the operating ambient temperature and storage temperature, all ratings are for T_a = 25°C.

*2: The voltage in the step-up voltage circuit exceeds the supply voltage.

For the allowable value of the step-up voltage, refer to "■ Electrical Characteristics".

*3: The power dissipation shown is the value of independent IC without a heat sink at T_a = 70°C. Refer to the P_D — T_a curves of the "■ Application Notes" for details.

*4: o = 17, 18, 21, 22, 23, 24, 25, 26, 27, 28, 31, 32

*5: m = 21, 22, 24, 25, 27, 28

*6: n = 2, 3, 4, 5, 6, 7, 8, 9, 11, 30

*7: n = 1

■ Recommended Operating Range

| Parameter | Symbol | Range | Unit |
|----------------|---------------|------------|------|
| Supply voltage | V_{DD} | 4.5 to 5.5 | V |
| | $V_{M11, 12}$ | | |
| | $V_{M21, 22}$ | | |

■ Electrical Characteristics at $T_a = 25^\circ\text{C}$

| Parameter | Symbol | Conditions | Min | Typ | Max | Unit |
|--------------------------------------|-------------|---|------|------|------|---------------|
| Overall | | | | | | |
| Circuit current 1 | I_{DD1} | $V_{DD} = 5\text{ V}$ in power save mode | — | 0 | 0.2 | mA |
| Circuit current 2 | I_{DD2} | $V_{DD} = 5\text{ V}$ including step-up circuit | — | 7 | 14 | mA |
| Start/stop | | | | | | |
| Start voltage | V_{START} | Voltage with which a circuit operates at $V_{DD} = 5\text{ V}$ and $L \rightarrow H$ | 2.7 | — | — | V |
| Stop voltage | V_{STOP} | Voltage with which a circuit becomes off at $V_{DD} = 5\text{ V}$ and $H \rightarrow L$ | — | — | 0.7 | V |
| Hall bias | | | | | | |
| Hall bias voltage | V_{HB} | $V_{DD} = 5\text{ V}$, $I_{HB} = 20\text{ mA}$ | 0.7 | 1.2 | 1.6 | V |
| Hall amplifier | | | | | | |
| Input bias current | I_{BH} | $V_{DD} = 5\text{ V}$ | — | 1 | 5 | μA |
| In-phase input voltage range | V_{HBR} | $V_{DD} = 5\text{ V}$, except for H2H, H2L | 1.5 | — | 4.0 | V |
| Minimum input level | V_{INH} | $V_{DD} = 5\text{ V}$ | 60 | — | — | mV[p-p] |
| Torque command | | | | | | |
| In-phase input voltage range | EC | $V_{DD} = 5\text{ V}$ | 0.5 | — | 3.9 | V |
| Offset voltage | EC_{OF} | $V_{DD} = 5\text{ V}$ | −100 | 0 | 100 | mV |
| Dead zone | EC_{DZ} | $V_{DD} = 5\text{ V}$ | 0 | 75 | 150 | mV |
| Input current | EC_{IN} | $V_{DD} = 5\text{ V}$, $EC = ECR = 2.5\text{ V}$ | −5 | −1 | — | μA |
| Input/output gain | A_{CS} | $V_{DD} = 5\text{ V}$, $R_{CS} = 0.33\ \Omega$ | 0.36 | 0.48 | 0.60 | A/V |
| Output | | | | | | |
| High-level output saturation voltage | V_{OH} | $V_{DD} = 5\text{ V}$, $I_O = -500\text{ mA}$ | — | 0.15 | 0.30 | V |
| Low-level output saturation voltage | V_{OL} | $V_{DD} = 5\text{ V}$, $I_O = 500\text{ mA}$ | — | 0.15 | 0.30 | V |
| Torque limit current | I_{TL} | $V_{DD} = 5\text{ V}$, $R_{CS} = 0.33\ \Omega$ | 455 | 570 | 685 | mA |
| FG | | | | | | |
| FG output high-level | FG_H | $V_{DD} = 5\text{ V}$, $I_{FG} = -0.01\text{ mA}$ | 3 | — | — | V |
| FG output low-level | FG_L | $V_{DD} = 5\text{ V}$, $I_{FG} = 0.01\text{ mA}$ | — | — | 0.5 | V |
| In-phase input voltage range | V_{FGR} | $V_{DD} = 5\text{ V}$ | 1.5 | — | 3.0 | V |
| FG hysteresis width | H_{FG} | $V_{DD} = 5\text{ V}$ | 5 | 10 | 20 | mV |
| Step-up circuit | | | | | | |
| Step-up voltage | V_{PUMP} | $V_{DD} = 5\text{ V}$ | 7 | — | 10 | V |

■ Electrical Characteristics at $T_a = 25^\circ\text{C}$ (continued)

| Parameter | Symbol | Conditions | Min | Typ | Max | Unit |
|----------------------------|-------------------------|------------------------------|-----|-----|-----|------|
| PWM oscillation changeover | | | | | | |
| Input high-level | PWM_{H} | $V_{\text{DD}} = 5\text{ V}$ | 4.5 | — | — | V |
| Input low-level | PWM_{L} | $V_{\text{DD}} = 5\text{ V}$ | — | — | 0.5 | V |

• Design reference data

Note) The characteristics listed below are theoretical values based on the IC design and are not guaranteed.

| Parameter | Symbol | Conditions | Min | Typ | Max | Unit |
|--|------------------------|---|-----|-----|-----|------------------|
| PWM oscillation changeover | | | | | | |
| PWM frequency high-level | f_{PWMH} | $V_{\text{DD}} = 5\text{ V}$, $\text{PWMSW} = \text{Low}$ | — | 80 | — | kHz |
| PWM frequency low-level | f_{PWML} | $V_{\text{DD}} = 5\text{ V}$, $\text{PWMSW} = \text{High}$ | — | 40 | — | kHz |
| Thermal protection | | | | | | |
| Thermal protection operating temperature | T_{SDON} | $V_{\text{DD}} = 5\text{ V}$ | — | 150 | — | $^\circ\text{C}$ |
| Thermal protection hysteresis width | ΔT_{SD} | $V_{\text{DD}} = 5\text{ V}$ | — | 40 | — | $^\circ\text{C}$ |

■ Usage Notes

- Prevent this IC from being line-to-ground fault.

(To be concrete, do not short-circuit any of A31 (pin 21), A32 (pin 22), A21 (pin 24), A22 (pin 25), A11 (pin 27) and A12 (pin 28) with GND pin (pin 15).)

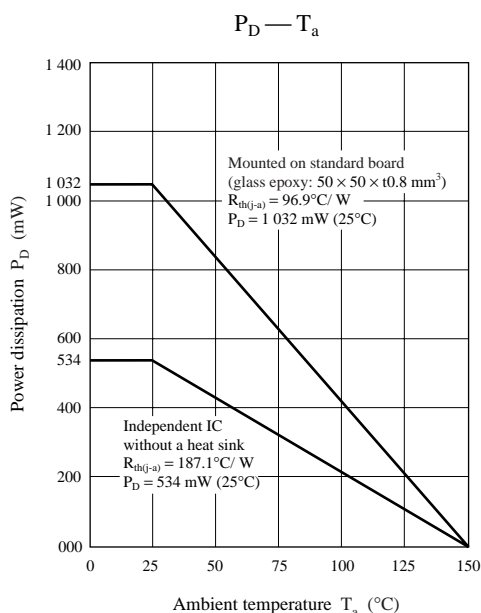
- Be careful of the following three pins because their static breakdown voltages are low. ($C = 200\text{ pF}$, $R = 0\text{ }\Omega$)

Pin 23: breakdown at 120 V

Pin 26: breakdown at 120 V

■ Application Notes

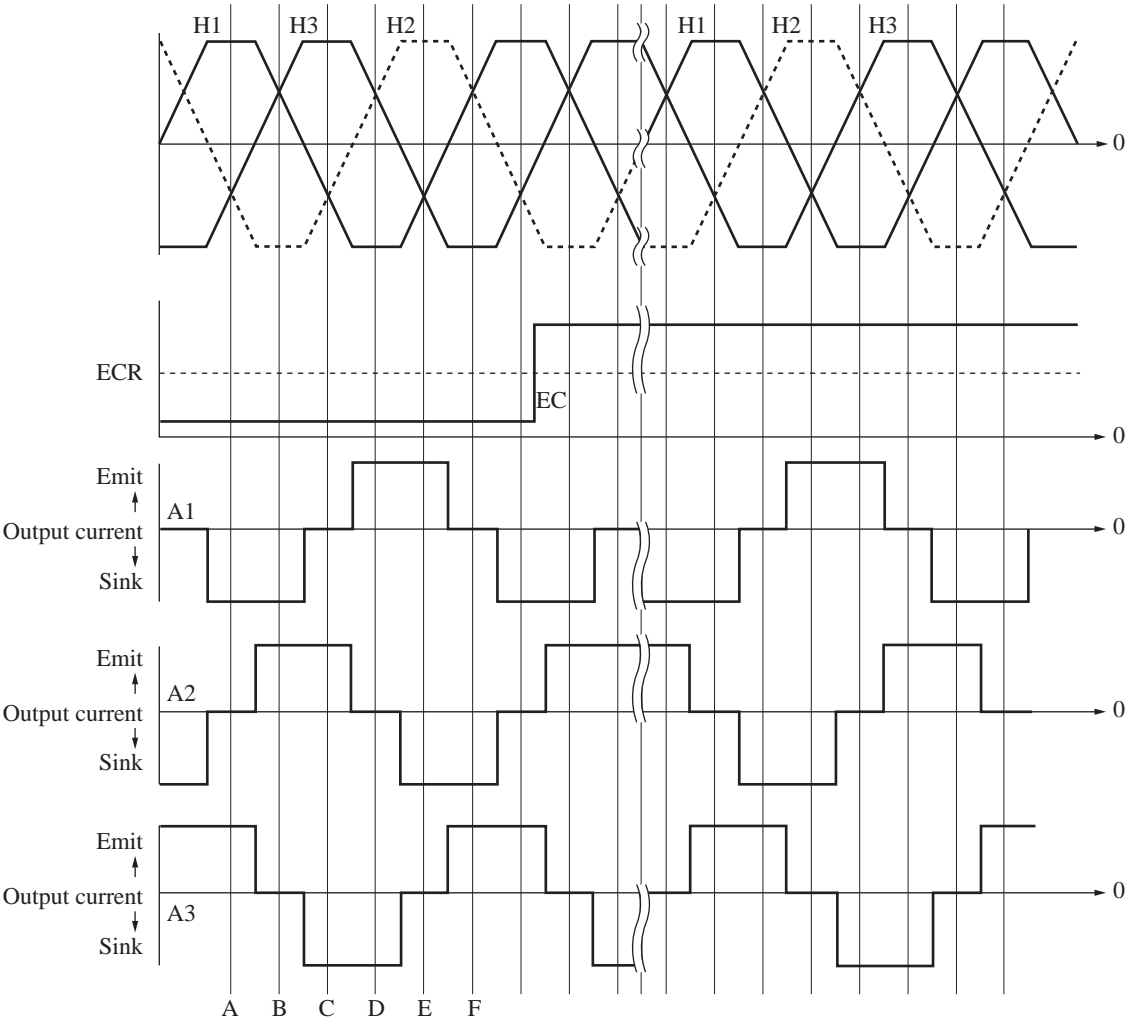
- $P_D - T_a$ curves of SSOP032-P-0300



■ Application Notes (continued)

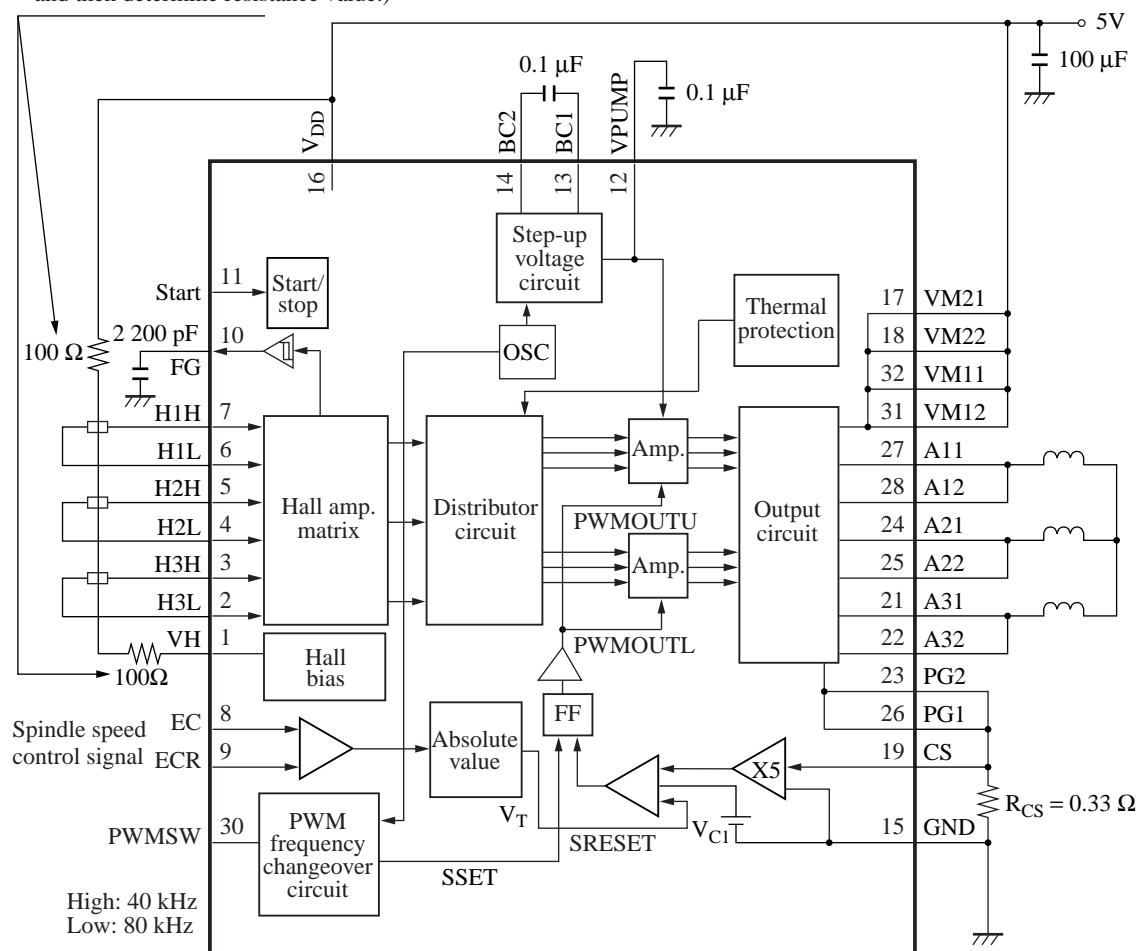
- Phase conditions between Hall input and output current

| Phase of Hall pin | | | |
|-------------------|-----|-----|-----|
| | H1H | H2H | H3H |
| A | H | ML | ML |
| B | MH | L | MH |
| C | ML | ML | H |
| D | L | MH | MH |
| E | ML | H | ML |
| F | MH | MH | L |



Application Circuit Example

(Check the stipulated value of electrical characteristics and then determine resistance value.)



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