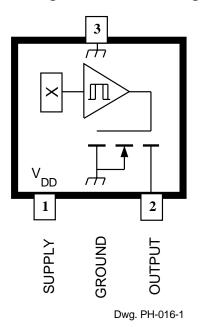
PRELIMINARY INFORMATION

(subject to change without notice) June 23, 1999

Package Suffix 'LH' Pinning



Pinning is shown viewed from branded side.

ABSOLUTE MAXIMUM RATINGS at $T_{\Delta} = +25^{\circ}C$

Supply Voltage, V _{DD} 5 V
Magnetic Flux Density, B Unlimited
Output OFF Voltage, V _{OUT} 5 V
Output Current, I _{OUT} 1 mA
Package Power Dissipation, P _D . See Graph
Junction Temperature, T _J +170°C
Operating Temperature Range,
T _A 40°C to +85°C
Storage Temperature Range,

 T_S -65°C to +170°C

MICROPOWER, ULTRA-SENSITIVE HALL-EFFECT SWITCH

The A3210ELH and A3210EUA Hall-effect switches are ultra-sensitive. pole independent, Hall-effect switches with a latched digital output. They are especially suited for operation in battery-operated, hand-held equipment such as cellular and cordless telephones, pagers, and palmtop computers. 2.5 to 3.5 volt operation and a unique clocking scheme reduce the average operating power requirements to typically 30 µW!

Unlike other Hall-effect switches, either a north or south pole of sufficient strength will turn the output ON; in the absence of a magnetic field, the output is OFF. The polarity independence and minimal power requirement allows these devices to easily replace reed switches for superior reliability and ease of manufacturing, while eliminating the requirement for signal conditioning.

Improved stability is made possible through chopper stabilization (dynamic offset cancellation), which reduces the residual offset voltage normally caused by device overmolding, temperature dependencies, and thermal stress.

These devices include on a single silicon chip a Hall-voltage generator, small-signal amplifier, chopper stabilization, a latch, and a MOSFET output. Advanced BiCMOS processing is used to take advantage of low-voltage and low-power requirements, component matching, very low input-offset errors, and small component geometries.

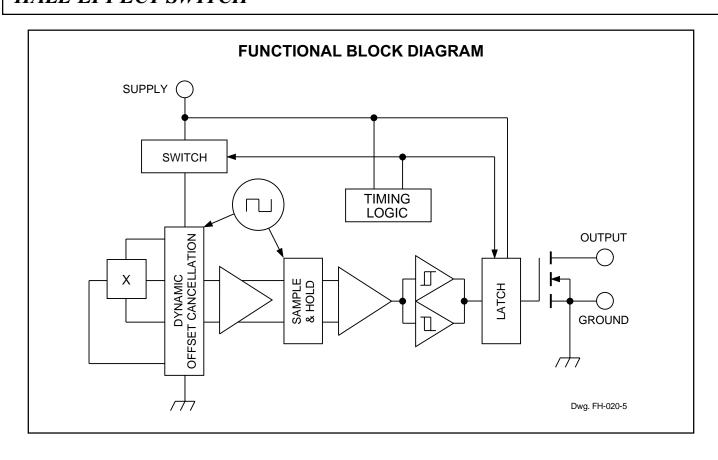
The A3210ELH and A3210EUA are rated for operation over a temperature range of -40°C to +85°C. Two package styles provide a magnetically optimized package for most applications. Suffix '-LH' is a miniature low-profile surface-mount package while suffix '-UA' is a three-lead ultra-mini-SIP for through-hole or surface mounting.

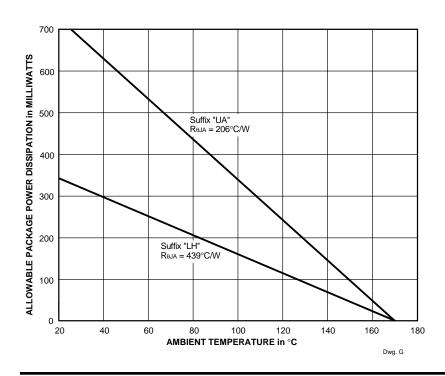
FEATURES

- Micropower Operation
- Operate with North or South Pole
- 2.5 V to 3.5 V Battery Operation
- Chopper Stabilized Superior Temperature Stability Extremely Low Switch-Point Drift Insensitive to Physical Stress
- Solid-State Reliability
- Small Size
- Easily Manufacturable with Magnet Pole Independence

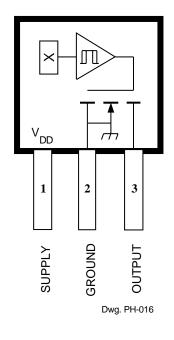
Always order by complete part number: the prefix 'A' + the basic four-digit part number + the suffix 'E' to indicate operating temperature range + a suffix to indicate package style, e.g., A3210ELH |.







Package Suffix 'UA' Pinning





ELECTRICAL CHARACTERISTICS at V_{DD} = 2.75 V, C_{BYPASS} = 0.1 μ F, and over operating temperature range.

			Limits			
Characteristic	Symbol	Test Conditions	Min.	Тур.	Max.	Units
Supply Voltage Range	V_{DD}	Operating ¹⁾	2.5	2.75	3.5	V
Output Leakage Current	I _{OFF}	$V_{OUT} = 3.5 \text{ V}, B_{RPN} < B < B_{RPS}$	_	«1.0	1.0	μΑ
Output ON Voltage	V _{OUT}	I _{OUT} = 1 mA, V _{DD} = 2.75 V	-	_	400	mV
Awake Time	t _{awake}		30	60	90	μs
Period	t _{period}		30	60	90	ms
Duty Cycle	d.c.		_	0.10	_	%
Chopping Frequency	f _C		-	340	_	kHz
Supply Current	I _{DD(EN)}	Chip awake (enabled)	0.1	-	3.0	mA
$(2.5 \le V_{DD} \le 3.5 \text{ V})$	I _{DD(DIS)}	Chip asleep (disabled)	1.0	10	50	μА
	I _{DD(AVG)}	V _{DD} = 2.75 V	2.0	8.8	25	μА
		V _{DD} = 3.5 V	2.0	13	60	μА

NOTES: 1. Operate and release points will vary with supply voltage.

- 2. B_{OPx} = operate point (output turns ON); B_{RPx} = release point (output turns OFF). 3. Typical Data is at T_A = +25°C and V_{DD} = 2.75 V and is for design information only.

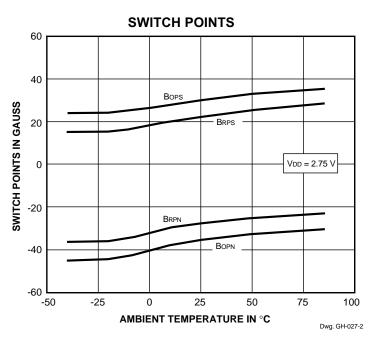
MAGNETIC CHARACTERISTICS at V_{DD} = 2.75 V, C_{BYPASS} = 0.1 μ F, and over operating temperature range.

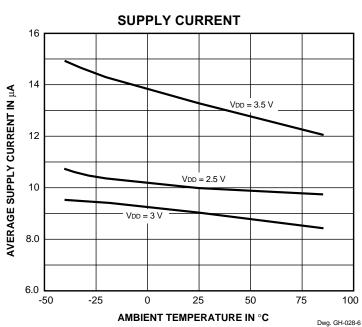
				Limits		
Characteristic	Symbol	Test Conditions	Min.	Тур.	Max.	Units
Operate Points	B _{OPS}		_	30	70	G
	B _{OPN}		-70	-35	_	G
Release Points	B _{RPS}		5.0	22	_	G
	B _{RPN}		_	-27	-5.0	G
Hysteresis	B _{hys}	B _{OPx} - B _{RPx}	_	7.7	_	G

NOTES: 1. As used here, negative flux densities are defined as less than zero (algebraic convention) and -50 G is less than +10 G.

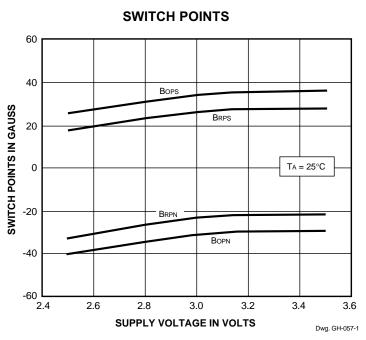
2. Typical Data is at T_A = +25°C and V_{DD} = 2.75 V and is for design information only.

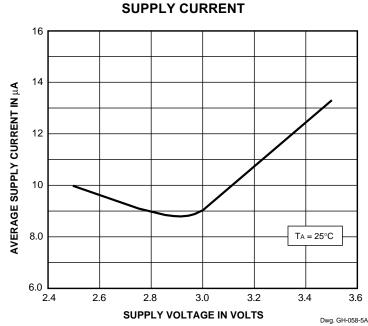
TYPICAL OPERATING CHARACTERISTICS as a function of temperature





as a function of supply voltage









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CRITERIA FOR DEVICE QUALIFICATION

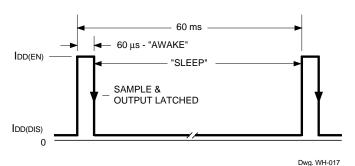
All Allegro sensors are subjected to stringent qualification requirements prior to being released to production. To become qualified, except for the destructive ESD tests, no failures are permitted.

Qualification Test	Test Method and Test Conditions	Test Length	Samples	Comments
Biased Humidity (HAST)	T _A = 130°C, RH = 85%	50 hrs	77	$V_{DD} = V_{OUT} = 3 V$
High-Temperature Operating Life (HTOL)	JESD22-A108, T _A = 150°C, T _J = 165°C	408 hrs	77	$V_{DD} = V_{OUT} = 3 V$
Accelerated HTOL	JESD22-A108, T _A = 175°C, T _J = 190°C	504 hrs	77	$V_{DD} = V_{OUT} = 3 V$
Autoclave, Unbiased	JESD22-A102, Condition C, T _A = 121°C, 15 psig	96 hrs	77	
High-Temperature (Bake) Storage Life	MIL-STD-883, Method 1008, T _A = 170°C	1000 hrs	77	
Temperature Cycle	MIL-STD-883, Method 1010, -65°C to +150°C	500 cycles	77	
Latch-Up	_	Pre/Post Reading	6	
Electro-Thermally Induced Gate Leakage	_	Pre/Post Reading	6	
ESD, Human Body Model	CDF-AEC-Q100-002	Pre/Post Reading	x per test	Test to failure, All leads > TBD
Electrical Distributions	Per Specification	_	30	

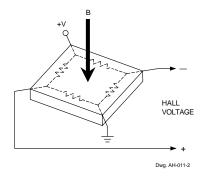


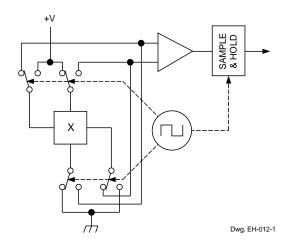
FUNCTIONAL DESCRIPTION

Low Average Power. Internal timing circuitry activates the sensor for $60~\mu s$ and deactivates it for the remainder of the 60~ms period (approximately 0.1% duty cycle). A short "wakeup" allows for stabilization prior to the sensor sampling and data latching on the falling edge of the timing pulse. The output during the "sleep" time is latched in the last sampled state. The supply current is not affected by the output state.



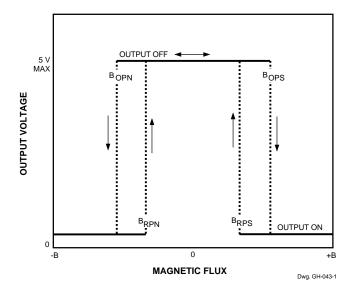
Chopper-Stabilized Technique. The Hall element can be considered as a resistor array similar to a Wheatstone bridge. A large portion of the offset is a result of the mismatching of these resistors. These devices use a proprietary dynamic offset cancellation technique, with an internal high-frequency clock to reduce the residual offset voltage of the Hall element that is normally caused by device overmolding, temperature dependencies, and thermal stress. The chopper-stabilizing technique cancels the mismatching of the resistors by changing the direction of the current flowing through the Hall plate and Hall voltage measurement taps, while maintaining the Hall-voltage signal that is induced by the external magnetic flux. The signal is, then, captured by a sample-and-hold circuit. This technique produces devices that have an extremely stable quiescent Hall output voltage, are immune to thermal stress, and have precise recoverability after temperature cycling. This technique will also slightly degrade the device output repeatability.





Operation. The output of these devices switch low (turn ON) when a magnetic field perpendicular to the Hall sensor exceeds the operate point B_{OPS} (or is less than B_{OPN}). After turn-ON, the output is capable of sinking up to 1 mA and the output voltage is $V_{OUT(ON)}$. When the magnetic field is reduced below the release point B_{RPS} (or increased above B_{RPN}), the device output goes high (turns OFF). The difference in the magnetic operate and release points is the hysteresis (B_{hys}) of the device. This built-in hysteresis allows clean switching of the output even in the presence of external mechanical vibration and electrical noise.

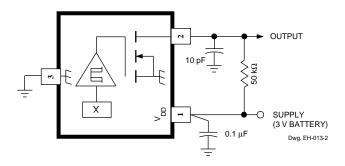
As used here, negative flux densities are defined as less than zero (algebraic convention) and -50 G is less than +10 G.



Applications. It is strongly recommended that an external bypass capacitor be connected (in close proximity to the Hall sensor) between the supply and ground of the device to reduce both external noise and noise generated by the chopper-stabilization technique. This is especially true due to the relatively high impedance of battery supplies.

The simplest form of magnet that will operate these devices is a bar magnet with either pole near the branded surface of the device. Many other methods of operation are possible. Extensive applications information on magnets and Hall-effect sensors is also available in the *Allegro Electronic Data Book* AMS-702 or *Application Note* 27701, or at

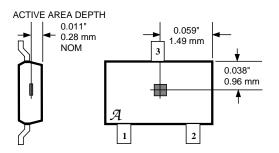
www.allegromicro.com



SENSOR LOCATIONS

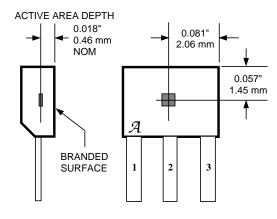
(±0.005" [0.13 mm] die placement)

Package Designator 'LH'



Dwg. MH-025

Package Designators 'UA' and 'UA-TL'



Dwg. MH-011-11

Although sensor location is accurate to three sigma for a particular design, product improvements may result in small changes to sensor location.



PACKAGE DESIGNATOR 'LH'

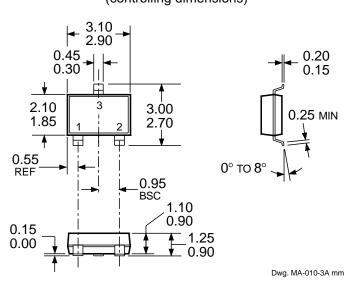
(fits SC-74A solder-pad layout)

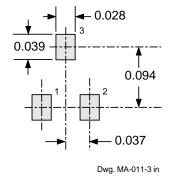
Dimensions in Inches

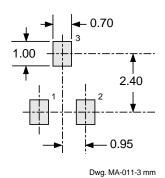
(for reference only)

0.122 $0.114\bar{}$ 0.018 0.0079 0.0059 0.0120.083 0.118 0.020 MIN 0.073 0.106 0.022 0° to 8° REF 0.037 BSC 0.043 0.035 0.006 0.049 0.035 0.000 Dwg. MA-010-3A in

Dimensions in Millimeters (controlling dimensions)







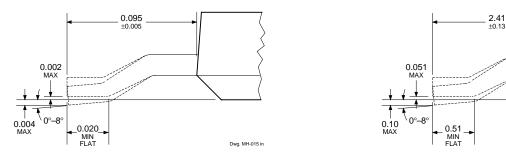
NOTES: 1. Tolerances on package height and width represent allowable mold offsets. Dimensions given are measured at the widest point (parting line).

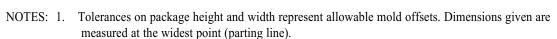
- 2. Exact body and lead configuration at vendor's option within limits shown.
- 3. Height does not include mold gate flash.
- 4. Where no tolerance is specified, dimension is nominal.

PACKAGE DESIGNATOR 'UA'

Dimensions in Millimeters Dimensions in Inches (for reference only) (controlling dimensions) 0.164 4.17 0.159 4.04 0.062 1.57 0.058 1.47 0.122 3.10 2.97 0.031 -0.085 2.16 MAX MAX 0.640 16.26 0.015 0.38 0.600 15.24 SEE NOTE SEE NOTE 0.016 0.050 BSC Dwg. MH-014D in Dwg. MH-014D mm

Surface-Mount Lead Form (Suffix '-TL')





- 2. Exact body and lead configuration at vendor's option within limits shown.
- 3. Height does not include mold gate flash.
- 4. Recommended minimum PWB hole diameter to clear transition area is 0.035" (0.89 mm).
- 5. Where no tolerance is specified, dimension is nominal.



Dwg. MH-015 mm

Allegro MicroSystems, Inc. reserves the right to make, from time to time, such departures from the detail specifications as may be required to permit improvements in the design of its products.

The information included herein is believed to be accurate and reliable. However, Allegro MicroSystems, Inc. assumes no responsibility for its use; nor for any infringements of patents or other rights of third parties which may result from its use.

HALL-EFFECT SENSORS SELECTION GUIDE

	Partial Part Avail. Oper. Characteristics at T _A = +25°C							
Number	Temp.	BOP(max)	BRP(min)	B _{hys(typ)}	Features	Notes		
HALL-EFFECT UNIPOLAR SWITCHES in order of BOP and Bhys								
3240	E/L	+50	+5.0	10	chopper stabilized	1		
3210	E	±70	±5.0	7.7	micropower, chopper stabilized			
3361	E E	+120	+50	5.0*	2-wire, chopper stabilized			
3362	E	+120	+50	5.0*	2-wire, chopper stabilized			
3161	E	+160	+30	20	2-wire			
3141	E/L	+160	+10	55				
3235	S	+175	+25	15*	output 1	2 2 1, 3		
		-25	-175	15*	output 2	2		
5140	E	+200	+50	55	300 mA output	1, 3		
3142	E/L	+230	+75	55		, -		
3143	E/L	+340	+165	55				
3144	E/L	+350	+50	55				
3122	E/L	+400	+140	105				
3123	E/L	+440	+180	105				
3121	E/L	+450	+125	105				
3150	J	+40 to +850	-	20	programmable, chopper stabilized	1		
0100						•		
	HALL-E	FFECT LATCHES	S & BIPOLA	R SWITCHES	in order of BOP and B _{hys}			
3260	E/L	+30	-30	20	bipolar, chopper stabilized			
3280	E/L	+40	-40	45	chopper stabilized			
3134	E/L	+50	-50	27	bipolar switch			
3133	K/L/S	+75	-75	52	bipolar switch			
3281	E/L	+90	-90	100	chopper stabilized			
3132	K/L/S	+95	-95	52	bipolar switch			
3187	E/L	+150	-150	100*	·			
3177	S	+150	-150	200				
3625	S	+150	-150	200	900 mA outputs	1, 3, 5		
3626	S	+150	-150	200	400 mA outputs	1, 3, 5		
3195	Ē/L	+160	-160	220	T	1. 4		
3197	L L	+160	-160	230		1, 4 1		
3175	S	+170	-170	200		•		
3188	E/L	+180	-180	200*				
3283	E/L	+180	-180	300	chopper stabilized			
3189	E/L	+230	-230	100*	5.1.5ppor otdomizod			
3275	S	+250	-250	100*		5		
3185	E/L	+270	-270	340*		0		
3105	L/L	TZ1 U	-210	340				

Operating Temperature Ranges:

 $S = -20^{\circ}\text{C}$ to $+85^{\circ}\text{C}$, $E = -40^{\circ}\text{C}$ to $+85^{\circ}\text{C}$, $J = -40^{\circ}\text{C}$ to $+115^{\circ}\text{C}$, $K = -40^{\circ}\text{C}$ to $+125^{\circ}\text{C}$, $L = -40^{\circ}\text{C}$ to $+150^{\circ}\text{C}$

Notes 1. Protected

- 2.Output 1 switches on south pole, output 2 switches on north pole for 2-phase, bifilar-wound, unipolar-driven brushless dc motor control.
- 3. Power driver output.
- 4. Active pull down.
- 5. Complementary outputs for 2-phase bifilar-wound, unipolar-driven brushless dc motor control.

Latches will <u>not</u> switch on removal of magnetic field; bipolar switches <u>may</u> switch on removal of field but require field reversal for reliable operation over operating temperature range.



^{*} Minimum.