

250kHz Low Supply Current High Efficiency 1.5A Switching Regulator

FEATURES

- 1mA I_Q at 250kHz
- Uses Small Inductors: 15 μ H
- All Surface Mount Components
- Only 0.6 Square Inch of Board Space
- Low Minimum Supply Voltage: 2.7V
- Constant Frequency Current Mode
- Current Limited Power Switch: 1.5A
- Regulates Positive or Negative Outputs
- Shutdown Supply Current: 12 μ A Typ
- Easy External Synchronization
- 8-Pin SO or PDIP Packages

APPLICATIONS


- Boost Regulators
- CCFL Backlight Driver
- Laptop Computer Supplies
- Multiple Output Flyback Supplies
- Inverting Supplies

DESCRIPTION

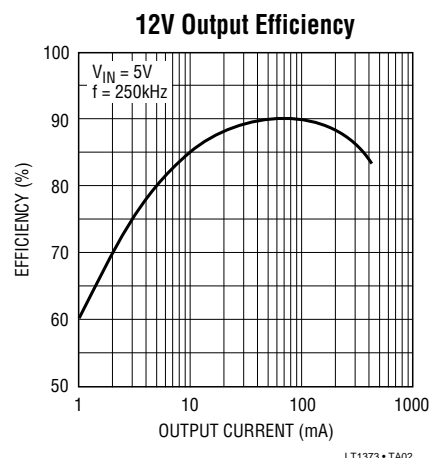
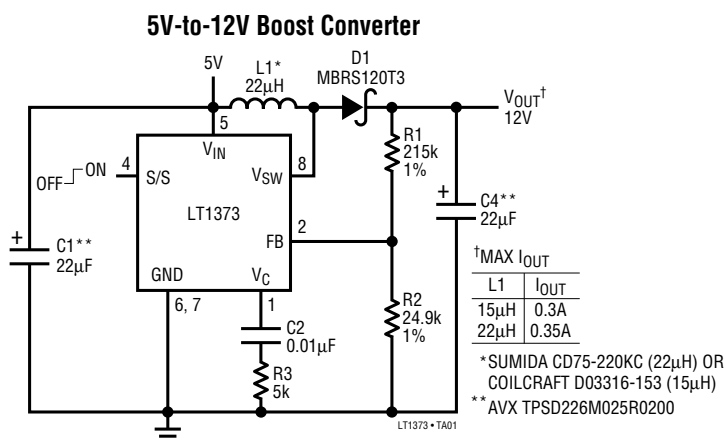
The LT[®]1373 is a low supply current high frequency current mode switching regulator. It can be operated in all standard switching configurations including boost, buck, flyback, forward, inverting and "Cuk." A 1.5A high efficiency switch is included on the die, along with all oscillator, control, and protection circuitry. All functions of the LT1373 are integrated into 8-pin SO/PDIP packages.

Compared to the 500kHz LT1372, which draws 4mA of quiescent current, the LT1373 switches at 250kHz, typically consumes only 1mA and has higher efficiency. High frequency switching allows for small inductors to be used. All surface mount components consume less than 0.6 square inch of board space.

New design techniques increase flexibility and maintain ease of use. Switching is easily synchronized to an external logic level source. A logic low on the shutdown pin reduces supply current to 12 μ A. Unique error amplifier circuitry can regulate positive or negative output voltage while maintaining simple frequency compensation techniques. Nonlinear error amplifier transconductance reduces output overshoot on start-up or overload recovery. Oscillator frequency shifting protects external components during overload conditions.

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TYPICAL APPLICATION

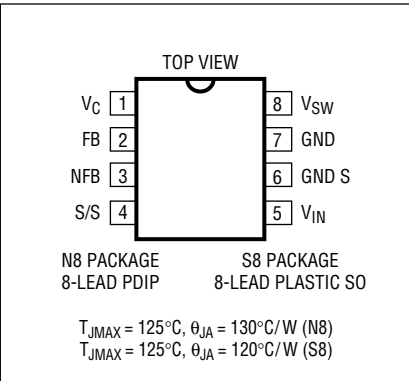


ABSOLUTE MAXIMUM RATINGS

Supply Voltage	30V
Switch Voltage	35V
S/S Pin Voltage	30V
Feedback Pin Voltage (Transient, 10ms)	±10V
Feedback Pin Current	10mA
Negative Feedback Pin Voltage (Transient, 10ms)	±10V
Operating Junction Temperature Range	
Operating	0°C to 125°C*
Short Circuit	0°C to 150°C
Storage Temperature Range	–65°C to 150°C
Lead Temperature (Soldering, 10 sec)	300°C

*Units shipped prior to Date Code 9552 are rated at 100°C maximum operating temperature.

PACKAGE/ORDER INFORMATION

 <p>TOP VIEW</p> <p>V_C 1 8 V_{SW} FB 2 7 GND NFB 3 6 GND S S/S 4 5 V_{IN}</p> <p>N8 PACKAGE 8-LEAD PDIP S8 PACKAGE 8-LEAD PLASTIC SO</p> <p>T_{JMAX} = 125°C, θ_{JA} = 130°C/W (N8) T_{JMAX} = 125°C, θ_{JA} = 120°C/W (S8)</p>	ORDER PART NUMBER
	LT1373CN8 LT1373CS8
	S8 PART MARKING
	1373

Consult factory for Industrial and Military grade parts.

ELECTRICAL CHARACTERISTICS

V_{IN} = 5V, V_C = 0.6V, V_{FB} = V_{REF}, V_{SW}, S/S and NFB pins open, unless otherwise noted.

SYMBOL	PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS
V _{REF}	Reference Voltage	Measured at Feedback Pin V _C = 0.8V	1.230 1.225	1.245 1.245	1.260 1.265	V V
I _{FB}	Feedback Input Current	V _{FB} = V _{REF}		50	150 275	nA nA
	Reference Voltage Line Regulation	2.7V ≤ V _{IN} ≤ 25V, V _C = 0.8V		0.01	0.03	%/V
V _{NFR}	Negative Feedback Reference Voltage	Measured at Negative Feedback Pin Feedback Pin Open, V _C = 0.8V		–2.490 –2.490		V V
I _{NFB}	Negative Feedback Input Current	V _{NFB} = V _{NFR}	–12	–7	–2	μA
	Negative Feedback Reference Voltage Line Regulation	2.7V ≤ V _{IN} ≤ 25V, V _C = 0.8V		0.01	0.05	%/V
g _m	Error Amplifier Transconductance	ΔI _C = ±5μA	250 150	375	500 600	μmho μmho
	Error Amplifier Source Current	V _{FB} = V _{REF} – 150mV, V _C = 1.5V	25	50	90	μA
	Error Amplifier Sink Current	V _{FB} = V _{REF} + 150mV, V _C = 1.5V		850	1500	μA
	Error Amplifier Clamp Voltage	High Clamp, V _{FB} = 1V Low Clamp, V _{FB} = 1.5V	1.70 0.25	1.95 0.40	2.30 0.52	V V
A _V	Error Amplifier Voltage Gain			250		V/V
	V _C Pin Threshold	Duty Cycle = 0%	0.8	1	1.25	V
f	Switching Frequency	2.7V ≤ V _{IN} ≤ 25V	225 210	250 250	275 290	kHz kHz
	Maximum Switch Duty Cycle		90	95		%
	Switch Current Limit Blanking Time			340	500	ns
BV	Output Switch Breakdown Voltage	2.7V ≤ V _{IN} ≤ 25V	35	47		V
V _{SAT}	Output Switch “On” Resistance	I _{SW} = 1A		0.5	0.85	Ω

ELECTRICAL CHARACTERISTICS

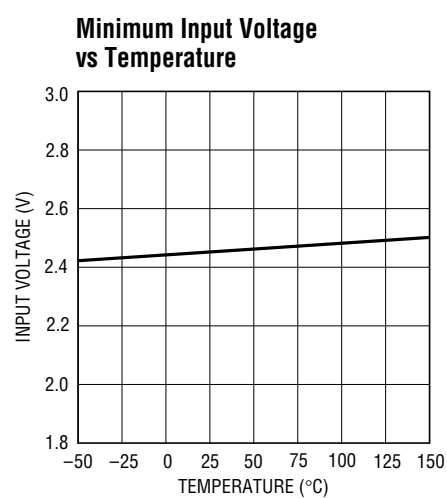
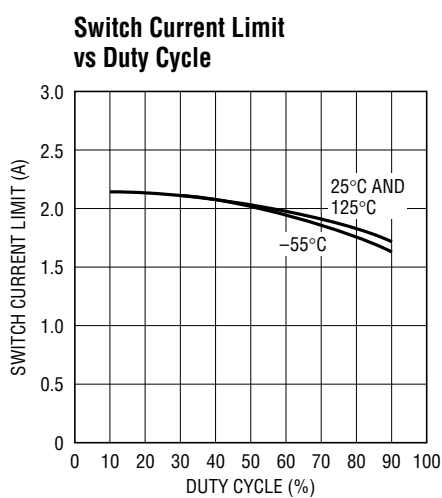
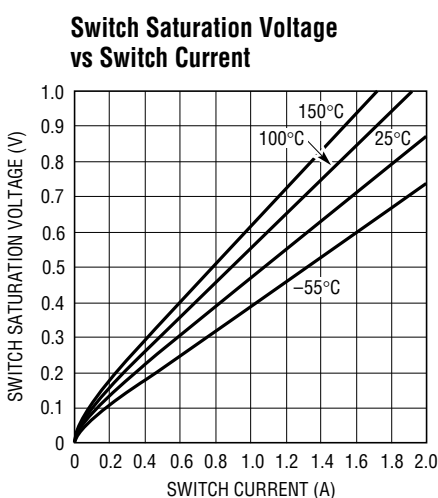
$V_{IN} = 5V$, $V_C = 0.6V$, $V_{FB} = V_{REF}$, V_{SW} , S/S and NFB pins open, unless otherwise noted.

SYMBOL	PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS
I_{LIM}	Switch Current Limit	Duty Cycle = 50% Duty Cycle = 80% (Note 1)	● 1.5 ● 1.3	1.9 1.7	2.4 2.2	A A
$\frac{\Delta I_{IN}}{\Delta I_{SW}}$	Supply Current Increase During Switch On-Time			10	20	mA/A
	Control Voltage to Switch Current Transconductance			2		A/V
	Minimum Input Voltage		●	2.4	2.7	V
I_Q	Supply Current	$2.7V \leq V_{IN} \leq 25V$	●	1	1.5	mA
	Shutdown Supply Current	$2.7V \leq V_{IN} \leq 25V$, $V_{S/S} \leq 0.6V$	●	12	30	μA
	Shutdown Threshold	$2.7V \leq V_{IN} \leq 25V$	●	0.6	1.3	V
	Shutdown Delay		●	5	12	μs
	S/S Pin Input Current	$0V \leq V_{S/S} \leq 5V$	●	-10	12	μA
	Synchronization Frequency Range		●	300	360	kHz

The ● denotes specifications which apply over the full operating temperature range.

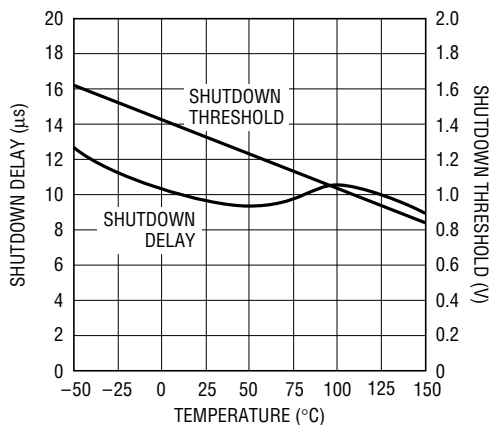
Note 1: For duty cycles (DC) between 50% and 90%, minimum guaranteed switch current is given by $I_{LIM} = 0.667 (2.75 - DC)$.

TYPICAL PERFORMANCE CHARACTERISTICS



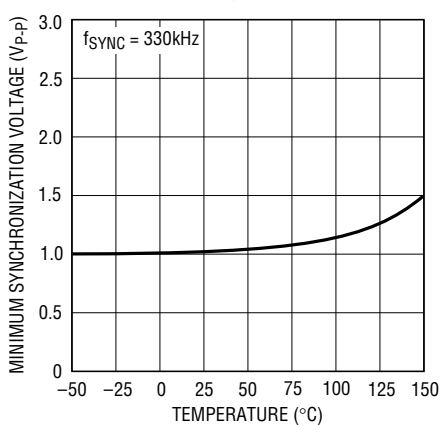
TYPICAL PERFORMANCE CHARACTERISTICS

Shutdown Delay and Threshold vs Temperature



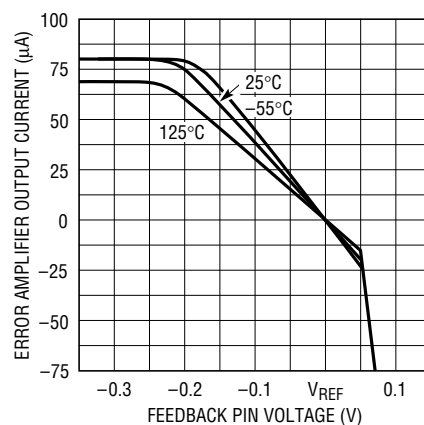
LT1373 • G04

Minimum Synchronization Voltage vs Temperature



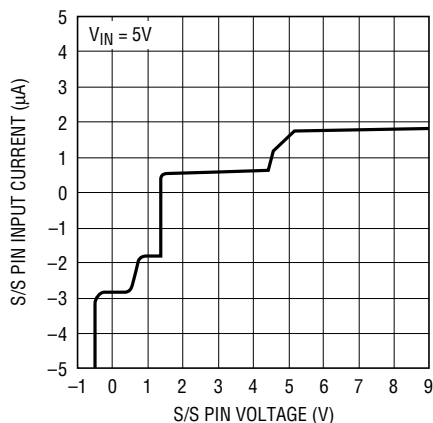
LT1373 • G05

Error Amplifier Output Current vs Feedback Pin Voltage



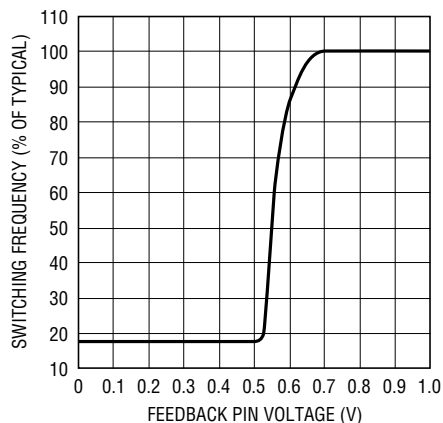
LT1373 • G06

S/S Pin Input Current vs Voltage



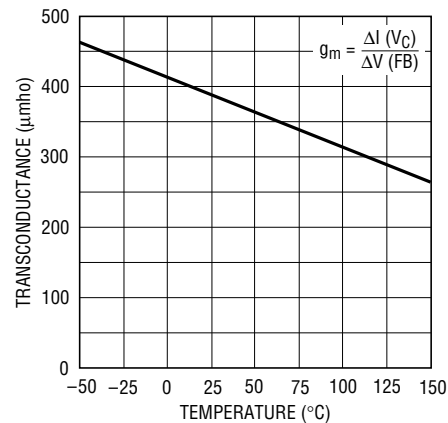
LT1373 • G07

Switching Frequency vs Feedback Pin Voltage



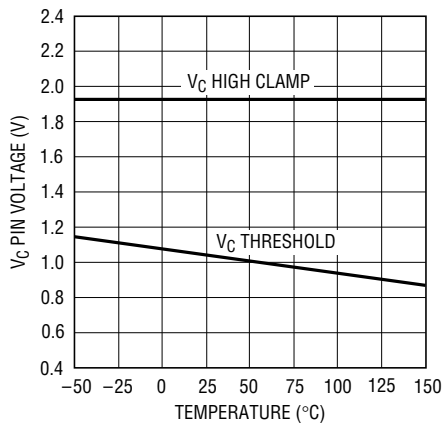
LT1373 • G08

Error Amplifier Transconductance vs Temperature



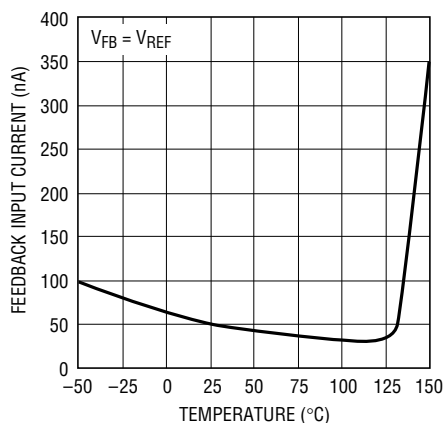
LT1373 • G09

V_C Pin Threshold and High Clamp Voltage vs Temperature



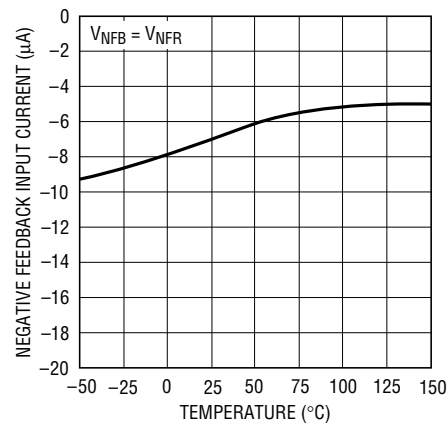
LT1373 • G10

Feedback Input Current vs Temperature



LT1373 • G11

Negative Feedback Input Current vs Temperature



LT1373 • G12

PIN FUNCTIONS

V_C (Pin 1): Compensation Pin. The V_C pin is used for frequency compensation, current limiting and soft start. It is the output of the error amplifier and the input of the current comparator. Loop frequency compensation can be performed with an RC network connected from the V_C pin to ground.

FB (Pin 2): The feedback pin is used for positive output voltage sensing and oscillator frequency shifting. It is the inverting input to the error amplifier. The noninverting input of this amplifier is internally tied to a 1.245V reference.

NFB (Pin 3): The negative feedback pin is used for negative output voltage sensing. It is connected to the inverting input of the negative feedback amplifier through a 400k source resistor.

S/S (Pin 4): Shutdown and Synchronization Pin. The S/S pin is logic level compatible. Shutdown is active low and the shutdown threshold is typically 1.3V. For normal operation, pull the S/S pin high, tie it to V_{IN} or leave it floating. To synchronize switching, drive the S/S pin between 300kHz and 360kHz.

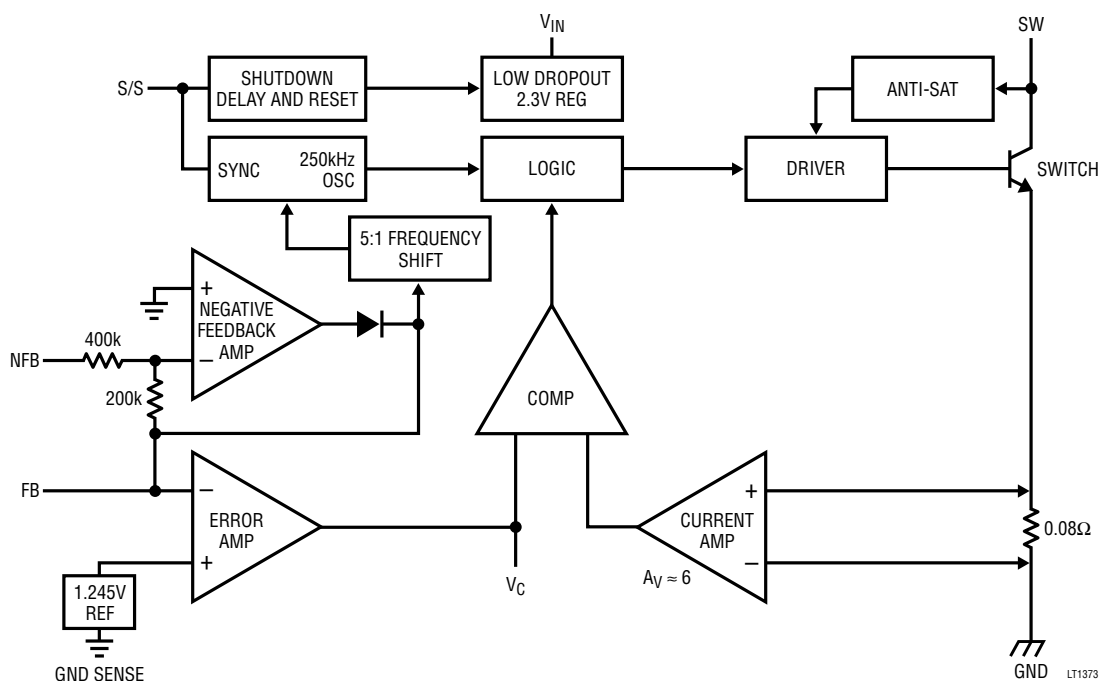
V_{IN} (Pin 5): Input Supply Pin. Bypass V_{IN} with 10μF or more. The part goes into undervoltage lockout when V_{IN} drops below 2.5V. Undervoltage lockout stops switching and pulls the V_C pin low.

GND S (Pin 6): The ground sense pin is a “clean” ground. The internal reference, error amplifier and negative feedback amplifier are referred to the ground sense pin. Connect it to ground. Keep the ground path connection to the output resistor divider and the V_C compensation network free of large ground currents.

GND (Pin 7): The ground pin is the emitter connection of the power switch and has large currents flowing through it. It should be connected directly to a good quality ground plane.

V_{SW} (Pin 8): The switch pin is the collector of the power switch and has large currents flowing through it. Keep the traces to the switching components as short as possible to minimize radiation and voltage spikes.

BLOCK DIAGRAM



OPERATION

The LT1373 is a current mode switcher. This means that switch duty cycle is directly controlled by switch current rather than by output voltage. Referring to the block diagram, the switch is turned “On” at the start of each oscillator cycle. It is turned “Off” when switch current reaches a predetermined level. Control of output voltage is obtained by using the output of a voltage sensing error amplifier to set current trip level. This technique has several advantages. First, it has immediate response to input voltage variations, unlike voltage mode switchers which have notoriously poor line transient response. Second, it reduces the 90° phase shift at mid-frequencies in the energy storage inductor. This greatly simplifies closed-loop frequency compensation under widely varying input voltage or output load conditions. Finally, it allows simple pulse-by-pulse current limiting to provide maximum switch protection under output overload or short conditions. A low dropout internal regulator provides a 2.3V supply for all internal circuitry. This low dropout design allows input voltage to vary from 2.7V to 25V with virtually no change in device performance. A 250kHz oscillator is the basic clock for all internal timing. It turns “On” the output switch via the logic and driver circuitry. Special adaptive anti-sat circuitry detects onset of saturation in the power switch and adjusts driver current instantaneously to limit switch saturation. This minimizes driver dissipation and provides very rapid turn-off of the switch.

A 1.245V bandgap reference biases the positive input of the error amplifier. The negative input of the amplifier is brought out for positive output voltage sensing. The error amplifier has nonlinear transconductance to reduce out-

put overshoot on start-up or overload recovery. When the feedback voltage exceeds the reference by 40mV, error amplifier transconductance increases ten times, which reduces output overshoot. The feedback input also invokes oscillator frequency shifting, which helps protect components during overload conditions. When the feedback voltage drops below 0.6V, the oscillator frequency is reduced 5:1. Lower switching frequency allows full control of switch current limit by reducing minimum switch duty cycle.

Unique error amplifier circuitry allows the LT1373 to directly regulate negative output voltages. The negative feedback amplifier's 400k source resistor is brought out for negative output voltage sensing. The NFB pin regulates at -2.49V while the amplifier output internally drives the FB pin to 1.245V. This architecture, which uses the same main error amplifier, prevents duplicating functions and maintains ease of use. (Consult Linear Technology Marketing for units that can regulate down to -1.25V.)

The error signal developed at the amplifier output is brought out externally. This pin (V_C) has three different functions. It is used for frequency compensation, current limit adjustment and soft starting. During normal regulator operation this pin sits at a voltage between 1V (low output current) and 1.9V (high output current). The error amplifier is a current output (g_m) type, so this voltage can be externally clamped for lowering current limit. Likewise, a capacitor coupled external clamp will provide soft start. Switch duty cycle goes to zero if the V_C pin is pulled below the control pin threshold, placing the LT1373 in an idle mode.

APPLICATIONS INFORMATION

Positive Output Voltage Setting

The LT1373 develops a 1.245V reference (V_{REF}) from the FB pin to ground. Output voltage is set by connecting the FB pin to an output resistor divider (Figure 1). The FB pin bias current represents a small error and can usually be ignored for values of R_2 up to 25k. The suggested value for R_2 is 24.9k. The NFB pin is normally left open for positive output applications. Positive fixed voltage versions are available. (Consult Linear Technology Marketing.)

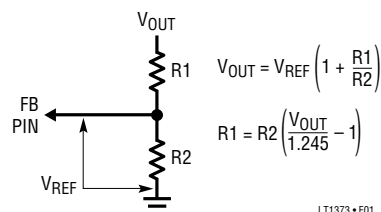


Figure 1. Positive Output Resistor Divider

APPLICATIONS INFORMATION

Negative Output Voltage Setting

The LT1373 develops a -2.49V reference (V_{NFB}) from the NFB pin to ground. Output voltage is set by connecting the NFB pin to an output resistor divider (Figure 2). The $-7\mu\text{A}$ NFB pin bias current (I_{NFB}) can cause output voltage errors and should not be ignored. This has been accounted for in the formula in Figure 2. The suggested value for R2 is 2.49k . The FB pin is normally left open for negative output applications.

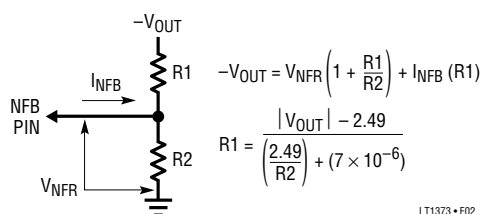


Figure 2. Negative Output Resistor Divider

Dual Polarity Output Voltage Sensing

Certain applications benefit from sensing both positive and negative output voltages. One example is the Dual Output Flyback Converter with Overvoltage Protection circuit shown in the Typical Applications section. Each output voltage resistor divider is individually set as described above. When both the FB and NFB pins are used, the LT1373 acts to prevent either output from going beyond its set output voltage. For example in this application, if the positive output were more heavily loaded than the negative, the negative output would be greater and would regulate at the desired set-point voltage. The positive output would sag slightly below its set-point voltage. This technique prevents either output from going unregulated high at no load.

Shutdown and Synchronization

The dual function S/S pin provides easy shutdown and synchronization. It is logic level compatible and can be pulled high, tied to V_{IN} or left floating for normal operation. A logic low on the S/S pin activates shutdown, reducing the part's supply current to $12\mu\text{A}$. Typical synchronization range is from 1.05 and 1.8 times the part's natural switching frequency, but is only guaranteed between 300kHz and 360kHz. A $12\mu\text{s}$ resettable shutdown delay network guar-

antees the part will not go into shutdown while receiving a synchronization signal.

Caution should be used when synchronizing above 330kHz because at higher sync frequencies the amplitude of the internal slope compensation used to prevent subharmonic switching is reduced. This type of subharmonic switching only occurs when the duty cycle of the switch is above 50%. Higher inductor values will tend to eliminate problems.

Thermal Considerations

Care should be taken to ensure that the worst-case input voltage and load current conditions do not cause excessive die temperatures. The packages are rated at 120°C/W for SO (S8) and 130°C/W for PDIP (N8).

Average supply current (including driver current) is:

$$I_{\text{IN}} = 1\text{mA} + \text{DC} (I_{\text{SW}}/60 + I_{\text{SW}} \times 0.004)$$

I_{SW} = switch current

DC = switch duty cycle

Switch power dissipation is given by:

$$P_{\text{SW}} = (I_{\text{SW}})^2 \times R_{\text{SW}} \times \text{DC}$$

R_{SW} = output switch "On" resistance

Total power dissipation of the die is the sum of supply current times supply voltage plus switch power:

$$P_{\text{D(TOTAL)}} = (I_{\text{IN}} \times V_{\text{IN}}) + P_{\text{SW}}$$

Choosing the Inductor

For most applications the inductor will fall in the range of $10\mu\text{H}$ to $50\mu\text{H}$. Lower values are chosen to reduce physical size of the inductor. Higher values allow more output current because they reduce peak current seen by the power switch which has a 1.5A limit. Higher values also reduce input ripple voltage, and reduce core loss.

When choosing an inductor you might have to consider maximum load current, core and copper losses, allowable component height, output voltage ripple, EMI, fault current in the inductor, saturation, and of course, cost. The following procedure is suggested as a way of handling these somewhat complicated and conflicting requirements.

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1. Assume that the average inductor current (for a boost converter) is equal to load current times V_{OUT}/V_{IN} and decide whether or not the inductor must withstand continuous overload conditions. If average inductor current at maximum load current is 0.5A, for instance, a 0.5A inductor may not survive a continuous 1.5A overload condition. Also, be aware that boost converters are not short-circuit protected, and that under output short conditions, inductor current is limited only by the available current of the input supply.
2. Calculate peak inductor current at full load current to ensure that the inductor will not saturate. Peak current can be significantly higher than output current, especially with smaller inductors and lighter loads, so don't omit this step. Powered iron cores are forgiving because they saturate softly, whereas ferrite cores saturate abruptly. Other core materials fall in between somewhere. The following formula assumes continuous mode operation, but it errors only slightly on the high side for discontinuous mode, so it can be used for all conditions.

$$I_{PEAK} = I_{OUT} \times \frac{V_{OUT}}{V_{IN}} + \frac{V_{IN}(V_{OUT} - V_{IN})}{2(f)(L)(V_{OUT})}$$

V_{IN} = minimum input voltage

f = 250kHz switching frequency

3. Decide if the design can tolerate an "open" core geometry like a rod or barrel, which have high magnetic field radiation, or whether it needs a closed core like a toroid to prevent EMI problems. One would not want an open core next to a magnetic storage media for instance! This is a tough decision because the rods or barrels are temptingly cheap and small, and there are no helpful guidelines to calculate when the magnetic field radiation will be a problem.
4. Start shopping for an inductor which meets the requirements of core shape, peak current (to avoid saturation), average current (to limit heating), and fault current, (if the inductor gets too hot, wire insulation will melt and cause turn-to-turn shorts). Keep in mind that all good things like high efficiency, low profile and high temperature operation will increase cost, sometimes dramatically.

5. After making an initial choice, consider the secondary things like output voltage ripple, second sourcing, etc. Use the experts in the Linear Technology application department if you feel uncertain about the final choice. They have experience with a wide range of inductor types and can tell you about the latest developments in low profile, surface mounting, etc.

Output Capacitor

The output capacitor is normally chosen by its effective series resistance (ESR), because this is what determines output ripple voltage. At 500kHz, any polarized capacitor is essentially resistive. To get low ESR takes *volume*, so physically smaller capacitors have high ESR. The ESR range for typical LT1373 applications is 0.05Ω to 0.5Ω. A typical output capacitor is an AVX type TPS, 22μF at 25V, with a guaranteed ESR less than 0.2Ω. This is a "D" size surface mount solid tantalum capacitor. TPS capacitors are specially constructed and tested for low ESR, so they give the lowest ESR for a given volume. To further reduce ESR, multiple output capacitors can be used in parallel. The value in microfarads is not particularly critical and values from 22μF to greater than 500μF work well, but you cannot cheat mother nature on ESR. If you find a tiny 22μF solid tantalum capacitor, it will have high ESR and output ripple voltage will be terrible. Table 1 shows some typical solid tantalum surface mount capacitors.

Table 1. Surface Mount Solid Tantalum Capacitor ESR and Ripple Current

E CASE SIZE	ESR (MAX Ω)	RIPPLE CURRENT (A)
AVX TPS, Sprague 593D	0.1 to 0.3	0.7 to 1.1
AVX TAJ	0.7 to 0.9	0.4
D CASE SIZE		
AVX TPS, Sprague 593D	0.1 to 0.3	0.7 to 1.1
AVX TAJ	0.9 to 2.0	0.36 to 0.24
C CASE SIZE		
AVX TPS	0.2 (Typ)	0.5 (Typ)
AVX TAJ	1.8 to 3.0	0.22 to 0.17
B CASE SIZE		
AVX TAJ	2.5 to 10	0.16 to 0.08

Many engineers have heard that solid tantalum capacitors are prone to failure if they undergo high surge currents. This is historically true and type TPS capacitors are

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specially tested for surge capability, but surge ruggedness is not a critical issue with the *output* capacitor. Solid tantalum capacitors fail during very high *turn-on* surges, which do not occur at the output of regulators. High *discharge* surges, such as when the regulator output is dead shorted, do not harm the capacitors.

Single inductor boost regulators have large RMS ripple current in the output capacitor, which must be rated to handle the current. The formula to calculate this is:

Output Capacitor Ripple Current (RMS)

$$I_{\text{RIPPLE}} (\text{RMS}) = I_{\text{OUT}} \sqrt{\frac{\text{DC}}{1 - \text{DC}}}$$

$$= I_{\text{OUT}} \sqrt{\frac{V_{\text{OUT}} - V_{\text{IN}}}{V_{\text{IN}}}}$$

Input Capacitors

The input capacitor of a boost converter is less critical due to the fact that the input current waveform is triangular, and does not contain large squarewave currents as is found in the output capacitor. Capacitors in the range of 10 μ F to 100 μ F with an ESR (effective series resistance) of 0.3 Ω or less work well up to a full 1.5A switch current. Higher ESR capacitors may be acceptable at low switch currents. Input capacitor ripple current for boost converter is:

$$I_{\text{RIPPLE}} = \frac{0.3(V_{\text{IN}})(V_{\text{OUT}} - V_{\text{IN}})}{(f)(L)(V_{\text{OUT}})}$$

f = 250kHz switching frequency

The input capacitor can see a very high surge current when a battery or high capacitance source is connected “live”, and solid tantalum capacitors can fail under this condition. Several manufacturers have developed a line of solid tantalum capacitors specially tested for surge capability (AVX TPS series, for instance), but even these units may fail if the input voltage approaches the maximum voltage rating of the capacitor. AVX recommends derating capacitor voltage by 2:1 for high surge applications. Ceramic and aluminum electrolytic capacitors may also be used and have a high tolerance to turn-on surges.

Ceramic Capacitors

Higher value, lower cost ceramic capacitors are now becoming available in smaller case sizes. These are tempting for switching regulator use because of their very low ESR. Unfortunately, the ESR is so low that it can cause loop stability problems. Solid tantalum capacitor ESR generates a loop “zero” at 5kHz to 50kHz that is instrumental in giving acceptable loop phase margin. Ceramic capacitors remain capacitive to beyond 300kHz and usually resonate with their ESL before ESR becomes effective. They are appropriate for input bypassing because of their high ripple current ratings and tolerance of turn-on surges. Linear Technology plans to issue a Design Note on the use of ceramic capacitors in the near future.

Output Diode

The suggested output diode (D1) is a 1N5818 Schottky or its Motorola equivalent, MBR130. It is rated at 1A average forward current and 30V reverse voltage. Typical forward voltage is 0.42V at 1A. The diode conducts current only during switch-off time. Peak reverse voltage for boost converters is equal to regulator output voltage. Average forward current in normal operation is equal to output current.

Frequency Compensation

Loop frequency compensation is performed on the output of the error amplifier (V_C pin) with a series R_C network. The main pole is formed by the series capacitor and the output impedance ($\approx 1\text{M}\Omega$) of the error amplifier. The pole falls in the range of 5Hz to 30Hz. The series resistor creates a “zero” at 2kHz to 10kHz, which improves loop stability and transient response. A second capacitor, typically one tenth the size of the main compensation capacitor, is sometimes used to reduce the switching frequency ripple on the V_C pin. V_C pin ripple is caused by output voltage ripple attenuated by the output divider and multiplied by the error amplifier. Without the second capacitor, V_C pin ripple is:

$$V_C \text{ Pin Ripple} = \frac{1.245(V_{\text{RIPPLE}})(g_m)(R_C)}{V_{\text{OUT}}}$$

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V_{RIPPLE} = output ripple (V_{P-P})

g_m = error amplifier transconductance ($\approx 375\mu mho$)

R_C = series resistor on V_C pin

V_{OUT} = DC output voltage

To prevent irregular switching, V_C pin ripple should be kept below $50mV_{P-P}$. Worst-case V_C pin ripple occurs at maximum output load current and will also be increased if poor quality (high ESR) output capacitors are used. The addition of a $0.001\mu F$ capacitor on the V_C pin reduces switching frequency ripple to only a few millivolts. A low value for R_C will also reduce V_C pin ripple, but loop phase margin may be inadequate.

Switch Node Considerations

For maximum efficiency, switch rise and fall time are made as short as possible. To prevent radiation and high frequency resonance problems, proper layout of the components connected to the switch node is essential. B field (magnetic) radiation is minimized by keeping output diode, switch pin and output bypass capacitor leads as short as possible. E field radiation is kept low by minimizing the length and area of all traces connected to the switch pin. A ground plane should always be used under the switcher circuitry to prevent interplane coupling.

The high speed switching current path is shown schematically in Figure 3. Minimum lead length in this path is essential to ensure clean switching and low EMI. The path including the switch, output diode and output capacitor is the only one containing nanosecond rise and fall times. Keep this path as short as possible.

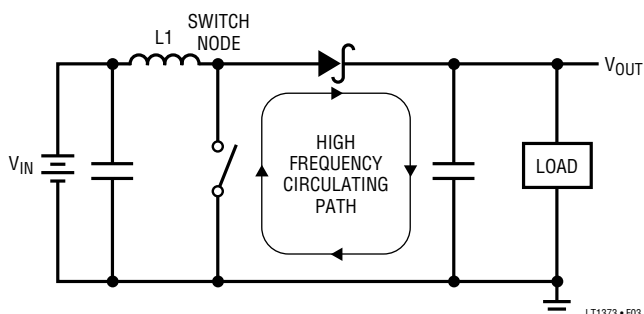


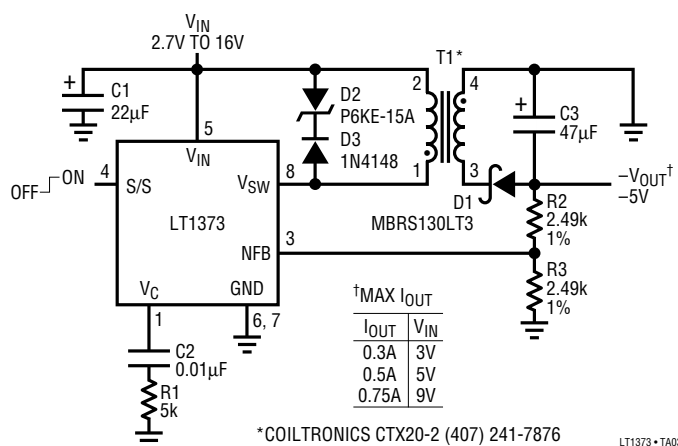
Figure 3

More Help

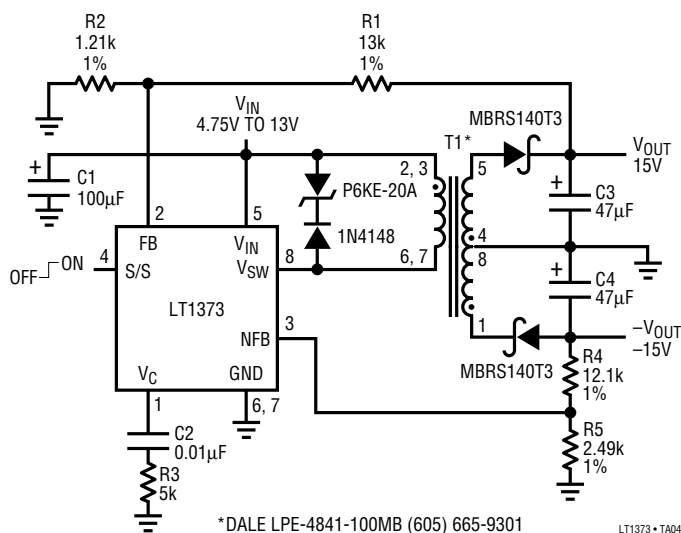
For more detailed information on switching regulator circuits, please see AN19. Linear Technology also offers a computer software program, SwitcherCAD, to assist in designing switching converters. SwitcherCAD will be updated in late 1995 for the LT1373. In addition, our applications department is always ready to lend a helping hand.

TYPICAL APPLICATIONS

Positive-to-Negative Converter with Direct Feedback

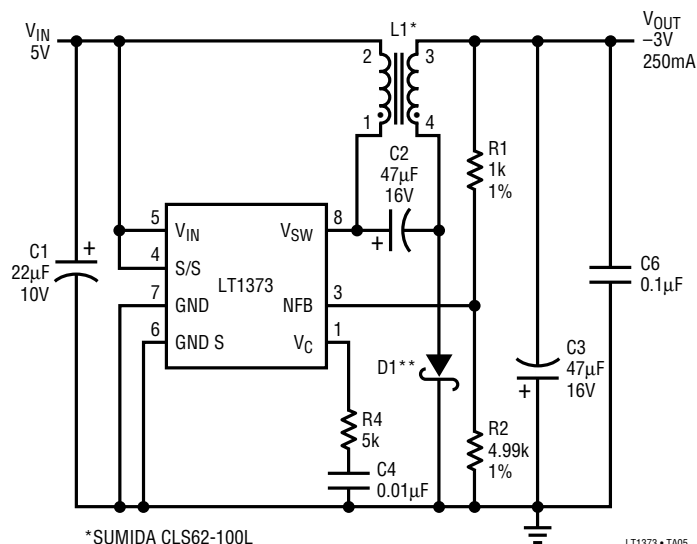


Dual Output Flyback Converter with Overvoltage Protection



TYPICAL APPLICATIONS

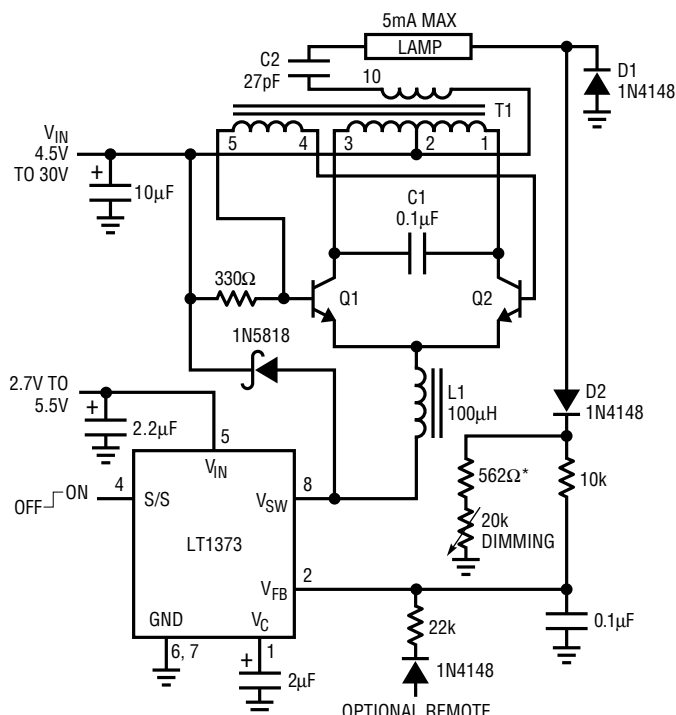
Low Ripple 5V to -3V "Cuk"† Converter



*SUMIDA CLS62-100L
**MOTOROLA MBR0520LT3
†PATENTS MAY APPLY

LT1373 • TA05

90% Efficient CCFL Supply



C1 = WIMA MKP-20
L1 = COILCRAFT D03316-104
Q1, Q2 = ZETEX ZTX849 OR ROHM 2SC5001
T1 = COILTRONICS CTX 110609
* = 1% FILM RESISTOR

OPTIONAL REMOTE
DIMMING

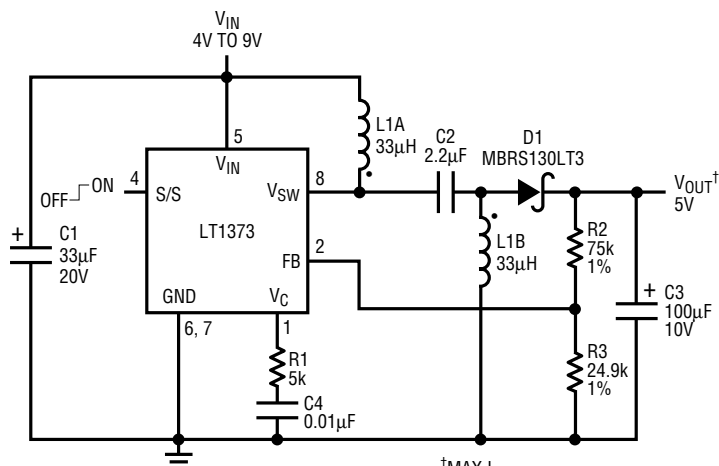
LT1372 • TA06

CCFL BACKLIGHT APPLICATION CIRCUITS
CONTAINED IN THIS DATA SHEET ARE
COVERED BY U.S. PATENT NUMBER 5408162
AND OTHER PATENTS PENDING

DO NOT SUBSTITUTE COMPONENTS

COILTRONICS (407) 241-7876
COILCRAFT (708) 639-6400

Two Li-Ion Cells to 5V SEPIC Converter



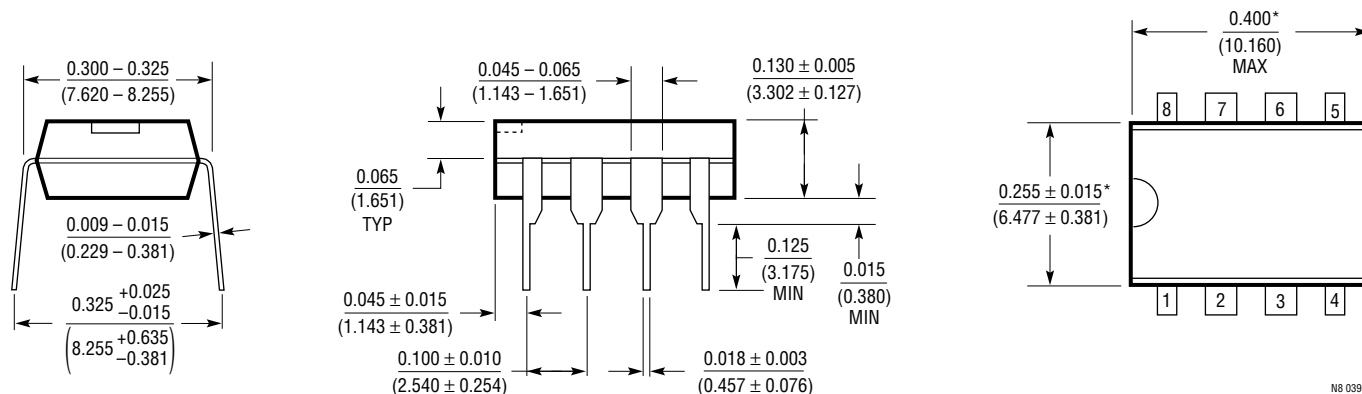
C1 = AVX TPSD 336M020R0200
C2 = TOKIN 1E225ZY5U-C203-F
C3 = AVX TPSD 107M010R0100
L1 = COILTRONICS CTX33-2, SINGLE
INDUCTOR WITH TWO WINDINGS

†MAX I _{OUT}		
I _{OUT}	V _{IN}	
0.45A	4V	
0.55A	5V	
0.65A	7V	
0.72A	9V	

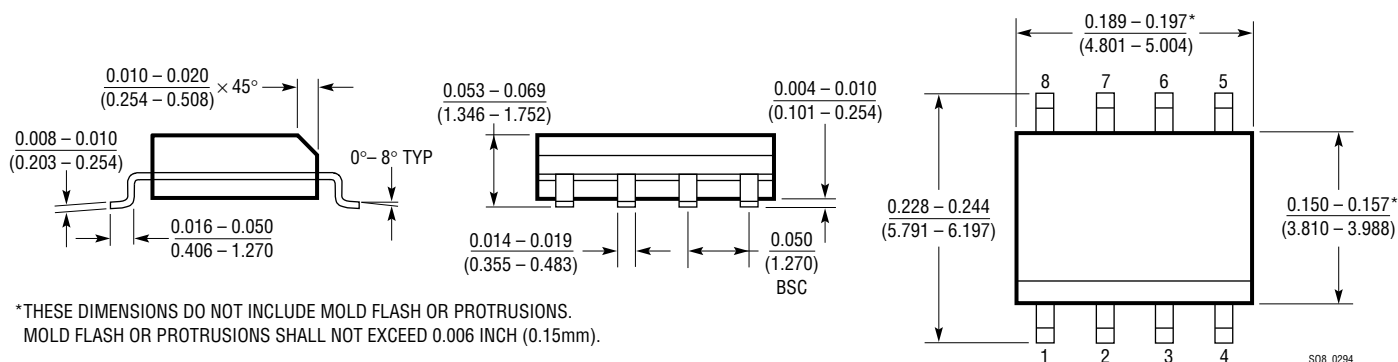
LT1373 • TA07

PACKAGE DESCRIPTION

Dimensions in inches (millimeters) unless otherwise noted.

**N8 Package
8-Pin Plastic DIP**

*THESE DIMENSIONS DO NOT INCLUDE MOLD FLASH OR PROTRUSIONS.
MOLD FLASH OR PROTRUSIONS SHALL NOT EXCEED 0.010 INCH (0.254mm).

**S8 Package
8-Pin Plastic SOIC**

*THESE DIMENSIONS DO NOT INCLUDE MOLD FLASH OR PROTRUSIONS.
MOLD FLASH OR PROTRUSIONS SHALL NOT EXCEED 0.006 INCH (0.15mm).

RELATED PARTS

PART NUMBER	DESCRIPTION	COMMENTS
LT1172	100kHz 1.25A Boost Switching Regulator	Also for Flyback, Buck and Inverting Configurations
LTC®1265	13V 1.2A Monolithic Buck Converter	Includes PMOS Switch On-Chip
LT1302	Micropower 2A Boost Converter	Converts 2V to 5V at 600mA
LT1372	500kHz 1.5A Boost Switching Regulator	Also Regulates Negative Flyback Outputs
LT1376	500kHz 1.5A Buck Switching Regulator	Handles Up to 25V Inputs
LT1377	1MHz 1.5A Boost Switching Regulator	Only 1MHz Integrated Switching Regulator Available