

TM8SK64JPN 8388608 BY 64-BIT SYNCHRONOUS DYNAMIC RAM MODULE — SODIMM

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- **Organization:**
 - TM8SK64JPN . . . 8 388 608 x 64 Bits
- **Single 3.3-V Power Supply**
(±10% Tolerance)
- **Designed for 66-MHz 4-Clock Systems**
- **JEDEC 144-Pin Small Outline Dual-In-Line Memory Module (SODIMM) Without Buffer for Use With Socket**
- **Uses Eight 64M-Bit Synchronous Dynamic RAMs (SDRAMs) (8M × 8-Bit) in Plastic Thin Small-Outline Packages (TSOPs)**
- **Byte-Read/Write Capability**
- **Performance Ranges:**
- **High-Speed, Low-Noise, Low-Voltage TTL (LVTTTL) Interface**
- **Read Latencies 2 and 3 Supported**
- **Support Burst-Interleave and Burst-Interrupt Operations**
- **Burst Length Programmable to 1, 2, 4, and 8**
- **Four Banks for On-Chip Interleaving (Gapless Access)**
- **Ambient Temperature Range 0°C to 70°C**
- **Gold-Plated Contacts**
- **Pipeline Architecture**
- **Serial Presence Detect (SPD) Using EEPROM**

	SYNCHRONOUS CLOCK CYCLE TIME		ACCESS TIME CLOCK TO OUTPUT		REFRESH INTERVAL
	t _{CK3}	t _{CK2}	t _{AC3}	t _{AC2}	t _{REF}
'8SK64JPN-10	10 ns	15 ns	7.5 ns	7.5 ns	64 ms

description

The TM8SK64JPN is a 64M-byte, 144-pin SODIMM. The SODIMM is composed of eight TMS664814DGE, 8388608 x 8-bit SDRAMs, each in a 400-mil, 54-pin plastic thin small-outline package (TSOP) mounted on a substrate with decoupling capacitors. See the TMS664814 data sheet (literature number SMOS695).

operation

The TM8SK64JPN operates as eight TMS664814DGE devices that are connected as shown in the functional block diagram.



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

PRODUCTION DATA information is current as of publication date. Products conform to specifications per the terms of Texas Instruments standard warranty. Production processing does not necessarily include testing of all parameters.

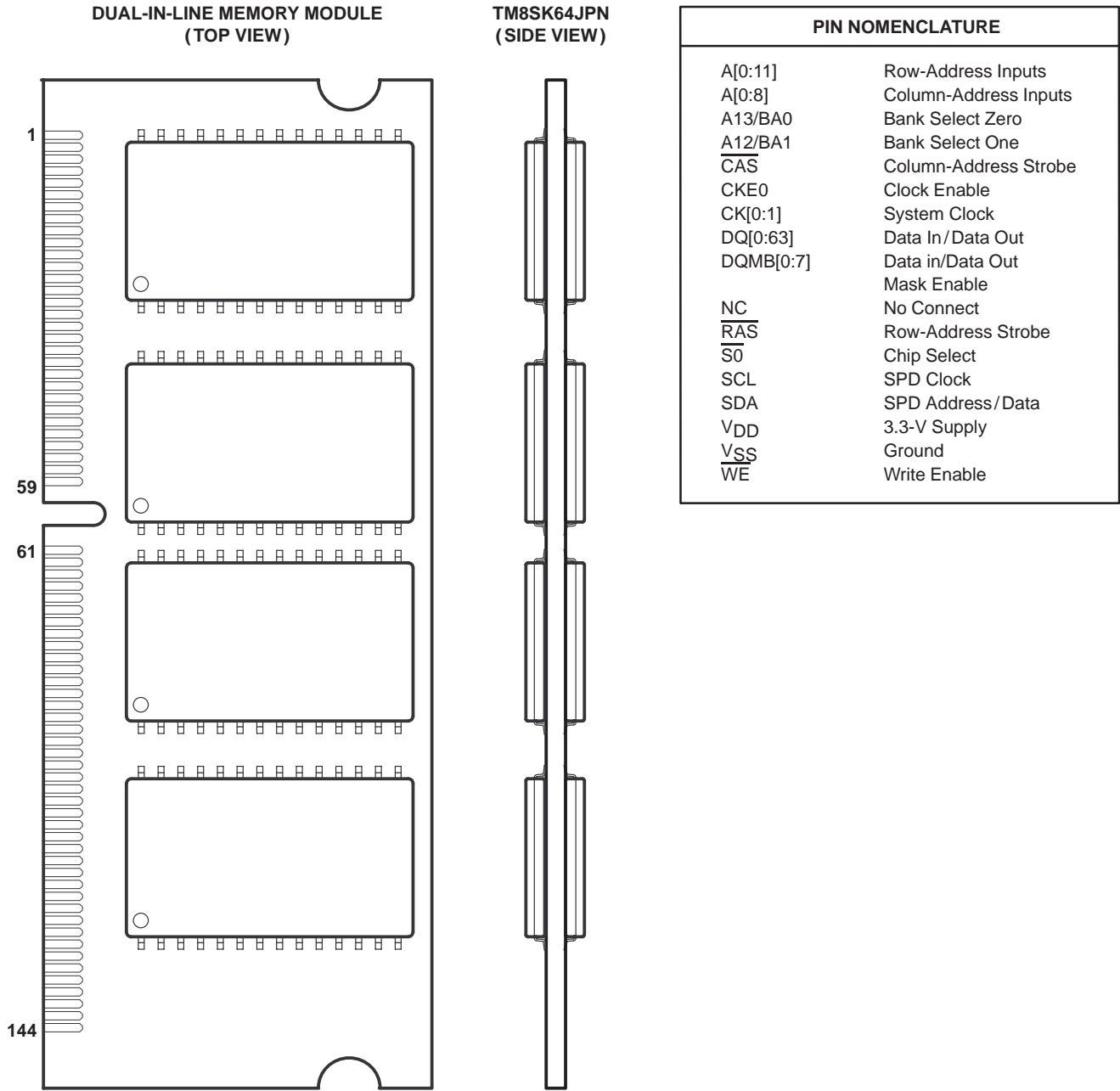
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INSTRUMENTS**

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Pin Assignments

NO.	PIN NAME	NO.	PIN NAME	NO.	PIN NAME	NO.	PIN NAME
1	V _{SS}	37	DQ8	73	NC	109	A9
2	V _{SS}	38	DQ40	74	CK1	110	A12/BA1
3	DQ0	39	DQ9	75	V _{SS}	111	A10
4	DQ32	40	DQ41	76	V _{SS}	112	A11
5	DQ1	41	DQ10	77	NC	113	V _{DD}
6	DQ33	42	DQ42	78	NC	114	V _{DD}
7	DQ2	43	DQ11	79	NC	115	DQMB2
8	DQ34	44	DQ43	80	NC	116	DQMB6
9	DQ3	45	V _{DD}	81	V _{DD}	117	DQMB3
10	DQ35	46	V _{DD}	82	V _{DD}	118	DQMB7
11	V _{DD}	47	DQ12	83	DQ16	119	V _{SS}
12	V _{DD}	48	DQ44	84	DQ48	120	V _{SS}
13	DQ4	49	DQ13	85	DQ17	121	DQ24
14	DQ36	50	DQ45	86	DQ49	122	DQ56
15	DQ5	51	DQ14	87	DQ18	123	DQ25
16	DQ37	52	DQ46	88	DQ50	124	DQ57
17	DQ6	53	DQ15	89	DQ19	125	DQ26
18	DQ38	54	DQ47	90	DQ51	126	DQ58
19	DQ7	55	V _{SS}	91	V _{SS}	127	DQ27
20	DQ39	56	V _{SS}	92	V _{SS}	128	DQ59
21	V _{SS}	57	NC	93	DQ20	129	V _{DD}
22	V _{SS}	58	NC	94	DQ52	130	V _{DD}
23	DQMB0	59	NC	95	DQ21	131	DQ28
24	DQMB4	60	NC	96	DQ53	132	DQ60
25	DQMB1	61	CK0	97	DQ22	133	DQ29
26	DQMB5	62	CKE0	98	DQ54	134	DQ61
27	V _{DD}	63	V _{DD}	99	DQ23	135	DQ30
28	V _{DD}	64	V _{DD}	100	DQ55	136	DQ62
29	A0	65	$\overline{\text{RAS}}$	101	V _{DD}	137	DQ31
30	A3	66	$\overline{\text{CAS}}$	102	V _{DD}	138	DQ63
31	A1	67	$\overline{\text{WE}}$	103	A6	139	V _{SS}
32	A4	68	NC	104	A7	140	V _{SS}
33	A2	69	$\overline{\text{S0}}$	105	A8	141	SDA
34	A5	70	NC	106	A13/BA0	142	SCL
35	V _{SS}	71	NC	107	V _{SS}	143	V _{DD}
36	V _{SS}	72	NC	108	V _{SS}	144	V _{DD}



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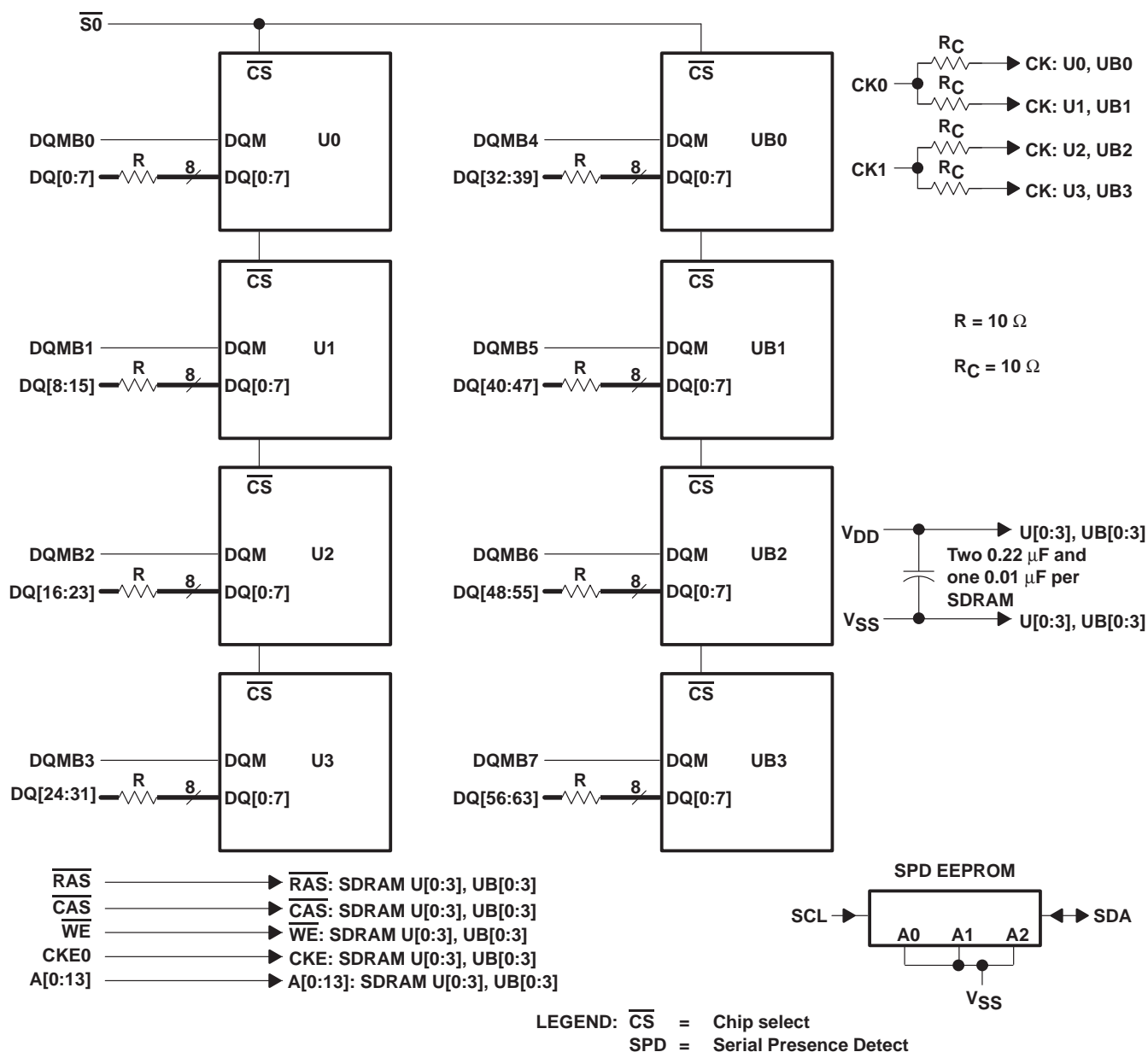
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small-outline dual-in-line memory module and components

The small-outline dual-in-line memory module and components include:

- PC substrate: $1,10 \pm 0,1$ mm (0.04 inch) nominal thickness
- Bypass capacitors: Multilayer ceramic
- Contact area: Nickel plate and gold plate over copper

functional block diagram



absolute maximum ratings over operating ambient temperature range (unless otherwise noted)[†]

Supply voltage range, V_{DD}	–0.5 V to 4.6 V
Voltage range on any pin (see Note 1)	– 0.5 V to 4.6 V
Short-circuit output current	50 mA
Power dissipation	8 W
Operating ambient temperature range, T_A	0°C to 70°C
Storage temperature range, T_{stg}	– 55°C to 125°C

[†] Stresses beyond those listed under “absolute maximum ratings” may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under “recommended operating conditions” is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

NOTE 1: All voltage values are with respect to V_{SS} .

recommended operating conditions

	MIN	NOM	MAX	UNIT
V_{DD} Supply voltage	3	3.3	3.6	V
V_{SS} Supply voltage		0		V
V_{IH} High-level input voltage	2		$V_{DD} + 0.3$	V
V_{IH-SPD} High-level input voltage for SPD device	2		5.5	V
V_{IL} Low-level input voltage	–0.3		0.8	V
T_A Operating ambient temperature	0		70	°C

capacitance over recommended ranges of supply voltage and ambient temperature, $f = 1$ MHz (see Note 2)[‡]

PARAMETER	MIN	MAX	UNIT
$C_i(CK)$ Input capacitance, CK input	2.5	4	pF
$C_i(AC)$ Input capacitance, address and control inputs: A0–A13, \overline{RAS} , \overline{CAS} , \overline{WE}	2.5	5	pF
$C_i(CKE)$ Input capacitance, CKE input		5	pF
C_o Output capacitance	4	6.5	pF
$C_i(DQMBx)$ Input capacitance, DQMBx input	2.5	5	pF
$C_i(Sx)$ Input capacitance, \overline{Sx} input	2.5	5	pF
$C_{i/o}(SDA)$ Input/output capacitance, SDA input		9	pF
$C_i(SPD)$ Input capacitance, SPD inputs (except SDA)		7	pF

[‡] Specifications in this table represent a single SDRAM device.

NOTE 2: $V_{DD} = 3.3 \text{ V} \pm 0.3 \text{ V}$. Bias on pins under test is 0 V.

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electrical characteristics over recommended ranges of supply voltage and ambient temperature (unless otherwise noted) (see Note 3)†

PARAMETER		TEST CONDITIONS	MIN	MAX	UNIT
V _{OH}	High-level output voltage	I _{OH} = – 2 mA	2.4		V
V _{OL}	Low-level output voltage	I _{OL} = 2 mA		0.4	V
I _I	Input current (leakage)	0 V < V _I < V _{DD} + 0.3 V, All other pins = 0 V to V _{DD}		± 10	μA
I _O	Output current (leakage)	0 V < V _O < V _{DD} + 0.3 V, Output disabled		± 10	μA
I _{CC1}	Operating current	Burst length = 1, t _{RC} ≥ t _{RC} MIN I _{OH} /I _{OL} = 0 mA, (see Notes 4, 5, and 6)	CAS latency = 2	105	mA
			CAS latency = 3	115	mA
I _{CC2P}	Precharge standby current in power-down mode	CKE ≤ V _{IL} MAX, t _{CK} = 15 ns (see Note 7)		1	mA
I _{CC2PS}		CKE and CK ≤ V _{IL} MAX, t _{CK} = ∞ (see Note 8)		1	mA
I _{CC2N}	Precharge standby current in nonpower-down mode	CKE ≥ V _{IH} MIN, t _{CK} = 15 ns (see Note 7)		40	mA
I _{CC2NS}		t _{CK} = ∞ (see Note 8)		5	mA
I _{CC3P}	Active standby current in power-down mode	CKE ≤ V _{IL} MAX, t _{CK} = 15 ns (see Notes 4 and 7)		8	mA
I _{CC3PS}		CKE and CK ≤ V _{IL} MAX, t _{CK} = ∞ (see Notes 4 and 8)		8	mA
I _{CC3N}	Active standby current in nonpower-down mode	CKE ≥ V _{IH} MIN, t _{CK} = 15 ns (see Notes 4 and 7)		60	mA
I _{CC3NS}		CKE ≥ V _{IH} MIN, CK ≤ V _{IL} MAX, t _{CK} = ∞ (see Notes 4 and 8)		10	mA
I _{CC4}	Burst current	Page burst, I _{OH} /I _{OL} = 0 mA All banks activated, n _{CCD} = one cycle (see Notes 9 and 10)	CAS latency = 2	140	mA
			CAS latency = 3	200	mA
I _{CC5}	Autorefresh current	t _{RC} ≤ t _{RC} MIN (see Notes 5 and 8)	CAS latency = 2	150	mA
			CAS latency = 3	150	mA
I _{CC6}	Self-refresh current	CKE ≤ V _{IL} MAX		2	mA

† Specifications in this table represent a single SDRAM device.

NOTES: 3. All specifications apply to the device after power-up initialization. All control and address inputs must be stable and valid.

4. Only one bank is activated.

5. t_{RC} ≥ t_{RC} MIN

6. Control and address inputs change state twice during t_{RC}.

7. Control and address inputs change state once every 30 ns.

8. Control and address inputs do not change state (stable).

9. Control and address inputs change state once every cycle.

10. Continuous burst access, n_{CCD} = 1 cycle



ac timing requirements†‡

			MIN	MAX	UNIT
tCK2	Cycle time, CK	CAS latency = 2	15		ns
tCK3	Cycle time, CK	CAS latency = 3	10		ns
tCH	Pulse duration, CK high		3		ns
tCL	Pulse duration, CK low		3		ns
tAC2	Access time, CK high to data out (see Note 11)	CAS latency = 2		7.5	ns
tAC3	Access time, CK high to data out (see Note 11)	CAS latency = 3		7.5	ns
tOH	Hold time, CK high to data out		3		ns
tLZ	Delay time, CK high to DQ in low-impedance state (see Note 12)		2		ns
tHZ	Delay time, CK high to DQ in high-impedance state (see Note 13)			10	ns
tIS	Setup time, address, control, and data input		2		ns
tIH	Hold time, address, control, and data input		1		ns
tCESP	Power down/self-refresh exit time		10		ns
tRAS	Delay time, ACTV command to DEAC or DCAB command		50	100000	ns
tRC	Delay time, ACTV, MRS, REFR, or SLFR to ACTV, MRS, REFR, or SLFR command		80		ns
tRCD	Delay time ACTV command to READ, READ-P, WRT, or WRT-P command (see Note 14)		30		ns
tRP	Delay time, DEAC or DCAB command to ACTV, MRS, REFR, or SLFR command		30		ns
tRRD	Delay time, ACTV command in one bank to ACTV command in the other bank		20		ns
tRSA	Delay time, MRS command to ACTV, MRS, REFR, or SLFR command		20		ns
tAPR	Final data out of READ-P operation to ACTV, MRS, SLFR, or REFR command		$t_{RP} - (CL-1) \cdot t_{CK}$		ns
tAPW	Final data in of WRT-P operation to ACTV, MRS, SLFR, or REFR command		$t_{RP} + 1 \cdot t_{CK}$		ns
tT	Transition time		1	5	ms

† All references are made to the rising transition of CK unless otherwise noted.

‡ Specifications in this table represent a single SDRAM device.

NOTES: 11. t_{AC} is referenced from the rising transition of CK that precedes the data-out cycle. For example, the first data out t_{AC} is referenced from the rising transition of CK that is read latency (one cycle after the READ command). Access time is measured at output reference level 1.4 V.

12. t_{LZ} is measured from the rising transition of CK that is read latency (one cycle after the READ command).

13. t_{HZ} (max) defines the time at which the outputs are no longer driven and is not referenced to output voltage levels.

14. For read or write operations with automatic deactivate, t_{RCD} must be set to satisfy minimum t_{RAS} .

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clock timing requirements†‡

		MIN	MAX	UNIT
t _{REF}	Refresh interval		64	ms
n _{CCD}	Delay time, READ or WRT command to an interrupting command	1		cycles
n _{CDD}	Delay time, $\overline{\text{CS}}$ low or high to input enabled or inhibited	0		cycles
n _{CLE}	Delay time, CKE high or low to CLK enabled or disabled	1	1	cycles
n _{CWL}	Delay time, final data in of WRT operation to READ, READ-P, WRT, or WRT-P	1		cycles
n _{DID}	Delay time, ENBL or MASK command to enabled or masked data in	0	0	cycles
n _{DOD}	Delay time, ENBL or MASK command to enabled or masked data out	2	2	cycles
n _{HZP2}	Delay time, DEAC or DCAB, command to DQ in high-impedance state	CAS latency = 2		2 cycles
n _{HZP3}	Delay time, DEAC or DCAB, command to DQ in high-impedance state	CAS latency = 3		3 cycles
n _{WCD}	Delay time, WRT command to first data in	0	0	cycles
n _{WR}	Delay time, final data in of WRT operation to DEAC or DCAB command	1		cycle

† All references are made to the rising transition of CK unless otherwise noted.

‡ A CK cycle can be considered as contributing to a timing requirement for those parameters defined in cycle units only when not gated by CKE (those CK cycles occurring during the time when CKE is asserted low).



serial presence detect

The serial presence detect (SPD) is contained in a 2K-bit serial EEPROM located on the module. The SPD nonvolatile EEPROM contains various data such as module configuration, SDRAM organization, and timing parameters (see Table 1). Only the first 128 bytes are programmed by Texas Instruments, while the remaining 128 bytes are available for customer use. Programming is done through an IIC bus using the clock (SCL) and data (SDA) signals. All Texas Instruments modules comply with the current JEDEC SPD standards. See the Texas Instruments *Serial Presence Detect Technical Reference* (literature number SMMU001) for further details. Table 1 lists the SPD contents.

Table 1. Serial Presence Detect Data

BYTE NO.	DESCRIPTION OF FUNCTION	ITEM	DATA
0	Defines number of bytes written into serial memory during module manufacturing	128 bytes	80h
1	Total number of bytes of SPD memory device	256 bytes	08h
2	Fundamental memory type (FPM, EDO, SDRAM, . . .)	SDRAM	04h
3	Number of row addresses on this assembly	12	0Ch
4	Number of column addresses on this assembly	9	09h
5	Number of module rows on this assembly	1 bank	01h
6	Data width of this assembly	64 bits	40h
7	Data width continuation		00h
8	Voltage interface standard of this assembly	LVTTTL	01h
9	SDRAM cycle time at maximum supported CAS latency (CL), CL = X	$t_{CK} = 10 \text{ ns}$	A0h
10	SDRAM access from clock at CL = X	$t_{AC} = 7.5 \text{ ns}$	75h
11	SODIMM configuration type (non-parity, parity, error correcting code [ECC])	Non-Parity	00h
12	Refresh rate/type	15.6 μs / self-refresh	80h
13	SDRAM width, primary DRAM	x8	08h
14	Error-checking SDRAM data width	N/A	00h
15	Minimum clock delay, back-to-back random column addresses	1 CK cycle	01h
16	Burst lengths supported	1, 2, 4, and 8	0Fh
17	Number of banks on each SDRAM device	4 banks	04h
18	CAS latencies supported	2, 3	06h
19	CS latency	0	01h
20	Write latency	0	01h
21	SDRAM module attributes	Non-buffered/ Non-registered	00h
22	SDRAM device attributes: general	V_{DD} tolerance = ($\pm 10\%$) Burst read/write, precharge all, auto precharge	0Eh
23	Minimum clock cycle time at CL = X – 1	$t_{CK} = 15 \text{ ns}$	F0h

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serial presence detect (continued)

Table 1. Serial Presence Detect Data (Continued)

BYTE NO.	DESCRIPTION OF FUNCTION	ITEM	DATA
24	Maximum data-access time from clock at CL = X – 1	t _{AC} = 7.5 ns	75h
25	Minimum clock cycle time at CL = X – 2	N/A	00h
26	Maximum data-access time from clock at CL = X – 2	N/A	00h
27	Minimum row-precharge time	t _{RP} = 30 ns	1Eh
28	Minimum row-active to row-active delay	t _{RRD} = 20 ns	14h
29	Minimum $\overline{\text{RAS}}$ -to- $\overline{\text{CAS}}$ delay	t _{RCD} = 30 ns	1Eh
30	Minimum $\overline{\text{RAS}}$ pulse width	t _{RAS} = 50 ns	32h
31	Command and address signal input setup time	t _{IS} = 2 ns	20h
32	Command and address signal input hold time	t _{IH} = 1 ns	10h
33	Data signal input setup time	t _{IS} = 2 ns	20h
34	Data signal input hold time	t _{IH} = 1 ns	10h
35–61	Superset features (may be used in the future)		
62	SPD revision	Rev. 1.2	12h
63	Checksum for byte 0–62	14	0Eh
64–71	Manufacturer's JEDEC ID code per JEP–106E	97	9700...00h
72	Manufacturing location†	TBD	
73	Manufacturer's part number	T	54h
74	Manufacturer's part number	M	4Dh
75	Manufacturer's part number	8	38h
76	Manufacturer's part number	S	53h
77	Manufacturer's part number	K	4Bh
78	Manufacturer's part number	6	36h
79	Manufacturer's part number	4	34h
80	Manufacturer's part number	J	4Ah
81	Manufacturer's part number	P	50h
82	Manufacturer's part number	N	4Eh
83	Manufacturer's part number	-	2Dh
84	Manufacturer's part number	1	31h
85	Manufacturer's part number	0	30h
86–90	Manufacturer's part number	SPACE	20h
91	Die revision code†	TBD	
92	PCB revision code†	TBD	
93–94	Manufacturing date†	TBD	
95–98	Assembly serial number†	TBD	
99–125	Manufacturer-specific data†	TBD	
126	Clock frequency	66 MHz	66h
127	SDRAM component and clock interconnection details	199	C7h
128–166	System integrator's specific data‡	TBD	
167–255	Open		

† TBD indicates values are determined at manufacturing time and are module dependent.

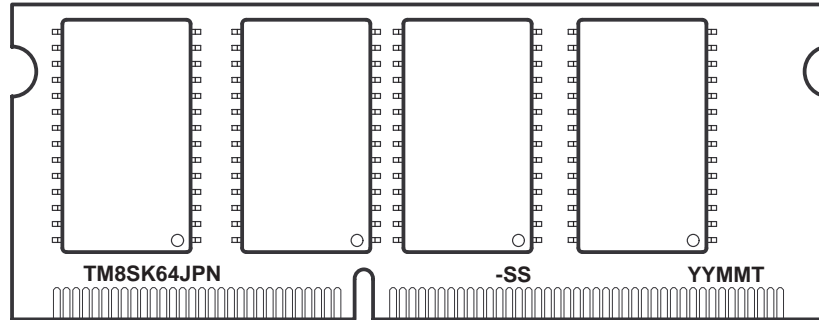
‡ These TBD values are determined and programmed by the customer (optional).



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device symbolization (TM8SK64JPN)



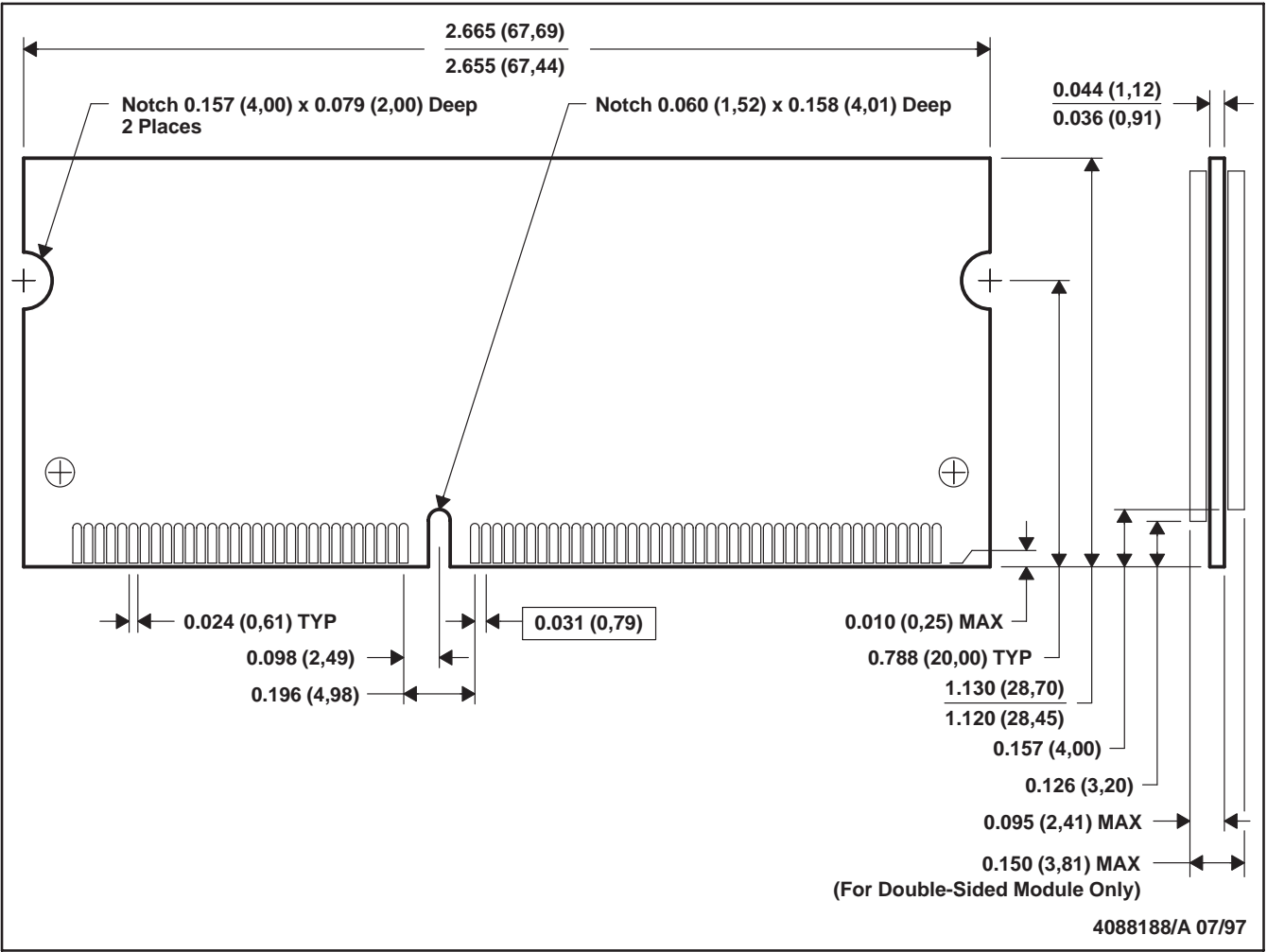
YY = Year Code
MM = Month Code
T = Assembly Site Code
-SS = Speed Code

NOTE A: Location of symbolization may vary.

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MECHANICAL DATA
BDQ (R-SODIMM-N144) SMALL OUTLINE DUAL IN-LINE MEMORY MODULE



NOTES: A. All linear dimensions are in inches (millimeters).
B. This drawing is subject to change without notice.
C. Falls within JEDEC MO-190

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