### INTEGRATED CIRCUITS

## DATA SHEET

# **TJA1050**High speed CAN transceiver

Preliminary specification Supersedes data of 1999 Sep 27 File under Integrated Circuits, IC18





**TJA1050** 

#### **FEATURES**

- Fully compatible with the "ISO 11898" standard
- High speed (up to 1 Mbaud)
- Very low ElectroMagnetic Emission (EME)
- Differential receiver with wide common-mode range for high ElectroMagnetic Immunity (EMI)
- An unpowered node does not disturb the bus lines
- Transmit Data (TXD) dominant time-out function
- · Silent mode in which the transmitter is disabled
- Bus pins protected against transients in an automotive environment
- Input levels compatible with 3.3 V devices
- · Thermally protected
- · Short-circuit proof to supply voltage and ground
- At least 110 nodes can be connected.

#### **GENERAL DESCRIPTION**

The TJA1050 is the interface between the Controller Area Network (CAN) protocol controller and the physical bus. The device provides differential transmit capability to the bus and differential receive capability to the CAN controller.

The TJA1050 is the successor to the PCA82C250 high-speed CAN transceiver. The most important improvements are:

- Much lower electromagnetic emission due to optimal matching of the output signals CANH and CANL
- Improved behaviour in case of an unpowered node.

#### **QUICK REFERENCE DATA**

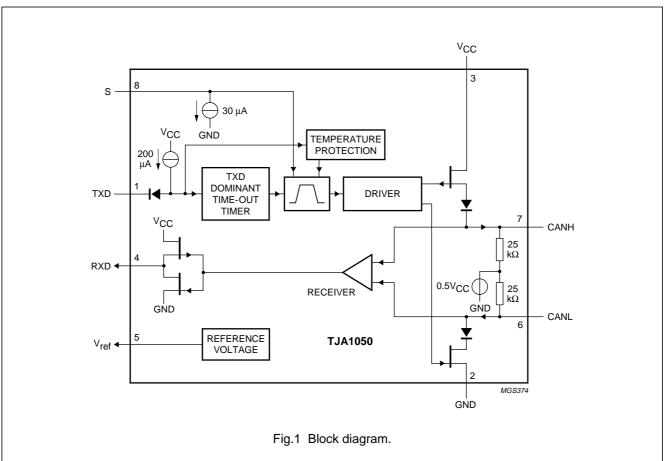
SYMBOL	PARAMETER	CONDITIONS	MIN.	MAX.	UNIT
V <sub>CC</sub>	supply voltage		4.75	5.25	V
V <sub>CANH</sub>	DC voltage at pin CANH	0 < V <sub>CC</sub> < 5.25 V; no time limit	-27	+40	V
V <sub>CANL</sub>	DC voltage at pin CANL	0 < V <sub>CC</sub> < 5.25 V; no time limit	-27	+40	V
V <sub>i(dif)(bus)</sub>	differential bus input voltage	dominant	1.5	3	V
t <sub>PD(TXD-RXD)</sub>	propagation delay TXD to RXD	V <sub>S</sub> = 0 V; see Fig.7	_	250	ns
T <sub>amb</sub>	ambient temperature		-40	+125	°C

#### ORDERING INFORMATION

TYPE		PACKAGE					
NUMBER	NAME	DESCRIPTION	VERSION				
TJA1050T	SO8	plastic small outline package; 8 leads; body width 3.9 mm	SOT96-1				
TJA1050U	_	bare die; die dimensions 1700 x 1280 x 380 μm	_				

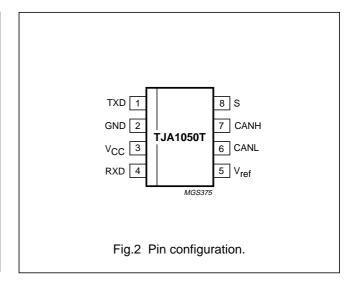
**TJA1050** 

### **BLOCK DIAGRAM**



### **PINNING**

SYMBOL	PIN	DESCRIPTION
TXD	1	transmit data input; reads in data from the CAN controller to the bus line drivers
GND	2	ground
V <sub>CC</sub>	3	supply voltage
RXD	4	receive data output; reads out data from the bus lines to the CAN controller
V <sub>ref</sub>	5	reference voltage output
CANL	6	LOW-level CAN bus line
CANH	7	HIGH-level CAN bus line
S	8	select input for high-speed mode or silent mode



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#### **FUNCTIONAL DESCRIPTION**

The TJA1050 is the interface between the CAN protocol controller and the physical bus. It is primarily intended for high-speed automotive applications using baud rates from 60 kbaud up to 1 Mbaud. It provides differential transmit capability to the bus and differential receiver capability to the CAN protocol controller. It is fully compatible to the "ISO 11898" standard.

A current-limiting circuit protects the transmitter output stage from damage caused by accidental short-circuit to either positive or negative supply voltage, although power dissipation increases during this fault condition.

A thermal protection circuit protects the IC from damage by switching off the transmitter if the junction temperature exceeds a value of approximately 165 °C. Because the transmitter dissipates most of the power, the power dissipation and temperature of the IC is reduced. All other IC functions continue to operate. The transmitter off-state resets when pin TXD goes HIGH. The thermal protection circuit is particularly needed when a bus line short-circuits.

The pins CANH and CANL are protected from automotive electrical transients (according to "ISO 7637", see Fig.4).

Control pin S allows two operating modes to be selected: high-speed mode or silent mode.

The high-speed mode is the normal operating mode and is selected by connecting pin S to ground. It is the default mode if pin S is not connected.

In the silent mode, the transmitter is disabled. All other IC functions continue to operate. The silent mode is selected by connecting pin S to  $V_{\rm CC}$  and can be used to prevent network communication from being blocked, due to a CAN controller which is out of control.

A 'TXD dominant time-out' timer circuit prevents the bus lines being driven to a permanent dominant state (blocking all network communication) if pin TXD is forced permanently LOW by a hardware and/or software application failure. The timer is triggered by a negative edge on pin TXD. If the duration of the LOW-level on pin TXD exceeds the internal timer value, the transmitter is disabled, driving the bus into a recessive state. The timer is reset by a positive edge on pin TXD.

**Table 1** Function table of the CAN transceiver; X = don't care

V <sub>CC</sub>	TXD	S	CANH	CANL	BUS STATE	RXD
4.75 to 5.25 V	0	0 (or floating)	HIGH	LOW	dominant	0
4.75 to 5.25 V	X	1	0.5V <sub>CC</sub>	0.5V <sub>CC</sub>	recessive	1
4.75 to 5.25 V	1 (or floating)	X	0.5V <sub>CC</sub>	0.5V <sub>CC</sub>	recessive	1
<2 V (not powered)	X	X	$0 \text{ V} < \text{V}_{\text{CANH}} < \text{V}_{\text{CC}}$	$0 \text{ V} < \text{V}_{\text{CANL}} < \text{V}_{\text{CC}}$	recessive	Χ
2 V < V <sub>CC</sub> < 4.75 V	>2 V	Х	$0 \text{ V} < \text{V}_{\text{CANH}} < \text{V}_{\text{CC}}$	$0 \text{ V} < \text{V}_{\text{CANL}} < \text{V}_{\text{CC}}$	recessive	Х

**TJA1050** 

#### LIMITING VALUES

In accordance with the Absolute Maximum Rating System (IEC 60134). All voltages are referenced to GND (pin 2). Positive currents flow into the IC.

SYMBOL	PARAMETER	CONDITIONS	MIN.	MAX.	UNIT
V <sub>CC</sub>	supply voltage		-0.3	+6	V
V <sub>CANH</sub>	DC voltage at pin CANH	0 < V <sub>CC</sub> < 5.25 V; no time limit	-27	+40	V
V <sub>CANL</sub>	DC voltage at pin CANL	0 < V <sub>CC</sub> < 5.25 V; no time limit	-27	+40	V
$V_{TXD}$	DC voltage at pin TXD		-0.3	V <sub>CC</sub> + 0.3	V
$V_{RXD}$	DC voltage at pin RXD		-0.3	V <sub>CC</sub> + 0.3	V
V <sub>ref</sub>	DC voltage at pin V <sub>ref</sub>		-0.3	V <sub>CC</sub> + 0.3	V
Vs	DC voltage at pin S		-0.3	V <sub>CC</sub> + 0.3	V
V <sub>trt(CANH)</sub>	transient voltage at pin CANH	note 1	-200	+200	V
V <sub>trt(CANL)</sub>	transient voltage at pin CANL	note 1	-200	+200	V
V <sub>es</sub>	electrostatic discharge voltage at all pins	note 2	-4000	+4000	V
		note 3	-200	+200	V
T <sub>stg</sub>	storage temperature		-55	+150	°C
T <sub>amb</sub>	ambient temperature		-40	+125	°C
T <sub>vj</sub>	virtual junction temperature	note 4	-40	+150	°C

#### **Notes**

- 1. The waveforms of the applied transients shall be in accordance with "ISO 7637 part 1", test pulses 1, 2, 3a and 3b (see Fig.4).
- 2. Human body model: C = 100 pF and R = 1.5 k $\Omega$ . In case of a discharge from pin CANH to all other non-supply pins:  $-3750 \text{ V} < \text{V}_{es} < +3750 \text{ V}$ .
- 3. Machine model: C = 200 pF, R = 10  $\Omega$  and L = 0.75  $\mu$ H. In case of a discharge from pin CANL to pin GND: -100 V < V<sub>es</sub> < +100 V; in case of a discharge from pin CANH to V<sub>CC</sub>: -150 V < V<sub>es</sub> < +150 V.
- 4. In accordance with "IEC 60747-1". An alternative definition of  $T_{vj}$  is:  $T_{vj} = T_{amb} + P \times R_{th(vj-a)}$ , where  $R_{th(vj-a)}$  is a fixed value to be used for the calculation of  $T_{vj}$ . The rating for  $T_{vj}$  limits the allowable combinations of power dissipation (P) and ambient temperature ( $T_{amb}$ ).

### THERMAL CHARACTERISTICS

According to IEC 60747-1.

SYMBOL	PARAMETER	CONDITIONS	VALUE	UNIT
R <sub>th(vj-a)</sub>	thermal resistance from junction to ambient in SO8 package	in free air	145	K/W
R <sub>th(vj-s)</sub>	thermal resistance from junction to substrate of bare die	in free air	50	K/W

#### **QUALITY SPECIFICATION**

Quality specification "SNW-FQ-611 part D" is applicable.

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### **CHARACTERISTICS**

 $V_{CC}$  = 4.75 to 5.25 V;  $T_{vj}$  = -40 to +150 °C;  $R_L$  = 60  $\Omega$  unless specified otherwise; all voltages are referenced to GND (pin 2); positive currents flow into the IC; see notes 1 and 2.

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
Supply (pin V	cc)	•	•	•	•	•
I <sub>CC</sub>	supply current	dominant; V <sub>TXD</sub> = 0 V	25	50	75	mA
		recessive; V <sub>TXD</sub> = V <sub>CC</sub>	2.5	5	10	mA
Transmitter d	ata input (pin TXD)		1	1		'
V <sub>IH</sub>	HIGH-level input voltage	output recessive	2.0	_	V <sub>CC</sub> + 0.3	٧
V <sub>IL</sub>	LOW-level input voltage	output dominant	-0.3	_	+0.8	V
I <sub>IH</sub>	HIGH-level input current	$V_{TXD} = V_{CC}$	-5	0	+5	μΑ
I <sub>IL</sub>	LOW-level input current	$V_{TXD} = 0 V$	-100	-200	-300	μΑ
C <sub>i</sub>	input capacitance	not tested	_	5	10	pF
Mode select i	nput (pin S)			-		
V <sub>IH</sub>	HIGH-level input voltage	silent mode	2.0	_	V <sub>CC</sub> + 0.3	V
V <sub>IL</sub>	LOW-level input voltage	high-speed mode	-0.3	_	+0.8	V
I <sub>IH</sub>	HIGH-level input current	V <sub>S</sub> = 2 V	20	30	50	μΑ
I <sub>IL</sub>	LOW-level input current	V <sub>S</sub> = 0.8 V	15	30	45	μΑ
Receiver data	output (pin RXD)		-1	•		'
I <sub>OH</sub>	HIGH-level output current	$V_{RXD} = 0.7V_{CC}$	-2	-6	-15	mA
I <sub>OL</sub>	LOW-level output current	V <sub>RXD</sub> = 0.45 V	2	8.5	20	mA
Reference vol	Itage output (pin V <sub>ref</sub> )		•	'	'	!
V <sub>ref</sub>	reference output voltage	$-50 \mu\text{A} < I_{\text{Vref}} < +50 \mu\text{A}$	0.45V <sub>CC</sub>	0.5V <sub>CC</sub>	0.55V <sub>CC</sub>	V
Bus lines (pin	s CANH and CANL)			•		•
V <sub>o(reces)</sub> (CANH)	recessive bus voltage at pin CANH	$V_{TXD} = V_{CC}$ ; no load	2.0	2.5	3.0	V
V <sub>o(reces)(CANL)</sub>	recessive bus voltage at pin CANL	$V_{TXD} = V_{CC}$ ; no load	2.0	2.5	3.0	V
I <sub>o(reces)(CANH)</sub>	recessive output current at pin CANH	-27 V < V <sub>CANH</sub> < +32 V; 0 V < V <sub>CC</sub> < 5.25 V	-2.0	_	+2.5	mA
I <sub>o(reces)(CANL)</sub>	recessive output current at pin CANL	-27 V < V <sub>CANL</sub> < +32 V; 0 V < V <sub>CC</sub> < 5.25 V	-2.0	_	+2.5	mA
V <sub>o(dom)(CANH)</sub>	dominant output voltage at pin CANH	V <sub>TXD</sub> = 0 V	3.0	3.6	4.25	V
V <sub>o(dom)(CANL)</sub>	dominant output voltage at pin CANL	$V_{TXD} = 0 V$	0.5	1.4	1.75	V
V <sub>i(dif)(bus)</sub>	differential bus input voltage (V <sub>CANH</sub> – V <sub>CANL</sub> )	$V_{TXD} = 0 \text{ V; dominant;}$ $42.5 < R_L < 60 \Omega$	1.5	2.25	3.0	V
		V <sub>TXD</sub> = V <sub>CC</sub> ; recessive; no load	-50	0	+50	mV

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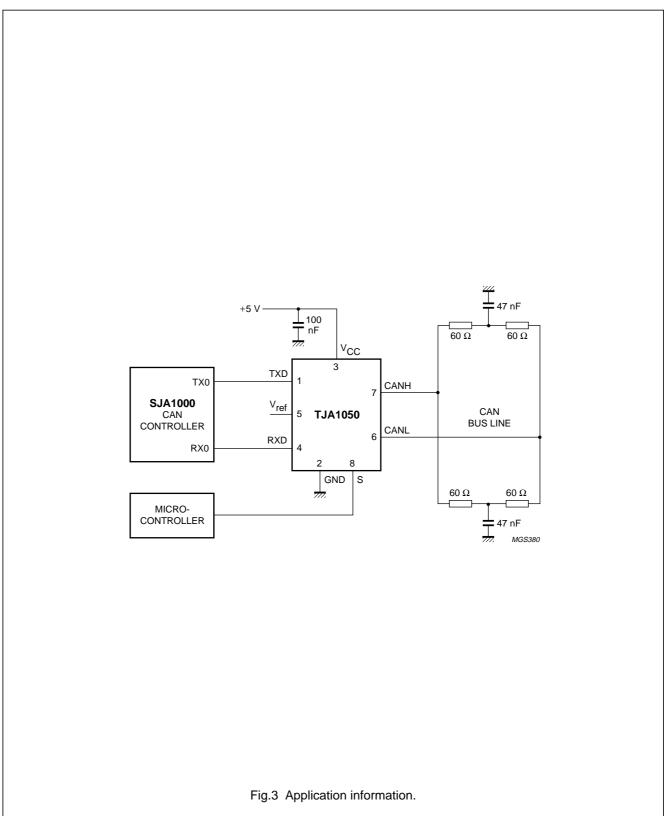
SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
I <sub>o(sc)(CANH)</sub>	short-circuit output current at pin CANH	$V_{CANH} = 0 \text{ V}; V_{TXD} = 0 \text{ V}$	-45	-70	-95	mA
I <sub>o(sc)(CANL)</sub>	short-circuit output current at pin CANL			70	100	mA
$V_{i(dif)(th)}$	differential receiver threshold voltage	-12 V < V <sub>CANL</sub> < +12 V; -12 V < V <sub>CANH</sub> < +12 V; see Fig.5	0.5	0.7	0.9	V
V <sub>i(dif)(hys)</sub>	differential receiver input voltage hysteresis	$-12 \text{ V} < \text{V}_{\text{CANL}} < +12 \text{ V};$ $-12 \text{ V} < \text{V}_{\text{CANH}} < +12 \text{ V};$ see Fig.5	50	70	100	mV
$R_{i(cm)(CANH)} \\$	common mode input resistance at pin CANH		15	25	35	kΩ
R <sub>i(cm)(CANL)</sub>	common mode input resistance at pin CANL		15	25	35	kΩ
R <sub>i(cm)(m)</sub>	matching between pin CANH and pin CANL common mode input resistance	V <sub>CANH</sub> = V <sub>CANL</sub>	-3	0	+3	%
$R_{i(dif)}$	differential input resistance		25	50	75	kΩ
$C_{i(CANH)}$	input capacitance at pin CANH	$V_{TXD} = V_{CC}$ ; not tested	_	7.5	20	pF
$C_{i(CANL)}$	input capacitance at pin CANL	$V_{TXD} = V_{CC}$ ; not tested	_	7.5	20	pF
C <sub>i(dif)</sub>	differential input capacitance	$V_{TXD} = V_{CC}$ ; not tested	_	3.75	10	pF
I <sub>LI(CANH)</sub>	input leakage current at pin CANH	$V_{CC} = 0 \text{ V}; V_{CANH} = 5 \text{ V}$	100	170	250	μΑ
I <sub>LI(CANL)</sub>	input leakage current at pin CANL	$V_{CC} = 0 \text{ V}; V_{CANL} = 5 \text{ V}$	100	170	250	μΑ
Thermal shute	down					
T <sub>j(sd)</sub>	shutdown junction temperature		155	165	180	°C
Timing charac	cteristics (see Figs.6 and 7)	•	•	•	•	•
t <sub>d(TXD-BUSon)</sub>	delay TXD to bus active	V <sub>S</sub> = 0 V	25	55	110	ns
t <sub>d(TXD-BUSoff)</sub>	delay TXD to bus inactive	V <sub>S</sub> = 0 V	25	60	95	ns
t <sub>d(BUSon-RXD)</sub>	delay bus active to RXD	V <sub>S</sub> = 0 V	20	50	110	ns
t <sub>d(BUSoff-RXD)</sub>	delay bus inactive to RXD	V <sub>S</sub> = 0 V	45	95	155	ns
t <sub>dom(TXD)</sub>	TXD dominant time for time-out	$V_{TXD} = 0 V$	250	450	750	μs

### **Notes**

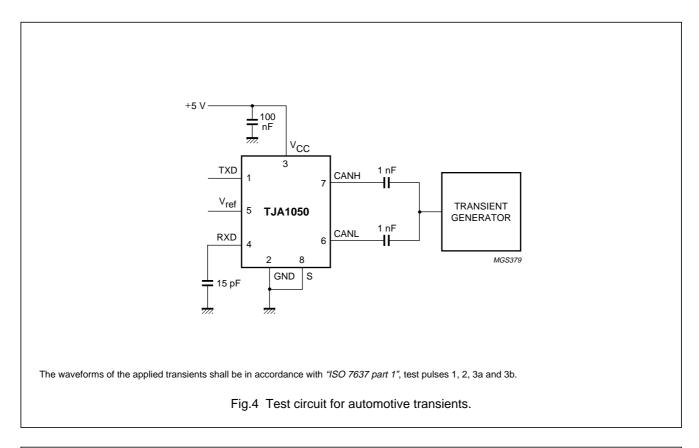
- 1. All parameters are guaranteed over the virtual junction temperature range by design, but only 100% tested at 125 °C ambient temperature for dies on wafer level and in addition to this 100% tested at 25 °C ambient temperature for cased products, unless specified otherwise.
- 2. For bare die, all parameters are only guaranteed if the backside of the bare die is connected to ground.

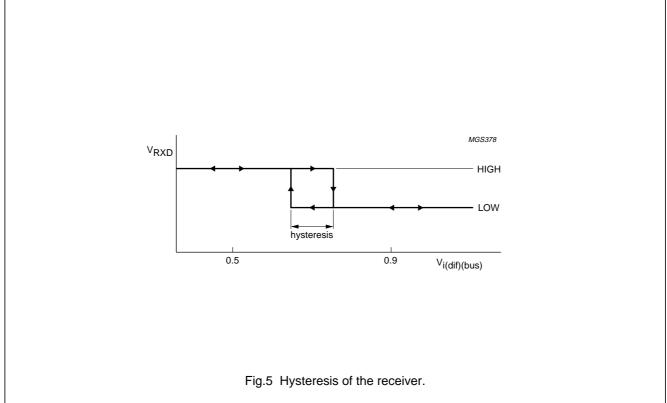
TJA1050

### **APPLICATION AND TEST INFORMATION**

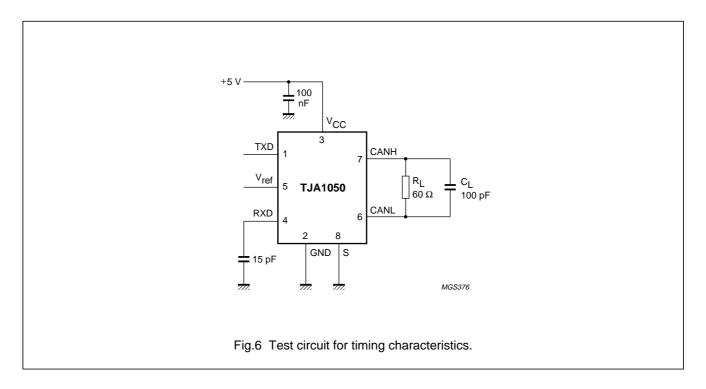


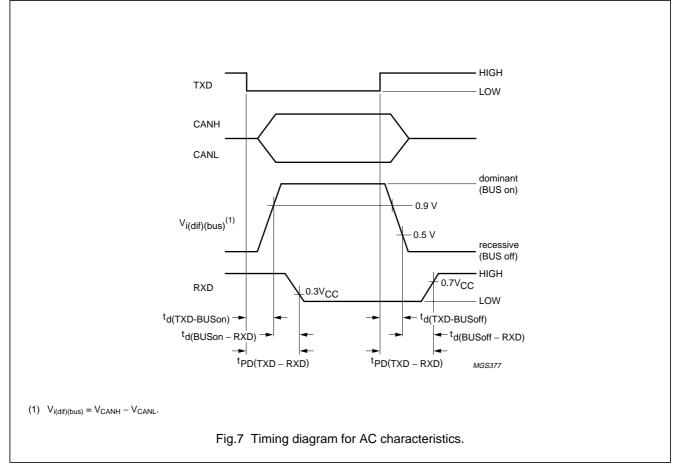
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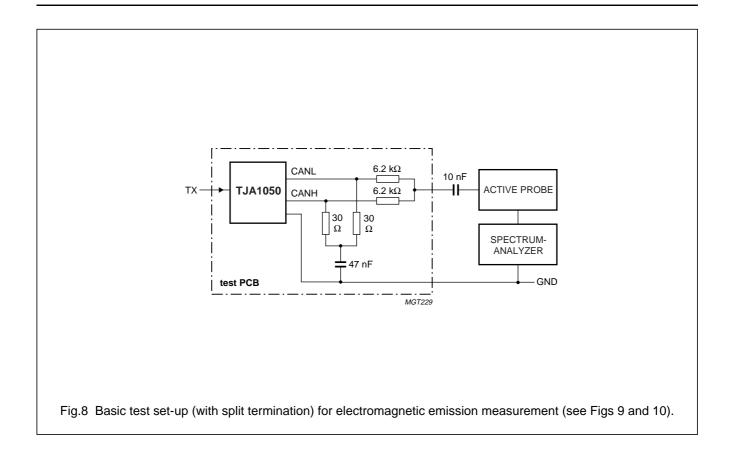


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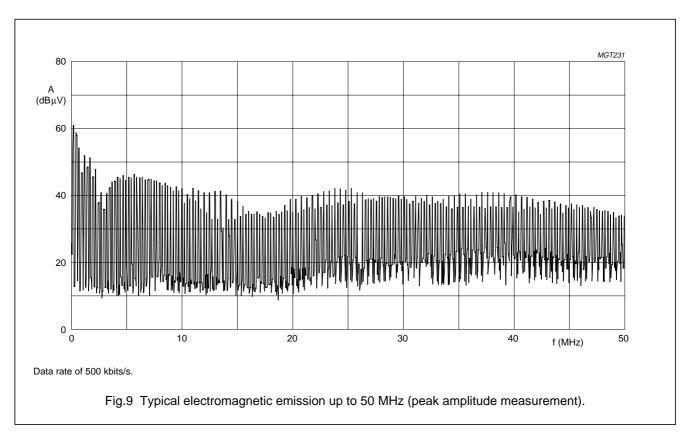


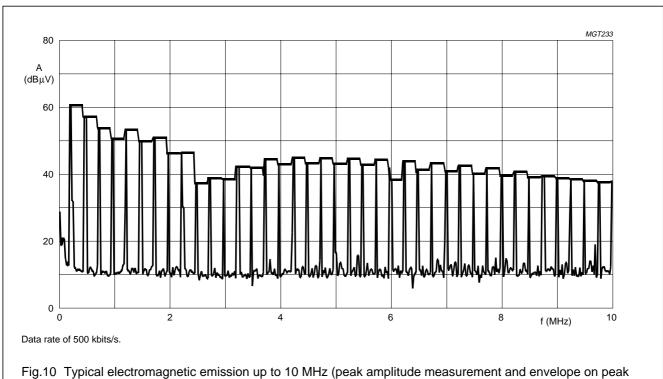


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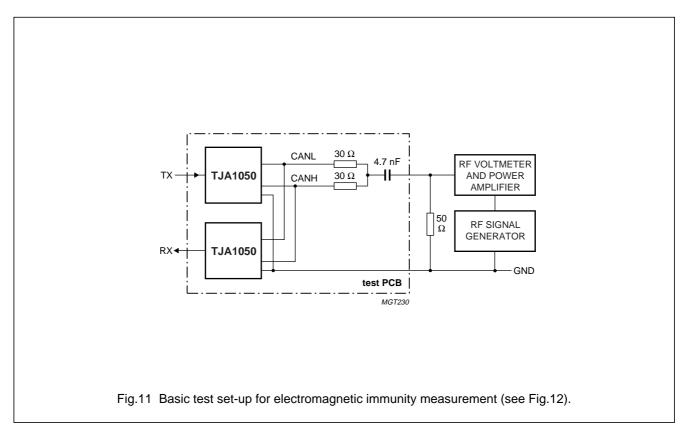


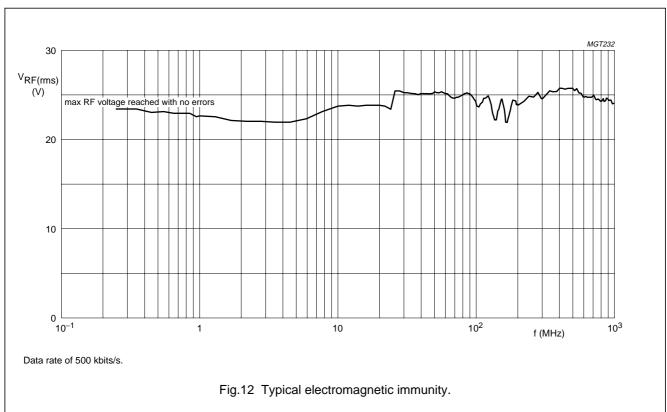


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amplitudes).

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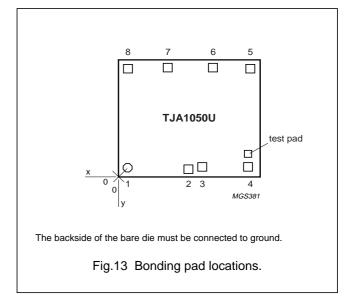
**TJA1050** 

### **BONDING PAD LOCATIONS**

SYMBOL	PAD	COORDI	NATES <sup>(1)</sup>
STIVIBUL	PAD	x	у
TXD	1	103	103
GND	2	740	85
V <sub>CC</sub>	3	886.5	111
RXD	4	1371.5	111
V <sub>ref</sub>	5	1394	1094
CANL	6	998	1115
CANH	7	538.5	1115
S	8	103	1097

#### Note

1. All x/y coordinates represent the position of the centre of each pad (in  $\mu$ m) with respect to x/y = 0 of the die (see Fig.13).

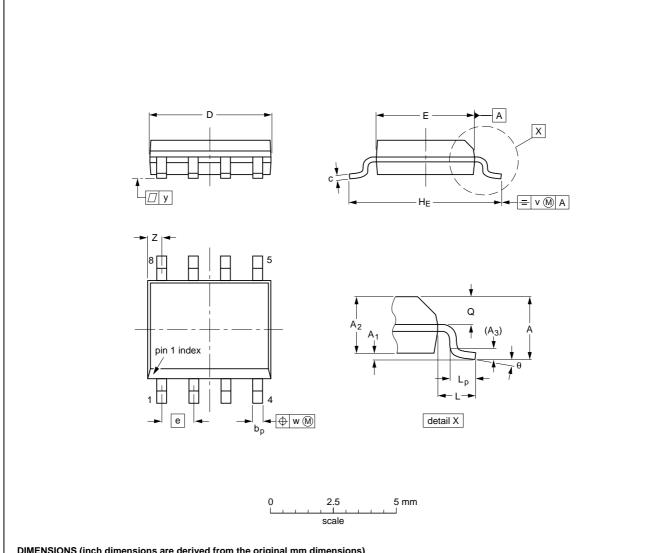


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### **PACKAGE OUTLINE**

SO8: plastic small outline package; 8 leads; body width 3.9 mm

SOT96-1



#### **DIMENSIONS** (inch dimensions are derived from the original mm dimensions)

UNIT	A max.	<b>A</b> <sub>1</sub>	A <sub>2</sub>	A <sub>3</sub>	bp	С	D <sup>(1)</sup>	E <sup>(2)</sup>	е	HE	L	Lp	Q	v	w	у	Z <sup>(1)</sup>	θ
mm	1.75	0.25 0.10	1.45 1.25	0.25	0.49 0.36	0.25 0.19	5.0 4.8	4.0 3.8	1.27	6.2 5.8	1.05	1.0 0.4	0.7 0.6	0.25	0.25	0.1	0.7 0.3	8°
inches	0.069	0.010 0.004	0.057 0.049	0.01		0.0100 0.0075	0.20 0.19	0.16 0.15	0.050	0.244 0.228	0.041	0.039 0.016	0.028 0.024	0.01	0.01	0.004	0.028 0.012	0°

- 1. Plastic or metal protrusions of 0.15 mm maximum per side are not included.
- 2. Plastic or metal protrusions of 0.25 mm maximum per side are not included.

OUTLINE		REFER	ENCES		EUROPEAN	ISSUE DATE	
VERSION	IEC	JEDEC	EIAJ	EIAJ PROJECTION		1990E DATE	
SOT96-1	076E03	MS-012				<del>97-05-22</del> 99-12-27	

Philips Semiconductors Preliminary specification

### High speed CAN transceiver

TJA1050

#### **SOLDERING**

### Introduction to soldering surface mount packages

This text gives a very brief insight to a complex technology. A more in-depth account of soldering ICs can be found in our "Data Handbook IC26; Integrated Circuit Packages" (document order number 9398 652 90011).

There is no soldering method that is ideal for all surface mount IC packages. Wave soldering is not always suitable for surface mount ICs, or for printed-circuit boards with high population densities. In these situations reflow soldering is often used.

### Reflow soldering

Reflow soldering requires solder paste (a suspension of fine solder particles, flux and binding agent) to be applied to the printed-circuit board by screen printing, stencilling or pressure-syringe dispensing before package placement.

Several methods exist for reflowing; for example, infrared/convection heating in a conveyor type oven. Throughput times (preheating, soldering and cooling) vary between 100 and 200 seconds depending on heating method.

Typical reflow peak temperatures range from 215 to 250 °C. The top-surface temperature of the packages should preferable be kept below 230 °C.

### Wave soldering

Conventional single wave soldering is not recommended for surface mount devices (SMDs) or printed-circuit boards with a high component density, as solder bridging and non-wetting can present major problems.

To overcome these problems the double-wave soldering method was specifically developed.

If wave soldering is used the following conditions must be observed for optimal results:

- Use a double-wave soldering method comprising a turbulent wave with high upward pressure followed by a smooth laminar wave.
- For packages with leads on two sides and a pitch (e):
  - larger than or equal to 1.27 mm, the footprint longitudinal axis is **preferred** to be parallel to the transport direction of the printed-circuit board;
  - smaller than 1.27 mm, the footprint longitudinal axis must be parallel to the transport direction of the printed-circuit board.

The footprint must incorporate solder thieves at the downstream end.

 For packages with leads on four sides, the footprint must be placed at a 45° angle to the transport direction of the printed-circuit board. The footprint must incorporate solder thieves downstream and at the side corners.

During placement and before soldering, the package must be fixed with a droplet of adhesive. The adhesive can be applied by screen printing, pin transfer or syringe dispensing. The package can be soldered after the adhesive is cured.

Typical dwell time is 4 seconds at 250 °C. A mildly-activated flux will eliminate the need for removal of corrosive residues in most applications.

### Manual soldering

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Fix the component by first soldering two diagonally-opposite end leads. Use a low voltage (24 V or less) soldering iron applied to the flat part of the lead. Contact time must be limited to 10 seconds at up to  $300\ ^{\circ}$ C.

When using a dedicated tool, all other leads can be soldered in one operation within 2 to 5 seconds between 270 and 320  $^{\circ}$ C.

Philips Semiconductors Preliminary specification

### High speed CAN transceiver

**TJA1050** 

### Suitability of surface mount IC packages for wave and reflow soldering methods

PACKAGE	SOLDERING METHOD					
FACRAGE	WAVE	REFLOW <sup>(1)</sup>				
BGA, SQFP	not suitable	suitable				
HLQFP, HSQFP, HSOP, HTSSOP, SMS	not suitable <sup>(2)</sup>	suitable				
PLCC <sup>(3)</sup> , SO, SOJ	suitable	suitable				
LQFP, QFP, TQFP	not recommended <sup>(3)(4)</sup>	suitable				
SSOP, TSSOP, VSO	not recommended <sup>(5)</sup>	suitable				

#### **Notes**

- 1. All surface mount (SMD) packages are moisture sensitive. Depending upon the moisture content, the maximum temperature (with respect to time) and body size of the package, there is a risk that internal or external package cracks may occur due to vaporization of the moisture in them (the so called popcorn effect). For details, refer to the Drypack information in the "Data Handbook IC26; Integrated Circuit Packages; Section: Packing Methods".
- 2. These packages are not suitable for wave soldering as a solder joint between the printed-circuit board and heatsink (at bottom version) can not be achieved, and as solder may stick to the heatsink (on top version).
- 3. If wave soldering is considered, then the package must be placed at a 45° angle to the solder wave direction. The package footprint must incorporate solder thieves downstream and at the side corners.
- 4. Wave soldering is only suitable for LQFP, TQFP and QFP packages with a pitch (e) equal to or larger than 0.8 mm; it is definitely not suitable for packages with a pitch (e) equal to or smaller than 0.65 mm.
- 5. Wave soldering is only suitable for SSOP and TSSOP packages with a pitch (e) equal to or larger than 0.65 mm; it is definitely not suitable for packages with a pitch (e) equal to or smaller than 0.5 mm.

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#### **DATA SHEET STATUS**

DATA SHEET STATUS	PRODUCT STATUS	DEFINITIONS (1)
Objective specification	Development	This data sheet contains the design target or goal specifications for product development. Specification may change in any manner without notice.
Preliminary specification	Qualification	This data sheet contains preliminary data, and supplementary data will be published at a later date. Philips Semiconductors reserves the right to make changes at any time without notice in order to improve design and supply the best possible product.
Product specification	Production	This data sheet contains final specifications. Philips Semiconductors reserves the right to make changes at any time without notice in order to improve design and supply the best possible product.

#### Note

1. Please consult the most recently issued data sheet before initiating or completing a design.

#### **DEFINITIONS**

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