

Data Sheet June 2003 FN2859.5

# 700ns, Low Distortion, Precision Sample and Hold Amplifier

The HA-5340 combines the advantages of two sample/ hold architectures to create a new generation of monolithic sample/hold. High amplitude, high frequency signals can be sampled with very low distortion being introduced. The combination of exceptionally fast acquisition time and specified/characterized hold mode distortion is an industry first. Additionally, the AC performance is only minimally affected by additional hold capacitance.

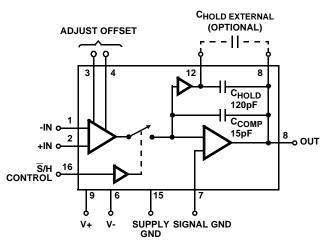
To achieve this level of performance, the benefits of an integrating output stage have been combined with the advantages of a buffered hold capacitor. To the user this translates to a front-end stage that has high bandwidth due to charging only a small capacitive load and an output stage with constant pedestal error which can be nulled out using the offset adjust pins. Since the performance penalty for additional hold capacitance is low, the designer can further minimize pedestal error and droop rate without sacrificing speed.

Low distortion, fast acquisition, and low droop rate are the result, making the HA-5340 the obvious choice for high speed, high accuracy sampling systems.

# **Ordering Information**

PART N	IUMBER	TEMP. RANGE (°C)	PACKAGE	PKG. DWG.#
HA9P534	0-5	0 to 75	16 Ld SOIC	M16.3

## Functional Diagram



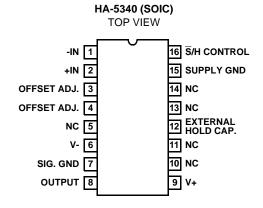
#### **Features**

- · Bandwidth Minimally Affected By External CH
- Fully Differential Analog Inputs
- · Built-In 135pF Hold Capacitor

## **Applications**

- · High Bandwidth Precision Data Acquisition Systems
- Inertial Navigation and Guidance Systems
- Ultrasonics
- SONAR
- RADAR

#### **Pinout**



## **Absolute Maximum Ratings**

Voltage Between V+ and V- Terminals	6V
Differential Input Voltage	4V
Digital Input Voltage +8V, -	6V
Output Current, Continuous±20r	nΑ
Temperature Range	
Temperature Range HA-5340-5	°С

### **Thermal Information**

CAUTION: Stresses above those listed in "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress only rating and operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied.

#### NOTES:

- 1. Maximum power dissipation must be designed to maintain the junction temperature below 150°C for the plastic packages.
- 2.  $\theta_{JA}$  is measured with the component mounted on an evaluation PC board in free air.

PARAMETER	TEST CONDITIONS	TEMP. (°C)	MIN	TYP	MAX	UNITS
INPUT CHARACTERISTICS	-	-	<u>I</u>			
Input Voltage Range		Full	-10	-	+10	V
Input Resistance (Note 3)		25	-	1	-	MΩ
Input Capacitance		25	-	-	3	pF
Input Offset Voltage		25	-	-	1.5	mV
		Full	-	-	3.0	mV
Offset Voltage Temperature Coefficient		Full	-	-	30	μV/ <sup>o</sup> C
Bias Current		25	-	±70	-	nA
		Full	-	-	±350	nA
Offset Current		25	-	±50	-	nA
		Full	-	-	±350	nA
Common Mode Range		Full	-10	-	+10	V
CMRR	±10V, Note 4	25	-	83	-	dB
		Full	72	-	-	dB
TRANSFER CHARACTERISTICS	<u> </u>	'		*		
Gain	DC	25	110	140	-	dB
Gain Bandwidth Product	C <sub>H</sub> External = 0pF	Full	-	10	-	MHz
	C <sub>H</sub> External = 100pF	Full	-	9.6	-	MHz
	C <sub>H</sub> External = 1000pF	Full	-	6.7	-	MHz
TRANSIENT RESPONSE	,	,			1	
Rise Time	200mV Step	25	-	20	30	ns
Overshoot	200mV Step	25	-	35	50	%
Slew Rate	10V Step	25	40	60	-	V/μs
DIGITAL INPUT CHARACTERISTICS		·				
Input Voltage	V <sub>IH</sub>	Full	2.0	-	-	V
	V <sub>IL</sub>	Full	-	-	0.8	V
Input Current	V <sub>IL</sub> = 0V	Full	-	7	40	μА
	V <sub>IH</sub> = 5V	Full	-	4	40	μА

PARAMETER	TEST CONDITIONS	TEMP. (°C)	MIN	TYP	MAX	UNITS
OUTPUT CHARACTERISTICS						
Output Voltage		Full	-10	-	+10	V
Output Current		Full	-10	-	+10	mA
Full Power Bandwidth (Note 5)		Full	0.6	0.9	-	MHz
Output Resistance	Hold Mode	25	-	0.05	0.1	Ω
		Full	-	0.07	0.15	Ω
Total Output Noise	Sample Mode	25	-	325	400	μV <sub>RMS</sub>
DC to 10MHz	Hold Mode	25	-	325	400	μV <sub>RMS</sub>
DISTORTION CHARACTERISTICS						
SAMPLE MODE						
Signal to Noise Ratio (RMS Signal to RMS Noise)	$V_{IN} = 200kHz, 20V_{P-P}$	Full	-	115	-	dB
Total Harmonic Distortion	V <sub>IN</sub> = 200kHz, 5V <sub>P-P</sub>	Full	-90	-100	-	dBc
	V <sub>IN</sub> = 200kHz, 10V <sub>P-P</sub>	Full	-76	-82	-	dBc
	V <sub>IN</sub> = 200kHz, 20V <sub>P-P</sub>	Full	-70	-74	-	dBc
	V <sub>IN</sub> = 500kHz, 5V <sub>P-P</sub>	Full	-66	-75	-	dBc
Intermodulation Distortion	$V_{IN} = 10V_{P-P}, f_1 = 20kHz,$ $f_2 = 21kHz$	Full	-78	-83	-	dBc
HOLD MODE (50% Duty Cycle S/H)						
Signal to Noise Ratio	$V_{IN} = 200kHz, 5V_{P-P}$	25	-	76	-	dB
(RMS Signal to RMS Noise) $f_S = 450kHz$	V <sub>IN</sub> = 200kHz, 10V <sub>P-P</sub>	25	-	76	-	dB
Total Harmonic Distortion						
$f_S = 450kHz$	$V_{IN} = 200kHz, 5V_{P-P}$	25	-	-72	-	dBc
	V <sub>IN</sub> = 200kHz, 10V <sub>P-P</sub>	25	-	-66	-	dBc
	V <sub>IN</sub> = 200kHz, 20V <sub>P-P</sub>	25	-	-56	-	dBc
f <sub>S</sub> = 450kHz	V <sub>IN</sub> = 100kHz, 5V <sub>P-P</sub>	25	-	-84	-	dBc
	V <sub>IN</sub> = 100kHz, 10V <sub>P-P</sub>	25	-	-71	-	dBc
	V <sub>IN</sub> = 100kHz, 20V <sub>P-P</sub>	25	-	-61	-	dBc
$f_S = 2f_{IN}(Nyquist)$	$V_{IN} = 20kHz, 5V_{P-P}$	25	-	-95	-	dBc
	$V_{IN} = 50kHz, 5V_{P-P}$	25	-	-91	-	dBc
	V <sub>IN</sub> = 100kHz, 5V <sub>P-P</sub>	25	-	-82	-	dBc
Intermodulation Distortion						
$f_S = 450 \text{kHz}$	$V_{IN} = 10V_{P-P}$ (f <sub>1</sub> = 20kHz, f <sub>2</sub> = 21kHz)	25	-	-79	-	dBc
SAMPLE AND HOLD CHARACTERISTICS					ı	-11
Acquisition Time	10V Step to 0.01%	25	-	700	-	ns
		Full	-	-	900	ns
	10V Step to 0.1%	25	-	430	600	ns
Droop Rate	C <sub>H</sub> = Internal	25	-	0.1	-	μV/μs
		Full	-	-	95	μV/μs
Hold Step Error	V <sub>IL</sub> = 0V, V <sub>IH</sub> = 4.0V, t <sub>R</sub> = 5ns	25	-	15	-	mV

 $\begin{tabular}{ll} \textbf{Electrical Specifications} & V_{SUPPLY} = \pm 15.0V; \ C_H = Internal = 135 pF; \ Digital Input: \ V_{IL} = +0.8V \ (Sample), \ V_{IH} = +2.0V \ (Hold). \ Non-Inverting Unity Gain Configuration (Output tied to -Input), \ R_L = 2k\Omega, \ C_L = 60 pF, \ Unless Otherwise Specified \ (Configuration Configuration Configur$ 

PARAMETER	TEST CONDITIONS	TEMP. (°C)	MIN	TYP	MAX	UNITS
Hold Mode Settling Time	To ±1mV	Full	-	200	300	ns
Hold Mode Feedthrough	20V <sub>P-P</sub> , 200kHz, Sine	Full	-	-76	-	dB
EADT (Effective Aperture Delay Time)		25	-	-15	-	ns
Aperture Uncertainty		25	-	0.2	-	ns
POWER SUPPLY CHARACTERISTICS						
Positive Supply Current		Full	-	19	25	mA
Negative Supply Current		Full	-	19	25	mA
PSRR	10% Delta	Full	75	82	-	dB

#### NOTES:

- 3. Derived from Computer Simulation only, not tested.
- 4. +CMRR is measured from 0V to +10V, -CMRR is measured from 0V to -10V.
- 5. Based on the calculation FPBW = Slew Rate/ $2\pi V_{PEAK}$  ( $V_{PEAK}$  = 10V).

### Test Circuits and Waveforms

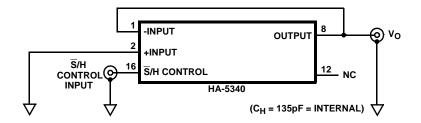
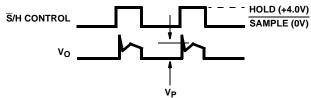
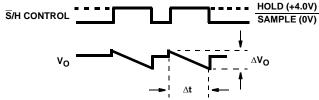


FIGURE 1. HOLD STEP ERROR AND DROOP RATE



#### NOTE:

6. Observe the "hold step" voltage V<sub>P.</sub>



#### NOTES:

- 7. Observe the voltage "droop",  $\Delta V_{O}/\Delta t$ .
- 8. Measure the slope of the output during hold,  $\Delta V_O/\Delta t$ .
- 9. Droop can be positive or negative usually to one rail or the other not to GND.

FIGURE 2. HOLD STEP ERROR

FIGURE 3. DROOP RATE TEST

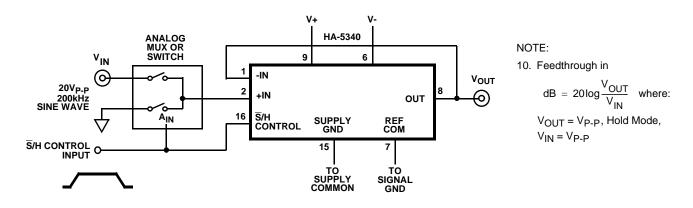


FIGURE 4. HOLD MODE FEEDTHROUGH ATTENUATION

## Application Information

The HA-5340 has the uncommitted differential inputs of an op amp, allowing the Sample and Hold function to be combined with many conventional op amp circuits. See the Intersil Application Note AN517 for a collection of circuit ideas.

#### Layout

A printed circuit board with ground plane is recommended for best performance. Bypass capacitors  $(0.01\mu F$  to  $0.1\mu F$ , ceramic) should be provided from each power supply terminal to the Supply Ground terminal on pin 15.

The ideal ground connections are pin 7 (SIG. GND) directly to the system Signal Ground, and pin 15 (Supply Ground) directly to the system Supply Common.

#### **Hold Capacitor**

The HA-5340 includes a 135pF MOS hold capacitor, sufficient for most high speed applications (the Electrical Specifications section is based on this internal capacitor). Additional capacitance may be added between pins 8 and 12. This external hold capacitance will reduce droop rate at the expense of acquisition time, and provide other trade-offs as shown in the Performance Curves.

The hold capacitor  $C_H$  should have high insulation resistance and low dielectric absorption, to minimize droop

errors. Teflon®, polystyrene and polypropylene dielectric capacitor types offer good performance over the specified operating temperature range.

The hold capacitor terminal (pin 12) remains at virtual ground potential. Any PC connection to this terminal should be kept short and "guarded" by the ground plane, since nearby signal lines or power supply voltages will introduce errors due to drift current.

## Typical Application

Figure 5 shows the HA-5340 connected as a unity gain noninverting amplifier - its most widely used configuration. As an input device for a fast successive - approximation A/D converter, it offers very high throughput rate for a monolithic IC sample/hold amplifier. Also, the HA-5340's hold step error is adjustable to zero using the Offset Adjust potentiometer, to deliver a 12-bit accurate output from the converter.

The HA-5340 output circuit does not include short circuit protection, and consequently its output impedance remains low at high frequencies. Thus, the step changes in load current which occur during an A/D conversion are absorbed at the S/H output with minimum voltage error. A momentary short circuit to ground is permissible, but the output is not designed to tolerate a short of indefinite duration.

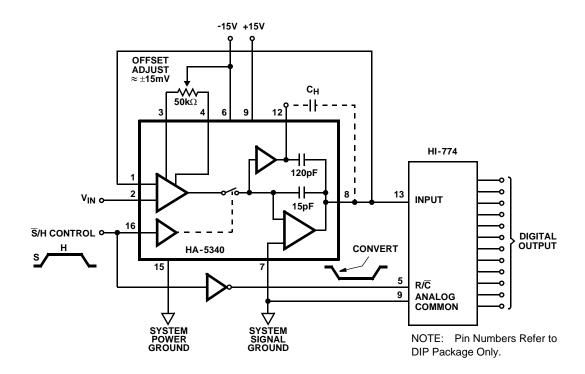


FIGURE 5. TYPICAL HA-5340 CONNECTIONS; NONINVERTING UNITY GAIN MODE

# **Typical Performance Curves** $T_A = 25^{\circ}C$ , $V_S = \pm 15V$ , Unless Otherwise Specified

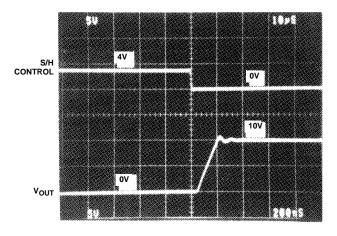


FIGURE 6. TACQ POS 0 TO +10 STEP

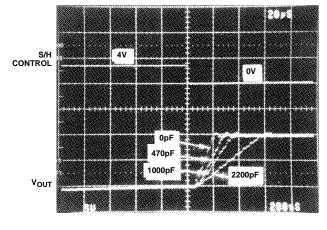


FIGURE 7. TACQ vs ADDITIONAL CH

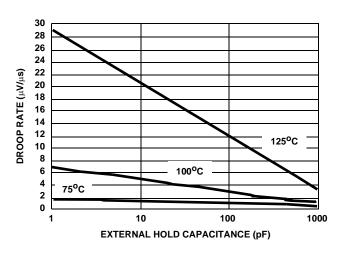


FIGURE 8. DROOP RATE vs HOLD CAPACITANCE

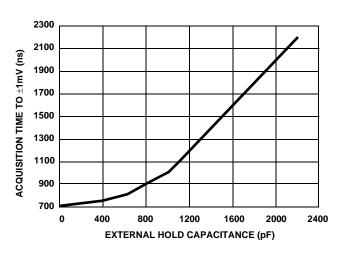


FIGURE 9. ACQUISITION TIME (0.01%) vs HOLD CAPACITANCE

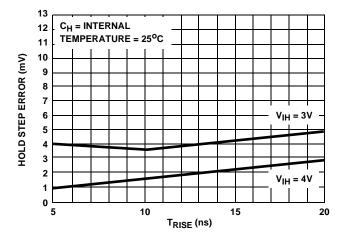


FIGURE 10. HOLD STEP ERROR vs TRISE

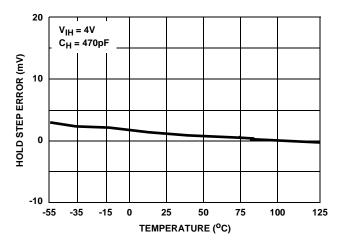


FIGURE 11. HOLD STEP ERROR vs TEMPERATURE

# **Typical Performance Curves** $T_A = 25^{\circ}C$ , $V_S = \pm 15V$ , Unless Otherwise Specified (Continued)

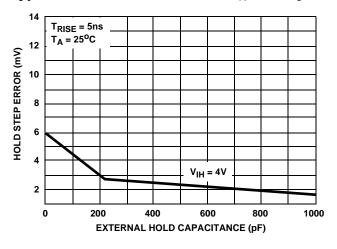


FIGURE 12. HOLD STEP ERROR vs HOLD CAPACITANCE

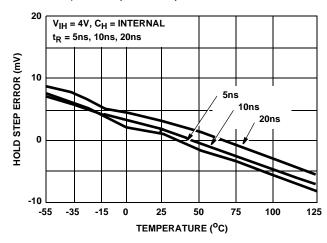
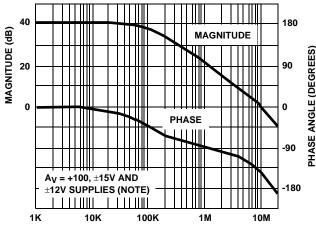


FIGURE 13. HOLD STEP ERROR vs TEMPERATURE



NOTE:  $\pm 15$ V and  $\pm 12$ V supplies trace the same line within the width of the line, therefore only one line is shown.

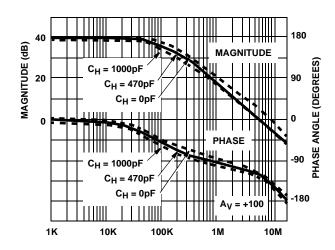


FIGURE 15. CLOSED LOOP PHASE/GAIN



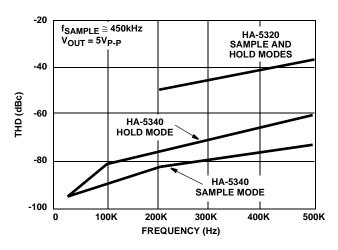


FIGURE 16. THD vs FREQUENCY

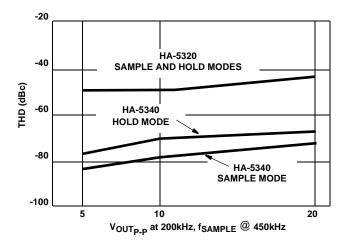


FIGURE 17. THD vs VOUT

## Die Characteristics

#### **DIE DIMENSIONS:**

84mils x 139mils x 19mils

#### **METALLIZATION:**

Type: Al, 1% Cu Thickness:  $16k\mathring{A} \pm 2k\mathring{A}$ 

#### **PASSIVATION:**

Type: Nitride  $(Si_3N_4)$  over Silox  $(SiO_2, 5\% Phos)$ 

Silox Thickness:  $12k\mathring{A} \pm 2.0k\mathring{A}$ Nitride Thickness:  $3.5k\mathring{A} \pm 1.5k\mathring{A}$ 

## SUBSTRATE POTENTIAL (POWERED UP):

V-

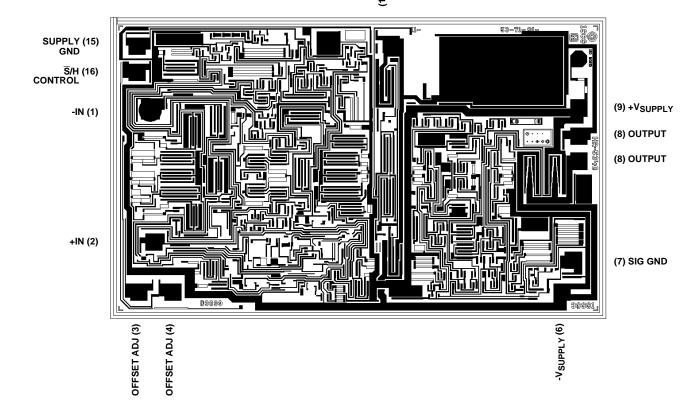
#### TRANSISTOR COUNT:

196

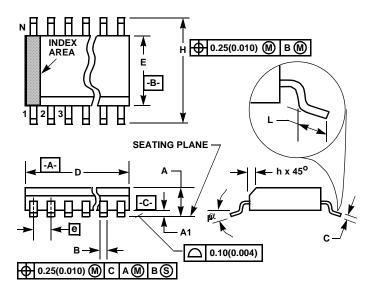
## Metallization Mask Layout

HA-5340

2) EXTERNAL



## Small Outline Plastic Packages (SOIC)



#### NOTES:

- Symbols are defined in the "MO Series Symbol List" in Section 2.2 of Publication Number 95.
- 2. Dimensioning and tolerancing per ANSI Y14.5M-1982.
- Dimension "D" does not include mold flash, protrusions or gate burrs.
   Mold flash, protrusion and gate burrs shall not exceed 0.15mm (0.006 inch) per side.
- Dimension "E" does not include interlead flash or protrusions. Interlead flash and protrusions shall not exceed 0.25mm (0.010 inch) per side.
- 5. The chamfer on the body is optional. If it is not present, a visual index feature must be located within the crosshatched area.
- 6. "L" is the length of terminal for soldering to a substrate.
- 7. "N" is the number of terminal positions.
- 8. Terminal numbers are shown for reference only.
- The lead width "B", as measured 0.36mm (0.014 inch) or greater above the seating plane, shall not exceed a maximum value of 0.61mm (0.024 inch)
- Controlling dimension: MILLIMETER. Converted inch dimensions are not necessarily exact.

M16.3 (JEDEC MS-013-AA ISSUE C)
16 LEAD WIDE BODY SMALL OUTLINE PLASTIC PACKAGE

	INCHES		MILLIN		
SYMBOL	MIN	MAX	MIN	MAX	NOTES
Α	0.0926	0.1043	2.35	2.65	-
A1	0.0040	0.0118	0.10	0.30	-
В	0.013	0.0200	0.33	0.51	9
С	0.0091	0.0125	0.23	0.32	-
D	0.3977	0.4133	10.10	10.50	3
Е	0.2914	0.2992	7.40	7.60	4
е	0.050	BSC	1.27 BSC		-
Н	0.394	0.419	10.00	10.65	-
h	0.010	0.029	0.25	0.75	5
L	0.016	0.050	0.40	1.27	6
N	1	6	16		7
α	0°	8 <sup>0</sup>	0°	8°	-

Rev. 0 12/93

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