# **ELPIDA**

#### **DATA SHEET**

# **Direct Rambus DRAM SO-RIMM<sup>TM</sup> Module**

# MC-4R64FKE8S (32M words × 18 bits)

#### Description

The Direct Rambus SO-RIMM module is a generalpurpose high-performance memory module subsystem suitable for use in a broad range of applications including computer memory, mobile personal computers, networking systems, and other applications where high bandwidth and low latency are required.

MC-4R64FKE8S modules consists of two 288M Direct Rambus DRAM (Direct RDRAM) devices ( $\mu$ PD488588). These are extremely high-speed CMOS DRAMs organized as 16M words by 18 bits. The use of Rambus Signaling Level (RSL) technology permits 800MHz transfer rates while using conventional system and board design technologies.

Direct RDRAM devices are capable of sustained data transfers at 1.25ns per two bytes (10ns per 16 bytes).

The architecture of the Direct RDRAM enables the highest sustained bandwidth for multiple, simultaneous, randomly addressed memory transactions. The separate control and data buses with independent row and column control yield high bus efficiency. The Direct RDRAM's multi-bank architecture supports up to four simultaneous transactions per device.

#### **Features**

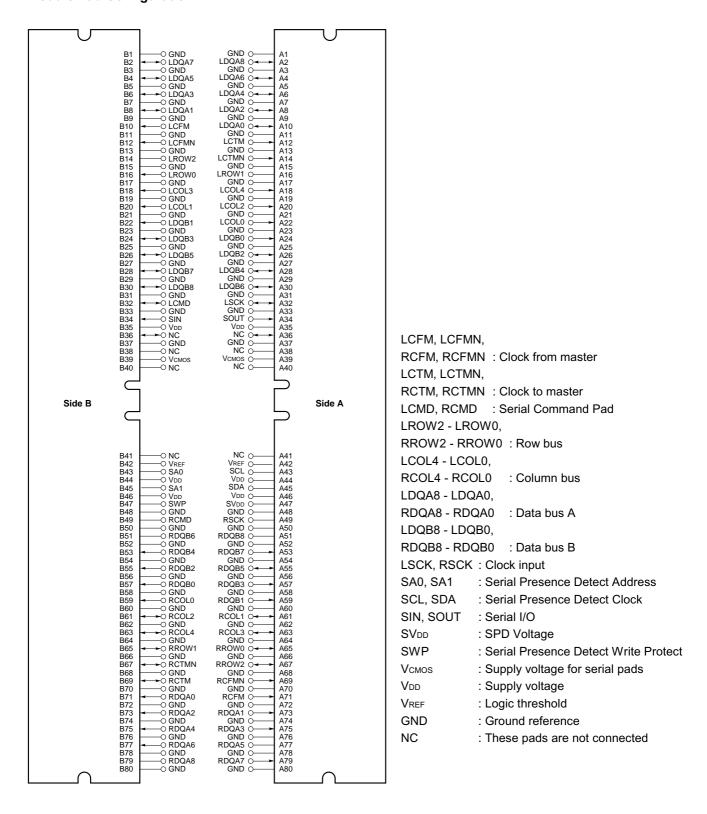
- 160 edge connector pads with 0.65mm pad spacing
- 64MB Direct RDRAM storage
- Each RDRAM® has 32 banks, for 64 banks total on module
- · Gold plated contacts
- RDRAMs use Chip Scale Package (CSP)
- Serial Presence Detect support
- Operates from a 2.5V supply
- Powerdown self refresh modes
- Separate Row and Column buses for higher efficiency

## **Order information**

Part number	Organization	I/O Freq. MHz	RAS access time ns	Package	Mounted devices
MC-4R64FKE8S - 845	32M x 18	800	45	160 edge connector pads SO-RIMM with heat spreader Edge connector: Gold plated	2 pieces of μPD488588FF FBGA (μBGA®) package

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#### **Module Pad Configuration**



## **Module Pad Names**

Pad	Signal Name	Pad	Signal Name
A1	GND	B1	GND
A2	LDQA8	B2	LDQA7
A3	GND	В3	GND
A4	LDQA6	B4	LDQA5
A5	GND	B5	GND
A6	LDQA4	В6	LDQA3
A7	GND	B7	GND
A8	LDQA2	В8	LDQA1
A9	GND	В9	GND
A10	LDQA0	B10	LCFM
A11	GND	B11	GND
A12	LCTM	B12	LCFMN
A13	GND	B13	GND
A14	LCTMN	B14	LROW2
A15	GND	B15	GND
A16	LROW1	B16	LROW0
A17	GND	B17	GND
A18	LCOL4	B18	LCOL3
A19	GND	B19	GND
A20	LCOL2	B20	LCOL1
A21	GND	B21	GND
A22	LCOL0	B22	LDQB1
A23	GND	B23	GND
A24	LDQB0	B24	LDQB3
A25	GND	B25	GND
A26	LDQB2	B26	LDQB5
A27	GND	B27	GND
A28	LDQB4	B28	LDQB7
A29	GND	B29	GND
A30	LDQB6	B30	LDQB8
A31	GND	B31	GND
A32	LSCK	B32	LCMD
A33	GND	B33	GND
A34	SOUT	B34	SIN
A35	V <sub>DD</sub>	B35	V <sub>DD</sub>
A36	NC	B36	NC
A37	GND	B37	GND
A38	NC	B38	NC
A39	Vcmos	B39	Vcmos
A40	NC	B40	NC

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Pad	Signal Name	Pad	Signal Name
A41	NC	B41	NC
A42	VREF	B42	VREF
A43	SCL	B43	SA0
A44	V <sub>DD</sub>	B44	V <sub>DD</sub>
A45	SDA	B45	SA1
A46	V <sub>DD</sub>	B46	V <sub>DD</sub>
A47	SVDD	B47	SWP
A48	GND	B48	GND
A49	RSCK	B49	RCMD
A50	GND	B50	GND
A51	RDQB8	B51	RDQB6
A52	GND	B52	GND
A53	RDQB7	B53	RDQB4
A54	GND	B54	GND
A55	RDQB5	B55	RDQB2
A56	GND	B56	GND
A57	RDQB3	B57	RDQB0
A58	GND	B58	GND
A59	RDQB1	B59	RCOL0
A60	GND	B60	GND
A61	RCOL1	B61	RCOL2
A62	GND	B62	GND
A63	RCOL3	B63	RCOL4
A64	GND	B64	GND
A65	RROW0	B65	RROW1
A66	GND	B66	GND
A67	RROW2	B67	RCTMN
A68	GND	B68	GND
A69	RCFMN	B69	RCTM
A70	GND	B70	GND
A71	RCFM	B71	RDQA0
A72	GND	B72	GND
A73	RDQA1	B73	RDQA2
A74	GND	B74	GND
A75	RDQA3	B75	RDQA4
A76	GND	B76	GND
A77	RDQA5	B77	RDQA6
A78	GND	B78	GND
A79	RDQA7	B79	RDQA8
A80	GND	B80	GND
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# **Module Connector Pad Description**

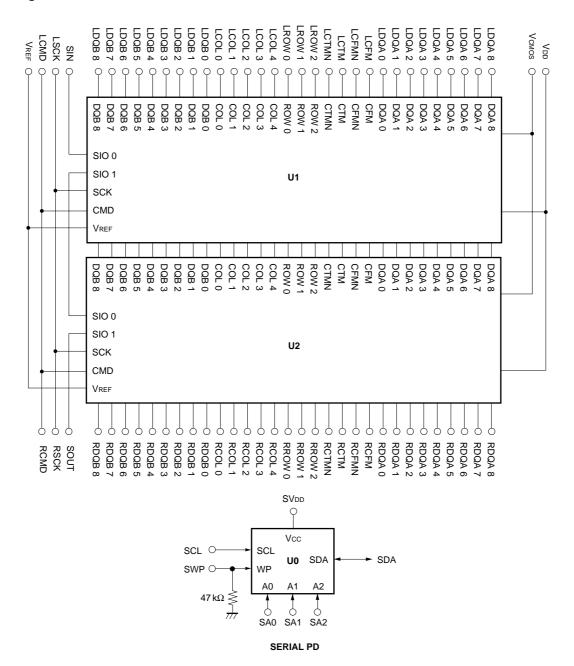
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Signal	I/O	Type	Description
GND	_	_	Ground reference for RDRAM core and interface.
LCFM	I	RSL	Clock from master. Interface clock used for receiving RSL signals from the Channel. Positive polarity.
LCFMN	-	RSL	Clock from master. Interface clock used for receiving RSL signals from the Channel. Negative polarity.
LCMD	Ι	Vcmos	Serial Command used to read from and write to the control registers. Also used for power management.
LCOL4LCOL0	_	RSL	Column bus. 5-bit bus containing control and address information for column accesses.
LCTM	_	RSL	Clock to master. Interface clock used for transmitting RSL signals to the Channel. Positive polarity.
LCTMN	_	RSL	Clock to master. Interface clock used for transmitting RSL signals to the Channel. Negative polarity.
LDQA8LDQA0	I/O	RSL	Data bus A. A 9-bit bus carrying a byte of read or write data between the Channel and the RDRAM. LDQA8 is non-functional on modules with x16 RDRAM devices.
LDQB8LDQB0	I/O	RSL	Data bus B. A 9-bit bus carrying a byte of read or write data between the Channel and the RDRAM. LDQB8 is non-functional on modules with x16 RDRAM devices.
LROW2LROW0	I	RSL	Row bus. 3-bit bus containing control and address information for row accesses.
LSCK	I	Vcmos	Serial clock input. Clock source used to read from and write to the RDRAM control registers.
NC	-	_	These pads are not connected. These 8 connector pads are reserved for future use.
RCFM	1	RSL	Clock from master. Interface clock used for receiving RSL signals from the Channel. Positive polarity.
RCFMN	I	RSL	Clock from master. Interface clock used for receiving RSL signals from the Channel. Negative polarity.
RCMD	I	Vcmos	Serial Command Input used to read from and write to the control registers. Also used for power management.
RCOL4RCOL0	I	RSL	Column bus. 5-bit bus containing control and address information for column accesses.
RCTM	I	RSL	Clock to master. Interface clock used for transmitting RSL signals to the Channel. Positive polarity.
RCTMN	I	RSL	Clock to master. Interface clock used for transmitting RSL signals to the Channel. Negative polarity.
RDQA8RDQA0	I/O	RSL	Data bus A. A 9-bit bus carrying a byte of read or write data between the Channel and the RDRAM. RDQA8 is non-functional on modules with x16 RDRAM devices.
RDQB8RDQB0	I/O	RSL	Data bus B. A 9-bit bus carrying a byte of read or write data between the Channel and the RDRAM. RDQB8 is non-functional on modules with x16 RDRAM devices.
RROW2RROW0	I	RSL	Row bus. 3-bit bus containing control and address information for row accesses.

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Signal	I/O	Туре	Description
RSCK	I	Vcmos	Serial clock input. Clock source used to read from and write to the RDRAM control registers.
SA0	I	SVDD	Serial Presence Detect Address 0.
SA1	I	SVDD	Serial Presence Detect Address 1.
SCL	I	SVDD	Serial Presence Detect Clock.
SDA	I/O	SVDD	Serial Presence Detect Data (Open Collector I/O).
SIN	I/O	Vcmos	Serial I/O for reading from and writing to the control registers. Attaches to SIO0 of the first RDRAM on the module.
SOUT	I/O	Vcmos	Serial I/O for reading from and writing to the control registers. Attaches to SIO1 of the last RDRAM on the module.
SVDD	_	_	SPD Voltage. Used for signals SCL, SDA, SWP, SA0, SA1 and SA2.
SWP	I	SVDD	Serial Presence Detect Write Protect (active high). When low, the SPD can be written as well as read.
Vcmos	_	_	CMOS I/O Voltage. Used for signals CMD, SCK, SIN, SOUT.
V <sub>DD</sub>	_	_	Supply voltage for the RDRAM core and interface logic.
VREF	_	_	Logic threshold reference voltage for RSL signals.

#### **Block Diagram**



Remarks 1. Rambus Channel signals form a loop through the SO-RIMM module, with the exception of the SIO chain.

2. See Serial Presence Detection Specification for information on the SPD device and its contents.

#### **Electrical Specification**

#### **Absolute Maximum Ratings**

Symbol	Parameter	MIN.	MAX.	Unit
VI,ABS	Voltage applied to any RSL or CMOS signal pad with respect to GND	-0.3	V <sub>DD</sub> + 0.3	V
V <sub>DD,ABS</sub>	Voltage on VDD with respect to GND	-0.5	VDD + 1.0	V
TSTORE	Storage temperature	-50	+100	°C

Caution Exposing the device to stress above those listed in Absolute Maximum Ratings could cause permanent damage. The device is not meant to be operated under conditions outside the limits described in the operational section of this specification. Exposure to Absolute Maximum Rating conditions for extended periods may affect device reliability.

#### **DC Recommended Electrical Conditions**

Symbol	Parameter and conditions	MIN.	MAX.	Unit	
Vdd	Supply voltage		2.50 – 0.13	2.50 + 0.13	V
Vcmos	CMOS I/O power supply at pad	2.5V controllers	V <sub>DD</sub>	V <sub>DD</sub>	V
		1.8V controllers	1.8 – 0.1	1.8 + 0.2	
VREF	Reference voltage		1.4 – 0.2	1.4 + 0.2	V
VSPD	Serial presence detector-positive power supply		2.2	3.6	V
VIL	RSL input low voltage	RSL input low voltage			V
ViH	RSL input high voltage	V <sub>REF</sub> + 0.2	V <sub>REF</sub> + 0.5	V	
VIL,CMOS	CMOS input low voltage	-0.3	0.5 V смо  - 0.25	V	
VIH,CMOS	CMOS input high voltage		0.5Vсмоs+0.25	Vсмоs + 0.3	V
Vol,cmos	CMOS output low voltage, IoL,CMOS = 1 mA		_	0.3	V
Voн,смоs	CMOS output high voltage, Iон,смоs = -0.25 mA	Vсмоs – 0.3	_	V	
IREF	Vref current, Vref,max	-20.0	+20.0	μΑ	
ISCK,CMD	CMOS input leakage current, (0 ≤ VcMos ≤ Vdd)	-20.0	+20.0	μΑ	
Isin,sout	CMOS input leakage current, (0 ≤ VcMos ≤ Vdd)	-10.0	+10.0	μΑ	

#### **AC Electrical Specifications**

Symbol	Parameter and Conditions			TYP.	MAX.	Unit
Z	Module Impedance of RSL signals		25.2	28.0	30.8	Ω
	Module Impedance of SCK and CMD signals		23.8	28.0	32.2	
T <sub>PD</sub>	Average clock delay from finger to finger of all RSL clock nets				1.06	ns
	(CTM, CTMN,CFM, and CFMN)					
$\DeltaT_PD$	Propagation delay variation of RSL signals with respect to TPD Note1,2				+21	ps
$\DeltaT$ PD-CMOS	Propagation delay variation of SCK signal with respect to an average clock delay Note1				+250	ps
$\DeltaT$ PD- SCK,CMD	Propagation delay variation of CMD signal with respect to SCK signal		-200		+200	ps
Vα/VIN	Attenuation Limit	-845			12.0	%
Vxf/Vin	Forward crosstalk coefficient	-845			2.0	%
Vxb/Vin	Backward crosstalk coefficient	-845			1.5	%
R <sub>DC</sub>	DC Resistance Limit	-845			0.9	Ω

- **Notes 1.** TPD or Average clock delay is defined as the average delay from finger to finger of all RSL clock nets (CTM, CTMN, CFM, and CFMN).
  - 2. If the SO-RIMM module meets the following specification, then it is compliant to the specification. If the SO-RIMM module does not meet these specifications, then the specification can be adjusted by the "Adjusted ΔTPD Specification" table.

#### Adjusted ATPD Specification

Symbol	Parameter and conditions	Adjusted MIN./MAX.	Abso	lute	Unit
			MIN.	MAX.	
$\DeltaT_PD$	Propagation delay variation of RSL signals with respect to TPD	$+/-[17+(18*N*\Delta Z0)]^{Note}$	-30	+30	ps

**Note** N = Number of RDRAM devices installed on the SO-RIMM module.

 $\Delta$ Z0 = delta Z0% = (MAX. Z0 – MIN. Z0) / (MIN. Z0)

(MAX. Z0 and MIN. Z0 are obtained from the loaded (high impedance) impedance coupons of all RSL layers on the module.)

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#### **SO-RIMM Module Current Profile**

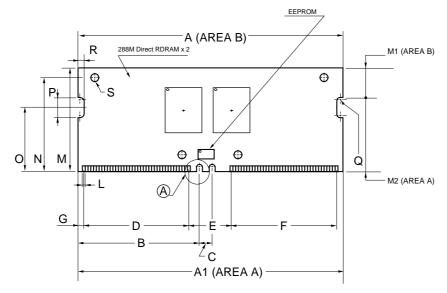
loo	RIMM module power conditions Note1	RIMM module power conditions Note1		Unit
I <sub>DD1</sub>	One RDRAM in Read Note2, balance in NAP mode	-845	704.2	mA
I <sub>DD2</sub>	One RDRAM in Read Note2, balance in Standby mode	-845	790	mA
IDD3	One RDRAM in Read Note2, balance in Active mode	-845	835	mA
I <sub>DD4</sub>	One RDRAM in Write, balance in NAP mode	-845	724.2	mA
I <sub>DD5</sub>	One RDRAM in Write, balance in Standby mode	-845	810	mA
I <sub>DD6</sub>	One RDRAM in Write, balance in Active mode	-845	855	mA

**Notes 1.** Actual power will depend on individual RDRAM component specifications, memory controller and usage patterns. Power does not include Refresh Current.

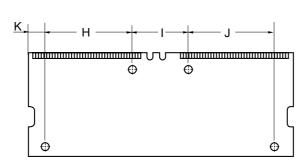
2. I/O current is a function of the % of 1's, to add I/O power for 50 % 1's for a x16 need to add 257 mA or 290 mA for x18 ECC module for the following:  $V_{DD} = 2.5 \text{ V}$ ,  $V_{TERM} = 1.8 \text{ V}$ ,  $V_{REF} = 1.4 \text{ V}$  and  $V_{DIL} = V_{REF} - 0.5 \text{ V}$ .

## **Package Drawings**

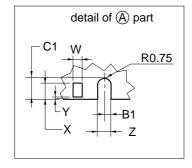
# 160 EDGE CONNECTOR PADS RIMM (SOCKET TYPE) (1/2)







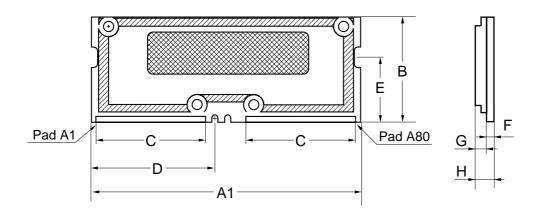
ITEM	MILLIMETERS
Α	67.60 TYP.
A1	$67.60 \pm 0.15$
В	30.00
B1	$0.75 \pm 0.10$
С	4.00
C1	$4.00 \pm 0.10$
D	25.35
F	13.60



07.00 111.
$67.60 \pm 0.15$
30.00
0.75 ± 0.10
4.00
4.00 ± 0.10
25.35
13.60
25.35
1.65
21.00
17.00
21.00
4.30
0.65 TYP.
$31.25 \pm 0.15$
8.75
22.50
29.25
20.00
$5.00 \pm 0.10$
R1.00
1.00 ± 0.10
φ2.00
1.0 ± 0.10
$0.43 \pm 0.03$
2.55 MIN.
0.25 MAX.
1.50 ± 0.10

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# 160 EDGE CONNECTOR PADS RIMM (SOCKET TYPE) (2/2)



ITEM	DESCRIPTION	MIN.	TYP.	MAX.	UNIT
A1	PCB length	67.45	67.60	67.75	mm
В	PCB height	31.10	31.25	31.40	mm
С	Center-center pad width from pad A1 to A40,	-	25.35	-	mm
	A41 to A80, B1 to B40 or B41 to B80				
D	Spacing from PCB left edge to connector key notch	-	30.00	-	mm
Е	Spacing from contact pad PCB edge	-	20.00	-	mm
	to side edge retainer notch				
F	PCB thickness	0.90	1.00	1.10	mm
G	Heat spreader thickness from PCB surface (one side) to	-	1.35	-	mm
	heat spreader top surface				
Н	RIMM thickness	-	2.35	-	mm

ECA-TS2-0060-02

#### **CAUTION FOR HANDLING MEMORY MODULES**

When handling or inserting memory modules, be sure not to touch any components on the modules, such as the memory ICs, chip capacitors and chip resistors. It is necessary to avoid undue mechanical stress on these components to prevent damaging them.

In particular, do not push module cover or drop the modules in order to protect from mechanical defects, which would be electrical defects.

When re-packing memory modules, be sure the modules are not touching each other.

Modules in contact with other modules may cause excessive mechanical stress, which may damage the modules.

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#### **NOTES FOR CMOS DEVICES -**

#### 1) PRECAUTION AGAINST ESD FOR MOS DEVICES

Exposing the MOS devices to a strong electric field can cause destruction of the gate oxide and ultimately degrade the MOS devices operation. Steps must be taken to stop generation of static electricity as much as possible, and quickly dissipate it, when once it has occurred. Environmental control must be adequate. When it is dry, humidifier should be used. It is recommended to avoid using insulators that easily build static electricity. MOS devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work bench and floor should be grounded. The operator should be grounded using wrist strap. MOS devices must not be touched with bare hands. Similar precautions need to be taken for PW boards with semiconductor MOS devices on it.

#### (2) HANDLING OF UNUSED INPUT PINS FOR CMOS DEVICES

No connection for CMOS devices input pins can be a cause of malfunction. If no connection is provided to the input pins, it is possible that an internal input level may be generated due to noise, etc., hence causing malfunction. CMOS devices behave differently than Bipolar or NMOS devices. Input levels of CMOS devices must be fixed high or low by using a pull-up or pull-down circuitry. Each unused pin should be connected to VDD or GND with a resistor, if it is considered to have a possibility of being an output pin. The unused pins must be handled in accordance with the related specifications.

#### (3) STATUS BEFORE INITIALIZATION OF MOS DEVICES

Power-on does not necessarily define initial status of MOS devices. Production process of MOS does not define the initial operation status of the device. Immediately after the power source is turned ON, the MOS devices with reset function have not yet been initialized. Hence, power-on does not guarantee output pin levels, I/O settings or contents of registers. MOS devices are not initialized until the reset signal is received. Reset operation must be executed immediately after power-on for MOS devices having reset function.

CME0107

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