EC-motor with planetary gear unit for automatic spindle positioning cycles

BG650



Features

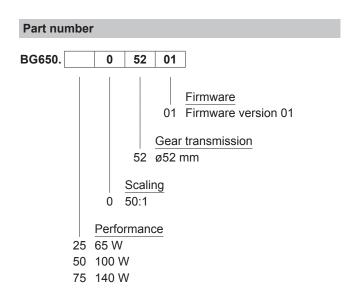
- Brushless DC-motor
- With integrated rotation speed electronics
- Nominal power 65 W, 100 W or 140 W
- Direct connection to spindle position display

BG650

Technical data - electrical ratings					
Voltage supply	24 (2030) VDC				
Ripple residue	<5 %				
Nominal current	4 A, 5.6 A, 7.8 A				
Nominal rating	65 W, 100 W, 140 W				
Undervoltage interruption	≤19 V				
External backup	8 AT (required)				
Excess temperature protection	110 °C at final power output circuit				
Peak current	≤27 A				
Control signals	Rotation speed 1 Rotation speed 2 Counterclockwise Clockwise Enable				
Outputs	Motor malfunction (Error)				
Inputs	Enable Start counterclockwise Start clockwise Clamp				

Technical data - mechanical design					
Operating temperature	-10+50 °C				
Protection DIN EN 60529	IP 54				
E-connection	 Round connector 8-pin, motor supply Round connector 12-pin, between motor - SPA DIN45326, Binder series 723 				
Permanent torque	≤8 Nm (with 65 W) ≤12 Nm (with 100 W) ≤16 Nm (with 140 W)				
Starting torque	≤40 Nm (with 65 W) ≤60 Nm (with 100 W) ≤130 Nm (with 140 W)				
Operating speed	≤72 rpm (highspeed) ≤4 rpm (slowspeed)				
Scaling ratio	50:1				
Number of stages	2				
Degree of efficiency	0.81				
Admitted shaft load	≤500 N axial ≤350 N radial				
Dimensions W x H x L	See dimensional drawing				
Weight approx.	1670 g, 2020 g, 2520 g				
Material	Aluminium profile, anodized in black				

BG650



Accessories						
Connectors and cables (page %S)						
Z 165.M01	Motor supply cable 1.5 m, 8-pin mating conntector					
Z 165.M02	Motor supply cable 3 m, 8-pin mating connector					

Description

Motors of the BG650 series are EC motors (brushless DC-motors) with integrated rotation speed electronics. BG650 series comprises three designs with different dimensions and output power of 65 W, 100 W and 140 W. The EC motor featuring a fully assembled planetary gear unit is a compact drive in electric spindle positioning operations of the multiconDrive system.

It provides a separate round connector output enabling direct motor connection to the spindle position display (N 142, N 152). This "interface" provides the motor with control signals for "clockwise", "counterclockwise" and "off" as well as with a signal for recalling two permanent motor speed parameters relating to high and low speed. Already predefined ramps for acceleration respectively deceleration secure smooth motor start and slow-down.

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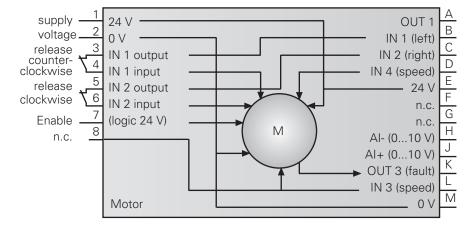
Terminal as	ssignment					
Connector – Motor, 8-pin			Connector – SPA, 12-pin			
Connector	Assignment	Function	Connector	Assignment	Function	
Pin 1	U _E	+24 VDC motor supply	Pin A	_	_	
Pin 2	GND	0 V related to ground für U _E	Pin B	IN 1	Motor left	
Pin 3	OUT left	Release counterclockwise	Pin C	IN 2	Motor right	
Pin 4	IN left	Release counterclockwise	Pin D	IN 4*	Speed	
Pin 5	OUT right	Release clockwise	Pin E	+24 V	n.c.	
Pin 6	IN right	Release clockwise	Pin F	n.c.	n.c.	
Pin 7	Enable	Logic +24 V	Pin G	n.c.	n.c.	
Pin 8	n.c.	n.c.	Pin H	_	n.c.	
			Pin J	_	n.c.	
			Pin K	OUT 3	Error signal	
			Pin L	IN 3*	Speed	
			Pin M	GND	GND	

IN 3* IN 4*

Rotation speed

1 0 200 1 1 3600

Circuit diagram



Motors

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Dimensions 8-pin connection 12-pin connection BG650.25 = 111°±0.2 disc spring 4x6.5 DIN6888 row A 90°±0.5° (BG650.50 = 136°±0.2) 45° M5x7.5 $(BG650.75 = 161^{\circ} \pm 0.2)$ ± Ā 5 3 25±1 $L \pm 1$ ø30±0.1 4x ø3.7 -0.11 ø36±0.1 ø40 ±0.1 gear stages **-** ∞ 0.15 A 4x ø4.66 -0.11 ø40±0.1 65,5 2 4x ø4.66 -0.11 ø48±0.1