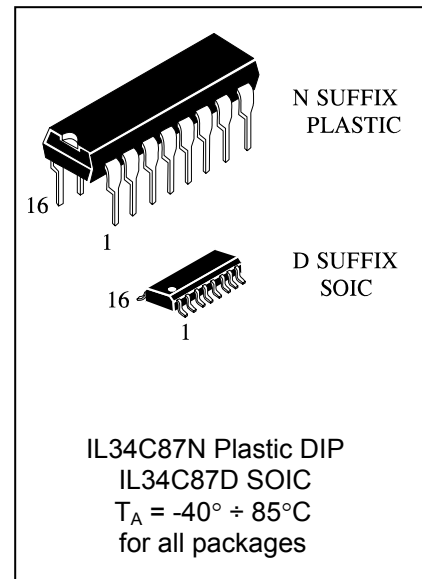


# CMOS Quad TRISTATE Differential Line Driver

**IL34C87**

## General Description

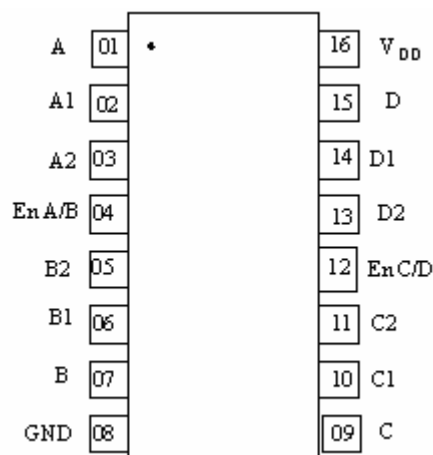
The IL34C87T is a quad differential line driver designed for digital data transmission over balanced lines. The IL34C87T meets all the requirements of EIA standard RS-422 while retaining the low power characteristics of CMOS. This enables the construction of serial and terminal interfaces while maintaining minimal power consumption. The IL34C87T accepts TTL or CMOS input levels and translates these to RS-422 output levels. This part uses special output circuitry that enables the individual drivers to power down without loading down the bus. This device has separate enable circuitry for each pair of the four drivers. All inputs are protected against damage due to electrostatic discharge by diodes to  $V_{DD}$  and ground.



## Features

- TTL input compatible
- Typical propagation delays: 6 ns
- Typical output skew: 0.5 ns
- Outputs won't load line when  $V_{DD} = 0V$
- Meets the requirements of EIA standard RS-422
- Operation from single 5V supply
- TRI-STATE outputs for connection to system buses
- Low quiescent current
- Available in surface mount

## Pin Configuration



## Pin Definitions and Functions

| Pin | Symbol          | Description  |
|-----|-----------------|--|
| 01  | A               | Input of driver A  |
| 02  | A1              | Output A   |
| 03  | A2              | Inverted output A  |
| 04  | En A/B          | input of switching outputs of A and B receivers into the third state |
| 05  | B2              | Inverted output B  |
| 06  | B1              | Output B   |
| 07  | B               | Input of driver B  |
| 08  | GND             | General pin  |
| 09  | C               | Input of driver C  |
| 10  | C1              | Output C   |
| 11  | C2              | Inverted output C  |
| 12  | En C/D          | input of switching outputs of C and D receivers into the third state |
| 13  | D2              | Inverted output B  |
| 14  | D1              | Output B   |
| 15  | D               | Input of driver B  |
| 16  | V <sub>DD</sub> | Pin of power supply  |

## Truth Table

| Input | Control Input | Non-Inverting Output | Inverting Output |
|-------|---------------|----------------------|------------------|
| H     | H             | H                    | L                |
| L     | H             | L                    | H                |
| X     | L             | Z                    | Z                |

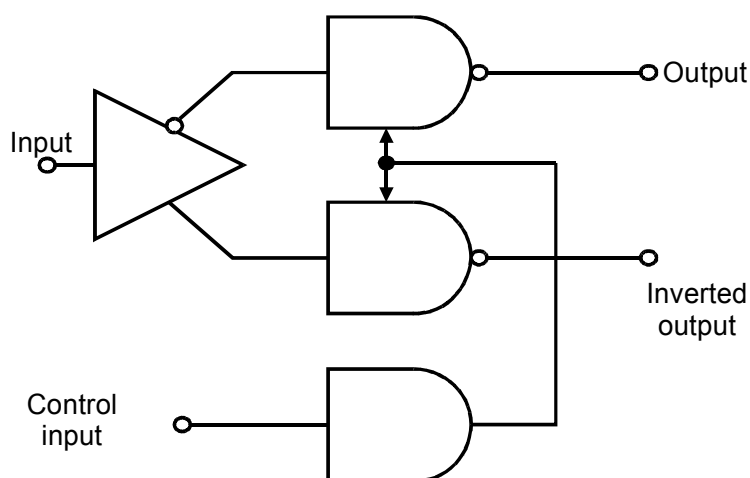
L = Low logic state

H = High logic state

X = Irrelevant

Z = TRI-STATE (high performance)

Block Diagram



Limiting and extreme parameters

Table 1

| Parameter                         | Symbol     | Operating condition |          | Maximum ratings |              | Unit |
|-----------------------------------|------------|---------------------|----------|-----------------|--------------|------|
|                                   |            | min                 | max      | min             | max          |      |
| Supply voltage                    | $V_{DD}$   | 4.50                | 5.50     | -0.5            | 7            | V    |
| DC input voltage                  | $V_{IN}$   | 0                   | $V_{CC}$ | -1.5            | $V_{CC}+1.5$ |      |
| DC output voltage                 | $V_{OUT}$  | 0                   | $V_{CC}$ | -0.5            | 7            |      |
| Protection diode current          | $V_{DIFF}$ | —                   | —        | -20             | +20          |      |
| Voltage on input Enable           | $V_{IN}$   | —                   | —        | —               | 7            |      |
| Output current                    | —          | —                   | —        | -150            | +150         | mA   |
| Input Rise or Fall Times (tr, tf) | $t_r, t_f$ | —                   | 500      | —               | —            | ns   |
| Dissipated power                  | DIP        | $P_D$               | —        | —               | 1736*        | mW   |
|                                   | SO         |                     | —        | —               | 1226*        |      |
| Operating Temperature Range (TA)  | $T_A$      | -40                 | +85      | —               | —            | °C   |
| Storage temperature               | $T_{STG}$  | —                   | —        | -65             | +150         |      |
| Temperature of soldering, 4s      | $T_L$      | —                   | —        | —               | 260          |      |

\* - at increasing temperature higher than 25°C  $P_D$  decreased on 13.89mW/°C for DIP package and on 9.80mW/°C for SO package.

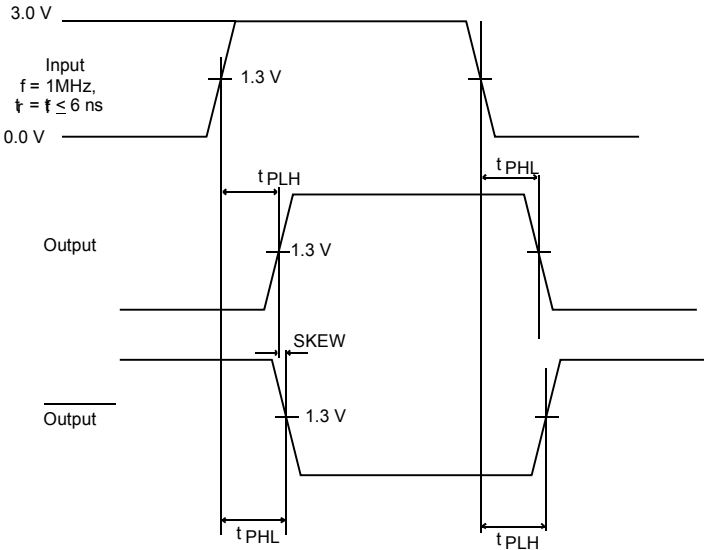
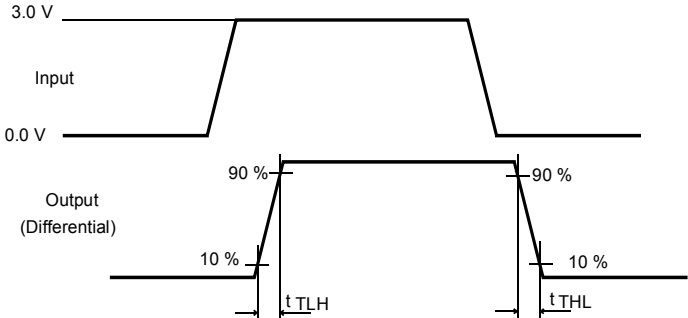
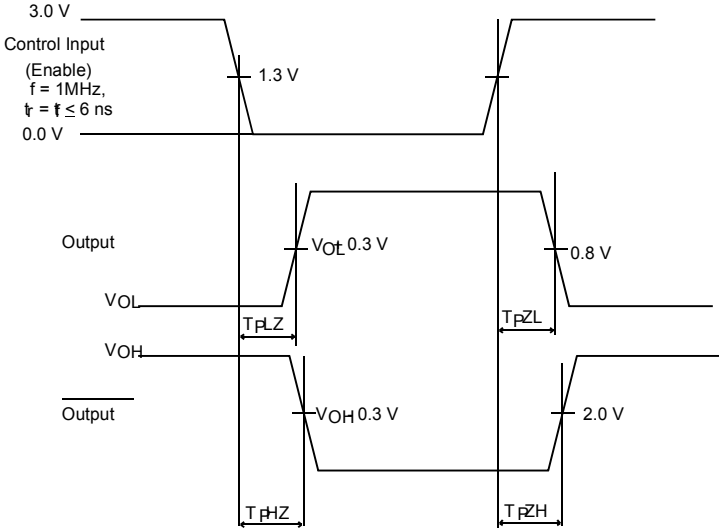
**Electrical Characteristics**

Table 2

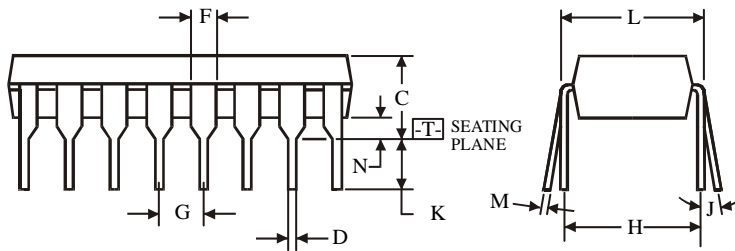
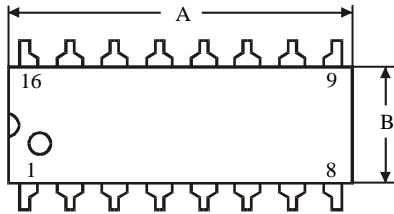
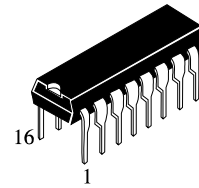
T= -40<sup>0</sup> ÷ +85<sup>0</sup>C

| Parameter   | Symbol                                | Test Conditions  | Values |      | Unit |
|---|---------------------------------------|--|--------|------|------|
|   |                                       |  | Min    | Max  |      |
| High level input voltage                                    | V <sub>IH</sub>                       |  | 2.0    | —    | V    |
| Low level input voltage                                     | V <sub>IL</sub>                       |  | —      | 0.8  |      |
| High level output voltage                                   | V <sub>OH</sub>                       | I <sub>OUT</sub> = -20mA   | 2.5    | —    | V    |
| Low level output voltage                                    | V <sub>OL</sub>                       | I <sub>OUT</sub> = +48mA   | —      | 0.5  |      |
| Differential output voltage                                 | V <sub>T</sub>                        | R <sub>L</sub> = 100 Ohm   | 2.0    | —    | V    |
| Difference in differential outputs                          | $ V_{T1} - \overline{V_{T1}} $        | R <sub>L</sub> = 100 Ohm   | —      | 0.4  | V    |
| Output voltage  | V <sub>OS</sub>                       | R <sub>L</sub> = 100 Ohm   | —      | 3.0  | V    |
| Difference in common mode output                            | $ V_{OS} - \overline{V_{OS}} $        | R <sub>L</sub> = 100 Ohm   | —      | 0.4  | V    |
| Input current   | I <sub>IN</sub>                       | V <sub>IN</sub> = V <sub>DD</sub> , 0V,<br>V <sub>IH</sub> or V <sub>IL</sub>    | —      | ±1.0 | mkA  |
| Consumption current   | I <sub>CC</sub>                       | I <sub>OUT</sub> = 0mkA,<br>V <sub>IN</sub> = V <sub>DD</sub> or 0V              | —      | 500  | mkA  |
|   |                                       | I <sub>OUT</sub> = 0mkA,<br>V <sub>IN</sub> = 2.4 or 0.5V                        | —      | 2.0  | mA   |
| Output current of the third state                           | I <sub>OZ</sub>                       | V <sub>OUT</sub> = V <sub>DD</sub> or 0V, V <sub>CONTROL</sub> = V <sub>IL</sub> | —      | ±5.0 | mkA  |
| Short circuit output current                                | I <sub>SC</sub>                       | V <sub>IN</sub> = V <sub>DD</sub> or 0V  | -30    | -150 | mA   |
| Output current of the off state                             | I <sub>OFF</sub>                      | V <sub>DD</sub> = 0V, V <sub>OUT</sub> = 6V                                      | —      | 100  | mkA  |
|   |                                       | V <sub>DD</sub> = 0V, V <sub>OUT</sub> = -0.25V                                  | —      | -100 |      |
| Time of propagation delay at switching off, switching on    | t <sub>PLH</sub> , t <sub>PHL</sub>   | t <sub>r</sub> , t <sub>f</sub> ≤ 6ns  | —      | 11   | ns   |
| Asymmetric transition time when switching in, switching off | Skew                                  | t <sub>r</sub> , t <sub>f</sub> ≤ 6ns  | —      | 3    |      |
| Transition time when switching in, switching off            | t <sub>RISE</sub> , t <sub>FALL</sub> | t <sub>r</sub> , t <sub>f</sub> ≤ 6ns  | —      | 10   |      |
| time of the third state propagation delay on input Enable   | t <sub>PZH</sub>                      | t <sub>r</sub> , t <sub>f</sub> ≤ 6ns  | —      | 25   |      |
| time of the third state propagation delay on input Enable   | t <sub>PZL</sub>                      | t <sub>r</sub> , t <sub>f</sub> ≤ 6ns  | —      | 26   |      |
| time of the third state propagation delay on input Enable   | t <sub>PHZ</sub>                      | t <sub>r</sub> , t <sub>f</sub> ≤ 6ns  | —      | 8    |      |
| time of the third state propagation delay on input Enable   | t <sub>PLZ</sub>                      | t <sub>r</sub> , t <sub>f</sub> ≤ 6ns  | —      | 12   |      |

**Time diagram  
of signals at changing dynamic parameters**  
 $t_{TLH}$ ,  $t_{THL}$ ,  $t_{PLH}$ ,  $t_{PHL}$ , SKEW.



**N SUFFIX PLASTIC DIP  
(MS - 001BB)**



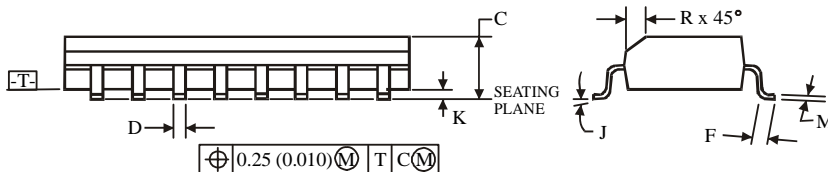
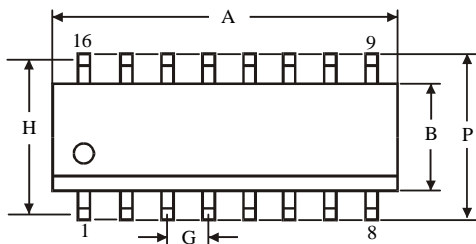
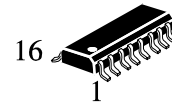
$\oplus 0.25 (0.010) \text{M} \text{T}$

**NOTES:**

- Dimensions "A", "B" do not include mold flash or protrusions.  
Maximum mold flash or protrusions 0.25 mm (0.010) per side.

| Symbol | Dimension, mm |       |
|--------|---------------|-------|
|        | MIN           | MAX   |
| A      | 18.67         | 19.69 |
| B      | 6.1           | 7.11  |
| C      |               | 5.33  |
| D      | 0.36          | 0.56  |
| F      | 1.14          | 1.78  |
| G      | 2.54          |       |
| H      | 7.62          |       |
| J      | 0°            | 10°   |
| K      | 2.92          | 3.81  |
| L      | 7.62          | 8.26  |
| M      | 0.2           | 0.36  |
| N      | 0.38          |       |

**D SUFFIX SOIC  
(MS - 012AC)**



$\oplus 0.25 (0.010) \text{M} \text{T} \text{C} \text{M}$

**NOTES:**

- Dimensions A and B do not include mold flash or protrusion.
- Maximum mold flash or protrusion 0.15 mm (0.006) per side for A; for B - 0.25 mm (0.010) per side.

| Symbol | Dimension, mm |      |
|--------|---------------|------|
|        | MIN           | MAX  |
| A      | 9.8           | 10   |
| B      | 3.8           | 4    |
| C      | 1.35          | 1.75 |
| D      | 0.33          | 0.51 |
| F      | 0.4           | 1.27 |
| G      | 1.27          |      |
| H      | 5.72          |      |
| J      | 0°            | 8°   |
| K      | 0.1           | 0.25 |
| M      | 0.19          | 0.25 |
| P      | 5.8           | 6.2  |
| R      | 0.25          | 0.5  |