

Capacitive Sensor Control IC Series

Capacitive Sensor Switch Control IC



BU21008MUV No.09048EBT04

Description

BU21008MUV are the capacitive sensor controller with 16 channels respectively. Half of sensor ports are available to use to LED driver with PWM function. PWM function can control light ambient. Also gesture function can recognize the short touch, long touch and finger motion.

Features

- 1) Gesture function
- 2) LED driver with PWM available
- 3) 2 wire serial interface
- 4) Power supply = 2.5V to 3.3V, I/O power supply = 1.7V to 3.3V
- 5) Integrated 10bit AD converter, clock and reset
- 6) Package VQFN032V5050

Applications

It is possible to use it widely as a switch such as a Mobile phone, Portable equipment, and Audiovisual apparatuses.

● Absolute Maximum Ratings (Ta=25°C)

	SYMBOL RAT		ATING	LINUT
PARAMETER			MAX	UNIT
ADDI IED VOLTAGE	AVDD	-0.3	4.5	V
APPLIED VOLTAGE	DVDD	-0.3	4.5	V
INDUT VOLTAGE	VAIN	-0.3	AVDD+0.3	V
INPUT VOLTAGE	VDIN	-0.3	DVDD+0.3	V
STORAGE TEMPERATURE RANGE	Tstg	-55	125	°C
POWER DISSIPATION	Pd	;	304	mW

Ambient temperature reduces a permission loss by 3.1mW per case more than 25 degrees Celsius, 1 degree Celsius.

Recommended Operating conditions

DADAMETED	CVMDOL		RATING		UNIT	
PARAMETER	SYMBOL	MIN	TYP	MAX	UNII	
ADDI IED VOLTAGE	AVDD	2.5	3.0	3.3	V	
APPLIED VOLTAGE	DVDD	1.7	3.0	3.3	V	
OPERATINGTEMPERATURE RANGE	Topr	-40	25	85	°C	

● Electrical characteristics(Especially, Topr=25°C and AVDD=DVDD=0 as long as it doesn't specify it.)

DADAMETED	CVMDOL	·	RATING		LINIT	Condition		
PARAMETER	SYMBOL	MIN	TYP	MAX	UNIT	Condit	ion	
H INPUT VOLTAGE	VIHIO	DVDDx0.8	-	DVDD+0.3	V			
L INPUT VOLTAGE	VILIO	DVSS-0.3	-	DVDDx0.2	V			
Output "H" voltage	Vоню	DVDD-0.7	i	DVDD	V	IOH=-2[mA]. Overshoot is 6	excluded.	
	VOLLED	AVSS	1	0.5		IOL=8[mA]. Undershoot is	excluded. LED output.	
Output "L" voltage				0.5		IOL=3[mA]. Undershoot is	DVDD > 2[V]	
	VOLTXD	DVSS	-	DVDDx0.3	V	excluded. SDA/TXD application.	DVDD ≦ 2[V]	
	VOLINT	DVSS	-	0.5		IOL=2[mA]. Undershoot is eapplication.	excluded. INT	
Input leakage current	lız	-1	-	1	μΑ			
Off leakage current	loz	-1	-	1	μA			
Standby current	Ist	-	-	2	μΑ	Shutdown (SDN="L")		
Current of operation	IDD	-	300	-	μΑ			

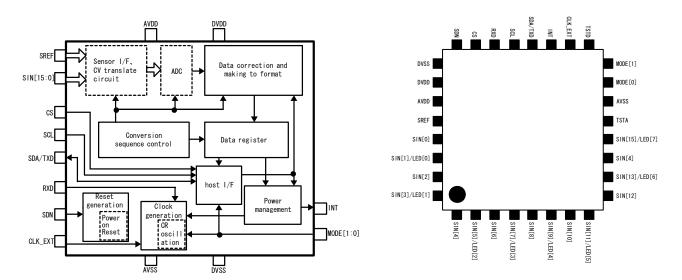
●A/D Converter

	0) (1 1 0 0 1		RATING		0 1111	
PARAMETER	SYMBOL	MIN	MIN TYP MAX		UNIT	Condition
Resolution		-	10	-	bit	
Analog Input voltage	VAIN	AVSS	-	AVDD	V	
change clock frequency	fadck	0.2	-	2.0	MHz	
change time	ftim	-	77	-	μsec	fadck = 1[MHz]
Zero scale voltage		-	-	AVSS+0.07	V	
full scale voltage		AVDD-0.07	-	-	V	
differential Non line accurate	DNL	-	-	±3	LSB	
Integrate Non line accurate	INL	-	-	±3	LSB	

●CR Oscillator characteristic

	CVADOL		RATING		UNIT	Condition
PARAMETER	SYMBOL	MIN	TYP	MAX	UNIT	Condition
Frequency Oscillation	fcr	0.4	0.8	2.0	MHz	

Block Diagram, Pin configuration



· Sensor I/F CV translate circuit

This module selects between sensor inputs. The selection sequences between all 16 channels.

AD Conversion

The voltage into which CV is converted is converted into a digital value.

Conversion is 10 bit and full scale corresponds to AVDD.

· Conversion sequence control

Performs timing generation for the analogue circuitry and a sequencer circuit for selection of the sensor channel for conversion.

· Data correction and making to format

This module provides the digital intelligence of the sensor.

The block includes, amongst other things, scaling, adding offsets and input filtering for de-bouncing.

Registers are formatted to simplify usage by the software application.

The block implements auto-calibration to manage drift in temperature, process variation, voltage variation and aging effects.

Data register

This stores the results for the software application. Please refer to the register map for details.

· HOST I/F

2 wire serial interface.

Power management

The power management block provides smart power control.

When the sensors are not in use, the Controller automatically transitions into a low-power mode.

When a sensor is touched, then the device automatically wakes up and enters its normal operation.

The chip drives an INT pin for alerting the controller device in this case.

Reset generation

The circuit is initialized by a either a soft reset command or by the external SDN pin.

Clock generation

The device has an internal oscillator.

Provision is also made if the application would like to make use of an external clock input.

●Pin Description

Reset Level "Hi-Z" "Hi-Z" "Hi-Z" "Hi-Z" "Hi-Z" "Hi-Z" "Hi-Z" "Hi-Z" "Hi-Z"	I/O Pad ④ ④ ④ ④ ④ ④
"Hi-Z" "Hi-Z" "Hi-Z" "Hi-Z" "Hi-Z" "Hi-Z"	4 4 4 4
"Hi-Z" "Hi-Z" "Hi-Z" "Hi-Z" "Hi-Z"	44444
"Hi-Z" "Hi-Z" "Hi-Z"	444
"Hi-Z" "Hi-Z"	4
"Hi-Z"	4
"Hi-Z"	
"Hi-Z"	4
	4
"Hi-Z"	4
-	-
-	1
-	1
-	1
-	1
"L"	3
"Hi-Z" -	(5) (2)
-	2
-	2
-	2
-	-
-	-
-	_
-	4
"Hi-Z"	4
"Hi-Z"	4
	4
"Hi-Z"	<u> </u>
"Hi-Z"	4
	- "L" "Hi-Z" "Hi-Z"

^{*1} Initial State When internal organs power-on reset is effective Halt condition SDN="L"

●I/O Circuit

D Circuit		
①CMOS INPUT	②CMOS Schmitt INPUT	③CMOS OUTPUT
CIN ■ PAD	CIN ■ PAD	I ⊠PAD
	⑤CMOS Schmitt INOUT	
ASW AIN I OE PAD	CIN	

●HOST I/F

• 2 wire serial, BUS (Pin configuration, MODE [1:0] =00b)

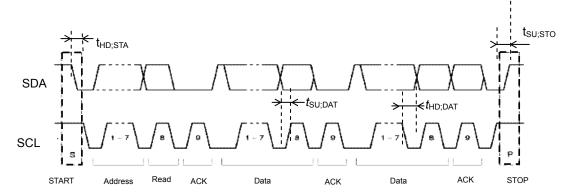
Slave mode only

Slave Address = 5Ah,5Bh selection possible. Normal (Normal mode. 100kHz Transfer rate)

Fs mode (Fast mode. 400kHz Transfer rate) also.

Not adapting sequential read / write.

[Data format]



Parameter	Standar	rd mode	High Spe	ed mode	Unit
Parameter	MIN	MAX	MIN	MAX	Offic
fSCL : SCL Clock Freq	0	100	0	400	kHz
thd;sta: START condition hold time	4.0	-	0.6	-	μsec
tLow: SCL "L"	4.7	-	1.3	-	µsec
thigh: SCL "H"	4.0	-	0.6	-	µsec
thd;dat : Data hold time	0.1	3.45	0.1	0.9	μsec
tsu;dat : Data setup time	0.25	-	0.1	-	μsec
tsu;sto: START condition hold time	4.0	-	0.6	-	µsec
tBUF: Free time of bus between STOP condition and START condition	4.7	-	1.3	-	μsec

[PROTOCOL]

Write Protocol

s	SLAVE ADDRESS	W	Α	REGISTER ADDRESS	Α	WRITE DATA	Α	Р
	7bit = 5Ah or 5Bh			8bit		8bit		

· Read Protocol

s	SLAVE ADDRESS	W	Α	REGISTER ADDRESS	Α	S	SLAVE ADDRESS	R	Α	READ DATA	N	Р
	7bit = 5Ah or 5Bh	8bit					7bit = 5Ah or 5Bh			8bit		
		from Master to Slave					= START condition	n				
		fro	om SI	ave to Master		Ρ	= STOP condition					
		=				R	= data direction R	EA) (S	DA HIGH)		
							= data direction W	/RIT	Έ (8	SDA LOW)		
						Α	= acknowledge (S	DA	LOV	V)		
							= not acknowledg	e (S	DA	HIGH)		

●Register map

Register name SENS_DATA BTN	R/W R	Length 1byte / channel	Explanation
_	R	1byte / channel	Onners autout data One for as a last a contract
BTN		To year and manner	Sensor output data. One for each channel.
	R	2byte	Button On/Off.
BTN_STATE	R	1byte	Button state data.
OFFSET	R	1byte / channel	Offset correction data. One for each channel.
GES_VEL	R	2byte	Gesture duration.
GES_DIR	R	1byte	Gesture direction.
FEAD_CTL	W	1byte	PWM control setting.
FEAD_CLK	W	1byte	PWM clock setting.
GES_CLR	W	1byte	Gesture clear control.
GES_CTL	W	1byte	Gesture control.
GES_CLK	W	1byte	Gesture clock setting.
GES_TIMEOUT	W	1byte	Gesture time-out data setting.
GES_TEST	W	1byte	Gesture test function.
CALIB	W	1byte	Soft calibration execution.
DONE	W	1byte	Setting done command.
SENS_CH	W	2byte	Sensor channel enables.
LED_CH	W	1byte	LED channel enables.
IDLE_CH	W	2byte	Idle mode release control.
LED_LINK	W	1byte	LED linkage to sensor input.
TIMES	W	1byte	Defines the sampling interval and number of samples required to recognize a button press.
TH_ON2	W	1byte	A second threshold value in the detection of a button going from OFF state to ON state.
TH_ON2_CH	W	2byte	Per channel selection of whether to use TH_ON or TH_ON2.
CMD	W	1byte	Simultaneous press and idle mode entry.
GAIN_FILTER	W	1byte	Gain setting, filter function.
TH_ON	W	1byte	A threshold value in the detection of a button going from OFF state to ON state.
TH_OFF	W	1byte	A threshold value in the detection of a button going from ON state to OFF state.
DLED	W	1byte	Register to allow simple writing to LEDs.
	GES_VEL GES_DIR FEAD_CTL FEAD_CLK GES_CLR GES_CTL GES_CLK GES_TIMEOUT GES_TEST CALIB DONE SENS_CH LED_CH IDLE_CH LED_LINK TIMES TH_ON2 TH_ON2_CH CMD GAIN_FILTER TH_ON TH_OFF	GES_VEL R GES_DIR R FEAD_CTL W FEAD_CLK W GES_CLR W GES_CTL W GES_TIMEOUT W GES_TEST W CALIB W DONE W SENS_CH W LED_CH W LED_CH W LED_LINK W TIMES W TH_ON2 W CMD W GAIN_FILTER W TH_ON W TH_OFF W	GES_VEL R 2byte GES_DIR R 1byte FEAD_CTL W 1byte FEAD_CLK W 1byte GES_CLR W 1byte GES_CLR W 1byte GES_CTL W 1byte GES_TIMEOUT W 1byte CALIB W 1byte DONE W 1byte SENS_CH W 2byte LED_CH W 2byte LED_LINK W 1byte TIMES W 1byte TH_ON2 W 1byte CALID W 2byte CMD W 1byte TH_ON W 1byte TH_ON W 1byte Th_OFF W 1byte Thyte Thyte

[1*h : Sensor Output Data]

Name: SENS_DATA

Address: 1* h (one byte per sensor channel)

Description: The sensor output that converts to 10bit. Scaling, offsets and filtering (when enabled) are applied.

The most significant 8 bits are presented to the software with this register.

	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
1*h	SD_*[7]	SD_*[6]	SD_*[5]	SD_*[4]	SD_*[3]	SD_*[2]	SD_*[1]	SD_*[0]
R/W	R	R	R	R	R	R	R	R
Initial val.	1	0	0	0	0	0	0	0

[32h / 33h : Button On/Off]

Name: BTN Address: 32h, 33h

Description: This is the state of the sensor when considered as an ON/OFF button. Here 1 : On. 0 :Off.

	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
32h	CH7	CH6	CH5	CH4	CH3	CH2	CH1	CH0
33h	CH15	CH14	CH13	CH12	CH11	CH10	CH9	CH8
R/W	R	R	R	R	R	R	R	R
Initial val.	0	0	0	0	0	0	0	0

[35h : Button State Data]

Name: BTN_STATE

Address: 35h

Description: This provides information about the press.

CH[3:0]: Effective channel:

This indicates which button is dominant.

SIMUL: Button effective:

This indicates that the effective channel corresponds to a valid button press according to the thresholds.

1 : On. 0 : Off.

CONTINU: A push and hold is effective:

Indicates that the button was pressed and held for more than push/hold judgment time. 1: On. 0: Off.

	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
35h	CONTINU	-	-	SIMUL	CH[3]	CH[2]	CH[1]	CH[0]
R/W	R	-	-	R	R	R	R	R
Initial val.	0	-	-	0	0	0	0	0

[4* h : Offset Correction Data]

Name: OFFSET

Address: 4* h (one byte per sensor channel)

Description: This is the offset required to correct the sense data to half scale during the calibration procedure.

	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
4*h	OFS_*[7]	OFS_*[6]	OFS_*[5]	OFS_*[4]	OFS_*[3]	OFS_*[2]	OFS_*[1]	OFS_*[0]
R/W	R	R	R	R	R	R	R	R
Initial val.	1	0	0	0	0	0	0	0

[60h / 61h : Gesture Duration]

Name: GES_VEL Address: 60h, 61h

Description: Indicates the duration of the gesture in number of internal clocks. The count is a clock set with

0xE4(GES_CLK). It is possible to count up to 0~4095 clocks. Gesture duration=(gesture sampling interval) * VEL [sec]

	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
60h	VEL[7]	VEL[6]	VEL[5]	VEL[4]	VEL[3]	VEL[2]	VEL[1]	VEL[0]
61h	-	-	-	-	VEL[11]	VEL[10]	VEL[9]	VEL[8]
R/W	R	R	R	R	R	R	R	R
Initial val.	0	0	0	0	0	0	0	0

[62h: Gesture Direction Judgment]

Name: GES_DIR Address: 62h

Description: Gesture direction judgment

DIR_A: gesture direction A 0xE3(GES_CTL) reference DIR_B: gesture direction B 0xE3(GES_CTL) reference

	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
62h	-	-	ı	-	1	-	DIR_B	DIR_A
R/W	-	-	-	-	-	-	R	R
Initial val.	-	-	-	-	1	-	0	0

[E0h: PWM Control Setting]

Name: FEAD_CTRL Address: E0h

Description: The following LEDs can be output as PWM-LED0, LED1, LED2, and LED3.

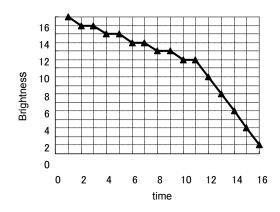
EN: enable

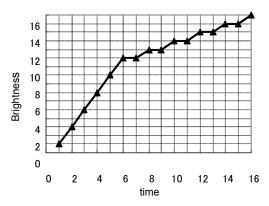
When the LED port is used as PWM, 1 is written. LED0 = EN[0], LED 1= EN[1], LED2 = EN[2], LED3 = EN[3].

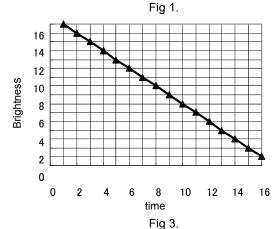
MODE: mode

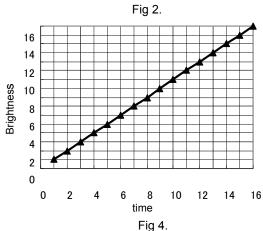
The mode of PWM is selected from four kinds.

mode	MO	DE	Fade in	Fade out
1	0	0	None	Fig 1
2	0	1	Fig 2	Fig 1
3	1	0	None	Fig 3
4	1	1	Fig 4	Fig 3









	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
E0h	-	-	MODE[1]	MODE[0]	EN[3]	EN[2]	EN[1]	EN[0]
R/W	-	-	W	W	W	W	W	W
Initial val.	-	-	0	0	1	1	1	1

[E1h: PWM Clock Setting]

Name: FEAD_CLK Address: E1h

Description: This register defines the divide ratio of the clock used for PWM.

This also relates to the fade-in and fade-out time according to the following relationship.

Fead in/out =1 / ((Internal oscillation frequency) / (2 * 16 * 16 * 16 * (F DIV+1) * 16)) [sec]

For example with an internal clock of 1.1MHz possible range is 0.119~1.906 [sec]

	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
E1h	-	-	-	-	F_DIV[3]	F_DIV[2]	F_DIV[1]	F_DIV[0]
R/W	-	-	-	-	W	W	W	W
Initial val.	-	-	-	-	0	1	1	1

[E2h: Gesture Clear]

Name: GES_CLR Address: E2h

Description: This register when written to clears GES_VEL and GES_DIR.

It is cleared by one, and it returns to 0 by the automatic operation.

	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
E2h	CLR	-	-	-	-	-	-	-
R/W	W	-	-	-	-	-	-	-
Initial val.	0	-	-	-	-	-	-	-

[E3h : Gesture Function Setting]

Name: GES_CTL Address: E3h

Description: This register controls what key-press sequence is recognized as a gesture.

Only 4 channels may be used-SIN0, SIN2, SIN4, and SIN6.

EN: enable

These are the enable bits. One is provided for each of the 4 sense inputs used for gesture. EN[0] is for SN0, EN[1] is for SN2, EN[2] is for SN4 and EN[3] is for SN6. 1 is to enable and 0 is for disable.

MODE: mode

- 0: Requires all sensors to be present in the sequence before the gesture is recognized.(All detection mode)
- 1 : Allows one or more of the keys to be missed in the sequence.(Verbose mode)

The condition and the direction of detection that can be detected in each mode are as follows.

mode	MODE	Direction(GES_DIR)	Detected
All detection	0	DIR_A	1)SIN0→SIN2→SIN4→SIN6
All detection	U	DIR_B	1)SIN6→SIN4→SIN2→SIN0
Verbose	1	DIR_A	1)SIN0→SIN2→SIN4 2)SIN0→SIN2→ SIN6 3) SIN2→SIN4→SIN6 4)SIN0→ SIN4 5) SIN2→ SIN6
verbose	1	DIR_B	$\begin{array}{cccc} 1) \text{SIN6} \rightarrow \text{SIN4} \rightarrow \text{SIN2} \\ 2) \text{SIN6} \rightarrow \text{SIN4} \rightarrow & \text{SIN0} \\ 3) & \text{SIN4} \rightarrow \text{SIN2} \rightarrow \text{SIN0} \\ 4) \text{SIN6} \rightarrow & \text{SIN2} \\ 5) & \text{SIN4} \rightarrow & \text{SIN0} \\ \end{array}$

	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
E3h	-	-	ı	MODE	EN[3]	EN[2]	EN[1]	EN[0]
R/W	-	-	-	W	W	W	W	W
Initial val.	-	-	Ī	1	1	1	1	1

[E4h : Gesture Clock Setting]

Name: GES_CLK Address: E4h

Description: This register allows setting of the time base for the gesture detection. It sets a divide ratio of the clock used.

The maximum judgment time and the sampling interval of the gesture can be set by changing this clock.

Gesture sampling interval =

Gesture maximum judgment time=(Gesture sampling interval) * TO * 16 [sec] For example with an internal clock of 1.1MHz

G_DIV	Gesture sampling interval[msec]	Gesture maximum judgment time[sec]
0	0.46	1.90
1	0.93	3.81
2	1.86	7.62
3	3.72	15.2

	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
E4h	-	-	-	-	-	-	G_DIV[1]	G_DIV[0]
R/W	-	-	-	-	-	-	W	W
Initial val.	-	-	-	-	-	-	1	0

[E5h : Gesture Timeout Data Setting]

Name: GES TIMEOUT

Address: E5h

Description: The maximum judgment time of the gesture is set.

A key sequence which exceeds this time is not recognized.

Gesture Maximum Judgment Time=(Gesture sampling interval) * TO * 16 [sec]

	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
E5h	TO[7]	TO[6]	TO[5]	TO[4]	TO[3]	TO[2]	TO[1]	TO[0]
R/W	W	W	W	W	W	W	W	W
Initial val.	1	1	1	1	1	1	1	1

[E6h: Gesture Test Setting]

Name: GES_TIMEOUT

Address: E6h

Description: When this test bit is enabled (1) then the lower 4 bits of 0xFE(DLED) are used for the gesture recognition

instead of the sensor inputs.

	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
E6h	-	-	-	-	-	-	-	TEST
R/W	-	-	-	-	-	-	-	W
Initial val.	ı	-	-	-	-	-	-	0

[EEh: Soft Calibration]

Name: CALIB Address: EEh

Description: This forces a chip re-calibration when a 1 is written and returns to 0 afterward automatically.

Please note that one should always re-calibrate after changing the gain adjustment value.

	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
EEh	-	-	-	-	-	-	-	CALIB
R/W	-	-	-	-	-	-	-	W
Initial val.	-	-	-	-	-	-	-	0

[EFh: Setting Done, Detect Start]

Name: DONE Address: EFh

Description: This register should be written to following register updates.

	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
EFh	-	-	-	-	-	-	-	DONE
R/W	-	-	-	-	-	-	-	W
Initial val.	-	-	-	_	-	-	-	0

[F0h / F1h : Sensor Channel Setting]

Name: SENS_CH Address: F0h / F1h

Description: Individual enabling and disabling of sensor channels. 1 : Effective 0 : Not in use

	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
F0h	SIN7	SIN6	SIN5	SIN4	SIN3	SIN2	SIN1	SIN0
F1h	SIN15	SIN14	SIN13	SIN12	SIN11	SIN10	SIN9	SIN8
R/W	W	W	W	W	W	W	W	W
Initial val.	0	0	0	0	0	0	0	0

[F2h: LED Channel Setting]

Name: LED_CH Address: F2h

Description: Enables and disables the channels to be used as LED outputs.

Valid for the 8 LED outputs.1 : Effective 0 : Not in use

	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
F2h	LED7	LED6	LED5	LED4	LED3	LED2	LED1	LED0
R/W	W	W	W	W	W	W	W	W
Initial val.	0	0	0	0	0	0	0	0

[F3h / F4h : Idle Exit Condition]

Name: IDLE_CH Address: F3h / F4h

Description: Defines which channels cause the device to wake up-i.e. go from idle mode to normal operation

on a key press. Selection is made on a per channel basis.

1 : Effective 0 : Not used

	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
F3h	SIN7	SIN6	SIN5	SIN4	SIN3	SIN2	SIN1	SIN0
F4h	SIN15	SIN14	SIN13	SIN12	SIN11	SIN10	SIN9	SIN8
R/W	W	W	W	W	W	W	W	W
Initial val.	1	1	1	1	1	1	1	1

[F5h: LED to Sensor Linkage]

Name: LED_LINK Address: F5h

Description: Allows the LED outputs to be automatically linked to the input channels without need for any software control.

1: It synchronizes with the button. 0: It synchronizes with data (The register name: DLED) from host.

	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
F5h	LED7	LED6	LED5	LED4	LED3	LED2	LED1	LED0
R/W	W	W	W	W	W	W	W	W
Initial val.	1	1	1	1	1	1	1	1

[F6h: Sampling Interval and Number of Samples Used for Button Press]

Name: TIMES Address: F6h

Description: Defines the sampling interval and number of samples required to recognise as a button press.

CONT_T[3:0]: Push and hold judgment time:

Governs how long it is before the chip decides it is push and hold. Given by the following equation: Push-Hold Time = system clockx2¹⁹xCONT_T (Example: system clock 1[MHz] time: About 520[msec]).

SAMP[3:0]: Sampling Interval:

Given by the following equation:

Sampling interval = system clockx2¹³xSAMP (Example: system clock 1[MHz] time : About 8.2[msec]).

	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
F6h	CONT_T[3]	CONT_T[2]	CONT_T[1]	CONT_T[0]	SAMP[3]	SAMP[2]	SAMP[1]	SAMP[0]
R/W	W	W	W	W	W	W	W	W
Initial val.	0	0	0	0	0	0	0	0

[F7h: Button OFF→ON Threshold]

Name: TH_ON2 Address: F7h

Description: A second threshold value for determining a button off→on judgment of sensor.

The sensor output value of 8bit (register SENS DATA) is compared with 128+ ON2 [6:0], and if it is larger,

the button is determined active.

	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
F7h	ı	ON2[6]	ON2[5]	ON2[4]	ON2[3]	ON2[2]	ON2[1]	ON2[0]
R/W	-	W	W	W	W	W	W	W
Initial val.	-	0	0	1	0	0	0	0

[F8h / F9h : Button OFF→ON Threshold Selection]

Name: TH_ON2_CH Address: F8h / F9h

Description: This register is used to relate either threshold TH ON or TH ON2 to particular sensor channels

for button press activity determination.

1 : TH_ON2 is applied 0 :TH_ON is applied

	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
F8h	SIN7	SIN6	SIN5	SIN4	SIN3	SIN2	SIN1	SIN0
F9h	SIN15	SIN14	SIN13	SIN12	SIN11	SIN10	SIN9	SIN8
R/W	W	W	W	W	W	W	W	W
Initial val.	0	0	0	0	0	0	0	0

[FAh: Simultaneous Press and Idle Mode Entry]

Name: CMD Address: FAh Description:

SIMUL_SEL: Simultaneous push judgment element choice:

In the case of simultaneous key press a decision must be made to select the dominant channel. The chip allows for two alternative methods. Either it can be based on whichever key press was first, or the priority can be based on the highest signal level.

1 : A level of a sensor gives priority 0 : Give priority to the channel pushed earliest

INTERMIT_EN: Intermittent and the drive are enable. :

Whether intermittent is driven at the idol mode is selected.

1 : Intermittent is driven. 0 : Intermittent is not driven. Initial state : Intermittent is driven.

IDLE_T[3:0] : non-detect time-out setting :

This sets the time the chip takes to go from normal mode to idle mode in a period key inactivity.

Duration = system clockx2¹⁹xIDLE_T (Example of system clock 1[MHz]time : About 520[msec])

	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
FAh	SIMUL_SEL	-	1	INTERMIT_EN	IDLE_T[3]	IDLE_T[2]	IDLE_T[1]	IDLE_T[0]
R/W	W	-	-	W	W	W	W	W
Initial val.	0	-	-	1	0	1	1	1

[FBh: Gain Setting, Filter Function]

Name: GAIN_FILTER

Address: FBh

Description: Gain adjustment and setting of noise filter function.

GAIN[2:0]: gain setting:

It uses it for the gain adjustment in eight stages. Initial adjustment value: x1

GAIN[2:0]	000	001	010	011	100	101	110	111
Adjustment value	x 1	x 4.22	x 8.4	x 16.5	x 23	x 46	x 69	x 92

FILTER_EN: Filter enable:

DELTA[3:0]: Filter follow count setting:

The follow count to which the noise filter function is effective is set.

	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
FBh	GAIN[2]	GAIN [1]	GAIN[0]	FILTER_EN	DELTA[3]	DELTA[2]	DELTA[1]	DELTA[0]
R/W	W	W	W	W	W	W	W	W
Initial val.	0	0	0	0	0	0	1	0

[FCh: Switch OFF -> ON Threshold]

Name: TH_ON Address: FCh

Description: This register provides a threshold value for determining if a sensor has transitioned from OFF to ON.

This is relative value from reference value (128d). So the absolute value of threshold is 128d+ON[6:0].

It makes a threshold value between TH_ON and TH_OFF.
TH_ON must be bigger than TH_OFF (TH_ON >= TH_OFF)
Maximum threshold is 256d and minimum value is 128d.

	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
FCh	-	ON[6]	ON[5]	ON[4]	ON[3]	ON[2]	ON[1]	ON[0]
R/W	-	W	W	W	W	W	W	W
Initial val.	-	0	0	1	0	0	0	0

[FDh: Switch ON -> OFF Threshold Value]

Name: TH_OFF Address: FDh

Description: This register provides a threshold value for transitioning from ON to OFF.

This is relative value from reference value (128d). So absolute value of threshold is 128d+OFF[6:0].

It makes a threshold value between TH_ON and TH_OFF. TH_OFF must be smaller than TH_ON (TH_OFF =< TH_ON)

Maximum value is 256d and minimum value is 128d.

	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
FDh	-	OFF[6]	OFF[5]	OFF[4]	OFF[3]	OFF[2]	OFF[1]	OFF[0]
R/W	-	W	W	W	W	W	W	W
Initial val.	-	0	0	0	0	0	0	1

[FEh: LED Port Data]

Name: DLED Address: FEh

Description: When LED is not linked with the sensor, it becomes a simple digital output that controls the LED.

1: Light. 0: Turned off.

	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
FEh	D7	D6	D5	D4	D3	D2	D1	D0
R/W	W	W	W	W	W	W	W	W
Initial val.	0	0	0	0	0	0	0	0

BU21008MUV Technical Note

Operation mode

This IC has a normal mode, idle mode and a shutdown mode as states of operation.

[Normal mode]

This is the normal operation of the device. Output pin INT="L".

[Idle mode]

This is the mode when the normal mode times out due to inactivity on the keys. In this mode the control interface is still alive.

*Usually time-out is aimed at about 200msec or less.

*Transition between normal and idle modes is automatic and without software control.

[Shutdown mode]

In this mode the device is completely stopped-and reset. This is achieved by making the terminal SDN L. All analog circuits and the logic circuits are stopped. The return from the shutdown mode returns by making the terminal SDN H.

*After shut-down all registers have their default values.

Interface and system clock selection

I/F selection with MODE [1:0] pin. System clock selection by RXD.

[Using 2wires serial bus mode (MODE [1:0] =00b)]

The 2wires serial bus is used for host I/F.

RXD=0 in the system clock: Built-in oscillator is used.

RXD=1 in the system clock: The clock input from CLK EXT is used.

Initialization procedure

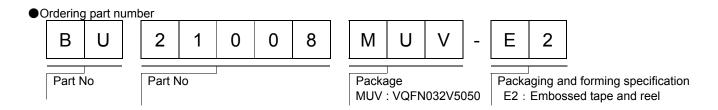
A normal power on sequence is:

- (1) Power on
- (2) Setup the registers
- (3) Write '1' to 0xEF (done register)

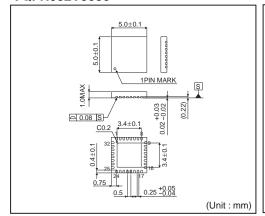
<sensing operation begins after auto-calibration occurs>

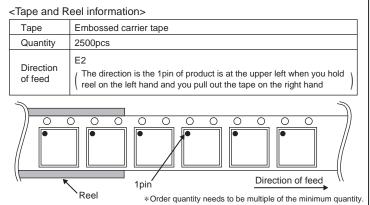
Power supply turning on procedure

You should always power on DVDD at the same time as AVDD or before AVDD.



VQFN032V5050





Notes

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