

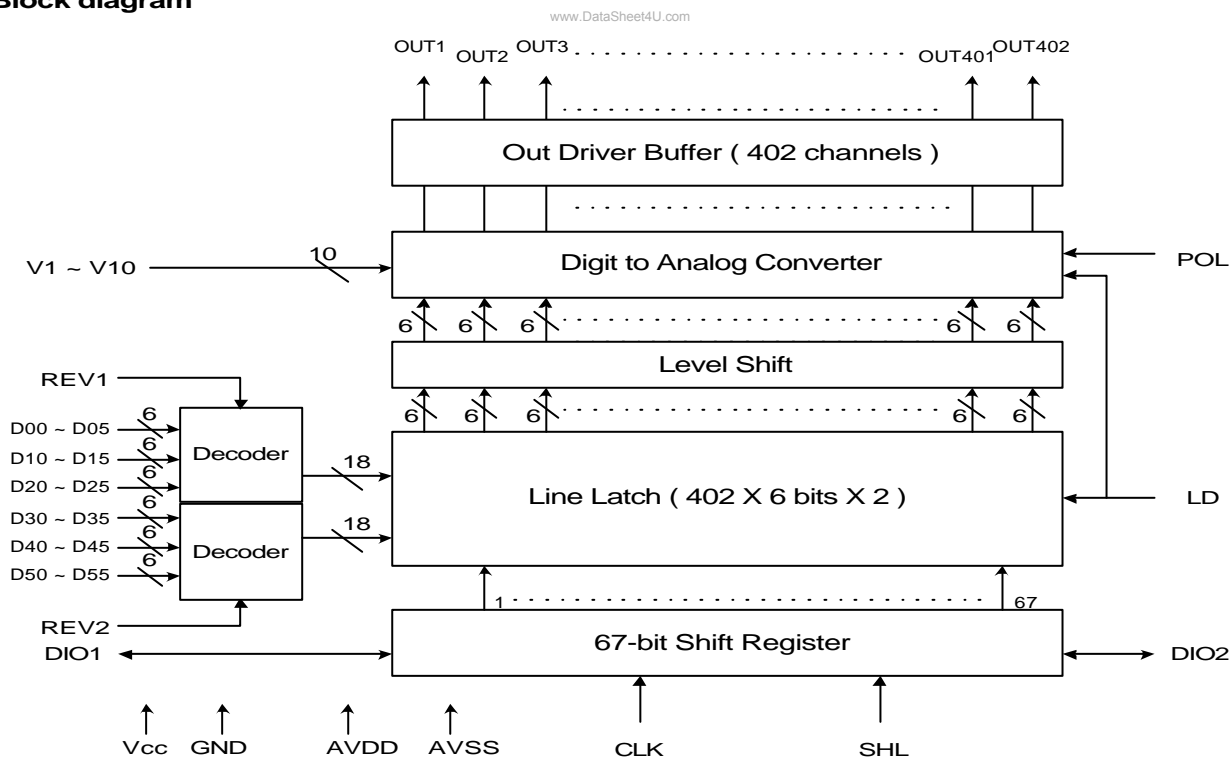
#### Features

- Output: 402 output channels
- 6-bit resolution /64 gray scales
- Dot inversion with polarity control
- V1 ~ V10 for adjusting Gamma correction
- Power for analog circuit: 6.5 ~ 10 V
- Output dynamic range: 0.1 ~ AVDD-0.1V
- Power consumption of analog circuit 3 mA
- Power for interface circuit: 2.5~3.6V
- Operating frequency: 65MHz
- Output deviation: 10 ~ 20mV
- Data inversion for reducing EMI
- Cascade function with bi-direction shift control
- CMOS silicon gate ( p-type substrate )
- TCP package

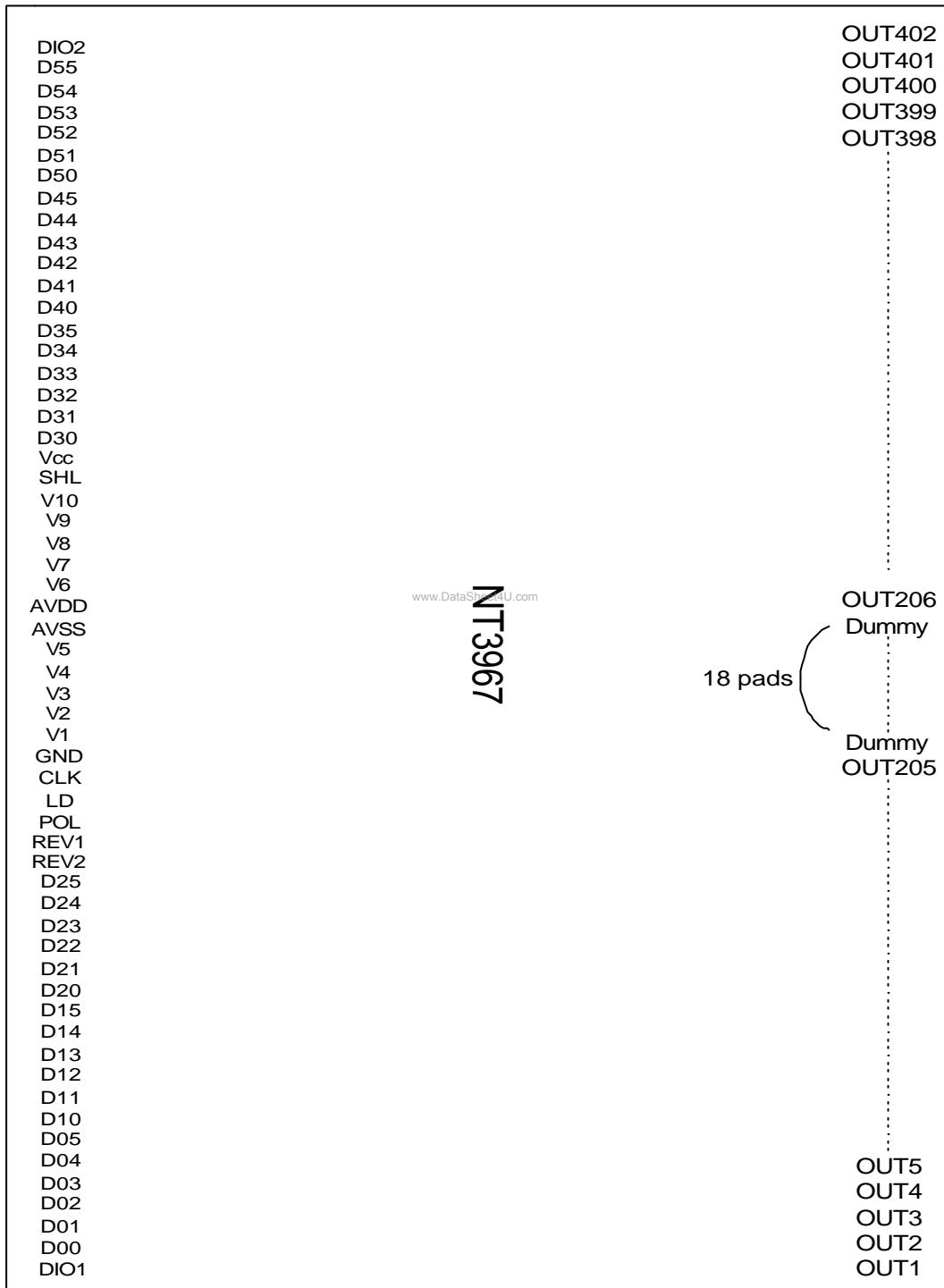
#### General Description

The NT3967 is a data driver IC for a color TFT LCD panel, SVGA(800\*600) and UXGA(1600\*1200) applications. For better performance, dot inversion and a wide range voltage output are designed in this chip and for reducing EMI, data inversion control is used. This chip supplies 10 sections of voltage-reference for Gamma correction.

#### Block diagram



**NT3967 Pad configuration (Face up): This figure does not specify the TCP package.**



**Pin Description**

Designation	I/O	Description												
D05 ~ D00 D15 ~ D10 D25 ~ D20 D35 ~ D30 D45 ~ D40 D55 ~ D50	I	Data input. For six 6-bit data, 2 pixels, or color data (R, G, B) DX5 : MSB; DX0 : LSB												
REV1	I	Controls whether the data of D00~D25 are inverted or not. When "REV1" =1 these data will be inverted. EX. "00" → "3F", "07" → "38", "15" → "2A", and so on.												
REV2	I	Controls whether the data of D30~D55 are inverted or not, same as REV1.												
CLK	I	Clock input; latching data onto the line latches at the rising edge.												
V1 ~ V10	I	Gamma correction reference voltage. The voltage of these pins must be AVSS < V10 < V9 < V8 < V7 < V6; V5 < V4 < V3 < V2 < V1 < AVDD												
OUT1 ~ OUT402	O	Output drive signals;												
SHL	I	Selects left or right shift; SHL="1" : DIO1 OUT1,2,3,4,5,6 OUT7,8,9,10,11,12-- OUT397,398,399,400,401,402= DIO2 SHL="0" : DIO1=OUT1,2,3,4,5,6 OUT7,8,9,10,11,12 -- OUT397,398,399,400,401,402 DIO2 <table border="1" style="margin-left: 40px;"> <thead> <tr> <th>SHL</th> <th>DIO1</th> <th>DIO2</th> <th>SHIFT</th> </tr> </thead> <tbody> <tr> <td>1</td> <td>Input</td> <td>Output</td> <td>Right</td> </tr> <tr> <td>0</td> <td>Output</td> <td>Input</td> <td>Left</td> </tr> </tbody> </table>	SHL	DIO1	DIO2	SHIFT	1	Input	Output	Right	0	Output	Input	Left
SHL	DIO1	DIO2	SHIFT											
1	Input	Output	Right											
0	Output	Input	Left											
DIO1 DIO2	I/O	Start pulse signal input/output When SHL is applied high (SHL="1"), a start high-pulse on DIO1 is latched at the rising edge of the CLK. Then the data are latched serially onto internal latches at the rising edge of the CLK. After all line latches are filled with data, 67 clocks, a pulse is shifted out through the DIO2 pin at the rising edge of the CLK. This function can cascade two or more devices for dot-size expansion. In normal applications, the DIO2 signal of the first device is connected to the DIO1 of the second stage, the DIO2 of the second one is connected to the DIO1 of the third, and so on, like a daisy chain. In contrast, when SHL is applied low, a start pulse inputs on DIO2, and a pulse outputs through DIO1. *Remark: The input pulse-width of DIO1/2 may exceed 1 clock-cycle.												
LD	I	Latches the polarity of outputs and switches the new data to outputs. 1. At the rising edge, latches the "POL" signal to control the polarity of the outputs. 2. The pin also controls the switch of the line registers that switches the new incoming data to outputs. *Remark: The LD may switch the new data to outputs at anytime even if the line data are not completely full.												
POL	I	Polarity selector for the dot-inversion control. Available at the rising edge of LD "POL" value is latched at the rising edge of "LD" to control the polarity of the even or odd outputs. "POL=1" indicates that even outputs are of positive polarity with a voltage range from V1~V5, and odd outputs are of negative polarity with a voltage range from V6 to V10. On the other hand, if LD receives low level "POL", even outputs are of negative polarity and odd outputs are of positive polarity. POL=1: Even outputs range from V1 ~ V5 Odd outputs range from V6 ~ V10 POL=0: Even outputs range from V6 ~ V10 Odd outputs range from V1 ~ V5												
AVDD	I	Power supply for analog circuit												
AVSS	I	Ground pin for analog circuit												
Vcc	I	Power supply for digital circuit												
GND	I	Ground pin for digital circuit												
Dummy	-	Dummy pads												

**Power on/off sequence:**

This IC is a high-voltage LCD driver, so it may be damaged by a large current flow when an incorrect power sequence is used. The recommended power on/off sequence is to first connect the logical power, Vcc & GND and then the drive power, AVDD&AVSS with V1~V10. When shutting off the power, first shut off the drive power and then the logic system, or turn off all power simultaneously.

**Relationship between the order of input data and output channels**

(1) SHL="1", Start pulse from DIO1, shift right

<b>Output</b>	OUT1	OUT2	OUT3	OUT4	OUT5	OUT6	---	OUT402
<b>Order</b>	First data						-->	Last data
<b>Data</b>	D05~D00	D15~D10	D25~D20	D35~D30	D45~D40	D55~D50	---	D55~D50

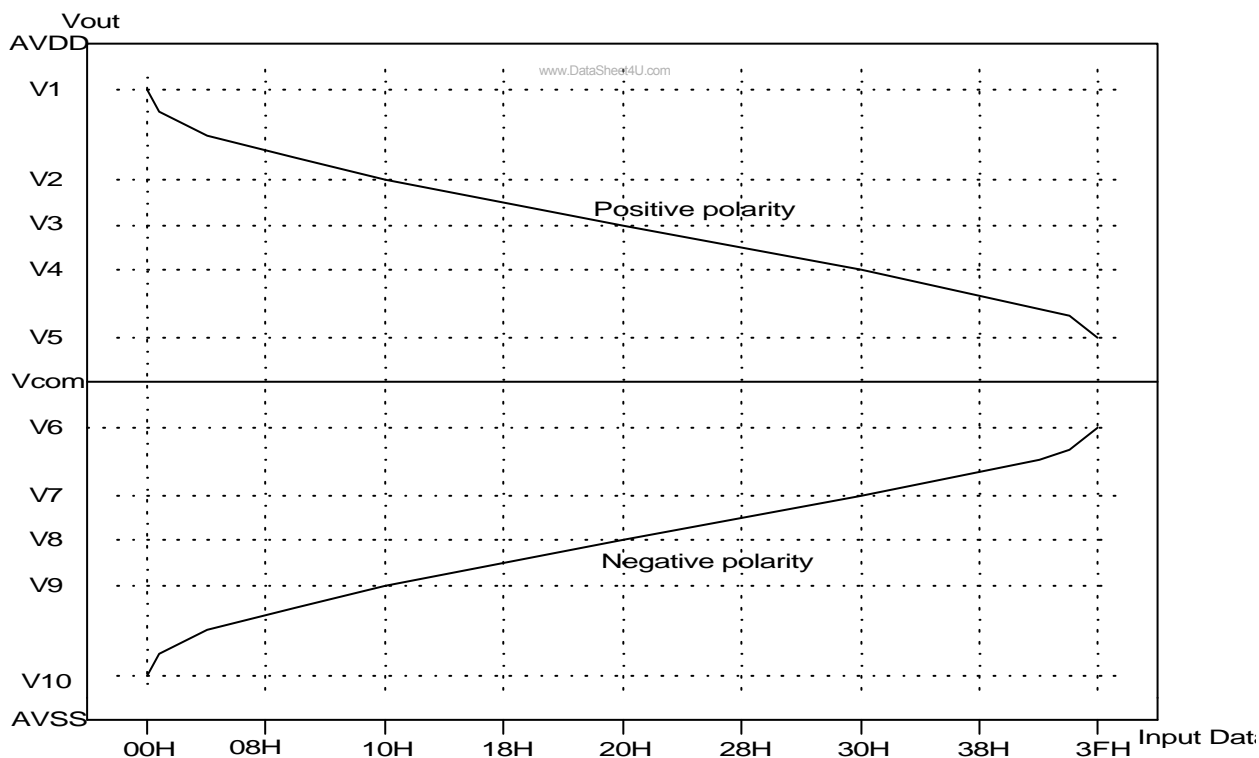
(2) SHL="0", Start pulse from DIO2, shift left

<b>Output</b>	OUT397	OUT398	OUT399	OUT400	OUT401	OUT402	---	OUT6
<b>Order</b>	First data						-->	Last data
<b>Data</b>	D05~D00	D15~D10	D25~D20	D35~D30	D45~D40	D55~D50	---	D55~D50

**Relationship between input data and output voltage**

The figure below shows the relationship between the input data and the output voltage with the polarity. The range of V1~V5 is for positive polarity, and V6 ~ V10 for negative polarity. Please refer to the following page to get the relative resistor value and voltage calculation method.

**Gamma correction diagram**



Remark: AVDD-0.1  $\geq$  V1  $\geq$  V2  $\geq$  V3  $\geq$  V4  $\geq$  V5; V6  $\geq$  V7  $\geq$  V8  $\geq$  V9  $\geq$  V10  $\geq$  AVSS+0.1V

**Gamma correction resistor**

Name	Resistor	Name	Resistor
R0	800	R32	100
R1	750	R33	100
R2	700	R34	100
R3	650	R35	100
R4	600	R36	100
R5	550	R37	100
R6	550	R38	100
R7	500	R39	100
R8	500	R40	100
R9	400	R41	100
R10	400	R42	100
R11	350	R43	100
R12	350	R44	100
R13	350	R45	100
R14	300	R46	100
R15	300	R47	100
R16	300	R48	100
R17	250	R49	100
R18	250	R50	100
R19	250	R51	100
R20	200	R52	100
R21	200	R53	150
R22	200	R54	150
R23	150	R55	150
R24	150	R56	200
R25	150	R57	200
R26	150	R58	250
R27	100	R59	250
R28	100	R60	300
R29	100	R61	500
R30	100	R62	800
R31	100		

Diagram annotations: On the left, a bracket from R0 to R14 is labeled 8.05K, and a bracket from R15 to R31 is labeled 2.75K. On the right, a bracket from R0 to R14 is labeled 1.6K, and a bracket from R15 to R31 is labeled 3.45K. Input labels V1, V10, V2, V9, and V3, V8 are on the left; V3, V8, V4, V7, and V5, V6 are on the right.

Total impedance,  $R_n=R_0 \sim R_{62}$ , equals 15.85K

**Output Voltage VS Input Data**

Data	Output Voltage ( Positive polarity )	Output Voltage ( Negative polarity )
00H	V1	V10
01H	$V2 + (V1 - V2) \times 7250/8050$	$V10 + (V9 - V10) \times 800/8050$
02H	$V2 + (V1 - V2) \times 6500/8050$	$V10 + (V9 - V10) \times 1550/8050$
03H	$V2 + (V1 - V2) \times 5800/8050$	$V10 + (V9 - V10) \times 2250/8050$
04H	$V2 + (V1 - V2) \times 5150/8050$	$V10 + (V9 - V10) \times 2900/8050$
05H	$V2 + (V1 - V2) \times 4550/8050$	$V10 + (V9 - V10) \times 3500/8050$
06H	$V2 + (V1 - V2) \times 4000/8050$	$V10 + (V9 - V10) \times 4050/8050$
07H	$V2 + (V1 - V2) \times 3450/8050$	$V10 + (V9 - V10) \times 4600/8050$
08H	$V2 + (V1 - V2) \times 2950/8050$	$V10 + (V9 - V10) \times 5100/8050$
09H	$V2 + (V1 - V2) \times 2450/8050$	$V10 + (V9 - V10) \times 5600/8050$
0AH	$V2 + (V1 - V2) \times 2050/8050$	$V10 + (V9 - V10) \times 6000/8050$
0BH	$V2 + (V1 - V2) \times 1650/8050$	$V10 + (V9 - V10) \times 6400/8050$
0CH	$V2 + (V1 - V2) \times 1300/8050$	$V10 + (V9 - V10) \times 6750/8050$
0DH	$V2 + (V1 - V2) \times 950/8050$	$V10 + (V9 - V10) \times 7100/8050$
0EH	$V2 + (V1 - V2) \times 600/8050$	$V10 + (V9 - V10) \times 7450/8050$
0FH	$V2 + (V1 - V2) \times 300/8050$	$V10 + (V9 - V10) \times 7750/8050$
10H	V2	V9
11H	$V3 + (V2 - V3) \times 2450/2750$	$V9 + (V8 - V9) \times 300/2750$
12H	$V3 + (V2 - V3) \times 2200/2750$	$V9 + (V8 - V9) \times 550/2750$
13H	$V3 + (V2 - V3) \times 1950/2750$	$V9 + (V8 - V9) \times 800/2750$
14H	$V3 + (V2 - V3) \times 1700/2750$	$V9 + (V8 - V9) \times 1050/2750$
15H	$V3 + (V2 - V3) \times 1500/2750$	$V9 + (V8 - V9) \times 1250/2750$
16H	$V3 + (V2 - V3) \times 1300/2750$	$V9 + (V8 - V9) \times 1450/2750$
17H	$V3 + (V2 - V3) \times 1100/2750$	$V9 + (V8 - V9) \times 1650/2750$
18H	$V3 + (V2 - V3) \times 950/2750$	$V9 + (V8 - V9) \times 1800/2750$
19H	$V3 + (V2 - V3) \times 800/2750$	$V9 + (V8 - V9) \times 1950/2750$
1AH	$V3 + (V2 - V3) \times 650/2750$	$V9 + (V8 - V9) \times 2100/2750$
1BH	$V3 + (V2 - V3) \times 500/2750$	$V9 + (V8 - V9) \times 2250/2750$
1CH	$V3 + (V2 - V3) \times 400/2750$	$V9 + (V8 - V9) \times 2350/2750$
1DH	$V3 + (V2 - V3) \times 300/2750$	$V9 + (V8 - V9) \times 2450/2750$
1EH	$V3 + (V2 - V3) \times 200/2750$	$V9 + (V8 - V9) \times 2550/2750$
1FH	$V3 + (V2 - V3) \times 100/2750$	$V9 + (V8 - V9) \times 2650/2750$
20H	V3	V8
21H	$V4 + (V3 - V4) \times 1500/1600$	$V8 + (V7 - V8) \times 100/1600$
22H	$V4 + (V3 - V4) \times 1400/1600$	$V8 + (V7 - V8) \times 200/1600$
23H	$V4 + (V3 - V4) \times 1300/1600$	$V8 + (V7 - V8) \times 300/1600$
24H	$V4 + (V3 - V4) \times 1200/1600$	$V8 + (V7 - V8) \times 400/1600$
25H	$V4 + (V3 - V4) \times 1100/1600$	$V8 + (V7 - V8) \times 500/1600$
26H	$V4 + (V3 - V4) \times 1000/1600$	$V8 + (V7 - V8) \times 600/1600$
27H	$V4 + (V3 - V4) \times 900/1600$	$V8 + (V7 - V8) \times 700/1600$
28H	$V4 + (V3 - V4) \times 800/1600$	$V8 + (V7 - V8) \times 800/1600$
29H	$V4 + (V3 - V4) \times 700/1600$	$V8 + (V7 - V8) \times 900/1600$
2AH	$V4 + (V3 - V4) \times 600/1600$	$V8 + (V7 - V8) \times 1000/1600$
2BH	$V4 + (V3 - V4) \times 500/1600$	$V8 + (V7 - V8) \times 1100/1600$
2CH	$V4 + (V3 - V4) \times 400/1600$	$V8 + (V7 - V8) \times 1200/1600$
2DH	$V4 + (V3 - V4) \times 300/1600$	$V8 + (V7 - V8) \times 1300/1600$
2EH	$V4 + (V3 - V4) \times 200/1600$	$V8 + (V7 - V8) \times 1400/1600$
2FH	$V4 + (V3 - V4) \times 100/1600$	$V8 + (V7 - V8) \times 1500/1600$

**Output Voltage VS Input Data (continued)**

Data	Output Voltage ( Positive polarity )	Output Voltage ( Negative polarity )
30H	V4	V7
31H	$V5 + (V4 - V5) \times 3350/3450$	$V7 + (V6 - V7) \times 100/3450$
32H	$V5 + (V4 - V5) \times 3250/3450$	$V7 + (V6 - V7) \times 200/3450$
33H	$V5 + (V4 - V5) \times 3150/3450$	$V7 + (V6 - V7) \times 300/3450$
34H	$V5 + (V4 - V5) \times 3050/3450$	$V7 + (V6 - V7) \times 400/3450$
35H	$V5 + (V4 - V5) \times 2950/3450$	$V7 + (V6 - V7) \times 500/3450$
36H	$V5 + (V4 - V5) \times 2800/3450$	$V7 + (V6 - V7) \times 650/3450$
37H	$V5 + (V4 - V5) \times 2650/3450$	$V7 + (V6 - V7) \times 800/3450$
38H	$V5 + (V4 - V5) \times 2500/3450$	$V7 + (V6 - V7) \times 950/3450$
39H	$V5 + (V4 - V5) \times 2300/3450$	$V7 + (V6 - V7) \times 1150/3450$
3AH	$V5 + (V4 - V5) \times 2100/3450$	$V7 + (V6 - V7) \times 1350/3450$
3BH	$V5 + (V4 - V5) \times 1850/3450$	$V7 + (V6 - V7) \times 1600/3450$
3CH	$V5 + (V4 - V5) \times 1600/3450$	$V7 + (V6 - V7) \times 1850/3450$
3DH	$V5 + (V4 - V5) \times 1300/3450$	$V7 + (V6 - V7) \times 2150/3450$
3EH	$V5 + (V4 - V5) \times 800/3450$	$V7 + (V6 - V7) \times 2650/3450$
3FH	V5	V6

[www.DataSheet4U.com](http://www.DataSheet4U.com)

**Absolute Maximum Ratings\***
**\*Comments**

Digital supply voltage, Vcc	-0.5V to 5V
Analog supply voltage, AVDD	-0.5V to +11V
Supply voltage, V1~ V10	-0.3 ~AVDD+0.3
Digital input voltage	-0.5V to Vcc+0.5V
Output voltage, DIO1 & DIO2	-0.5V to Vcc+0.5V
Output voltage, OUT1~OUT420	-0.5V to AVDD+0.5V
Storage temperature	-55 to 100
Operating temperature	-10 to 75

Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only. Functional operation of this device at these or under any other conditions above those indicated in the operational sections of this specification are not implied and exposure to absolute maximum rating conditions for extended periods may affect device reliability.

**DC Electrical Characteristics** (Vcc=2.5~3.6V , AVDD=6.5~10V, AVSS=GND=0V, TA=-10 ~75 )  
 (For the digital circuit)

Parameter	Symbol	Min.	Typ.	Max.	Unit	Conditions
Supply Voltage	Vcc	2.5	-	3.6	V	Digital power
Low Level Input Voltage	Vil	0	-	0.3xVcc	V	For the digital circuit
High Level Input Voltage	Vih	0.7xVcc	-	Vcc	V	For the digital circuit
High Level Output Voltage	Voh	Vcc-0.3V	-	-	V	DIO1/2, Ioh=500uA
Low Level Output Voltage	Vol	-	-	GND+0.3V	V	DIO1/2, Iol=-500uA
Input Leakage Current	Ii	-	-	±1	µA	For the digital circuit
Digital Stand-by current	Ist	-	-	50	µA	CLK is stopped, DIO1/2 No load
Digital Operating Current	Icc	-	3	5	mA	Fclk=40 MHz, FLD=50KHz

(For the analog circuit)

Parameter	Symbol	Min.	Typ.	Max.	Unit	Conditions
Supply Voltage	AVDD	6.5	8.4	10	V	For the analog circuit power
Input level of V1 ~ V5	Vref	0.4AVDD	-	AVDD-0.1	V	Gamma correction voltage
Input level of V6 ~ V10	Vref	0.1	-	0.6AVDD	V	Gamma correction voltage
Voltage Output Deviation	Vvd	-	±20	±25	mV	V <sub>o</sub> =0.1V ~ 1.5V & AVDD-1.5 ~ AVDD-0.1V
			±10	±20	mV	V <sub>o</sub> =1.5V ~ AVDD-1.5V
Voltage Output Offset	Voc	-	±10	-	mV	
Dynamic Range of Output	Vdr	0.1	-	AVDD-0.1	V	OUT1 ~ OUT402
Sinking Current of outputs	IOL	-150	-180	-	µA	OUT1 ~ OUT402; V <sub>o</sub> =0.1V V.S 1.1V
Driving Current of outputs	IOH	150	200	-	µA	OUT1 ~ OUT402; V <sub>o</sub> =9.9V V.S 8.9V
Impedance of Gamma Correction	Ri	0.8*Rn	Rn	1.3*Rn	ohm	Rn=15850 ohm, from V1 ~ V5 & V6~V10
Analog Operating Current	IDD	-	3	6	mA	No load, Fclk=33MHz, FLD=50KHz



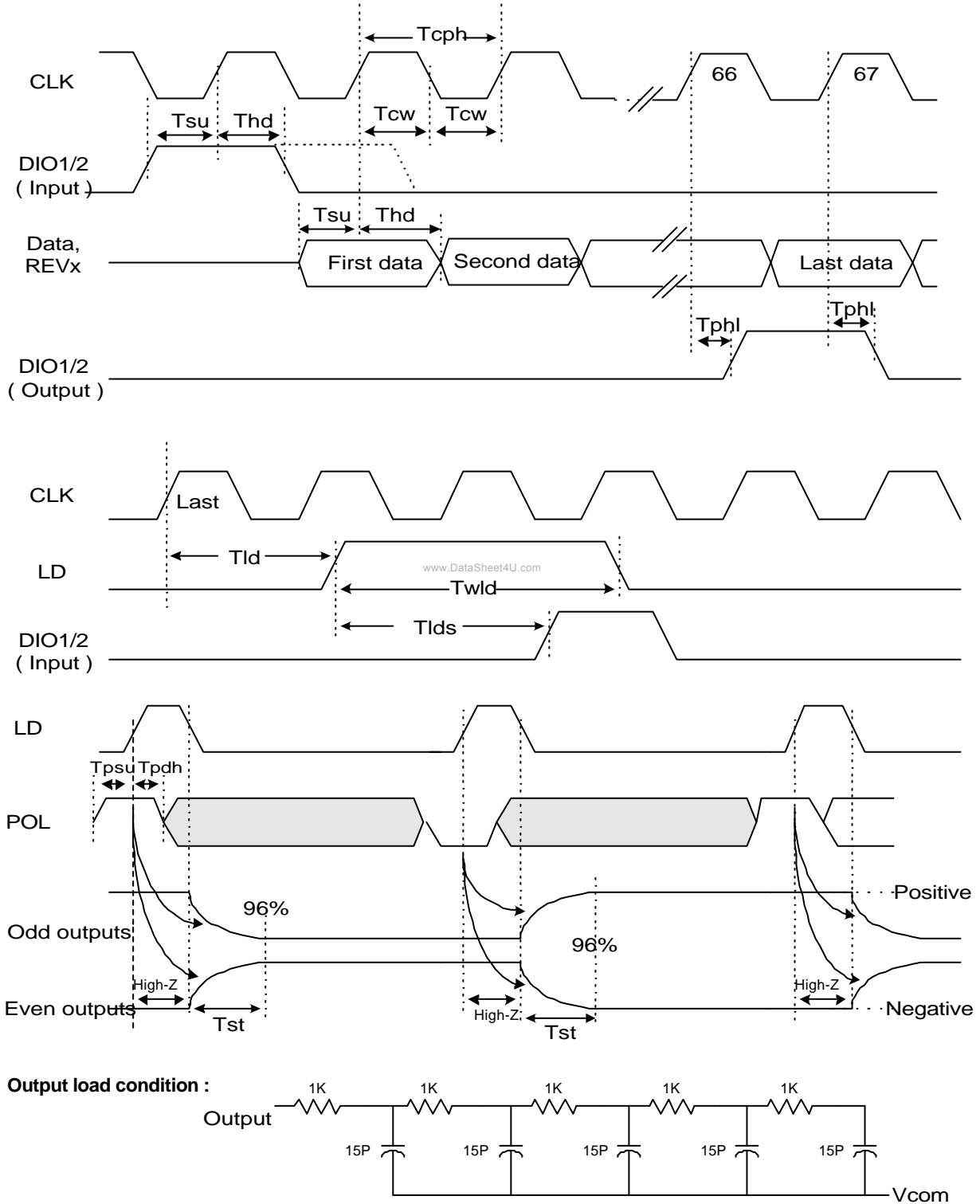
**AC Electrical Characteristics 1** ( $V_{CC}=3.0\sim 3.6V$  ,  $AV_{DD}=6.5\sim 10V$ ,  $AV_{SS}=GND=0V$ ,  $T_A=-10\sim 75$  )

Parameter	Symbol	Min.	Typ.	Max.	Unit	Conditions
CLK frequency	Fclk	-	-	65	Mhz	
CLK period cycle	Tcph	15	-	-	ns	
CLK pulse width	Tcw	6	-	-	ns	
Data set-up time	Tsu	4	-	-	ns	D00 ~ D55, REVx and DIO1/2 to CLK
Data hold time	Thd	2	-	-	ns	D00 ~ D55, REVx and DIO1/2 to CLK
Propagation delay of DIO2/1	Tphi	6	-	11	ns	CL=25pF ( Output )
Time that the last data to LD	Tld	1	-	-	Tcph	
Pulse width of LD	Tlwd	2	-	-	Tcph	
Time that LD to DIO1/2	Tlds	2	-	-	Tcph	
POL set-up time	Tpsu	6	-	-	ns	POL to LD
POL hold time	Tphd	6	-	-	ns	POL to LD
Output stable time	Tst	-	4.5	9	us	96% final value or below with 30mV precision , CL=75pF, R=5K ohm
Output loading	CL	-	-	75	pF	For OUT1 ~ OUT402

**AC Electrical Characteristics 2** ( $V_{CC}=2.5\sim 3.0V$  ,  $AV_{DD}=6.5\sim 10V$ ,  $AV_{SS}=GND=0V$ ,  $T_A=-10\sim 75$  )

Parameter	Symbol	Min.	Typ.	Max.	Unit	Conditions
CLK frequency	Fclk	-	-	45	Mhz	
CLK period cycle	Tcph	22	-	-	ns	
CLK pulse width	Tcw	8	-	-	ns	
Data set-up time	Tsu	6	-	-	ns	D00 ~ D55, REVx and DIO1/2 to CLK
Data hold time	Thd	2	-	-	ns	D00 ~ D55, REVx and DIO1/2 to CLK
Propagation delay of DIO2/1	Tphi	-	-	15	ns	CL=25pF ( Output )
Time that the last data to LD	Tld	1	-	-	Tcph	
Pulse width of LD	Tlwd	2	-	-	Tcph	
Time that LD to DIO1/2	Tlds	2	-	-	Tcph	
POL set-up time	Tpsu	6	-	-	ns	POL to LD
POL hold time	Tphd	6	-	-	ns	POL to LD
Output stable time	Tst	-	4.5	9	us	96% final value or below with 30mV precision , CL=75pF, R=5K ohm
Output loading	CL	-	-	75	pF	For OUT1 ~ OUT402

**Timing Diagram**



**Function operation**

