Advanced Micro

Devices

Am29CPL154H-25/30

CMOS 512-Word Field-Programmable Controller (FPC)

DISTINCTIVE CHARACTERISTICS

- Implements complex state machines
- High-speed, low-power CMOS EPROM technology
- Functional upgrade from the Am29CPL151
- Eight conditional inputs (each can be registered as a programmable option), 16 outputs
- Up to 30-MHz maximum frequency

- 512-word by 36-bit CMOS EPROM
- Space-saving 28-pin OTP plastic SKINNYDIPe and PLCC packages and windowed ceramic SKINNYDIP package
- 28 instructions
 - Conditional branching, conditional looping, conditional subroutine call, multiway branch

GENERAL DESCRIPTION

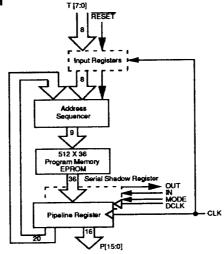
The Am29CPL154 is a CMOS, single-chip Field Programmable Controller (FPC). It allows implementation of complex state machines and controllers by programming the appropriate sequence of instructions. Jumps, loops, and subroutine calls, conditionally executed based on the test inputs, provide the designer with powerful control flow primitives.

Intelligent control may be distributed throughout the system by using FPCs to control various self-contained functional units, such as register file/ALU, I/O, interrupt, diagnostic, and bus control units. An address sequencer, the heart of the FPC, provides the address to an internal 512-word by 36-bit EPROM.

The Am29CPL154 is manufactured in CMOS technology and offers a space-saving 300-mil SKINNYDIP package. A pin-compatible smaller FPC is offered as the Am29CPL151 with a 64 x 32 memory.

This UV-erasable and reprogrammable device utilizes proven floating-gate CMOS EPROM technology to ensure high reliability, easy programming, and better than 99.9% programming yields. The Am29CPL154 is offered in both windowed and One-Time Programmable (OTP) packages. OTP plastic SKINNYDIP and PLCC devices are ideal for volume production.

SIMPLIFIED BLOCK DIAGRAM

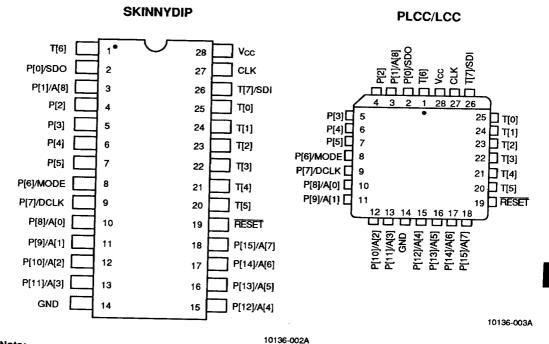


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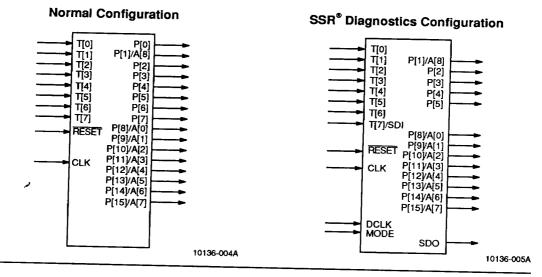
CONNECTION DIAGRAMS Top View



Note:

Pin 1 is marked for orientation.

LOGIC SYMBOLS



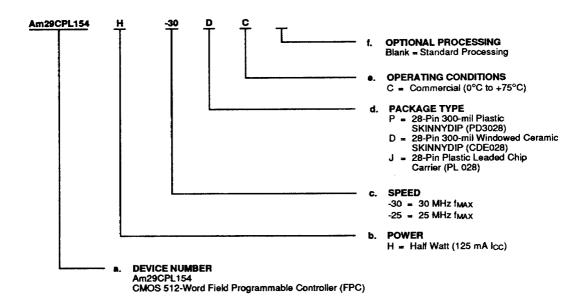
Am29CPL154

ORDERING INFORMATION **Commercial Products**

AMD products for commercial applications are available with several ordering options. The order number (Valid Combination) is formed by a combination of: a. Device Number

- b. Power
- c. Speed
- d. Package Type

 e. Operating Conditions
- f. Optional Processing



Valid Combinations							
Am29CPL154H-30	PC. DC. JC						
Am29CPL154H-25	FO, DO, 30						

Valid Combinations

The Valid Combinations table lists configurations planned to be supported in volume for this device. Consult the local AMD sales office to confirm availability of specific valid combinations, and to check on newly released combinations.

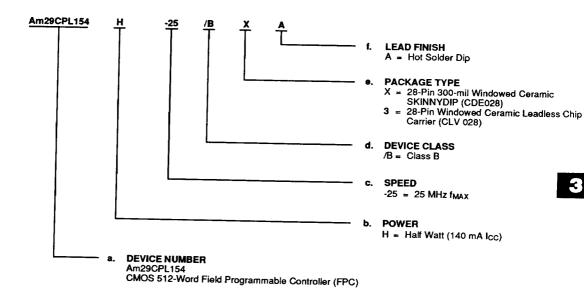
Note: Marked with AMD logo.

ORDERING INFORMATION APL Products

AMD products for Aerospace and Defense applications are available with several ordering options. APL (Approved Products List) products are fully compliant with MIL-STD-883 requirements. The order number (Valid Combination) is formed by a combination of:

a. Device Number

- b. Power c. Speed
- d. Device Class
- e. Package Type Lead Finish



Valid Combinations								
Am29CPL154H-25	/BXA, /B3A							

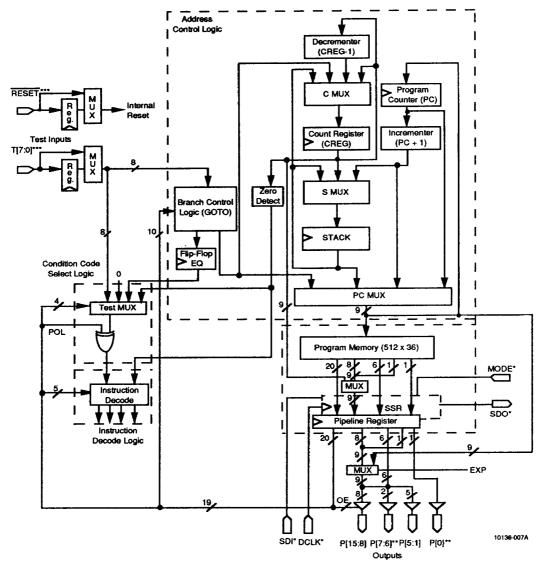
Valid Combinations

The Valid Combinations table lists configurations planned to be supported in volume for this device. Consult the local AMD sales office to confirm availability of specific valid combinations, and to check on newly released combinations.

Note: Marked with AMD logo.

Group A Tests

Group A tests consists of Subgroups 1, 2, 3, 7, 8, 9, 10, 11,



^{*} These pins available only in SSR mode.

10136-007A

Figure 1. Am29CPL154 Detailed Block Diagram

^{**} These pins available only in normal mode.

^{***} Each of the T[7:0] and RESET inputs can be individually registered or left unregistered as a programmable option.

PIN DESCRIPTION

CLK

Clock Input

The rising edge of the clock latches the program counter, count register (CREG), subroutine register (SREG), pipeline register, and EQ flag. The rising edge of the clock also latches the test input registers and the RESET register if their respective configuration bits are set to enable internal synchronizing registers.

P[15:8]/A[7:0] Outputs

The upper eight general-purpose control outputs are enabled by the OE signal from the pipeline register. When OE is HIGH, P[15:8] are enabled and when LOW, P[15:8] are disabled.

A controller Expansion (EXP) cell can be programmed to set pins P[1] and P[15:8] to output the program address A[8] and A[7:0] from the PC MUX. These can be used to address external registered memories to provide more control outputs.

The contents of the internal count register (CREG) can also be routed to the control output pins P[1] and P[15:8], using the OUTPUT instruction. Thus, the control outputs can be changed dynamically.

P[7:0] [DCLK, MODE, SDO] Outputs

The lower eight general-purpose control outputs are permanently enabled. In the SSR diagnostic configuration, P[7] becomes the diagnostic clock input DCLK, P[6] becomes the diagnostic control input MODE, and P[0] becomes the serial Data Output [SDO].

RESET

Optionally Registered Reset Input; Active LOW

When the reset input is LOW, the output of the PC MUX is forced to the uppermost program address (511). On the next rising edge of the clock, this address (511) is loaded into the program counter; the instruction at location 511 is loaded into the pipeline register, and the EQ flag is cleared. A programmable configuration bit allows the option of making this a registered input. If RESET is internally registered, the first rising edge of the clock latches it. On the next rising edge of the clock, the EQ flip-flop is cleared and the contents of memory location 511 are loaded into the pipeline register. The default state of this input is registered.

T[7:0] [SDI] Optionally Registered Test Inputs

In conditional instructions, the TEST inputs can be used as individual condition codes selected by the TEST field in the pipeline register. The T[7:0] inputs can also be used as a branch address when performing a program branch or as a count value to be loaded into the CREG. When this is done, a ninth bit from the microword is added as the MSB of the test inputs to yield a nine-bit value. Each of these inputs has an EPROM bit associated with it. This bit may be programmed such that the corresponding input becomes an unregistered input. The default state of these inputs is registered. In SSR diagnostics mode, T[7] becomes the Serial Data Input (SDI).

FUNCTIONAL DESCRIPTION

Figure 1, the detailed block diagram of the Am29CPL154, shows logic blocks and interconnecting buses that permit parallel performance of different operations in a single instruction. The FPC consists of four main logic blocks: the program memory, address control logic, condition code selection logic, and instruction decode. A fifth optional block is the Serial Shadow Register (SSR).

The program memory contains the user-defined instruction flow and output sequence. The address control logic addresses the program memory. This control logic supports high-level instruction functions including conditional branches, subroutine calls and returns, loops, and multiway branches. The condition code selection logic selects the condition code input to be tested when a conditional instruction is executed. The polarity of the selected condition code input is controlled by the POL bit in the microword. The instruction decode generates the control signals necessary to perform the instruction specified by the instruction part (P[35:16]) of the microword. The SSR enables in-system testing to isolate problems down to the IC level.

Program Memory

The FPC program memory is a 512-word by 36-bit EPROM with a 36-bit pipeline register at its output. The upper 20 bits (P[35:16]) of the pipeline register are internal to the FPC and form the instruction to control address sequencing. The format for instructions is: a one-bit synchronous Output Enable OE, a five-bit OPCODE,

a one-bit test polarity select POL, a four-bit TEST condition select field, and a nine-bit immediate DATA field. The DATA field is used to provide branch addresses, test input masks, and counter values.

The lower 16 bits (P[15:0]) of the pipeline register are brought out as user-defined, general-purpose control outputs. The upper eight control outputs (P[15:8]) are disabled when OE is programmed as a LOW. The lower eight control bits (P[7:0]) are always enabled.

Outputs P[1] and P[15:8] will contain the next instruction address when the optional bit EXP is set. The contents of the count register are also available at P[1] and P[15:18] by using the OUTPUT instruction regardless of whether the EXP bit is set.

Controlling External PROM

By programming the EXP bit, PC MUX is output over pins P[1,15:8]/A[8:0]. This feature can be used to extend the width of the output control word when external registered memories are used. In the diagram below, the Am29CPL154 controls external registered PROMs to provide an output control word (7 + N) bits wide (where N is the bit width of the PROMs).

When the OUTPUT instruction is executed, the CREG contents are output over pins P[1], P[15:8]/A[8], A[7:0] on the following cycle. Consequently, if the CREG contents must be read after programming the EXP cell, the system design should be modified to handle this exception.

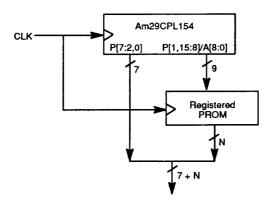


Figure 2. Controlling External PROM

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Address Control Logic

The address control logic consists of four smaller logic blocks. These are:

PC GRP - Program counter multiplexer (PCMUX), program counter register (PC) and

program counter register (PC) and combinatorial incrementer (PC + 1)

STACK - 17-word by 9-bit-wide stack with subroutine mux (S MUX)

ino max (o mox)

- Count register (CREG) with counter mux (C MUX), combinatorial decrementer

(CREG-1), and zero detect

GOTO - Multifunction branch control logic

PC GRP

CNTR

The PC GRP consists of a 4:1 multiplexer, a program counter (PC) register, and a 9-bit combinatorial incrementer (PC + 1). It selects the PC, PC + 1, the branch address, or the top of stack as the next instruction address input to the program memory and the PC.

When RESET is internally registered, the first clock edge after RESET goes LOW latches RESET internally. The next clock edge loads the contents of location 511 decimal into the instruction-pipeline register and clears the EQ flag. A programmable configuration bit allows the option of bypassing the synchronizing register. In this case, after RESET goes LOW, the output of the PC MUX is forced to all "1"s (address 511 decimal) during the setup time, and the first clock edge loads the contents of location 511 decimal into the instruction-pipeline register and clears the EQ flag. Note: by default, the RESET input is registered.

STACK

This 17-deep, 9-bit-wide stack block consists of a 3:1 multiplexer (S MUX) that stores the data into the topmost location of the stack. The STACK register is incremented by one after an item is written onto the STACK (post-incremented) and decremented by one before an item is read from the STACK (pre-decremented). The S MUX chooses from three sources: PC +1, count register, and the top of the stack (for holding). PC + 1 is the input source when doing subroutine calls. PC MUX is the output destination when a return-from-subroutine instruction is performed. The PSHCNTR and POPCNTR instructions can be used for nested counts up to the depth of the STACK. Table 1 shows how the stack operates when more than 17 values are pushed. Table 2 shows how the stack operates when more than 17 values are popped.

CNTR

The CNTR block consists of a nine-bit, four-to-one multiplexer (C MUX), driving a nine-bit register (CREG); a six-bit combinatorial decrementer (CREG-1); and a zero-detection circuit. The CNTR logic block is typically used for timing functions and iterative loop counting.

The CMUX has the following input sources: top of stack, the branch-logic output, CREG - 1, and the CREG (for holding).

GOTO

The GOTO logic block serves three functions:

- It provides a nine-bit count value from the DATA field in the pipeline register (P[24:16]) or from the TEST inputs T[7:0] masked by the DATA field P[23:16]. This is represented by T*M.
- It provides a branch address from the DATA field in the pipeline register P[24:16] or from the TEST inputs T[7:0] masked by the 8 LSBs of the DATA field P[23:16]. This is represented by T*M. The MSB or ninth bit of the branch address will be the MSB of the DATA field.
- It compares T[7:0] masked by the MASK field P[23:16], called T*M, to the CONSTANT field from the pipeline register P[31:24]. If a match occurs, the EQ flip-flop is set. EQ remains unchanged if there is no match. Constant field bits that correspond to masked test bits must be zero.

The EQ flag can be tested by the condition code selection logic. Multiple tests of any group of T inputs in a manner analogous to sum-of-products can be performed since a no-match comparison does not reset the EQ flag. Any conditional branch on EQ will reset the EQ flag. Conditional returns on EQ will not change the EQ flag. RESET input LOW will reset the EQ flag.

Note: A zero in the MASK field blocks the corresponding bit in the TEST field; a one activates the corresponding bit.

The constant field bits that correspond to masked test field bits must be zero. A zero is substituted for masked test field bits. The "POL" bit is a "don't care" when using test inputs to load registers.

Note that when the inputs are internally registered (programmable option) they must meet the register setup time on the cycle preceding the one in which they are to be used.

Condition Code Selection Logic

The condition code selection logic consists of a 16:1 multiplexer. The 16 condition inputs are the eight test bits, the EQ flag, CREG ZERO status, and six UNCOND test conditions connected to zero for the unconditional mode. The TEST field in the pipeline register (P[28:25]) selects one of the 16 conditions. If one of the UNCOND is chosen, and the POL bit is a one, the instruction is executed with a "forced PASS" condition. If one of the UNCOND is chosen, and the POL bit is zero, the instruction is executed with a "forced FAIL" condition. See opcode descriptions for more details.

The polarity bit POL in the instruction allows the user to test for either a pass or fail condition. Refer to Table 3 for details.

Note that when the inputs are internally registered (programmable option) they must meet the register setup time on the cycle preceding the one in which they are to be used.

Instruction Decode

The instruction decoder is a PLA that generates the control for 28 different instructions. The decoder inputs include the OPCODE field P[34:30], the zero detection flag from the CNTR, and the selected test condition code from the condition code selection logic.

Operational Modes

Am29CPL154 operates as а nine-bit microcontroller in normal mode, and there are several configuration bits that can be programmed to modify this normal operation. The EXP bit allows the nine program address lines from the PC MUX to be output on the output pins (P[1,15:8]) so that a user can expand the width of the control lines by using external registered memories. The SSR bit allows on-chip diagnostic capabilities for in-system testing. The remaining bits serve to individually select whether the input pins will be synchronized or not. The default setting of these bits (unprogrammed,1) will cause each pin to be synchronized, and so programming a given bit (to 0) will cause that corresponding input to become internally unsynchronized.

TABLE 1.

STACK LOCATION	PSH																		
1	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19
2	Х	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18
3	х	×	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17
4	Х	X	Х	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16
5	x	Х	Х	X	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
6	x	х	X	X	Х	1	2	3	4	5	6	7	8	9	10	11	12	13	14
7	×	х	X	Х	Х	х	1	2	3	4	5	6	7	8	9	10	11	12	13
8	x	х	Х	X	X	Х	х	1	2	3	4	5	6	7	8	9	10	11	12
9	х	х	Х	X	X	Х	х	х	1	2	3	4	5	6	7	8	9	10	11
10	x	X	Х	Х	х	х	х	х	х	1	2	3	4	5	6	7	8	9	10
11	x	х	X.	Х	×	х	х	х	х	Х	1	2	3	4	5	6	7	8	9
12	х	х	Х	Х	х	×	х	×	х	х	х	1	2	3	4	5	6	7	8
13	х	х	х	х	х	х	Х	х	х	х	х	х	1	2	3	4	5	6	7
14	х	×	х	х	Х	×	х	х	х	х	х	x	х	1	2	3	4	5	6
15	x	×	х	х	Х	х	х	x	х	×	х	х	х	×	1	2	3	4	5
16	X	х	х	×	X	х	х	х	х	x	х	х	x	х	x	1	2	3	4
17	X	Х	х	X	Х	х	х	х	х	х	х	×	х	х	×	х	1	2	3

TABLE 2.

STACK LOCATION	POP																		
1	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	18	17
2	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	18	17	16
3	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	18	17	16	15
4	16	15	14	13	12	11	10	9	8	7	6	5	4	3	18	17	16	15	14
5	15	14	13	12	11	10	9	В	7	6	5	4	3	10	17	16	15	14	13
6	14	13	12	11	10	9	8	7	6	5	4	3	18	17	16	15	14	13	12
7	13	12	11	10	9	8	7	6	5	4	3	18	17	16	15	14	13	12	11
8	12	11	10	9	8	7	6	5	4	3	18	17	16	15	14	13	12	11	10
9	11	10	9	8	7	6	5	4	3	18	17	16	15	14	13	12	11	10	9
10	10	9	8	7	6	5	4	3	18	17	16	15	14	13	12	11	10	9	8
11	9	8	7	6	5	4	3	18	17	16	15	14	13	12	11	10	9	8	7
12	8	7	6	5	4	3	18	17	16	15	14	13	12	11	10	9	8	7	6
13	7	6	5	4	3	18	17	16	15	14	13	12	11	10	9	8	7	6	5
14	6	5	4	3	18	17	16	15	14	13	12	11	10	9	В	7	6	5	4
15	5	4	3	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3
16	4	3	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	18
17	3	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	18	17

10136-008A

Am29CPL154 General Instruction Format

TEST OE DATA USER-DEFINED

WHERE: OE

= Synchronous Output Enable for P[15:8].

OPCODE A five-bit opcode field for selecting one of the 27 single-data-field instructions. POL A one-bit test condition polarity select (refer to Table 3).

TEST A four-bit test condition select.

> TEST[28:25] **UNDER TEST** 0000 0001 0010 0011 0100 0101 0110 0111 1000 1001 **CREG ZERO** 1010-1111 **UNCONDITIONAL** [0]

DATA = A nine-bit conditional branch address, test input mask, or counter value field designated as PL in instruction mnemonics.

Table 3

Input Condition Being Tested	POL	Test Result
0	0	Fail
0	1	Pass
1	0	Pass
1	1	Fail

Am29CPL154 Comparison Instruction Format

32 15 CONSTANT USER-DEFINED **OUTPUTS**

10136-009A

WHERE:

OE Synchronous Output Enable for P[15:8]. OPCODE

= Compare instruction (binary 100).

CONSTANT = An eight-bit constant for equal-to comparison with T*M. MASK

= An eight-bit mask field for masking the incoming T[7:0] inputs.

Am29CPL154

Am29CPL154 INSTRUCTION SET DEFINITION

- = Other instruction
- Instruction being described
- O = Register in part

P = Test Pass

F = Test Fail

X,Y are arbitrary values in the CREG or STACK

Opcode Mnemonic

19

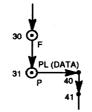
GOTOPL

Description

IF (cond) THEN GOTO PL (data)

Conditional branch to the address in the PL (DATA field). The EQ flag will be reset if the test field selects it and the condition passes. The instruction is executed with a forced PASS condition if the test field is UNCOND and POL = 1. The instruction is executed with a forced FAIL condition if the test field is UNCOND and POL = 0.

Execution Example



Register Transfer Description

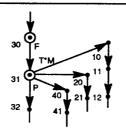
If (cond = true) Then PC = PL(data) Fise PC = PC + 1

10135-009A

IF GOTOTM

IF (cond) THEN GOTO TM (data)

Conditional branch to the address defined by the T*M (T[7:0] under bitwise mask from the 8 LSBS of the DATA field). This instruction is intended for multiway branches. The EQ flag will be reset if the test field selects it and the condition passes. The instruction is executed with a forced PASS condition if the test field is UNCOND and POL = 1. The instruction is executed with a forced FAIL condition if the test field is UNCOND and POL = 0. The MSB of the branch address will be the MSB of the DATA field.



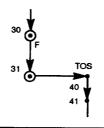
If (cond = true) Then PC = T*M Else

PC = PC + 1

10135-011A

03

GOTOSTK IF (cond) THEN GOTO (STACK) Conditional branch to the address at the top of the stack, or else continue. The EQ flag will be reset if the test field selects it and the condition passes. The instruction is executed with a forced PASS condition if the test field is UNCOND and POL = 1. The instruction is executed with a forced FAIL condition if the test field is UNCOND and POL = 0.



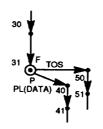
If (cond = true) Then PC = TOS Else PC = PC + 1

10136-010A

18 **FORK**

IF (cond) THEN GOTO PL (data) ELSE GOTO (STACK)

Conditional branch to the address in the PL (DATA field) or the TOS. A branch to PL is taken if the condition is true and a branch to TOS if false. The EQ flag will be reset if the test field selects it and the condition passes. The instruction is executed with a forced PASS condition if the test field is UNCOND and POL = 1. The instruction is executed with a forced FAIL condition if the test field is UNCOND and POL = 0.



If (cond = true) Then PC = PL(data) Else PC = TOS

10136-011A

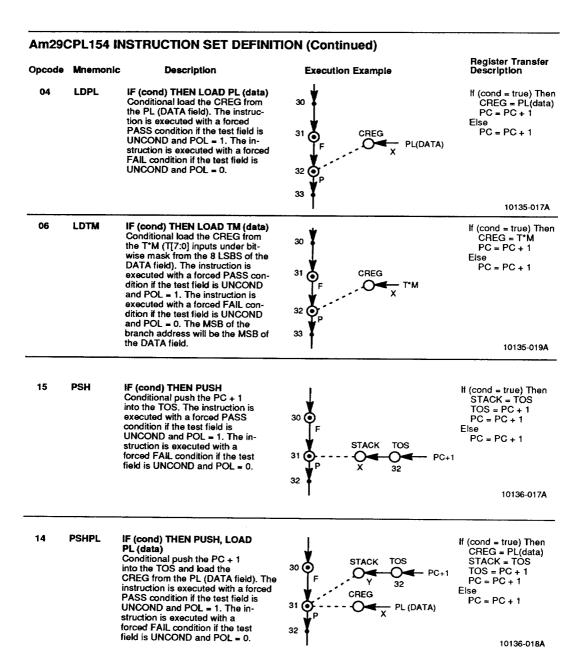
3-108

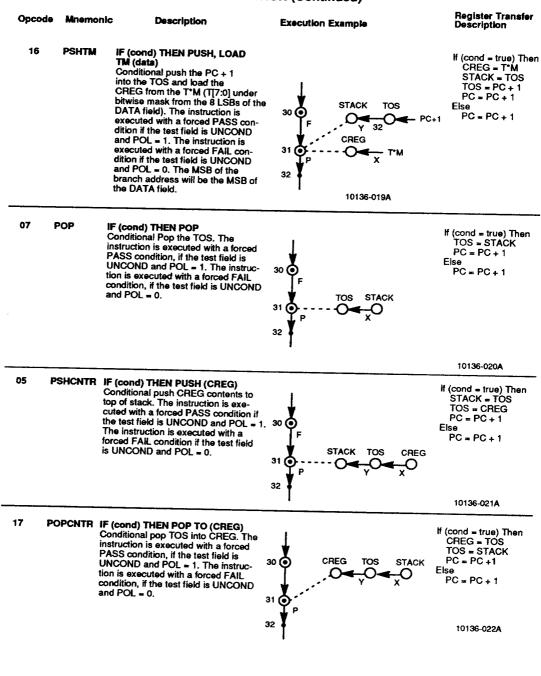
Am29CPL154

Register Transfer Opcode Mnemonic Description **Execution Example** Description 1C CALPL IF (cond) THEN CALL PL (data) If (cond = true) Then Conditional jump to subroutine STACK TOS STACK = TOS at the address in the PL (DATA -PC+1 30 @ TOS = PC + 1 field). The PC + 1 is pushed into 32 the TOS as the return address. PC = PL(data) Else The EQ flag will be reset if the PL (DATA) PC = PC + 1test field selects it and the 31 condition passes. The instruction is 32 executed with a forced PASS condition if the test field is UNCOND and POL = 1. The instruction is exe cuted with a forced FAIL condition if 33 the test field is UNCOND and POL = 0 10136-012A 1E IF (cond) THEN CALL TM (data), CALTM If (cond = true) Then Conditional jump to subroutine at the address specified by the T*M STACK = TOS TOS = PC + 1 (T[7:0] under bitwise mask from the SREG TOS PC = T*M 8 LSBs of the DATA field). The Else PC + 1 is pushed into the TOS as the 32 PC = PC + 1 return address. The EQ flag will be reset if the test field selects it and the condition passes. The instruction is 32 executed with a forced PASS condition if the test field is UNCOND and POL = 1. The instruction is executed with a forced FAIL condition if the 10136-013A test field is UNCOND and POL = 0. The MSB of the branch address will be the MSB of the DATA field. 02 RET IF (cond) THEN RET STACK TOS If (cond = true) Then Conditional return from sub-PC = TOS routine. The TOS provides 30 TOS = STACK 32 the return from subroutine Else address and the stack is PC = PC + 1 31 popped. The instruction is executed with a forced PASS condition if the test field is 32 UNCOND and POL = 1. The instruction is executed with a TOS STACK forced FAIL condition if the test field is UNCOND and POL = 0. 10136-014A 00 RETPL IF (cond) THEN RET, LOAD If (cond = true) Then STACK TOS PL (data) Conditional return from sub-PC = TOS **←** PC+1 30 TOS = STACK routine and load the CREG 32 CREG = PL(data) from the PL (DATA field). Else The TOS provides the 31 PC = PC + 1 return from subroutine address and the STACK is 32 popped. The instruction is exe-TOS STACK cuted with a forced PASS condition if the test field is UNCOND and POL = 1. The 33 CREG instruction is executed with a forced FAIL condition if the test O PL (DATA) 10136-015A field is UNCOND and POL = 0.

Am29CPL154

10136-015A





Am29CPL154 INSTRUCTION SET DEFINITION (Continued) Register Transfer **Execution Example** Description Opcode Mnemonic Description 0B DEC IF (cond) THEN DEC If (cond = true) Then 30 CREG = CREG -1 Conditional decrement of the CREG. The instruction is PC = PC + 1executed with a forced PASS Else 31 condition if the test field is UN-PC = PC + 1COND and POL = 1. The in-CREG DECREMENTER struction is executed with a 32 forced FAIL condition if the test field is UNCOND and POL = 0. 33 10135-029A OC DECPL WHILE (CREG < > 0) WAIT While (CREG < > 0) **ELSE LOAD PL (data)** CRÈG = CREG -1 Conditional Hold until the counter PC = PCEnd While is equal to zero, then load CREG from the PL (DATA field). This CREG = PL(data) instruction is intended for timing PC = PC + 1waveform generation. If the CREG CREG DECREMENTER is not equal to zero, the same instruction is refetched while CREG 30 is decremented. Timing is complete when the CREG is equal to zero. causing the next instruction to be CREG≠0 fetched and the CREG to be reloaded from PL. This instruction 10135-030A CREG=0 32 does not depend on the pass/fail PL (DATA) condition. 0E **DECTM** WHILE (CREG < > 0) WAIT While (CREG < > 0) ELSE LOAD TM (data) CREG = CREG -1 Conditional Hold until the counter is PC = PC equal to zero, then load CREG from End While the T*M (T[7:0] under bitwise mask CREG = T*M from the 8 LSBs of the DATA field). PC = PC + 1This instruction is intended for timing CREG DECREMENTER waveform generation. If the CREG is not equal to zero, the same instruct-30 tion is refetched while the CREG is decremented. Timing is complete CREG#0 when the CREG is equal to zero, causing the next instruction to be CREG fetched and the CREG to be reloaded from T*M. This instruction does not depend on the pass/fail condition. The MSB of the branch 10135-031A address will be the MSB of the DATA field 1D DECGOPL If (cond) THEN GOTO PL (data) While (cond = false) ELSE WHILE (CREG <> 0) WAIT If (CREG < > 0) Conditional Hold/Count. The current CREG = CREG -1 PC = PC instruction will be refetched and the CREG decremented until the condi-Else PC = PC + 1 tion under test becomes true or the counter is equal to zero. If the condi-CREG DECREMENTER End While PC = PL (data) tion becomes true, a branch to the 30 address in the PL (DATA field) is executed. If the counter becomes zero without the condition becoming true, a CONTINUE is executed. The F and CREG#0 EQ flag will be reset if the test field PL (DATA) selects it and the condition passes. 32 The instruction is executed with a forced PASS condition if the test 10135-032A field is UNCOND and POL = 1. The instruction is executed with a forced FAIL condition if the test field is UNCOND and POL = 0.

Opcode Mnemonic

WAITPL

WAITTM

1A

1B

Description IF (cond) THEN GOTO PL (data)

Execution Example

Register Transfer Description

If (cond = true) Then PC = PL (data) Fise

PC = PC

ELSE WAIT Conditional Hold. The current instruction will be refetched and executed until the condition under

test becomes true. When true, a branch to the address in the PL (DATA field) is executed. The EQ flag will be reset if the test field selects it and the condition passes. The instruction is executed with a forced PASS condition if the test field is UNCOND and POL = 1. The instruction is executed with a forced FAIL condition if the test field is UNCOND

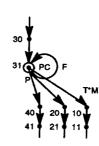
PL (DATA)

10135-033A

and POL = 0.

ELSE WAIT Conditional Hold. The current instruction will be refetched and executed until the condition under test becomes true. When the condition is true, a branch to the T*M address (T[7:0] under bitwise mask from the eight LSBs of the DATA field) is executed. The EQ flag will be reset if the test field selects it and the condition passes. The instruction is executed with a forced PASS condition, if the test field is UNCOND and POL = 1. The instruction is executed with a forced FAIL condition, if the test field is UNCOND and POL = 0. The MSB of the branch address will be the MSB of the DATA field.

IF (cond) THEN GOTO TM (data),



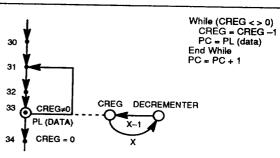
If (cond = true) Then PC = T*M Else PC = PC

10136-023A

08 LPPL

WHILE (CREG < > 0) LOOP

TO PL (data) Conditional loop to the address in the PL (DATA field). This instruction is intended to be placed at the bottom of an iterative loop. If the CREG is not equal to zero, it is decremented (signifying completion of an iteration), and a branch to the PL (DATA field) (top of the loop) is executed. If the CREG is equal to zero, looping is complete and the next sequential instruction is executed. This instruction does not depend on the pass/fail condition. The EQ flag will be reset if the test field selects it and CREG is not equal to zero.



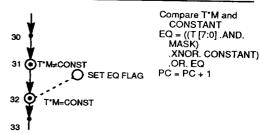
10135-034A

Register Transfer Description **Execution Example** Opcode Mnemonic Description While (CREG < > 0) 0A **LPTM** WHILE (CREG < > 0) LOOP CREG = CREG -1 TO TM (data) PC = T*M Conditional loop to the address End While T*M (T[7:0] under bitwise mask PC = PC + 1from the eight LSBs of the DATA field). This instruction should be 31 placed at the bottom of an iterative loop. If CREG is not equal to zero, 32 it is decremented (signifying com-CREG DECREMENTER CREG ≠ 0 pletion of an iteration), and a 33 6 branch to the address specified by T°M (top of the loop) is executed. If CREG is equal to zero, looping is CREG = 0 complete and the next sequential 10136-024A instruction is executed. This does not depend on the pass/fail condition. The EQ flag will be reset if the test field selects it and CREG is not equal to zero. The MSB of the branch address will be the MSB of the DATA field. While (CREG < > 0) WHILE (CREG < > 0) LOOP TO 0F LPSTK CREG = CREG -1 (STACK) Conditional loop to the address in PC = TOS 30 End While the TOS. If CREG ≠ 0, the CREG TOS = STACK is decremened and a branch to PC = PC + 131 the TOS address is executed. If the CREG = 0, looping is complete, the stack is popped, and the next 32 sequential instruction is executed. CREG DECREMENTER CREG ≠0 This instruction does not depend 33 on the pass/fail condition. The EQ TOS flag will be reset if the test field selects it and CREG is not equal to CREG ~ 0 zero. STACK 10136-025A PC = PC + 10D CONT CONTINUE The next sequential instruction is fetched unconditionally. This 30 instruction can be used to reset the EQ flag by selecting EQ in the TEST field. 31 32 10135-036A

Opcode	Mnemonic	Description	Execution Example	Register Transfer Description
01		IF (cond) THEN OUTPUT The CREG contents will be output on pins P[1] and P[15:8] during the next clock cycle. Care should be taken to ensure that the outputs are enabled for the next sequential instruction by setting the microcode bit OE = 1. The instruction is executed with a forced PASS condition, if the test field is UNCOND and POL = 1. The instruction is exe- cuted with a forced FAIL con- dition, if the test field is UNCOND and POL = 0.	30 Pipeline Register 31 P P[1] and P[15:8	If (cond = ture) Then P[1] and P[15:8] = CREG PC = PC + 1 Else PC = PC + 1 CREG X
	, , , , , , , , , , , , , , , , , , , ,			

10-13 CMP (100XX binary)

CMP TM (mask) TO PL (constant) This instruction performs bitwise Exclusive-OR of T*M (T[7:0] under bitwise mask from the MASK field) with CONSTANT (P[31:24]). If T*M equals CONSTANT, the EQ flag is set to one, which may be branched on in a following instruction. If not equal, the EQ flag is unaffected. This allows sequences of compares, in a manner analogous to sum-to-products, to be performed which can be followed by a single conditional branch if one or more of the comparisons are true. Note: The EQ flag is set to zero on reset or when EQ is selected as the test condition in a branch. Conditional returns on EQ leave the flag unchanged. Constant field bits that correspond to masked test field bits must be zero. This instruction does not depend on the pass/fail condition.



10135-037A

INSTRUCTIONS BASED ON TEST CONDITIONS

				Conditio	n Pass			Con	dition Fa	ali	
Op- code	Mnemonic	Assembler Statement	PC MUX	STACK	CREG	EQ FLAG	PC MUX	STACK	CREG	EQ FLAG	Notes
00	RETPL	IF (cond) THEN RET, LOAD PL (data)	TOS	Pop	Load PL	NC	PC + 1	Hold	Hold	NC	5
01	OUTPUT	IF (cond) THEN OUTPUT	PC+1	Hold	Hold	NC	PC + 1	Hold	Hold	NC	1
02	RET	IF (cond) THEN RET	TOS	Рор	Hold	NC	PC + 1	Hold	Hold	NC	5
03	GOTOSTK	IF (cond) THEN GOTO (STACK)	TOS	Hold	Hold	Reset	PC + 1	Hold	Hold	NC	3
04	LDPL	IF (cond) THEN LOAD PL (data)	PC + 1	Hold	Load PL	NC	PC + 1	Hold	Hold	NC	
05	PSHCNTR	IF (cond) THEN PUSH (CREG)	PC + 1	Push CREG	Hold	NC	PC + 1	Hold	Hold	NC	6
06	LDTM	IF (cond) THEN LOAD TM (data)	PC + 1	Hold	Load TM	NC	PC + 1	Hold	Hold	NC	
07	POP	IF (cond) THEN POP	PC+1	Рор	Hold	NC	PC + 1	Hold	Hold	NC	5
0B	DEC	IF (cond) THEN DEC	PC+1	Hold	DEC	NC	PC + 1	Hold	Hold	NC	
14	PSHPL	IF (cond) THEN PUSH, LOAD PL (data)	PC + 1	Push PC + 1	Load PL	NC	PC + 1	Hold	Hold	NC	6
15	PSH	IF (cond) THEN PUSH	PC + 1	Push PC + 1	Hold	NC	PC + 1	Hold	Hold	NC	6
16	PSHTM	IF (cond) THEN PUSH, LOAD TM (data)	PC + 1	Push PC + 1	Load TM	NC	PC + 1	Hold	Hold	NC	6
17	POPCNTR	IF (cond) THEN POP TO (CREG)	PC+1	Рор	Load TOS	NC	PC + 1	Hold	Hold	NC	5
18	FORK	IF (cond) THEN GOTO PL (data) ELSE GOTO (STACK)	PL	Hold	Hold	Reset	TOS	Hold	Hold	NC	3
19	GOTOPL	IF (cond) THEN GOTO PL (data)	PL	Hold	Hold	Reset	PC + 1	Hold	Hold	NC	3
1A	WAITPL	IF (cond) THEN GOTO PL (data) ELSE WAIT	PL	Hold	Hold	Reset	PC	Hold	Hold	NC	3
1B	WAITTM	IF (cond) THEN GOTO TM (data), ELSE WAIT	ТМ	Hold	Hold	Reset	PC	Hold	Hold	NC	3
1C	CALPL	IF (cond) THEN CALL PL (data)	PL	Push PC + 1	Hold	Reset	PC + 1	Hold	Hold	NC	3,6
1E	CALTM	IF (cond) THEN CALL TM (data)	ТМ	Push PC + 1	Hold	Reset	PC + 1	Hold	Hold	NC	3,6
1F	GOTOTM	IF (cond) THEN GOTO TM (data)	TM	Hold	Hold	Reset	PC + 1	Hold	Hold	NC	3

Key: PC

- Program Counter

TOS

- Top of Stack

CREG

- Counter Register

PL

= Pipeline (data) Field

TM (data) = Test Inputs Masked by DATA Field

TM (mask) = Test Inputs Masked by MASK Field

DEC

= Decrement

NC

■ No Change

Notes:

- 1. If condition Passes, Output CREG contents on next clock cycle.
- 2. If Condition = EQ, reset EQ flag.
- 3. If Condition = EQ and Conditon Passes, reset EQ flag.
- 4. If Condition = EQ and CREG ≠ 0, reset EQ flag.
- 5. When Stack is popped, the next value in the Stack is transferred to TOS.
- 6. When Stack is pushed, TOS is transferred to next available Stack location before value is written into TOS.
- 7. Set EQ Flag if CONST field = T*M.

INSTRUCTIONS DEPENDENT ON CREG

		•		CREG	= 0						
Op-	Mnemonic	Assembler Statement	PC MUX	STACK	CREG	EQ FLAG	PC MUX	STACK	CREG	EQ FLAG	Notes
80	LPPL	WHILE (CREG < > 0) LOOP TO PL (data)	PC + 1	Hold	Hold	NC	PL	Hold	DEC	Reset	4
0 A	LPTM	WHILE (CREG < > 0) LOOP TO TM (data)	PC + 1	Hold	Hold	NC	TM	Hold	DEC	Reset	4
0C	DECPL	WHILE (CREG <> 0) WAIT ELSE LOAD PL (data)	PC + 1	Hold	Load PL	NC	PC	Hold	DEC	NC	
0E	DECTM	WHILE (CREG <> 0) WAIT ELSE LOAD TM (data)	PC + 1	Hold	Load TM	NC	PC	Hold	DEC	NC	
0F	LPSTK	WHILE (CREG <> 0) LOOP TO (STACK)	PC + 1	Рор	Hold	NC	TOS	Hold	DEC	Reset	4

INSTRUCTIONS DEPENDENT ON TEST CONDITION AND CREG VALUE

	THE CITE OF THE COLOR												
					Con	dition Pa	195						
Op- code Mnemonic	Assembler Statement	CREG Content	PC MUX	STACK	CREG	EQ FLAG	PC MUX	STACK	CREG	EQ FLAG	Notes		
		IF (cond)					T					110103	
1D	D DECGOPL THEN PL (da	THEN GOTO	≠ 0	PL	Hold	Hold	Reset	PC	Hold	DEC	NC		
ID DEC		ELSE WHILE (CREG < > 0)	= 0	PL	Hold	Hold	Reset	PC + 1	Hold	Hold	NC	3	

UNCONDITIONAL INSTRUCTIONS

Opcode	Mnemonic	Assembler Statement	PC MUX	STACK	CREG	EQ FLAG	Notes
0D	CONT	CONTINUE	PC + 1	Hold	Hold	NC	
10-13 (Binary 100XX)	СМР	CMP TM (mask) TO PL (constant)	PG + 1	Hold	Hold	Set	7

Key: PC

= Program Counter

SREG

= Stack Register

CREG

= Counter Register

PL

= Pipeline (data) Field

TM (data) = Test Inputs Masked by DATA Field

TM (mask) = Test Inputs Masked by MASK Field

DEC NC

= Decrement

= No Change

Notes:

- 1. If condition Passes, Output CREG contents on next clock cycle.
- 2. If Condition = EQ, reset EQ flag.
- 3. If Condition = EQ and Conditon Passes, reset EQ flag.
- 4. If Condition = EQ and CREG ≠ 0, reset EQ flag.
- 5. When Stack is popped, the next value in the Stack is transferred to TOS.
- 6. When Stack is pushed, TOS is transferred to next available Stack location before value is written into TOS.
- 7. Set EQ Flag if CONST field = T*M.

Am29CPL154

Am29CPL154 SSR Diagnostics Option

As a programmable option, the Am29CPL154 FPC may be configured to contain Serial Shadow Register (SSR) diagnostics capability. SSR diagnostics is a simple, straightforward method of in-system testing to isolate problems down to the IC level.

The SSR diagnostics configuration activates a 36-bitwide D-type register called a "shadow" register, on the pipeline register inputs. The shadow register can be serially loaded from the SDI pin, parallel loaded from the pipeline register, or held. The pipeline register can be loaded from the Program Memory in normal mode or from the shadow register during diagnostics. A redefinition of four device pins is required to control the different diagnostics functions. T[7] also functions as the Serial Data Input (SDI), P[0] becomes the Serial Data Output (SDO), P[7] becomes the diagnostic clock (DCLK), and P[6] becomes the diagnostic mode control (MODE). The various diagnostic and normal modes are shown in table 4.

Serially loading a test instruction into the shadow register and parallel loading the shadow register contents into the pipeline register forces execution of the test instruction. The test result can then be clocked into the pipeline register as in normal operation mode, parallel loaded into the shadow register, and serially shifted out for system diagnostics.

Table 4

		Inputs			Outputs		
SDI	MODE	DCLK	CLK	SDO	Shadow Register	Pipeline Register	Operation
X	L	Î	H, L, ↓	S ₀	$\begin{array}{c} S_{i-1} \leftarrow S_i \\ S_{35} \leftarrow SDI \end{array}$	Hold	Serial Right - Shift Shadow Register
T [7] (Note 1)	L	H, L, ↓	1	S ₀	Hold	P _i ← EPROM _i	Normal Operation; Load Pipeline Register from EPROM
L	Н	1	Н, L, ↓	L	S _i ← P _i	Hold	Load Shadow Register from Pipeline Register (Note 2)
×	Н	H, L, ↓	↑	SDI	Hold	P _i ← S _i	Load Pipeline Register from Shadow Register
Н	Н	1	H, L, ↓	Н	Hold	Hold	Hold Shadow Register

Notes:

- 1. During normal operation, this pin behaves as the T[7] test input.
- S7, S6 are undefined. S[15:8] load from the source driving pins P[15:8]. If P[35] in the microword is a ONE, S[15:8] are loaded from the pipeline register. If P[35] in the microword is a ZERO, S[15:8] are loaded from an external source.

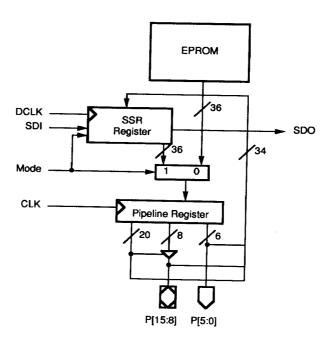
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H = HIGH

L = LOW X = Don't Care

1 = LOW-to-HIGH transition

↓ = HIGH-to-LOW transition



10136-027A

Figure 3. SSR Diagnostics Logic

Erasure

In order to fully erase all memory locations, it is necessary to expose the memory array to a standard ultraviolet light source having a wavelength of 2537 angstroms. The minimum recommended dose (UV intensity x exposure time) is 15 Wsec/cm². For a UV lamp with a 12 mW/cm² power rating, the exposure time would be about 30 minutes. The device should be located one inch from the source in a direct line.

It should be noted that erasure will begin with exposure to light having wavelengths less than 4000 angstroms.

To prevent exposure to sunlight or fluorescent lighting, an opaque label should be affixed over the window after programming.

OTP (One-Time Programmable) Am29CPL154 devices are available in plastic and are ideal for volume production. They can be inventoried unprogrammed and used with current software revisions; there is no window to be covered to prevent light from changing data.

ABSOLUTE MAXIMUM RATINGS

-65°C to +150°C Storage Temperature

ings may cause permanent device failure. Functionality at or above these limits is not implied. Exposure to Absolute Maximum Ratings for extended periods may affect device reliabil-

Ambient Temperature with

Power Applied Supply Voltage with -55°C to +125°C

Respect to Ground DC Input Voltage

-0.5 V to +7.0 V -0.3 V to Vcc + 0.3 V

DC Output or I/O Pin Voltage

-0.3 V to Vcc + 0.3 V

DC Input Current Stresses above those listed under Absolute Maximum Rat-

ity. Programming conditions may differ.

-10 mA to +10 mA

OPERATING RANGES

Commerciai (C) Devices

Ambient Temperature (T_A)

Operating in Free Air

Supply Voltage (Vcc)

0°C to +75°C

with Respect to Ground

+4.5 V to +5.5 V

Operating ranges define those limits between which the func-

tionality of the device is guaranteed.

DC CHARACTERISTICS over COMMERCIAL operating range unless otherwise specified

Parameter Symbol	Parameter Description	Test Condition	s		Min.	Max.	Unit
V _{OH}	Output HIGH Voltage	I _{OH} = -3.0 mA	V _{IN} =	V _{IH} or V _{IL} Min.	2.4		٧
Vol	Output LOW Voltage	lo _L = 16 mA		0.5	٧		
ViH	Input HIGH Voltage	Guaranteed Inp Voltage for all Ir	2.0		٧		
VIL	Input LOW Voltage	Guaranteed Inp Voltage for all Ir		8.0	V		
let	Input HIGH Leakage Current	V _{IN} = V _{CC} - 0.5 (Note 2)		10	μA		
IIL	Input LOW Leakage Current	V _{IN} = 0.5 V, V _{CC}	; = Max.	(Note 2)		-10	μА
lozн	Off-State Output Leakage Current HIGH	Vout = 2.4 V, V VIN = VIH of VIL		C.		10	μА
lozi	Off-State Output Leakage Current LOW	Vout = 0.5 V, V Vin = ViH or Vil.		x.		-10	μА
lcc	Supply Current	Outputs Open (lour = 0 mA) Vcc = Max.	CMOS TTL	V _{IN} = GND or V _{CC} V _{IN} = 0.5 V or 2.4 V		115 125	mA
C _{PD}	Power Dissipation Capacitance (Note 3)	V _{CC} = Max. T _A = 25°C No Load			100	рҒ Турк	al

Notes:

- 1. These are absolute values with respect to device ground and all overshoots due to system and/or tester noise are included.
- 2. I/O pin leakage is the worst case of I_{IL} and I_{OZL} (or I_{IH} and I_{OZH}).
- 3. The dynamic current consumption is: tcc (Total) = tcc (Static) + (Cpp + nCt) Vcc (f/2), where f is the clock frequency, Ct = the output load capacitance, and n is the number of loads.

CAPACITANCE (Note 1)

Parameter Symbol	Parameter Description	on	Test Conditio	ns	Max.	Unit
CIN	Input Capacitance	RESET	V _{IN} = 2.0 V	V _{CC} = 4.5 V to 5.5 V	25	†
		Others		_ T _A = -55°C to +125°C	15	pF
Соит	Output Capacitance		$V_{OUT} = 2.0 \text{ V}$	f = 1 MHz	15	1

Note:

 These parameters are not 100% tested, but are evaluated at initial characterization and at any time the design is modified where capacitance may be affected.

SWITCHING CHARACTERISTICS over COMMERCIAL operating range (Note 2)

	Parameter			H-	30	H-25			
No.	Symbol	Parameter	Parameter Description		Max.	Min.	Max.	Unit	
1	tco	CLK to P[15	5:0]		18		20	ns	
2		CLK to A[8:	0]		30		36	ns	
3	ts	T[7:0] to CL	K, Registered	8		8		ns	
4		T[7:0] to CL (Note 3)	K, Asynchronous	33		40		ns	
5		RESET to CLK, Registered		12		12		ns	
6		RESET to CLK, Asynchronous (Note 3)		30		40		ns	
7	tH	CLK to Τ[7:0)]	0		0		ns	
8	(Note 4)	CLK to RESI	ĒĪ	0		0		ns	
9	t _{PZX}	CLK to P[15	:8] Enable		33		40	ns	
10	t _{PXZ}	CLK to P[15	:8] Disable		33		40	ns	
11	twL		LOW	14		16	-40		
12	twn	CLK Width	HIGH	14		16		ns	
13	tр	CLK Period (Note 3)		33		40		ns	
14	fmax		equency (1/t _P)					ns	
			equency (mp)	30		25		MHz	

Note:

- 2. See Switching Test Circuit for test conditions.
- 3. These parameters are measured indirectly on unprogrammed devices. They are determined as follows:
 - a. Measure delay from input (T[7:0], RESET, or CLK) to EPROM address out in test mode. This will measure the delay through the sequence logic.
 - b. Measure setup time from T[7:0] input through EPROM test columns to pipeline register in verify test column mode. This will measure the delay through the EPROM and register setup.
 - c. Measure delay from T[7:0] input to EPROM address out in verify test column mode. This will measure the delay through the logic and P[15:0] outputs.

To calculate the desired parameter measurement, the following formula is used:

Measurement (a) + Measurement (b) - Measurement (c)

CLK PERIOD:

RESET to CLK setup time:

CLK (a) + (b) - (c) = CLK PERIOD

RESET (a) + (b) - (c) = RESET to CLK setup time

T[7:0] to CLK setup time:

T[7:0] (a) + (b) - (c) = T[7:0] to CLK setup time

4. These hold time parameters are tested on a sample basis.

SWITCHING CHARACTERISTICS over COMMERCIAL operating range (Continued)

	Parameter			H-	-30	H-	25	
No.	Symbol	Parameter Description		Min.	Max.	Min.	Max.	Unit
SSR Configuration								
15	t _{PD}	Mode to SDC)		25		30	ns
16		SDI to SDO			25		30	ns
17	tco	DCLK to SDC)		32		36	ns
18	ts	Mode to CLK		25		30		ns
19		Mode to DCLK		25		30		ns
20		SDI to DCLK		25		30		ns
21		P[15:8] to DCLK		25		30		ns
22	t⊣	CLK to Mode		6		6		ns
23	(Note 1)	DCLK to Mod	e	0		0		ns
24		DCLK to SDI		0		0		ns
25		DCLK to P[15	5:8]	0		0		ns
26	tw∟	DCLK Width	LOW	20		25		ns
27	twн		HIGH	20		25		ns
28	t₽	DCLK Period		40		50		ns

Note:

^{1.} These hold time parameters are tested on a sample basis.

ABSOLUTE MAXIMUM RATINGS

Storage Temperature -65°C to +150°C

Ambient Temperature with Power Applied

-55°C to +125°C

Supply Voltage with

Respect to Ground

-0.5 V to +7.0 V

DC Input Voltage -0.3 V to V_{CC} + 0.3 V

DC Output or I/O Pin Voltage DC Input Current -0.3 V to V_{CC} + 0.3 V -10 mA to +10 mA

Stresses above those listed under Absolute Maximum Ratings may cause permanent device failure. Functionality at or above these limits is not implied. Exposure to Absolute Maximum Ratings for extended periods may affect device reliability. Programming conditions may differ. Absolute Maximum Ratings are for system design reference; parameters given are not tested.

OPERATING RANGES

Military (M) Devices

Ambient Temperature (T_A)

-55°C to +125°C

Operating in Free Air

Supply Voltage (Vcc) with

+4.5 V to +5.5 V

Respect to Ground

Operating Ranges define those limits between which the functionality of the device is guaranteed.

Note:

 Military products are tested at T_C = 25°C, 125°C and -55°C.

DC CHARACTERISTICS over MILITARY operating range unless otherwise specified

Parameter Symbol	Parameter Description	Test Conditio		ungo umess ome	Min.	Max.	Unit
V _{ОН}	Output HIGH Voltage	I _{OH} = -1.0 mA		V _{IN} = V _{IH} or V _{IL} V _{CC} = Min.	2.4		٧
V _{OL}	Output LOW Voltage	I _{OL} = 12 mA		V _{IN} = V _{IH} or V _{IL} V _{CC} = Min.		0.5	٧
V _H	Input HIGH Voltage	Guaranteed In Voltage for all	Guaranteed Input Logical HIGH Voltage for all Inputs (Note 1)				٧
ViL	Input LOW Voltage	Guaranteed Input Logical LOW Voltage for all Inputs (Note 1)				0.8	٧
l _{IH}	Input HIGH Leakage Current	$V_{IN} = V_{CC} - 0.5 \text{ V}, V_{CC} = \text{Max}.$ (Note 2)				10	μА
l _{IL}	Input LOW Leakage Current	V _{IN} = 0.5 V, V _{CC} = Max. (Note 2)				-10	μА
ЮZН	Off-State Output Leakage Current HIGH	Vout = 2.4 V, V V _{IN} = V _{IH} or V _{IL}	/ _{CC} = Ma (Note 2)	х.		10	μА
lozL	Off-State Output Leakage Current LOW	Vout = 0.5 V, V V _{IN} = V _{IH} or V _{IL}	cc = Ma (Note 2)	x.		-10	μА
Icc	Supply Current	Outputs Open (Iout = 0 mA) V _{CC} = Max.	CMOS TTL	V _{IN} = GND or V _{CC} V _{IN} = 0.5 V or 2.4 V		130 140	mA
C _{PD}	Power Dissipation Capacitance (Note 3)	V _{CC} = Max. T _A = 25°C No Load			100 p	oF Typica	al

Notes:

- 1. These are absolute values with respect to device ground and all overshoots due to system and/or tester noise are included.
- 2. I/O pin leakage is the worst case of I_{IL} and I_{OZL} (or I_{IH} and I_{OZH}).
- The dynamic current consumption is: lcc (Total) = lcc (Static) + (CpD + nCL) Vcc (f/2), where f is the clock frequency, C_L = the output load capacitance, and n is the number of loads.

CAPACITANCE (Note 1)

Parameter Symbol	Parameter Descripti	on	Test Condition	ns	Max.	Unit
CiN	Input Capacitance	RESET	V _{IN} = 2.0 V	V _{CC} = 4.5 V to 5.5 V	25	
		Others		T _A = -55°C to +125°C	15	DF
Соит	Output Capacitance		V _{OUT} = 2.0 V	f = 1 MHz	15	1 ' :

Note:

SWITCHING CHARACTERISTICS over MILITARY operating range (for APL Products, Group A, Subgroups 9, 10, 11 are tested unless otherwise noted) (Note 2)

No. Parameter No. Symbol				Н	-25	1
		Parameter	Description	Min.	Max.	Unit
1	tco	CLK to P[15	:0]		25	ns
2		CLK to A[8:	0]		40	ns
3	ts	T[7:0] to CL	K, Registered	10		ns
4		T[7:0] to CL (Note 3)	T[7:0] to CLK, Asynchronous			ns
5		RESET to CLK, Registered		16		ns
6		RESET to CI (Note 2)	K, Asynchronous	40		ns
7	tн	CLK to T[7:0]		0		ns
8	(Note 4)	CLK to RES	ET	0		ns
9	tpzx	CLK to P[15	:8] Enable		40	ns
10	texz	CLK to P[15	:8] Disable		35	ns
11	tw.	CLK Width	LOW	20		ns
12	twn	HIGH		20		ns
13	tр	CLK Period (Note 3)		40		ns
14	f _{MAX}	Maximum Fr	equency (1/t _P)	25		MHz

Note:

- 2. See Switching Test Circuit for test conditions.
- 3. These parameters are measured indirectly on unprogrammed devices. They are determined as follows:
 - a. Measure delay from input (T[7:0], FIESET, or CLK) to EPROM address out in test mode. This will measure the delay through the sequence logic.
 - b. Measure setup time from T[7:0] input through EPROM test columns to pipeline register in verify test column mode. This will measure the delay through the EPROM and register setup.
 - Measure delay from T[7:0] input to EPROM address out in verify test column mode. This will measure the delay through the logic and P[15:0] outputs.

To calculate the desired parameter measurement, the following formula is used:

Measurement (a) + Measurement (b) - Measurement (c)

CLK PERIOD:

CLK (a) + (b) - (c) = CLK PERIOD

T[7:0] to CLK setup time:

T[7:0] (a) + (b) - (c) = T[7:0] to CLK setup time

4. These hold time parameters are tested on a sample basis.

RESET to CLK setup time:

RESET (a) + (b) - (c) = RESET to CLK setup time

These parameters are not 100% tested, but are evaluated at initial characterization and at any time the design is modified where capacitance may be affected.

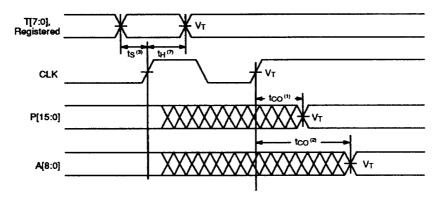
SWITCHING CHARACTERISTICS over MILITARY operating range (Continued)

	Davamatar		***************************************		H-25	
No.	Parameter Symbol	Parameter De	escription	Mir	. Max.	Unit
SSR Co	nfiguration					
15	tpD	Mode to SDO			30	ns
16		SDI to SDO			30	ns
17	tco	DCLK to SDC			30	ns
18	ts	Mode to CLK		30		ns
19		Mode to DCL	<	30		ns
20	1	SDI to DCLK		30		ns
21		P[15:8] to DC	LK	30		กร
22	tн	CLK to Mode		6		ns
23	(Note 1)	DCLK to Mod	e	0		ns
24		DCLK to SDI		0		ns
25		DCLK to P[15	DCLK to P[15:8]			ns
26	twL	DCLK Width	LOW	30		ns
27	twн		HIGH	30		ns
28	tр	DCLK Period		60		ns

Note:

1. These hold time parameters are tested on a sample basis.

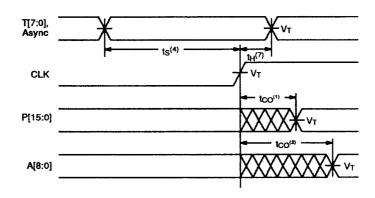
SWITCHING WAVEFORMS Normal Configuration



Registered Test Inputs

10136-028A

10136-029A



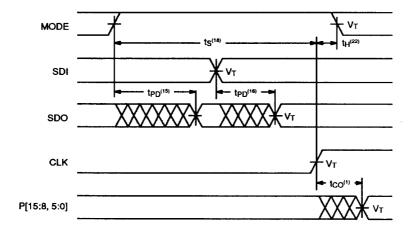
Asynchronous Test Inputs

SWITCHING WAVEFORMS (Continued) Normal Configuration RESET, Registered CLK tco(1) P[15:0] 10136-030A Registered RESET RESET, Async CLK P[15:0] 10136-031A Asynchronous RESET CLK P[15:8] 10136-032A CLK to Output Disable/Enable twH(12) CLK 10136-033A

Am29CPL154

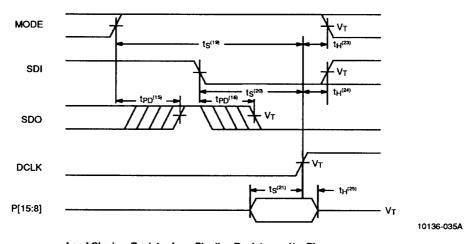
Clock Width/Period

SWITCHING WAVEFORMS (Continued) SSR Configuration



Load Pipeline Register from Shadow Register

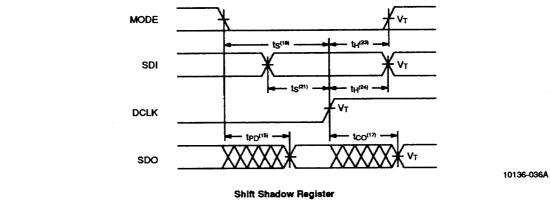
10136-034A



Load Shadow Register from Pipeline Register and/or Pins

3-129

SWITCHING WAVEFORMS (Continued) SSR Configuration

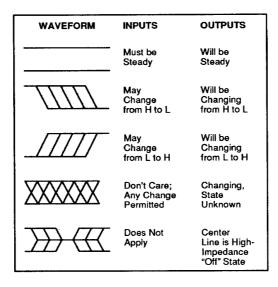


DCLK tp(28)

DCLK Width/Period

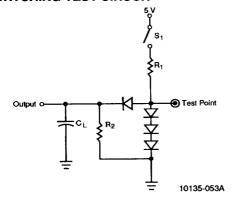
10136-037A

KEY TO SWITCHING WAVEFORMS

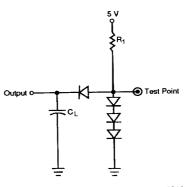


KS000010-PAL

SWITCHING TEST CIRCUIT



Three



10135-054A

-State Outputs	Two-State	Outputs
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			Commercial		Military		Measured
Specification	S ₁	CL	R ₁	R ₂	R₁	R ₂	Output Value
tpp, tco	Closed						1.5 V
tpzx	Z → H: Open Z → L: Closed	50 pF	667 Ω	5 kΩ	667 Ω	5 kΩ	1.5 V
texz	H → Z: Open L → Z: Closed	5 pF					$H \rightarrow Z$: $V_{OH} - 0.5 V$ $L \rightarrow Z$: $V_{OL} + 0.5 V$

Note:

Pulse generator for all pulses: Rate \leq 1.0 MHz; $Z_O = 50~\Omega$: $t_r \leq$ 2.5 ns.

3-130 Am29CPL154

TEST PHILOSOPHY AND METHODS

The following eight points describe AMD's philosophy for high volume, high speed automatic testing.

- Ensure that the part is adequately decoupled at the test head. Large changes in V_{CC} current as the device switches may cause erroneous function failures due to V_{CC} changes.
- Do not leave inputs floating during any tests, as they may start to oscillate at high frequency.
- Do not attempt to perform threshold tests at high speed. Following an output transition, ground current may change by as much as 400 mA in 5–8 ns. Inductance in the ground cable may allow the ground pin at the device to rise by hundreds of millivolts momentarily.
- 4. Use extreme care in defining point input levels for AC tests. Many inputs may be changed at once, so there will be significant noise at the device pins and they may not actually reach V_{IL} or V_{IH} until the noise has settled. AMD recommends using V_{IL} ≤ 0 V and V_{IH} ≥ 3.0 V for AC tests.
- To simplify failure analysis, programs should be designed to perform DC, function, and AC tests as three distinct groups of tests.
- 6. Capacitive Loading for AC Testing

Automatic testers and their associated hardware have stray capacitance that varies from one type of tester to another but is generally around 50 pF. This, of course, makes it impossible to make direct measurements of parameters which call for smaller capacitive load than the associated stray capacitance. Typical examples of this are the so-called "float delays," which measure the propagation delays into the

high-impedance state and are usually specified at a load capacitance of 5.0 pF. In these cases, the test is performed at the higher load capacitance (typically 50 pF), and engineering correlations based on data taken with a bench setup are used to predict the result at the lower capacitance.

7. Threshold Testing

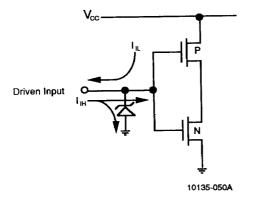
The noise associated with automatic testing (due to the long, inductive cables) and the high gain of the tested device when in the vicinity of the actual device threshold, frequently give rise to oscillations when testing high-speed circuits. These oscillations are not indicative of a reject device but instead of an overtaxed test system. To minimize this problem, thresholds are tested at least once for each input pin. Thereafter, "hard" high and low levels are used for other tests. Generally this means that function and AC testing are performed at "hard" input levels rather than at V_{IL} Max. and V_{IH} Min.

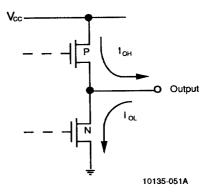
8. AC Testing

Occasionally, parameters are specified that cannot be measured directly on automatic testers because of tester limitations. Data input hold times often fall into this category. In these cases, the parameter in question is guaranteed by correlating these tests with other AC tests that have been performed. These correlations are arrived at by the cognizant engineer by using precise bench measurements in conjunction with the knowledge that certain DC parameters have already been measured and are within spec.

In some cases, certain AC tests are redundant, since they can be shown to be predicted by some other tests which have already been performed. In these cases, the redundant tests are not performed.

INPUT/OUTPUT EQUIVALENT SCHEMATICS





Thermal Inpedance Values (θ_{JA}), Typical 28-Pin Plastic SKINNYDIP (PD3028) 28-Pin Windowed Ceramic SKINNYDIP (CDE028) 28-Pin Plastic Leaded Chip Carrier (PL 028) 28-Pin Windowed Ceramic Leadless Chip Carrier (CLV028)

50°C/W 40°C/W 55°C/W 55°C/W