

Technical description

The KHU8-DW-1.D is a device used to **indicate and monitor periodic signals** which occur in almost all areas of automation and process engineering, i.e. frequencies in general and rotational speeds in particular.

The input signals are evaluated using the cycle method, i.e. by measuring the duration of a period, and then converted by a very fast μ -controller to frequency, or rotational speed.

The frequently occurring special case of rotational speed measurement was given particular attention. For this reason, **indications and inputs** can be either in **Hz** or in **rpm**.

In addition, the possibility exists, on applications involving lengthy processes, whose sensors provide a **number of pulses per revolution**, to operate automatically with the **actual rotational speed** of the drive, by presetting the number of pulses.

Indication of the measured value is achieved by means of a **4-digit 7-segment-LED-display** on the front of the device, with **up to 3 places following the decimal point**.

The monitoring function is actuated by a **limiting value**, whose upper and lower hysteresis values can be **selected** within the appropriate measuring and indicating range.

The **output signal** is generated by a change-over relay when the hysteresis limits are either **exceeded or fallen below**. Due to its high switching capability, the relay output can be used to **directly drive** an actuator, or as an **input signal to a higher level control**.

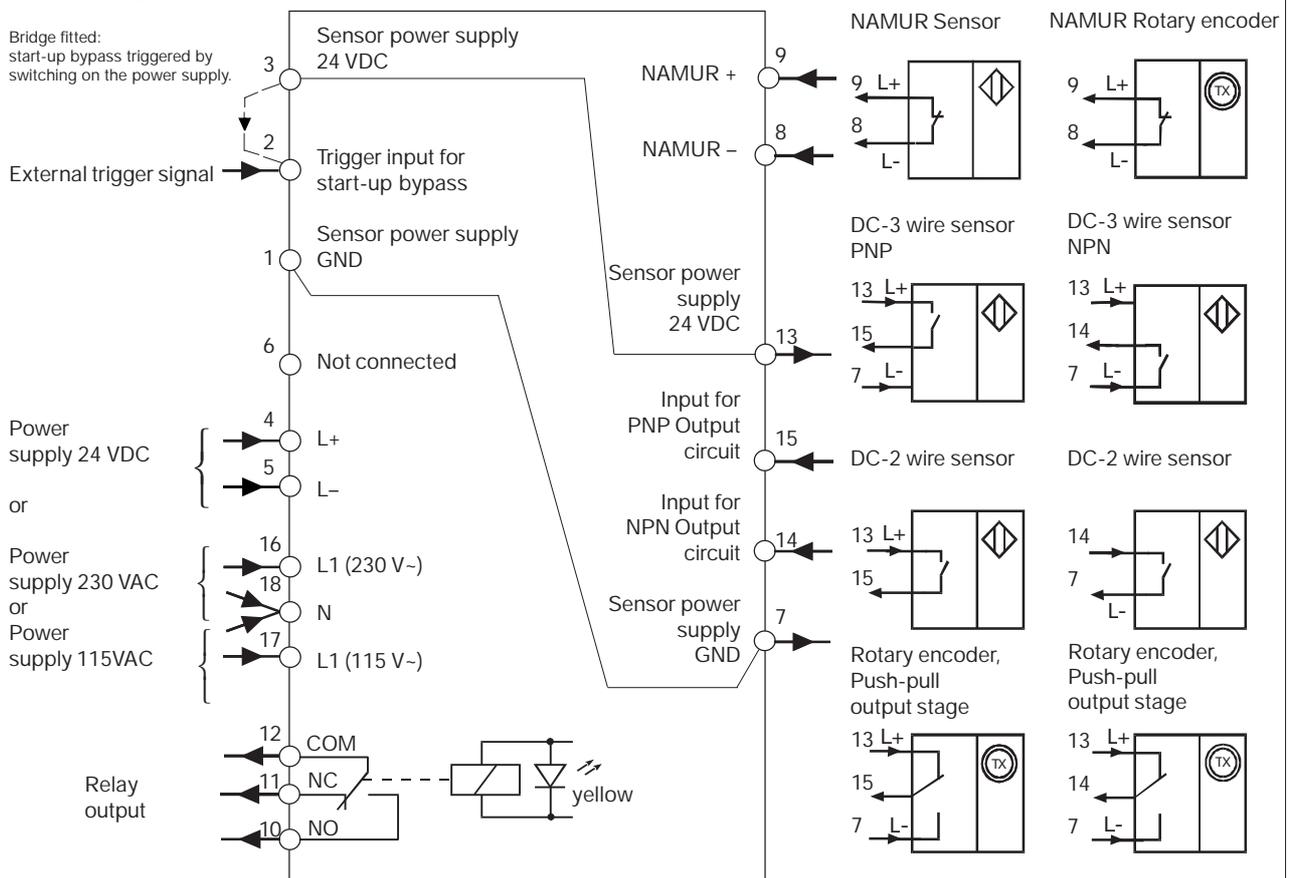
In addition, the switching state of the relay is indicated by a **yellow LED** on the front face of the device.

A function block is connected in line with the output relay, which enables **10 different timer functions** to be employed; thus there is no need to connect a separate timer relay in series. In addition to **ON delay and OFF delay, defined ON time and pulse lengthening**, the **direction of operation of the relay**, i.e. to monitor underspeed or overspeed, can also be selected. The built-in **start-up bypass**, triggered by switching on the supply voltage, or by an external signal, **prevents false signals** from occurring during the start-up of the monitored system.

The speed monitor may be supplied with **115 VAC, 230 VAC or 24 VDC**. When an alternating voltage is connected, a **24 VDC source is available for the signal transducer**.

All currently available **two-, three- or four-wire proximity switches** and incremental **rotary encoders** are acceptable as the **sensor**. Moreover two terminals are reserved for the connection of **proximity switches to DIN 19234 (NAMUR)**.

Connection diagram



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Technical data

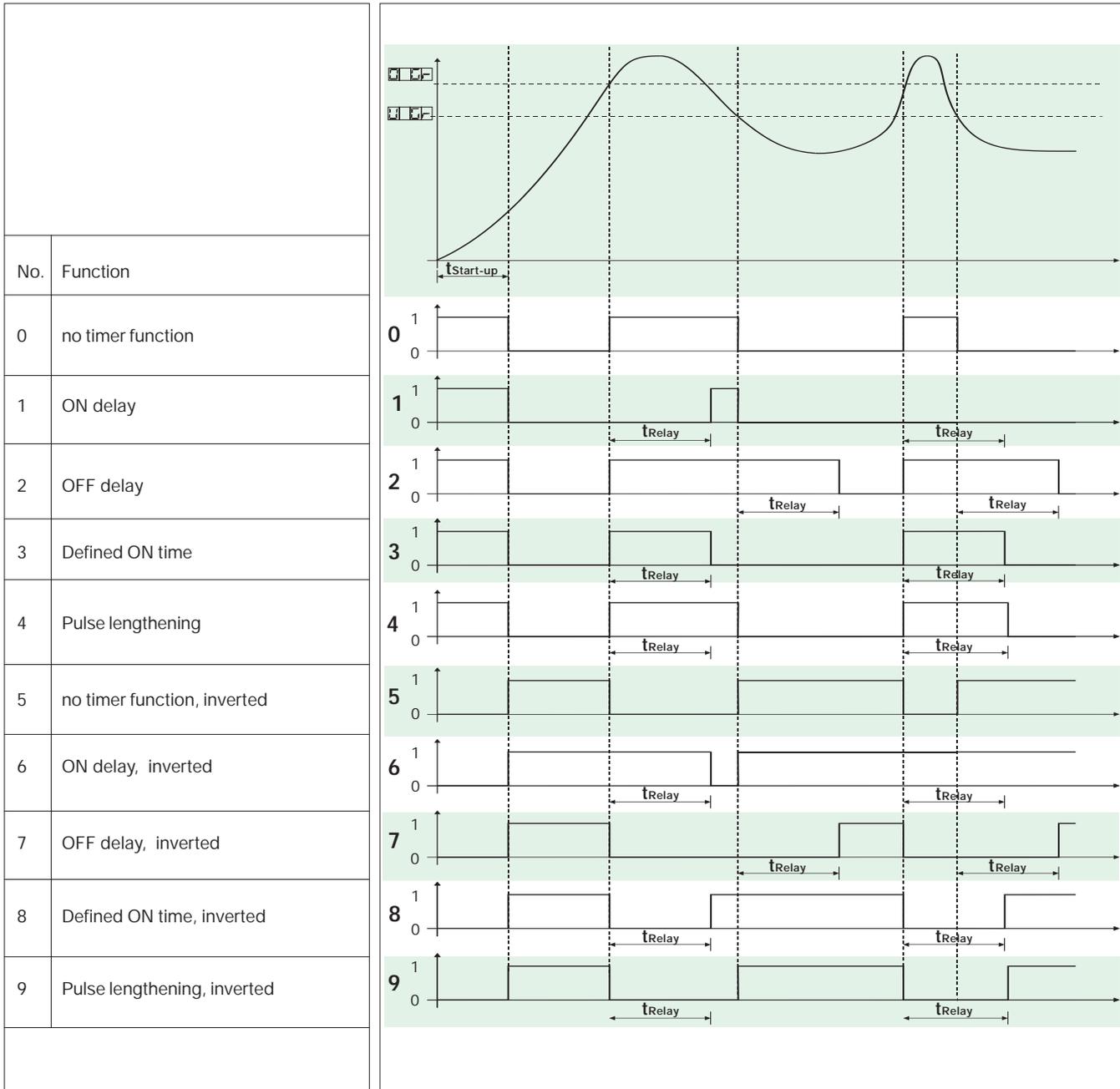
Supply voltages	230 VAC \pm 10 %, 47 Hz ... 63 Hz, < 5 VA (Terminal 16, 18) 115 VAC \pm 10 %, 47 Hz ... 63 Hz, < 5 VA (Terminal 17, 18) 24 VDC +15/-10 %, $u_{ss} \leq$ 10 %, < 5 W (Terminal 4, 5)
Signal inputs	
Frequency	0.001 Hz ... 5000 Hz Minimum pulse length/duration: 20 μ s
NAMUR	Switch points: \geq 1.2 mA; \leq 2.1 mA (Terminal 8, 9) No load voltage: 8.2 V; Short circuit current: 6.5 mA Impedance: 1.2 k Ω
PNP-sensor	Switch point: 12 V (Terminal 15) Max. input voltage: 30 V Impedance: 2.8 k Ω
NPN-sensor	Switch point: 12 V (Terminal 14) Impedance: 3.3 k Ω
Triggerinput	Switch point: 12 V (Terminal 2) Max. input voltage: 30 V Impedance: 2.8 k Ω
Output relay	Terminal 10: NO; Terminal 11: NC; Terminal 12: COM 250 VAC, 2 A, $\cos \phi \geq$ 0.7 40 VDC, 2 A ON/OFF delay (incl. computation time) \leq 20 ms Mechanical life \geq 30 000 000 switch cycles
Switch state indicator	3 mm - yellow LED
Timer functions	ON/OFF delay, defined ON time, pulse lengthening Timer period: 0 s ... 999.9 s
Direction of operation	reversible
Sensor power supply	Terminal 3, 13: L+; Terminal 1, 7: L- 24 VDC \pm 10 %, $U_{ss} \leq$ 10 %, 30 mA short circuit protected
Start-up bypass	Triggered by external signal (Terminal 2) or by switching on the supply voltage (Terminal 2 and Terminal 3 bridged) Bypass time: 0.1 s ... 999.9 s
Error of measurement	0.001 Hz ... 100 Hz: \leq 0.1 % 100 Hz ... 1 kHz: \leq 0.3 % 1 kHz ... 5 kHz: \leq 1.5 % Display: \pm 1 digit
Ready delay	\leq 400 ms
Display rate of rotation and frequency	4-digit 7-segment-LED-display, red, digit height: 7 mm
Design	Modular terminal housing of Makrolon
Mounting	By clipping onto 35 mm standard rail according to DIN EN 50022 or screw mountable by pull-out clip with 90 mm grid
Terminal connections	Self-opening instrument terminals cross sectional area: \leq 2 x 2.5 mm ²
Operating temperature	-25 °C ... +70 °C
Storage temperature	-40 °C ... +85 °C
Protection class	IP 20
EMC to	EN 50081-2, EN 50082-2

4. Terminal allocation

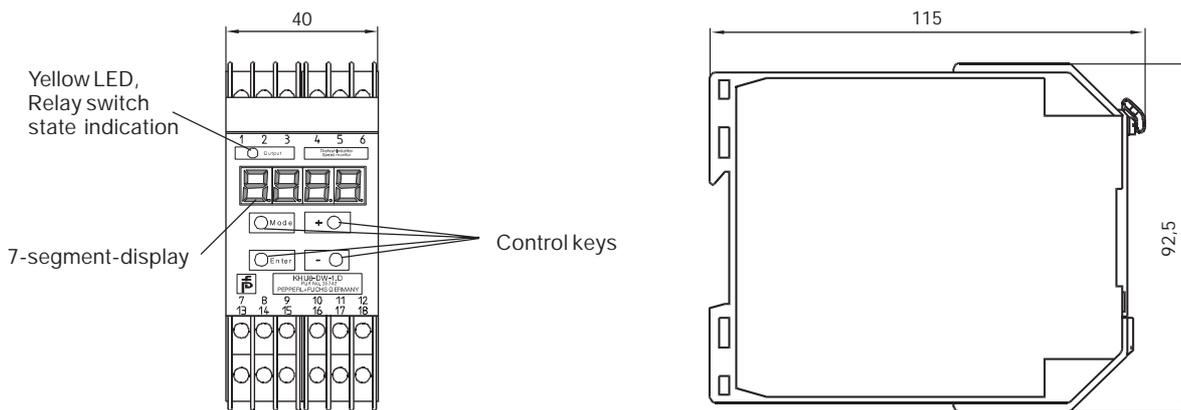
Term. 1: Sensor power supply, GND	Term. 10: Relay normally open contact, NO
Term. 2: Trigger input for start-up bypass	Term. 11: Relay normally close contact, NC
Term. 3: Sensor power supply, 24 VDC	Term. 12: Relay root, COM
Term. 4: Power supply, 24 VDC	Term. 13: Sensor power supply, 24 VDC
Term. 5: Power supply, GND	Term. 14: for NPN-sensor Input
Term. 6: Not connected	Term. 15: for PNP-sensor Input
Term. 7: Sensor power supply, GND	Term. 16: Power supply L1, 230 VAC
Term. 8: NAMUR input L-	Term. 17: Power supply L1, 115 VAC
Term. 9: NAMUR input L+	Term. 18: Power supply N

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Timer functions, reversal of direction of action of the output relay

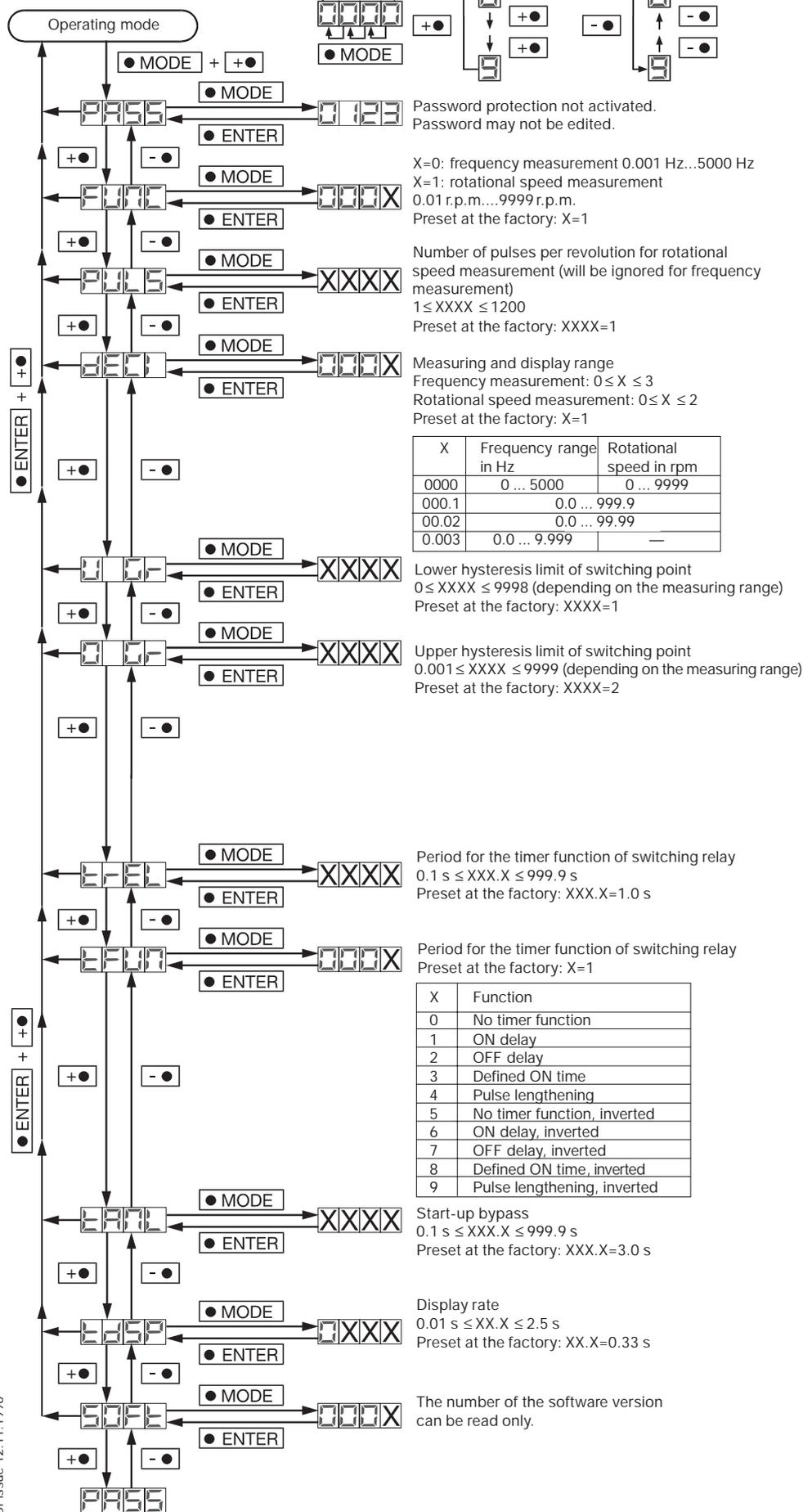


Dimensions, controls and indicators



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Function Description



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