



## ABSOLUTE MAXIMUM RATINGS

(Note 1)

### Input Supplies

$V_{CC}, V_L$  .....  $-0.3V$  to  $7V$

### Generated Supplies

$V_{DD}$  .....  $V_{CC} - 0.3V$  to  $7.5V$

$V_{EE}$  .....  $0.3V$  to  $-7.5V$

$V_{DD} - V_{EE}$  .....  $15V$

SW .....  $-0.3V$  to  $(V_{DD} + 0.3V)$

CAP .....  $0.3V$  to  $(V_{EE} - 0.3V)$

A1, A2, B1, B2, Y1, Y2, Z1, Z2 .....  $-15V$  to  $15V$

DY1, DY2, DZ1, DZ2,  $\overline{RXEN1}$ ,  $\overline{RXEN2}$ , DXEN1, DXEN2,

LB, H/F, TE485\_1, TE485\_2,

485/232\_1, 485/232\_2 .....  $-0.3V$  to  $7V$

FEN, RA1, RA2, RB1, RB2 .....  $-0.3V$  to  $(V_L + 0.3V)$

### Differential Enabled Terminator Voltage

(A1-B1 or A2-B2 or Y1-Z1 or Y2-Z2) .....  $\pm 6V$

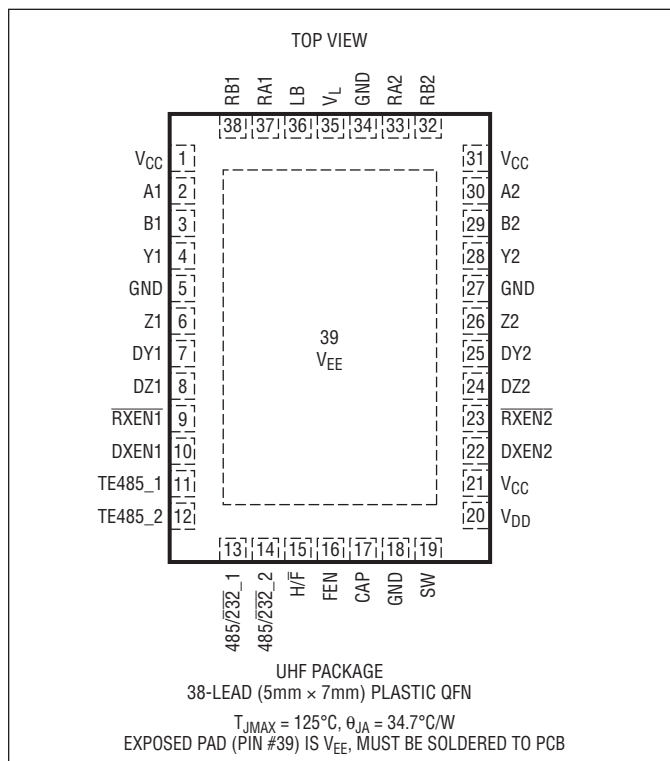
### Operating Temperature

LTC2872C .....  $0^\circ C$  to  $70^\circ C$

LTC2872I .....  $-40^\circ C$  to  $85^\circ C$

Storage Temperature Range .....  $-65^\circ C$  to  $125^\circ C$

## PIN CONFIGURATION



## ORDER INFORMATION

LEAD FREE FINISH	TAPE AND REEL	PART MARKING*	PACKAGE DESCRIPTION	TEMPERATURE RANGE
LTC2872CUHF#PBF	LTC2872CUHF#TRPBF	2872	38-Lead (5mm × 7mm) Plastic QFN	0°C to 70°C
LTC2872IUHF#PBF	LTC2872IUHF#TRPBF	2872	38-Lead (5mm × 7mm) Plastic QFN	-40°C to 85°C

Consult LTC Marketing for parts specified with wider operating temperature ranges. \*The temperature grade is identified by a label on the shipping container. Consult LTC Marketing for information on non-standard lead based finish parts.

For more information on lead free part marking, go to: <http://www.linear.com/leadfree/>

For more information on tape and reel specifications, go to: <http://www.linear.com/tapeandreeel/>

**ELECTRICAL CHARACTERISTICS** The ● denotes the specifications which apply over the full operating temperature range, otherwise specifications are at  $T_A = 25^\circ\text{C}$ .  $V_{CC} = V_L = 3.3\text{V}$ ,  $\text{TE485}_1 = \text{TE485}_2 = 0\text{V}$ ,  $\text{LB} = 0\text{V}$  unless otherwise noted.

SYMBOL	PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS
<b>Power Supply</b>						
$V_{CC}$	Supply Voltage Operating Range		●	3	5.5	V
$V_L$	Logic Supply Voltage Operating Range	$V_L \leq V_{CC}$	●	1.7	$V_{CC}$	V
	$V_{CC}$ Supply Current in Shutdown Mode	$\overline{\text{RXEN1}} = \overline{\text{RXEN2}} = V_L$ , $\text{DXEN1} = \text{DXEN2} = \text{FEN} = \text{H}/\overline{\text{F}} = 0\text{V}$	●	8	60	$\mu\text{A}$
	$V_{CC}$ Supply Current in RS485 Transceiver Mode (Outputs Unloaded) (Note 3)	$485/232\_1 = 485/232\_2 = \text{DXEN1} = \text{DXEN2} = V_L$ , $\overline{\text{RXEN1}} = \overline{\text{RXEN2}} = 0\text{V}$	●	4.5	7	mA
	$V_{CC}$ Supply Current in RS232 Transceiver Mode (Outputs Unloaded) (Note 3)	$\text{DXEN1} = \text{DXEN2} = V_L$ ; $485/232\_1 = 485/232\_2 = \overline{\text{RXEN1}} = \overline{\text{RXEN2}} = 0\text{V}$	●	5.5	8	mA
	$V_L$ Supply Current in RS485 or RS232 Transceiver Mode (Outputs Unloaded)	$\text{DXEN1} = \text{DXEN2} = V_L$ , $\overline{\text{RXEN1}} = \overline{\text{RXEN2}} = 0\text{V}$	●	0	5	$\mu\text{A}$
<b>RS485 Drivers</b>						
$ V_{OD} $	Differential Output Voltage	$R_L = \infty$ , $V_{CC} = 3\text{V}$ (Figure 1) $R_L = 27\Omega$ , $V_{CC} = 4.5\text{V}$ (Figure 1) $R_L = 27\Omega$ , $V_{CC} = 3\text{V}$ (Figure 1) $R_L = 50\Omega$ , $V_{CC} = 3.13\text{V}$ (Figure 1)	● ● ● ●	2.1 1.5 2	6 $V_{CC}$ $V_{CC}$ $V_{CC}$	V V V V
$\Delta V_{OD} $	Difference in Magnitude of Differential Output Voltage for Complementary Output States	$R_L = 27\Omega$ , $V_{CC} = 3\text{V}$ (Figure 1) $R_L = 50\Omega$ , $V_{CC} = 3.13\text{V}$ (Figure 1)	● ●		0.2 0.2	V V
$V_{OC}$	Common Mode Output Voltage	$R_L = 27\Omega$ or $50\Omega$ (Figure 1)	●		3	V
$\Delta V_{OC} $	Difference in Magnitude of Common Mode Output Voltage for Complementary Output States	$R_L = 27\Omega$ or $50\Omega$ (Figure 1)	●		0.2	V
$I_{OZD485}$	Three-State (High Impedance) Output Current	$V_{OUT} = 12\text{V}$ or $-7\text{V}$ , $V_{CC} = 0\text{V}$ or $3.3\text{V}$ (Figure 2)	●	-100	125	$\mu\text{A}$
$I_{OSD485}$	Maximum Short-Circuit Current	$-7\text{V} \leq V_{OUT} \leq 12\text{V}$ (Figure 2)	●	-250	250	mA
<b>RS485 Receiver</b>						
$I_{IN485}$	Input Current	$V_{IN} = 12\text{V}$ or $-7\text{V}$ , $V_{CC} = 0\text{V}$ or $3.3\text{V}$ (Figure 3) (Note 5)	●	-100	125	$\mu\text{A}$
$R_{IN485}$	Input Resistance	$V_{IN} = 12\text{V}$ or $-7\text{V}$ , $V_{CC} = 0\text{V}$ or $3.3\text{V}$ (Figure 3) (Note 5)		125		k $\Omega$
	Differential Input Signal Threshold Voltage (A–B)	$-7\text{V} \leq (\text{A or B}) \leq 12$ (Note 5)	●		$\pm 200$	mV
	Differential Input Signal Hysteresis	$B = 0\text{V}$ (Notes 3, 5)		190		mV
	Differential Input DC Failsafe Threshold Voltage (A–B)	$-7\text{V} \leq (\text{A or B}) \leq 12$ (Note 5)	●	-200	-65 0	mV
	Differential Input DC Failsafe Hysteresis	$B = 0\text{V}$ (Note 5)		30		mV
$V_{OL}$	Output Low Voltage	Output Low, $I(\text{RA}) = 3\text{mA}$ (Sinking), $3\text{V} \leq V_L \leq 5.5\text{V}$	●		0.4	V
		Output Low, $I(\text{RA}) = 1\text{mA}$ (Sinking), $1.7\text{V} \leq V_L < 3\text{V}$	●		0.4	V
$V_{OH}$	Output High Voltage	Output High, $I(\text{RA}) = -3\text{mA}$ (Sourcing), $3\text{V} \leq V_L \leq 5.5\text{V}$	●	$V_L - 0.4$		V
		Output High, $I(\text{RA}) = -1\text{mA}$ (Sourcing), $1.7\text{V} \leq V_L < 3\text{V}$	●	$V_L - 0.4$		V
	Three-State (High Impedance) Output Current	$0\text{V} \leq \text{RA} \leq V_L$ , $V_L = 5.5\text{V}$	●	0	$\pm 5$	$\mu\text{A}$
	Short-Circuit Output Current	$0\text{V} \leq \text{RA} \leq V_L$ , $V_L = 5.5\text{V}$	●		$\pm 135$	mA
$R_{\text{TERM}}$	Terminating Resistor	$\text{TE485} = V_L$ , $\text{A–B} = 2\text{V}$ , $\text{B} = -7\text{V}, 0\text{V}, 10\text{V}$ (Figure 8) (Note 5)	●	108	120 156	$\Omega$

## ELECTRICAL CHARACTERISTICS

The ● denotes the specifications which apply over the full operating temperature range, otherwise specifications are at  $T_A = 25^\circ\text{C}$ .  $V_{CC} = V_L = 3.3\text{V}$ ,  $\text{TE485}_1 = \text{TE485}_2 = 0\text{V}$ ,  $\text{LB} = 0\text{V}$  unless otherwise noted.

SYMBOL	PARAMETER	CONDITIONS		MIN	TYP	MAX	UNITS
<b>RS232 Driver</b>							
$V_{OLD}$	Output Low Voltage	$R_L = 3\text{k}\Omega$ , $V_{EE} \leq -6\text{V}$	●	-5	-5.7	$V_{EE}$	V
$V_{OHD}$	Output High Voltage	$R_L = 3\text{k}\Omega$ , $V_{DD} \geq 6.5\text{V}$	●	5	6.2	$V_{DD}$	V
	Three-State (High Impedance) Output Current	$Y$ or $Z = \pm 15\text{V}$	●			$\pm 156$	$\mu\text{A}$
	Output Short-Circuit Current	$Y$ or $Z = 0\text{V}$	●		$\pm 35$	$\pm 90$	$\text{mA}$
<b>RS232 Receiver</b>							
	Input Threshold Voltage		●	0.6	1.5	2.5	V
	Input Hysteresis		●	0.1	0.4	1.0	V
	Output Low Voltage	$I(\text{RA}, \text{RB}) = 1\text{mA}$ (Sinking), $1.7\text{V} \leq V_L \leq 5.5\text{V}$	●			0.4	V
	Output High Voltage	$I(\text{RA}, \text{RB}) = -1\text{mA}$ (Sourcing), $1.7\text{V} \leq V_L \leq 5.5\text{V}$	●	$V_L - 0.4$			V
	Input Resistance	$-15\text{V} \leq (\text{A}, \text{B}) \leq 15\text{V}$ , Receiver Enabled	●	3	5	7	$\text{k}\Omega$
	Three-State (High Impedance) Output Current	$0\text{V} \leq (\text{RA}, \text{RB}) \leq V_L$	●		0	$\pm 5$	$\mu\text{A}$
	Output Short-Circuit Current	$V_L = 5.5\text{V}$ , $0\text{V} \leq (\text{RA}, \text{RB}) \leq V_L$	●		$\pm 25$	$\pm 50$	$\text{mA}$
<b>Logic Inputs</b>							
	Threshold Voltage		●	0.4		$0.75 \cdot V_L$	V
	Input Current		●		0	$\pm 5$	$\mu\text{A}$
<b>Power Supply Generator</b>							
$V_{DD}$	Regulated $V_{DD}$ Output Voltage	RS232 Drivers Enabled, Outputs Loaded with $R_L = 3\text{k}\Omega$ to GND, $\text{DY1} = \text{DY2} = V_L$ , $\text{DZ1} = \text{DZ2} = 0\text{V}$ (Note 3)			7		V
$V_{EE}$	Regulated $V_{EE}$ Output Voltage				-6.3		V
<b>ESD</b>							
	Interface Pins (A, B, Y, Z)	Human Body Model to GND or $V_{CC}$ , Powered or Unpowered (Note 7)			$\pm 16$		$\text{kV}$
	All Other Pins	Human Body Model (Note 7)			$\pm 4$		$\text{kV}$

## SWITCHING CHARACTERISTICS

The ● denotes the specifications which apply over the full operating temperature range, otherwise specifications are at  $T_A = 25^\circ\text{C}$ .  $V_{CC} = V_L = 3.3\text{V}$ ,  $\text{TE485}_1 = \text{TE485}_2 = 0\text{V}$ ,  $\text{LB} = 0\text{V}$  unless otherwise noted.  $V_L \leq V_{CC}$ .

SYMBOL	PARAMETER	CONDITIONS		MIN	TYP	MAX	UNITS
<b>RS485 AC Characteristics</b>							
	Maximum Data Rate	(Note 3)	●	20			Mbps
$t_{\text{PLHD485}}$ $t_{\text{PHLD485}}$	Driver Propagation Delay	$R_{\text{DIFF}} = 54\Omega$ , $C_L = 100\text{pF}$ (Figure 4)	●		20	70	ns
	Driver Propagation Delay Difference $ t_{\text{PLHD485}} - t_{\text{PHLD485}} $	$R_{\text{DIFF}} = 54\Omega$ , $C_L = 100\text{pF}$ (Figure 4)	●		1	6	ns
$t_{\text{SKEWD485}}$	Driver Skew (Y to Z)	$R_{\text{DIFF}} = 54\Omega$ , $C_L = 100\text{pF}$ (Figure 4)	●		1.5	$\pm 8$	ns
$t_{\text{RD485}}$ , $t_{\text{FD485}}$	Driver Rise or Fall Time	$R_{\text{DIFF}} = 54\Omega$ , $C_L = 100\text{pF}$ (Figure 4)	●		7.6	15	ns
$t_{\text{ZLD485}}$ , $t_{\text{ZHD485}}$ , $t_{\text{LZD485}}$ , $t_{\text{HZD485}}$	Driver Output Enable or Disable Time	$\text{FEN} = V_L$ , $R_L = 500\Omega$ , $C_L = 50\text{pF}$ (Figure 5)	●			120	ns
$t_{\text{ZHSD485}}$ , $t_{\text{ZLSD485}}$	Driver Enable from Shutdown	$\text{FEN} = 0\text{V}$ , $R_L = 500\Omega$ , $C_L = 50\text{pF}$ (Figure 5)	●		0.2	2	ms
$t_{\text{PLHR485}}$ , $t_{\text{PHLR485}}$	Receiver Input to Output	$C_L = 15\text{pF}$ , $V_{\text{CM}} = 1.5\text{V}$ , $ A-B  = 1.5\text{V}$ , (Figure 6) (Note 5)	●		55	85	ns
$t_{\text{SKEWR485}}$	Differential Receiver Skew $ t_{\text{PLHR485}} - t_{\text{PHLR485}} $	$C_L = 15\text{pF}$ (Figure 6)	●		1	9	ns
$t_{\text{RR485}}$ , $t_{\text{FR485}}$	Receiver Output Rise or Fall Time	$C_L = 15\text{pF}$ (Figure 6)	●		3	15	ns
$t_{\text{ZLR485}}$ , $t_{\text{ZHR485}}$ $t_{\text{LZR485}}$ , $t_{\text{HZR485}}$	Receiver Output Enable or Disable Time	$\text{FEN} = V_L$ , $R_L = 1\text{k}$ , $C_L = 15\text{pF}$ (Figure 7)	●		30	85	ns
$t_{\text{RTEN485}}$ , $t_{\text{RTZ485}}$	Termination Enable or Disable Time	$\text{FEN} = V_L$ , $V_B = 0\text{V}$ , $V_{\text{AB}} = 2\text{V}$ (Figure 8) (Note 5)	●			100	$\mu\text{s}$
<b>RS232 AC Characteristics</b>							
	Maximum Data Rate	$R_L = 3\text{k}\Omega$ , $C_L = 2500\text{pF}$ , $R_L = 3\text{k}\Omega$ , $C_L = 500\text{pF}$ (Note 3)	● ●	100 500			kbps kbps
	Driver Slew Rate (Figure 9)	$R_L = 3\text{k}\Omega$ , $C_L = 2500\text{pF}$ $R_L = 3\text{k}\Omega$ , $C_L = 50\text{pF}$	● ●	4		30	$\text{V}/\mu\text{s}$ $\text{V}/\mu\text{s}$
$t_{\text{PHLD232}}$ , $t_{\text{PLHD232}}$	Driver Propagation Delay	$R_L = 3\text{k}\Omega$ , $C_L = 50\text{pF}$ (Figure 9)	●		1	2	$\mu\text{s}$
$t_{\text{SKEWD232}}$	Driver Skew	$R_L = 3\text{k}\Omega$ , $C_L = 50\text{pF}$ (Figure 9)			50		ns
$t_{\text{ZLD232}}$ , $t_{\text{ZHD232}}$ $t_{\text{LZD232}}$ , $t_{\text{HZD232}}$	Driver Output Enable or Disable Time	$\text{FEN} = V_L$ , $R_L = 3\text{k}\Omega$ , $C_L = 50\text{pF}$ (Figure 10)	●		0.4	2	$\mu\text{s}$
$t_{\text{PHLR232}}$ , $t_{\text{PLHR232}}$	Receiver Propagation Delay	$C_L = 150\text{pF}$ (Figure 11)	●		60	200	ns
$t_{\text{SKEWR232}}$	Receiver Skew	$C_L = 150\text{pF}$ (Figure 11)			25		ns
$t_{\text{RR232}}$ , $t_{\text{FR232}}$	Receiver Rise or Fall Time	$C_L = 150\text{pF}$ (Figure 11)	●		60	200	ns
$t_{\text{ZLR232}}$ , $t_{\text{ZHR232}}$ , $t_{\text{LZR232}}$ , $t_{\text{HZR232}}$	Receiver Output Enable or Disable Time	$\text{FEN} = V_L$ , $R_L = 1\text{k}\Omega$ , $C_L = 150\text{pF}$ (Figure 12)	●		0.7	2	$\mu\text{s}$
<b>Power Supply Generator</b>							
	$V_{\text{DD}}/V_{\text{EE}}$ Supply Rise Time	$\text{FEN} = \overline{\text{F}}$ , (Notes 3 and 4)	●		0.2	2	ms

**Note 1:** Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. Exposure to any Absolute Maximum Rating condition for extended periods may affect device reliability and lifetime.

**Note 2:** All currents into device pins are positive; all currents out of device pins are negative. All voltages are referenced to device ground unless otherwise specified.

**Note 3:** Guaranteed by other measured parameters and not tested directly.

**Note 4:** Time from  $\text{FEN} = \overline{\text{F}}$  until  $V_{\text{DD}} \geq 5\text{V}$  and  $V_{\text{EE}} \leq -5\text{V}$ . External components as shown in typical application.

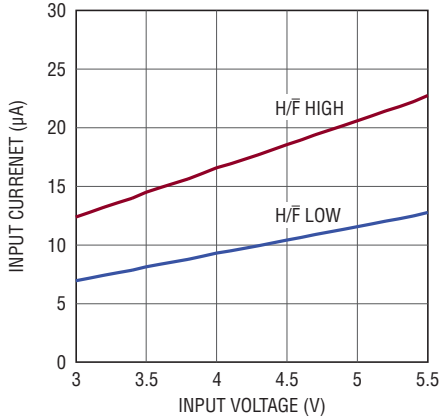
**Note 5:** Condition applies to A, B for  $\text{H}/\overline{\text{F}} = 0\text{V}$ , and Y, Z for  $\text{H}/\overline{\text{F}} = V_L$ .

**Note 6:** This IC includes overtemperature protection that is intended to protect the device during momentary overload conditions. Overtemperature protection activates at a junction temperature exceeding  $150^\circ\text{C}$ . Continuous operation above the specified maximum operating junction temperature may result in device degradation or failure.

**Note 7:** Guaranteed by design and not subject to production test.

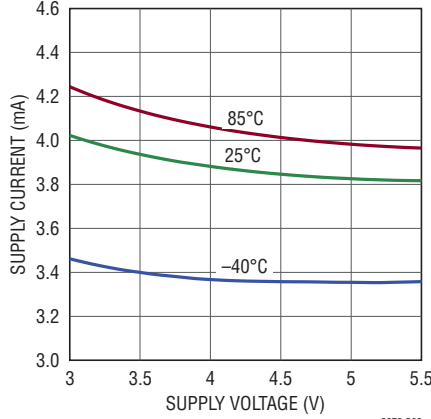
TYPICAL PERFORMANCE CHARACTERISTICS

V<sub>CC</sub> Supply Current vs Supply Voltage in Shutdown Mode



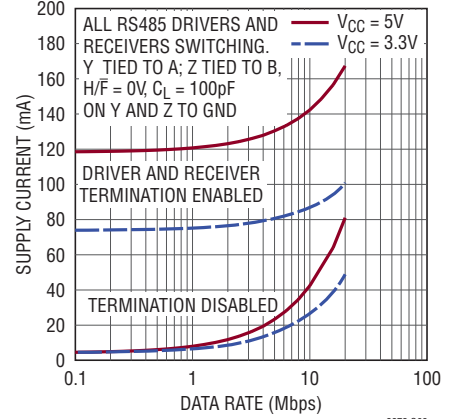
2872 G01

V<sub>CC</sub> Supply Current vs Supply Voltage in Fast Enable Mode



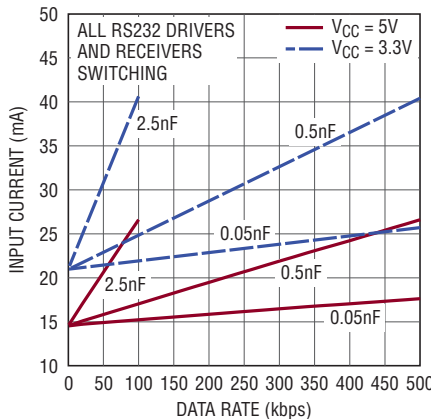
2872 G02

V<sub>CC</sub> Supply Current vs RS485 Data Rate



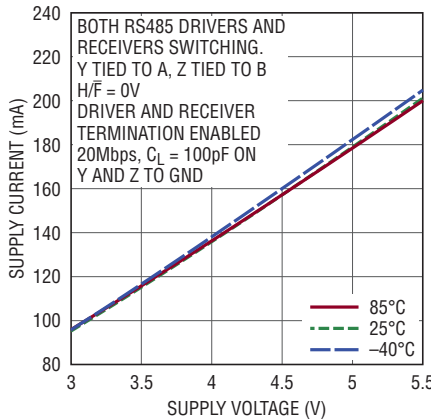
2872 G03

V<sub>CC</sub> Supply Current vs RS232 Data Rate



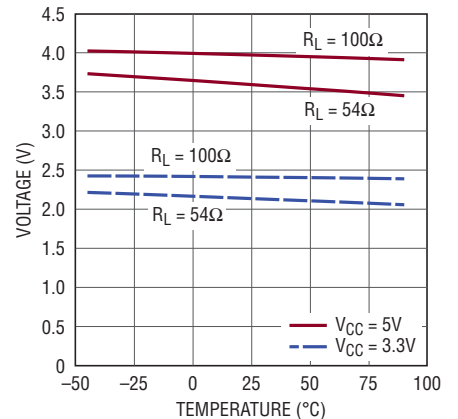
2872 G04

V<sub>CC</sub> Supply Current vs Supply Voltage for RS485 at Maximum Data Rate



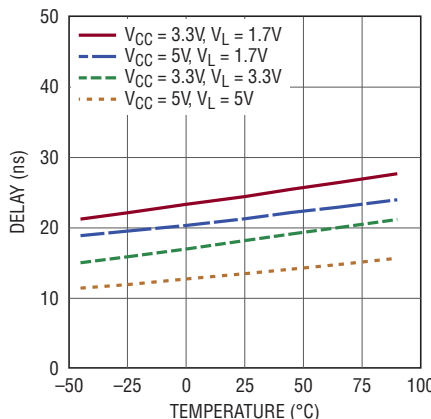
2872 G05

RS485 Driver Differential Output Voltage vs Temperature



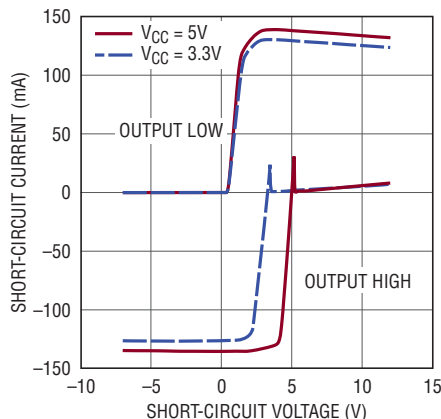
2872 G06

RS485 Driver Propagation Delay vs Temperature



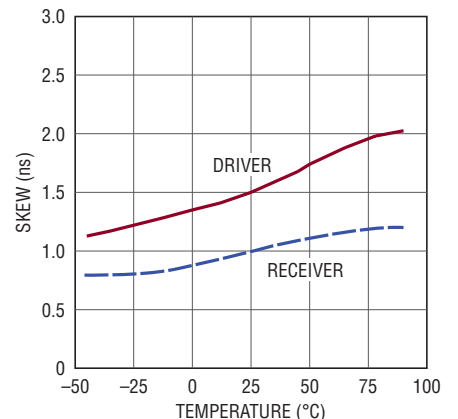
2872 G07

RS485 Driver Short-Circuit Current vs Short-Circuit Voltage



2872 G08

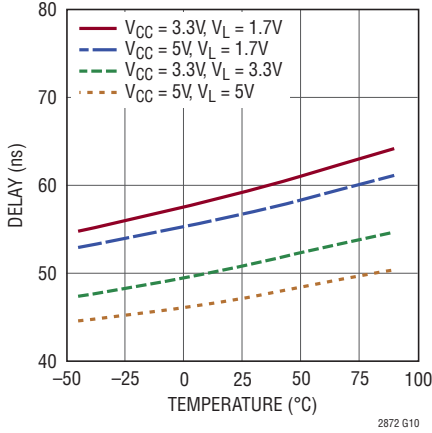
RS485 Driver and Receiver Skew vs Temperature



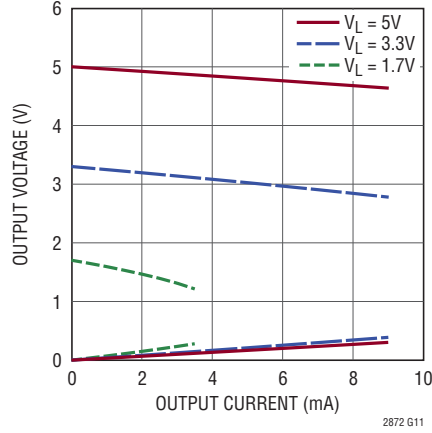
2872 G09

# TYPICAL PERFORMANCE CHARACTERISTICS

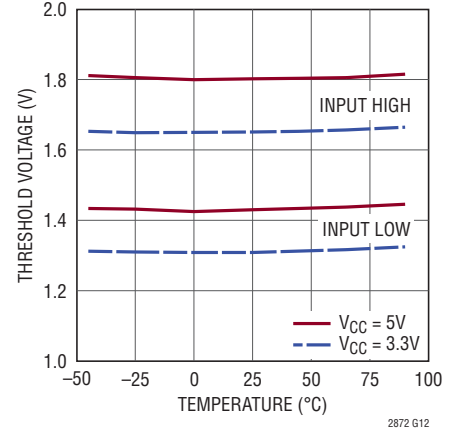
**RS485 Receiver Propagation Delay vs Temperature**



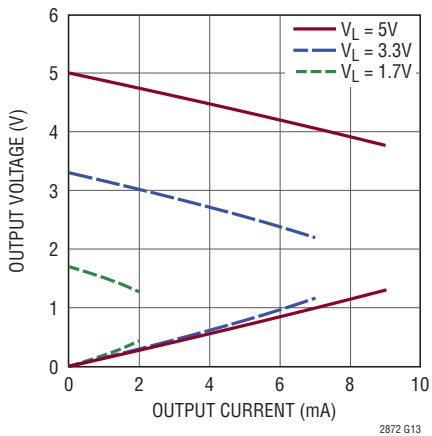
**RS485 Receiver Output Voltage vs Load Current**



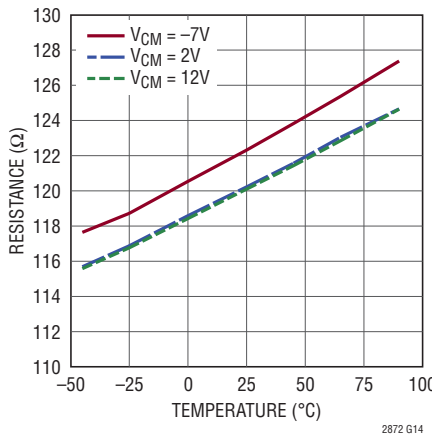
**RS232 Receiver Input Threshold vs Temperature**



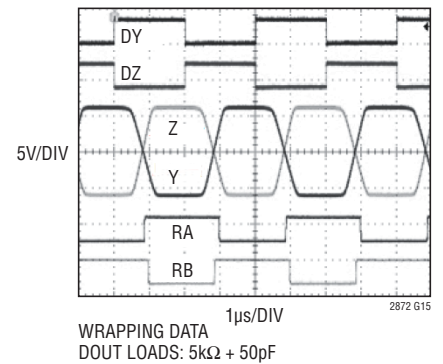
**RS232 Receiver Output Voltage vs Load Current**



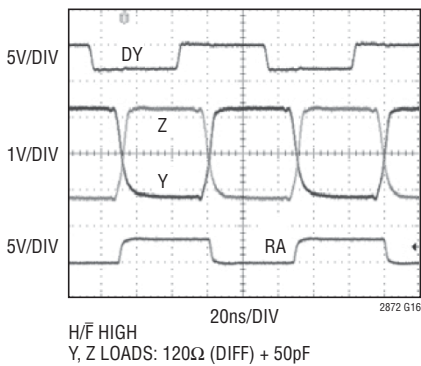
**RS485 Termination Resistance vs Temperature**



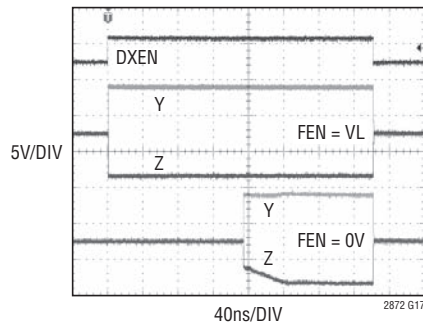
**RS232 Operation at 500kbps**



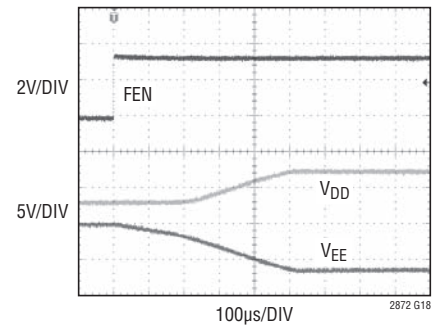
**RS485 Operation at 20Mbps**



**RS232 Driver Outputs Enabling and Disabling**



**VDD and VEE Powering Up**



## PIN FUNCTIONS

**V<sub>CC</sub> (Pins 1, 21, 31):** Input Supply (3.0V to 5.5V). Tie all three pins together and connect 2.2 $\mu$ F capacitor between V<sub>CC</sub> and GND.

**V<sub>L</sub> (Pin 35):** Logic Supply (1.7V to 5.5V) for the receiver outputs, driver inputs, and control inputs. This pin should be bypassed to GND with a 0.1 $\mu$ F capacitor if it is not tied to V<sub>CC</sub>. V<sub>L</sub> must be less than or equal to V<sub>CC</sub> for proper operation.

**V<sub>DD</sub> (Pin 20):** Generated Positive Supply Voltage for RS232 Driver (7V). Connect 2.2 $\mu$ F capacitor between V<sub>DD</sub> and GND.

**V<sub>EE</sub> (Pin 39):** Generated Negative Supply Voltage for RS232 Driver (-6.3V). Tie all pins together and connect 2.2 $\mu$ F capacitor between V<sub>EE</sub> and GND.

**GND (Pins 5, 18, 27, 34):** Ground. Tie all four pins together.

**CAP (Pin 17):** Charge Pump Capacitor for Generated Negative Supply Voltage. Connect a 470nF capacitor between CAP and SW.

**SW (Pin 19):** Switch Pin. Connect 22 $\mu$ H inductor between SW and V<sub>CC</sub>.

**A1 (Pin 2):** RS485 Differential Receiver #1 Positive Input (Full-Duplex Mode) or RS232 Receiver #1a Input.

**A2 (Pin 30):** RS485 Differential Receiver #2 Positive Input (Full-Duplex Mode) or RS232 Receiver #2a Input.

**B1 (Pin 3):** RS485 Differential Receiver #1 Negative Input (Full-Duplex Mode) or RS232 Receiver #1b Input.

**B2 (Pin 29):** RS485 Differential Receiver #1 Negative Input (Full-Duplex Mode) or RS232 Receiver #2b Input.

**RA1 (Pin 37):** RS485 Differential Receiver #1 Output or RS232 Receiver #1a Output.

**RA2 (Pin 33):** RS485 Differential Receiver #2 Output or RS232 Receiver #2a Output.

**RB1 (Pin 38):** RS232 Receiver #1b Output.

**RB2 (Pin 32):** RS232 Receiver #2b Output.

**DY1 (Pin 7):** RS485 Differential Driver #1 Input or RS232 Driver #1y Input.

**DY2 (Pin 25):** RS485 Differential Driver #2 Input or RS232 Driver #2y Input.

**DZ1 (Pin 8):** RS232 Driver #1z Input.

**DZ2 (Pin 24):** RS232 Driver #2z Input.

**Y1 (Pin 4):** RS485 Differential Driver #1 Positive Output or RS232 Driver #1y Output, RS485 Differential Receiver #1 Positive Input (Half-Duplex Mode).

**Y2 (Pin 28):** RS485 Differential Driver #2 Positive Output or RS232 Driver #2y Output, RS485 Differential Receiver #2 Positive Input (Half-Duplex Mode).

**Z1 (Pin 6):** RS485 Differential Driver #1 Negative Output or RS232 Driver #1z Output, RS485 Differential Receiver #1 Negative Input (Half-Duplex Mode).

**Z2 (Pin 26):** RS485 Differential Driver #2 Negative Output or RS232 Driver #2z Output, RS485 Differential Receiver #2 Negative Input (Half-Duplex Mode).

**485/232\_1 (Pin 13):** Interface Select #1 Input. A logic low enables RS232 mode and a high enables RS485 mode for transceiver #1. The mode determines which transceiver inputs and outputs are accessible at the LTC2872 pins as well as which is controlled by the driver and receiver enable pins.

**485/232\_2 (Pin 14):** Interface Select #2 Input. A logic low enables RS232 mode and a high enables RS485 mode for transceiver #2. The mode determines which transceiver inputs and outputs are accessible at the LTC2872 pins as well as which is controlled by the driver and receiver enable pins.

**RXEN1 (Pin 9):** Receivers #1 Enable. A logic high disables RS232 and RS485 receivers in transceiver #1, leaving their outputs Hi-Z. A logic low enables the RS232 or RS485 receivers in transceiver #1, depending on the state of the Interface Select Input 485/232\_1.

**RXEN2 (Pin 23):** Receivers #2 Enable. A logic high disables RS232 and RS485 receivers in transceiver #2, leaving their outputs Hi-Z. A logic low enables the RS232 or RS485 receivers in transceiver #2, depending on the state of the Interface Select Input 485/232\_2.



## PIN FUNCTIONS

**DXEN1 (Pin 10):** Drivers #1 Enable. A logic low disables the RS232 and RS485 drivers in transceiver #1, leaving their outputs in a Hi-Z state. A logic high enables the RS232 or RS485 drivers in transceiver #1, depending on the state of the Interface Select Input 485/232\_1.

**DXEN2 (Pin 22):** Drivers #2 Enable. A logic low disables the RS232 and RS485 drivers in transceiver #2, leaving their outputs in a Hi-Z state. A logic high enables the RS232 or RS485 drivers in transceiver #2, depending on the state of the Interface Select Input 485/232\_2.

**TE485\_1 (Pin 11):** RS485 Termination Enable for Transceiver #1. A logic high enables a 120Ω resistor between pins A1 and B1. If DZ1 is also high, a 120Ω resistor is enabled between pins Y1 and Z1. A logic low on TE485\_1 opens the resistors, leaving A1/B1 and Y1/Z1 unterminated, independent of DZ1. The differential termination resistors are never enabled in RS232 mode.

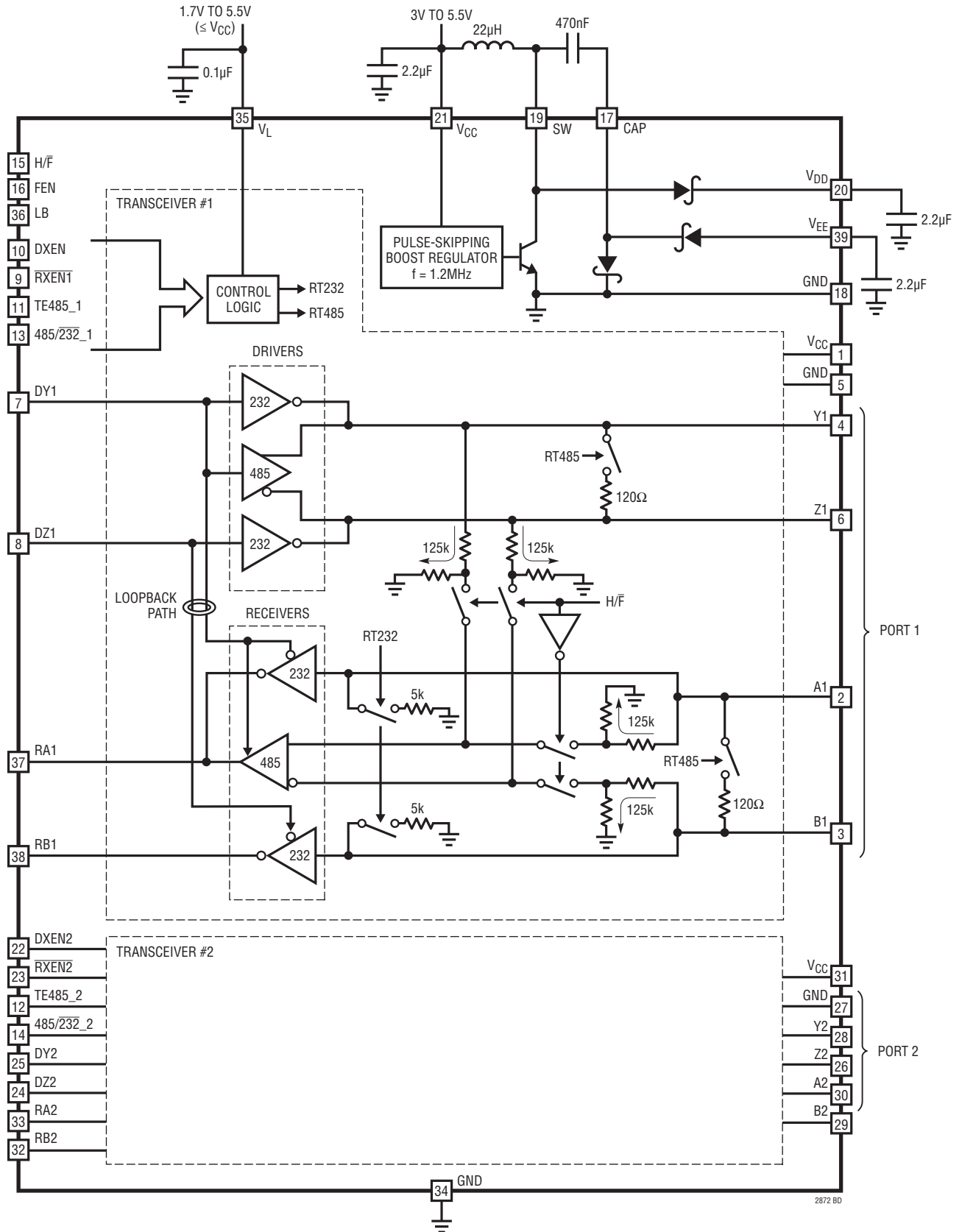
**TE485\_2 (Pin 12):** RS485 Termination Enable for Transceiver #2. A logic high enables a 120Ω resistor between pins A2 and B2. If DZ2 is also high, a 120Ω resistor is enabled between pins Y2 and Z2. A logic low on TE485\_2 opens the resistors, leaving A2/B2 and Y2/Z2 unterminated, independent of DZ2. The differential termination resistors are never enabled in RS232 mode.

**H/ $\bar{F}$  (Pin 15):** RS485 Half-duplex Select Input for Transceivers #1 and #2. A logic low is used for full duplex operation where pins A and B are the receiver inputs and pins Y and Z are the driver outputs. A logic high is used for half duplex operation where pins Y and Z are both the receiver inputs and driver outputs and pins A and B do not serve as the receiver inputs. The impedance on A and B and state of differential termination between A and B is independent of the state of H/ $\bar{F}$ . The H/ $\bar{F}$  pin has no effect on RS232 operation.

**FEN (Pin 16):** Fast Enable. A logic high enables Fast Enable Mode. In fast enable mode the integrated DC/DC converter is active independent of the state of driver, receiver, and termination enable pins allowing faster circuit enable times than are otherwise possible. A logic low disables Fast Enable Mode leaving the state of the DC/DC converter dependent on the state of driver, receiver, and termination enable control inputs. The DC/DC converter powers down only when FEN is low and all drivers, receivers, and terminators are disabled (refer to Table 1).

**LB (Pin 36):** Loopback Enable for Transceivers #1 and #2. A logic high enables Logic Loopback diagnostic mode, internally routing the driver input logic levels to the receiver output pins within the same transceiver. This applies to both RS232 channels as well as the RS485 driver/receiver. The targeted receiver must be enabled for the loopback signal to be available on its output. A logic low disables loopback mode. In loopback mode, signals are not inverted from driver inputs to receiver outputs.

**BLOCK DIAGRAM**



# TEST CIRCUITS

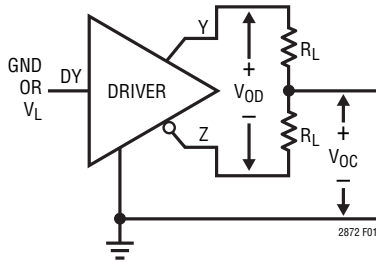


Figure 1. RS485 Driver DC Characteristics

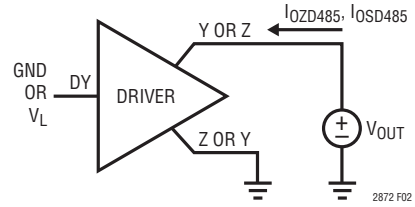


Figure 2. RS485 Driver Output Short-Circuit Current

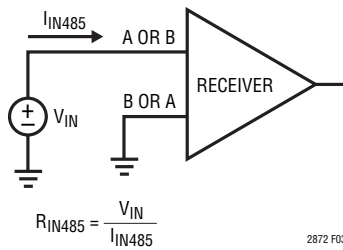


Figure 3. RS485 Receiver Input Current and Resistance (Note 5)

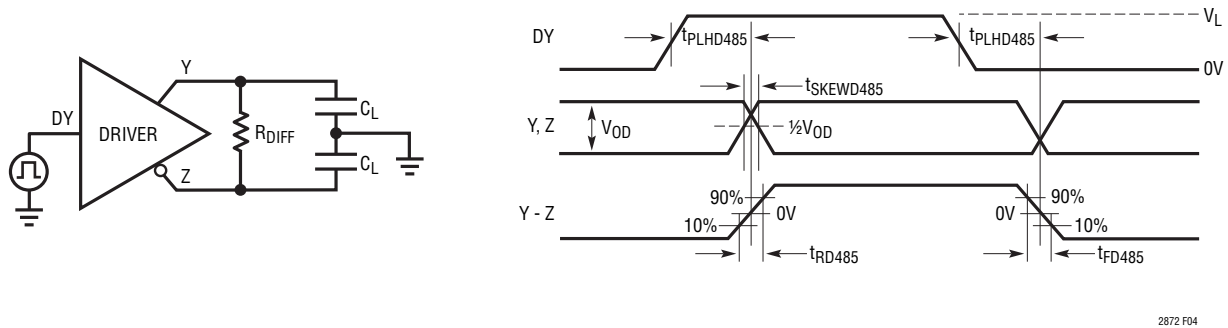
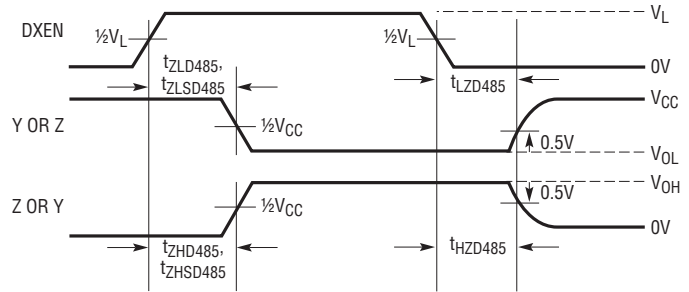
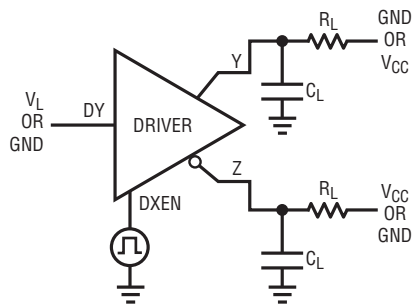


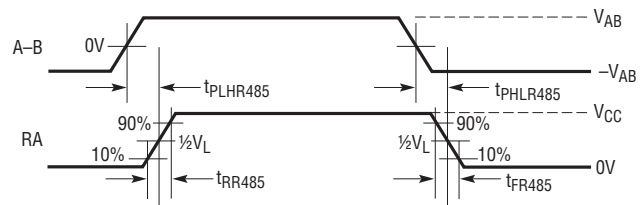
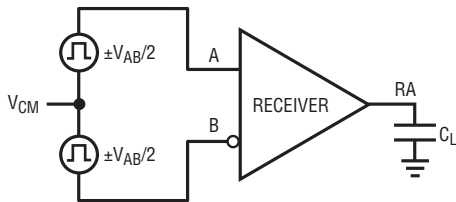
Figure 4. RS485 Driver Timing Measurement

TEST CIRCUITS



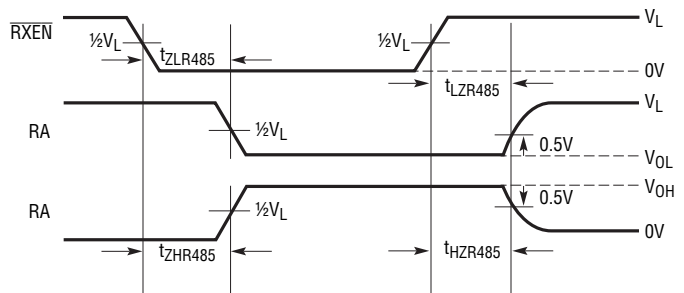
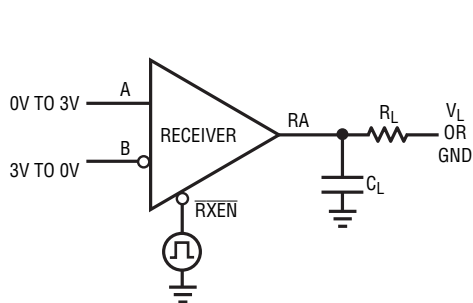
2872 F05

Figure 5. RS485 Driver Enable and Disable Timing Measurements



2872 F06

Figure 6. RS485 Receiver Propagation Delay Measurements (Note 5)



2872 F07

Figure 7. RS485 Receiver Enable and Disable Timing Measurements (Note 5)

# TEST CIRCUITS

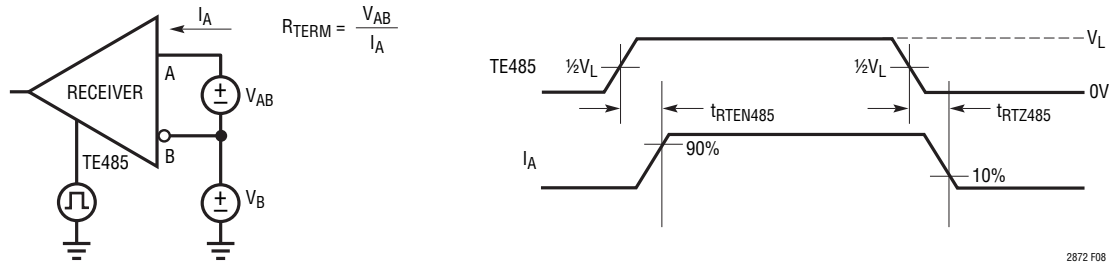


Figure 8. RS485 Termination Resistance and Timing Measurements (Note 5)

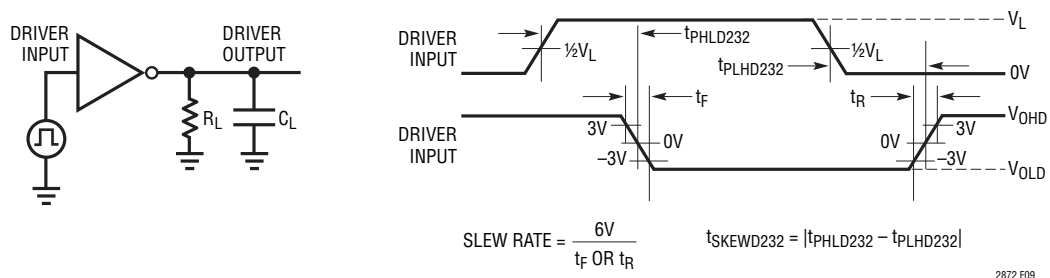


Figure 9. RS232 Driver Timing and Slew Rate Measurements

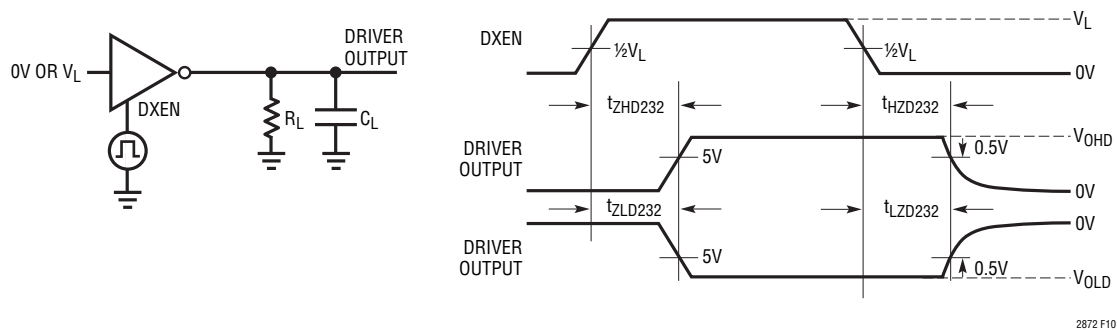


Figure 10. RS232 Driver Enable and Disable Times

TEST CIRCUITS

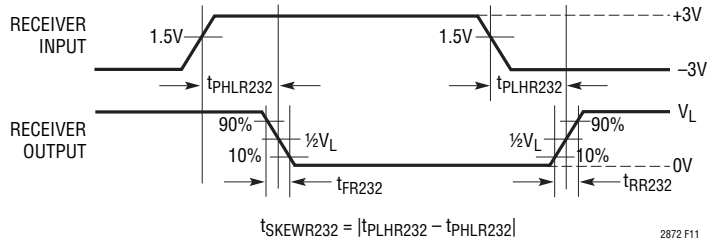
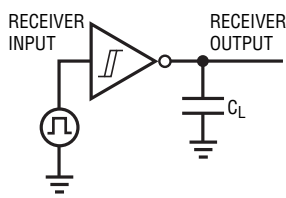


Figure 11. RS232 Receiver Timing Measurements

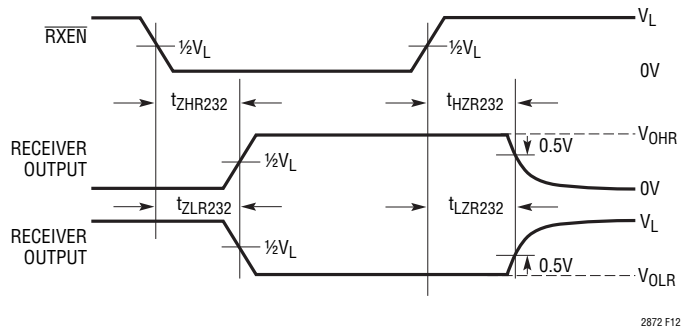
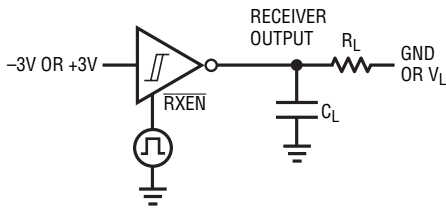


Figure 12. RS232 Receiver Enable and Disable Times

## FUNCTION TABLES

**Table 1. Shutdown and Fast Enable Modes**

FEN	485/232_1 AND 485/232_2	RXEN1 AND RXEN2	DXEN1 AND DXEN2	TE485_1 AND TE485_2	H/ $\bar{F}$	LB	DC/DC CONVERTER	MODE AND COMMENTS
0	X	1	0	0	X	X	OFF	Shutdown: All Main Functions Off
1	X	1	0	0	X	X	ON	Fast-Enable: DC/DC Converter On Only

**Table 2. Mode Selection Table for a Given Port (FEX = X)**

485/232	RXEN	DXEN	TE485	H/ $\bar{F}$	LB	DC/DC CONVERTER	MODE AND COMMENTS
0	X	1	X	X	0	ON	RS232 Drivers On
0	0	X	X	X	0	ON	RS232 Receivers On
1	X	1	X	X	0	ON	RS485 Driver On
1	0	X	X	X	0	ON	RS485 Receiver On
1	X	X	1	X	X	ON	RS485 Termination Mode (See Table 7)
1	X	X	X	0	0	X	RS485 Full Duplex Mode
1	X	X	X	1	0	X	RS485 Half Duplex Mode
1	0	X	X	X	1	ON	RS485 Loopback Mode
0	0	X	X	X	1	ON	RS232 Loopback Mode

**Table 3. RS232 Receiver Mode for a Given Port (485/232 = 0)**

RXEN	RECEIVER INPUT (A, B)	CONDITIONS	RECEIVER OUTPUTS (RA, RB)	RECEIVER INPUTS (A, B)
1	X	No Fault	Hi-Z	125k $\Omega$
0	0	No Fault	1	5k $\Omega$
0	1	No Fault	0	5k $\Omega$
0	X	Thermal Fault	Hi-Z	5k $\Omega$

**Table 4. RS232 Driver Mode for a Given Port (485/232 = 0)**

DXENX	DRIVER INPUT (DY, DZ)	CONDITIONS	DRIVER OUTPUT (Y, Z)
0	X	No Fault	125k $\Omega$
1	0	No Fault	1
1	1	No Fault	0
X	X	Thermal Fault	125k $\Omega$

## FUNCTION TABLES

**Table 5. RS485 Driver Mode for a Given Port ( $485/\overline{232} = 1$ ,  $TE485 = 0$ )**

DXEN	DY	CONDITIONS	Y	Z
0	X	No Fault	125k $\Omega$	125k $\Omega$
1	0	No Fault	0	1
1	1	No Fault	1	0
X	X	Thermal Fault	125k $\Omega$	125k $\Omega$

**Table 6. RS485 Receiver Mode for a Given Port ( $485/\overline{232} = 1$ ,  $LB = 0$ )**

RXEN	A-B (NOTE 5)	CONDITIONS	RA
1	X	No Fault	Hi-Z
0	< -200mV	No Fault	0
0	> 200mV	No Fault	1
0	Inputs Open or Shorted Together (DC)	No Fault	1
X	X	Thermal Fault	Hi-Z

**Table 7. RS485 Termination for a Given Port ( $485/\overline{232} = 1$ )**

TE485	DZ	H/ $\overline{F}$ , LB	CONDITIONS	R(A TO B)	R(Y TO Z)
0	X	X	No Fault	Hi-Z	Hi-Z
1	0	X	No Fault	120 $\Omega$	Hi-Z
1	1	X	No Fault	120 $\Omega$	120 $\Omega$
X	X	X	Thermal Fault	Hi-Z	Hi-Z

**Table 8. RS485 Duplex Control for Given Port ( $485/\overline{232} = 1$ )**

H/ $\overline{F}$	RS485 DRIVER OUTPUTS	RS485 RECEIVER INPUTS
0	Y, Z	A, B
1	Y, Z	Y, Z

**Table 9. Loopback Functions for a Given Port**

LB	$\overline{RXEN}$	TRANSCEIVER MODE
0	X	Not Loopback
1	1	Not Loopback
1	0	Loopback (RA = DY, RB = DZ)



## APPLICATIONS INFORMATION

### Overview

The LTC2872 is a flexible multiprotocol transceiver supporting RS485/RS422 and RS232 protocols. It can be powered from a single 3.0V to 5.5V supply with optional logic interface supply as low as 1.7V. An integrated DC/DC converter provides the positive and negative supply rails needed for RS232 operation. Automatically selected integrated termination resistors for both RS232 and RS485 protocols are included, eliminating the need for external components and switching relays. Both parts include loopback control for self-test and debug as well as logically-switchable half- and full-duplex control of the RS485 bus interface.

The LTC2872 offers two ports that can be independently configured as either two RS232 receivers and drivers or one RS485/RS422 receiver and driver depending on the state of its 485/232 pins. Control inputs DXEN and  $\overline{\text{RXEN}}$  provide independent control of driver and receiver operation for either RS232 or RS485 transceivers, depending on the selected operating protocol.

The LTC2872 features rugged operation with an ESD rating of  $\pm 15\text{kV}$  HBM on the receiver inputs and driver outputs, both powered and unpowered. All other pins offer protection exceeding  $\pm 4\text{kV}$ .

### DC/DC Converter

The on-chip DC/DC converter operates from the  $V_{CC}$  input, generating a 7V  $V_{DD}$  supply and a charge pumped  $-6.3\text{V}$   $V_{EE}$  supply, as shown in Figure 13.  $V_{DD}$  and  $V_{EE}$  power the output stage of the RS232 drivers and are regulated to levels that guarantee greater than  $\pm 5\text{V}$  output swing. The DC/DC converter requires a  $22\mu\text{H}$  inductor (L1) and a bypass capacitor (C4) of  $2.2\mu\text{F}$  or larger. The charge pump capacitor (C1) is  $470\text{nF}$  and the storage capacitors (C2 and C3) are  $2.2\mu\text{F}$ . Larger storage capacitors up to  $4.7\mu\text{F}$  may be used if C1 and C4 are scaled proportionately. Locate C1-C4 close to their associated pins.

Bypass capacitor C5 on the logic supply pin can be omitted if  $V_L$  is connected to  $V_{CC}$ . See the  $V_L$  Logic Supply section for more details about the  $V_L$  logic supply.

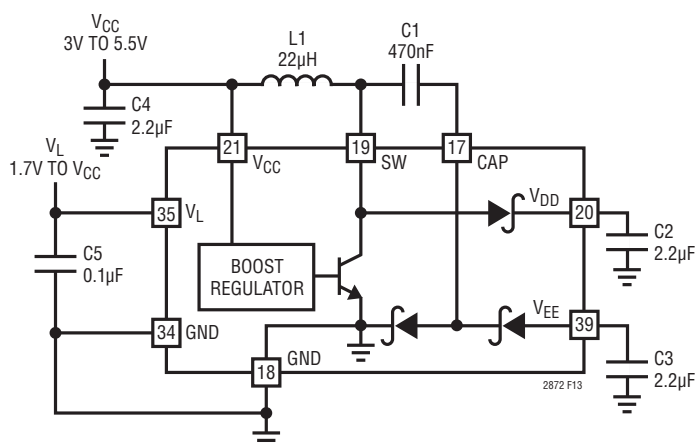


Figure 13. DC/DC Converter with Required External Components

### Inductor Selection

An inductor with a value of  $22\mu\text{H} \pm 20\%$  is required. It must have a saturation current ( $I_{SAT}$ ) rating of at least 200mA and a DCR (copper wire resistance) of less than  $1.3\Omega$ . Some small inductors meeting these requirements are listed in Table 10.

Table 10. Recommended Inductors

PART NUMBER	L ( $\mu\text{H}$ )	$I_{SAT}$ (mA)	MAX DCR ( $\Omega$ )	SIZE (mm)	MANUFACTURER
BRC2016T220M	22	310	1.3	$2 \times 1.6 \times 1.6$	Taiyo Yuden
CBC2518T220M	22	320	1.0	$2.5 \times 1.8 \times 1.8$	t-yuden.com
LQH32CN220K53	22	250	0.92	$3.2 \times 2.5 \times 1.6$	Murata murata.com

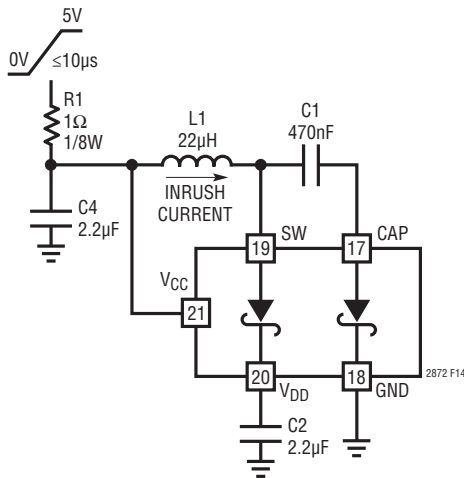
### Capacitor Selection

The small size of ceramic capacitors makes them ideal for the LTC2872. Use X5R or X7R dielectric types; their ESR is low and they retain their capacitance over relatively wide voltage and temperature ranges. Use a voltage rating of at least 10V.

## APPLICATIONS INFORMATION

### Inrush Current and Supply Overshoot Precaution

In certain applications fast supply slew rates are generated when power is connected. If  $V_{CC}$ 's voltage is greater than 4.5V and its rise time is faster than  $10\mu\text{s}$ , the pins  $V_{DD}$  and SW can exceed their Absolute Maximum values during start-up. When supply voltage is applied to  $V_{CC}$ , the voltage difference between  $V_{CC}$  and  $V_{DD}$  generates inrush current flowing through inductor L1 and capacitors C1 and C2. The peak inrush current must not exceed 2A. To avoid this condition, add a  $1\Omega$  resistor as shown in Figure 14. This precaution is not relevant for supply voltages below 4.5V or rise times longer than  $10\mu\text{s}$ .



**Figure 14. Supply Current Overshoot Protection for Input Supplies of 4.5V or Higher**

### $V_L$ Logic Supply

A separate logic supply pin  $V_L$  allows the LTC2872 to interface with any logic signal from 1.7V to 5.5V. All logic I/Os use  $V_L$  as their high supply. For proper operation,  $V_L$  should not be greater than  $V_{CC}$ . During power-up, if  $V_L$  is higher than  $V_{CC}$ , the device will not be damaged, but behavior of the device is not guaranteed. If  $V_L$  is not connected to  $V_{CC}$ , bypass  $V_L$  with a  $0.1\mu\text{F}$  capacitor.

RS232 and RS485 driver outputs are undriven and the RS485 termination resistors are disabled when  $V_L$  or  $V_{CC}$  is grounded or  $V_{CC}$  is disconnected.

Although all logic input pins reference  $V_L$  as their high supply, they can be driven up to 7V, independent of  $V_L$  and  $V_{CC}$ , with the exception of FEN, which must not exceed  $V_L$

by more than 1V for proper operation. Logic input pins do not have internal biasing devices to pull them up or down. They must be driven high or low to establish valid logic levels; do not float.

### RS485 Driver

The RS485 driver provides full RS485/RS422 compatibility. When enabled, if DI is high, Y–Z is positive. When the driver is disabled, Y and Z output resistance is greater than 96k (typically 125k) to ground over the entire common mode range of  $-7\text{V}$  to  $12\text{V}$ . This resistance is equivalent to the input resistance on these lines when the driver is configured in half-duplex mode and Y and Z act as the RS485 receiver inputs.

### Driver Overvoltage and Overcurrent Protection

The RS232 and RS485 driver outputs are protected from short circuits to any voltage within the Absolute Maximum range  $\pm 15\text{V}$ . The maximum current in this condition is 90mA for the RS232 driver and 250mA for the RS485 driver.

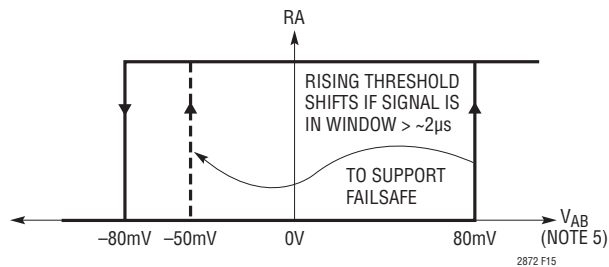
If an RS485 driver output is shorted to a voltage greater than  $V_{CC}$ , when active high, positive current of about 100mA can flow from the driver output back to  $V_{CC}$ . If the system power supply or loading cannot sink this excess current, clamp  $V_{CC}$  to GND with a Zener diode (e.g., 5.6V, 1W, 1N4734) to prevent an overvoltage condition on  $V_{CC}$ .

All devices also feature thermal shutdown protection that disables the drivers, receivers, and RS485 terminators in case of excessive power dissipation (see Note 6).

### RS485 Balanced Receiver with Full Failsafe Support

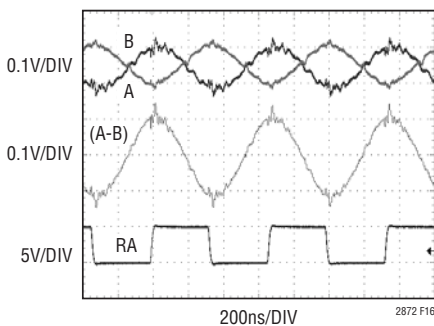
The LTC2872 RS485 receiver has a differential threshold voltage that is about 80mV for signals that are rising and  $-80\text{mV}$  for signals that are falling, as illustrated in Figure 15. If a differential input signal lingers in the window between these thresholds for more than about  $2\mu\text{s}$ , the rising threshold changes from 80mV to  $-50\text{mV}$ , while the falling threshold remains at  $-80\text{mV}$ . Thus, differential inputs that are shorted, open, or terminated but not driven for more than  $2\mu\text{s}$  produce a high on the receiver output, indicating a failsafe condition.

## APPLICATIONS INFORMATION



**Figure 15. RS485 Receiver Input Threshold Characteristics with Typical Values Shown**

The benefit of this dual threshold architecture is that it supports full failsafe operation yet offers a balanced threshold, centered on 0V, for normal data signals. This balance preserves duty cycle for small input signals with heavily slewed edges, typical of what might be seen at the end of a very long cable. This performance is highlighted in Figure 16, where a signal is driven through 4000 feet of CAT5e cable at 3Mbps. Even though the differential signal peaks at just over 100mV and is heavily slewed, the output maintains a nearly perfect signal with almost no duty cycle distortion.



**Figure 16. A 3Mbps Signal Driven Down 4000ft of CAT5e Cable. Top Traces: Received Signals After Transmission Through Cable; Middle Trace: Math Showing Differences of Top Two Signals; Bottom Trace: Receiver Output**

An additional benefit of the balanced architecture is excellent noise immunity due to the wide effective differential input signal hysteresis of 160mV for signals transitioning through the window region in less than 2 $\mu$ s. Increasingly slower signals will have increasingly less effective hysteresis, limited by the DC failsafe hysteresis of about 30mV.

### RS485 Biasing Network Not Required

RS485 networks are often biased with a resistive divider to generate a differential voltage of  $\geq 200$ mV on the data

lines, which establishes a logic-high state when all the transmitters on the network are disabled. The values of the biasing resistors depend on the number and type of transceivers on the line and the number and value of terminating resistors. Therefore, the values of the biasing resistors must be customized to each specific network installation, and may change if nodes are added to or removed from the network.

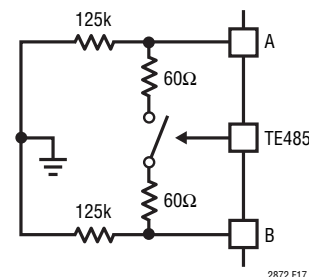
The internal failsafe feature of the LTC2872 eliminates the need for external network biasing resistors provided they are used in a network of transceivers with similar internal failsafe features. This also allows the network to support a high number of nodes, up to 256, by eliminating the bias resistor loading. The LTC2872 transceivers will operate correctly on biased, unbiased, or under-biased networks.

### Receiver Outputs

The RS232 and RS485 receiver outputs are internally driven high (to  $V_L$ ) or low (to GND) with no external pull-up needed. When the receivers are disabled, the output pin becomes Hi-Z with leakage of less than  $\pm 5\mu$ A for voltages within the  $V_L$  supply range.

### RS485 Receiver Input Resistance

The RS485 receiver input resistance from A or B to GND (Y or Z to GND in half-duplex mode with driver disabled) is greater than 96k (typically 125k) when the integrated termination is disabled. This permits up to a total of 256 receivers per system without exceeding the RS485 receiver loading specification. The input resistance of the receiver is unaffected by enabling/disabling the receiver or whether the part is in half-duplex, full-duplex, loopback mode, or even unpowered. The equivalent input resistance looking into the RS485 receiver pins is shown in Figure 17.



**Figure 17. Equivalent RS485 Receiver Input Resistance Into A and B (Note 5)**

## APPLICATIONS INFORMATION

### Selectable RS485 Termination

Proper cable termination is important for good signal fidelity. When the cable is not terminated with its characteristic impedance, reflections cause waveform distortion.

The LTC2872 offers integrated switchable  $120\Omega$  termination resistors between the differential receiver inputs and also between the differential driver outputs. This provides the advantage of being able to easily change, through logic control, the proper line termination for correct operation when configuring transceiver networks. Termination should be enabled on transceivers positioned at both ends of a network bus.

Termination on the driver nodes is important for cases where the driver is disabled but there is communication on the connecting bus from another node. Driver termination across Y and Z can be disabled independently from the termination across A and B by setting DZ low. See Table 7 for details.

The termination resistance is maintained over the entire RS485 common mode range of  $-7V$  to  $12V$  as shown in Figure 18. The voltage across pins with the terminating resistor enabled should not exceed  $6V$  as indicated in the Absolute Maximum Ratings table.

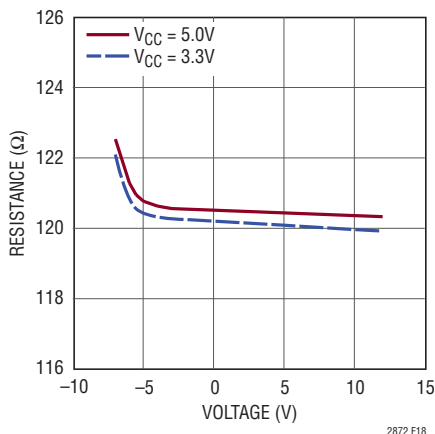


Figure 18. Typical Resistance of the Enabled RS485 Terminator vs Common Mode Voltage of A and B

### RS485 Half- and Full-Duplex Control

The LTC2872 is equipped with a control to change the RS485 transceiver operation from full-duplex to half-duplex. With the H/ $\bar{F}$  pin set to a logic-low, the A and B pins serve as

the differential receiver inputs. With the H/ $\bar{F}$  pin set to a logic-high, the Y and Z pins serve as the differential inputs. In either configuration, the RS485 driver outputs are always on Y and Z. The impedance looking into the A and B pins is not affected by H/ $\bar{F}$  control, including the differential termination resistance. The H/ $\bar{F}$  control does not affect RS232 operation.

### Logic Loopback

A loopback mode connects the driver inputs to the receiver outputs (noninverting) for self test. This applies to both RS232 and RS485 transceivers. Loopback mode is entered when the LB pin is set to a logic-high and the relevant receiver is enabled.

In loopback mode, the drivers function normally. They can be disabled with output in a Hi-Z state or left enabled to allow loopback testing in normal operation. Loopback works in half- or full-duplex modes and does not affect the termination resistors.

### RS485 Cable Length vs Data Rate

Many factors contribute to the maximum cable length that can be used for RS485 or RS422 communication, including driver transition times, receiver threshold, duty cycle distortion, cable properties and data rate. A typical curve of cable length versus maximum data rate is shown in Figure 19. Various regions of this curve reflect different performance limiting factors in data transmission.

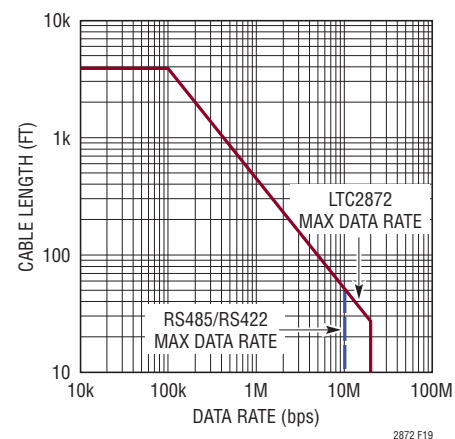


Figure 19. Cable Length vs Data Rate (RS485/RS422 Standard Shown in Vertical Solid Line)

## APPLICATIONS INFORMATION

At frequencies below 100kbps, the maximum cable length is determined by DC resistance in the cable. In this example, a cable longer than 4000ft will attenuate the signal at the far end to less than what can be reliably detected by the receiver.

For data rates above 100kbps, the capacitive and inductive properties of the cable begin to dominate this relationship. The attenuation of the cable is frequency and length dependent, resulting in increased rise and fall times at the far end of the cable. At high data rates or long cable lengths, these transition times become a significant part of the signal bit time. Jitter and intersymbol interference aggravate this so that the time window for capturing valid data at the receiver becomes impossibly small.

The boundary at 20Mbps in Figure 19 represents the guaranteed maximum operating rate of the LTC2872. The dashed vertical line at 10Mbps represents the specified maximum data rate in the RS485 standard. This boundary is not a limit, but reflects the maximum data rate that the specification was written for.

It should be emphasized that the plot in Figure 19 shows a typical relation between maximum data rate and cable length. Results with the LTC2872 will vary, depending on cable properties such as conductor gauge, characteristic impedance, insulation material, and solid versus stranded conductors.

### Layout Considerations

All  $V_{CC}$  pins must be connected together and all ground pins must be connected together on the PC board with very low impedance traces or dedicated planes. A 2.2 $\mu$ F, or larger, bypass capacitor should be placed less than 0.7cm away from  $V_{CC}$  Pin 21. This  $V_{CC}$  pin, as well as GND Pin 18, mainly service the DC/DC converter. Additional bypass capacitors of 0.1 $\mu$ F or larger, can be added to  $V_{CC}$

Pins 1 and 31 if the traces back to the 2.2 $\mu$ F capacitor are indirect or narrow. These  $V_{CC}$  pins mainly service the transceivers #1 and #2, respectively. Table 11 summarizes the bypass capacitor requirements. The capacitors listed in the table should be placed closest to their respective supply and ground pin.

**Table 11. Bypass Capacitor Requirements**

CAPACITOR	SUPPLY (PIN)	RETURN (PIN)	COMMENT
2.2 $\mu$ F	$V_{CC}$ (21)	GND (18)	Required
2.2 $\mu$ F	$V_{DD}$ (20)	GND (18)	Required
2.2 $\mu$ F	$V_{EE}$ (39)	GND (18)	Required
0.1 $\mu$ F	$V_L$ (35)	GND (34)	Required*
0.1 $\mu$ F	$V_{CC}$ (1)	GND (5)	Optional
0.1 $\mu$ F	$V_{CC}$ (31)	GND (27)	Optional

\* If  $V_L$  is not connected to  $V_{CC}$ .

Place the charge pump capacitor, C1, directly adjacent to the SW and CAP pins, with no more than one centimeter of total trace length to maintain low inductance. Close placement of the inductor, L1, is of secondary importance compared to the placement of C1 but should include no more than two centimeters of total trace length.

The PC board traces connected to high speed signals A/B and Y/Z should be symmetrical and as short as possible to minimize capacitive imbalance and to maintain good differential signal integrity. To minimize capacitive loading effects, the differential signals should be separated by more than the width of a trace and should not be routed on top of each other if they are on different signal planes.

Care should be taken to route outputs away from any sensitive inputs to reduce feedback effects that might cause noise, jitter, or even oscillations. For example, DI and A/B should not be routed near the driver or receiver outputs.

## TYPICAL APPLICATIONS $V_{CC} = 3V$ to $5.5V$ , $V_L = 1.7V$ to $V_{CC}$ . Logic input pins not shown are tied to a valid logic state. External components necessary for operation are not shown.

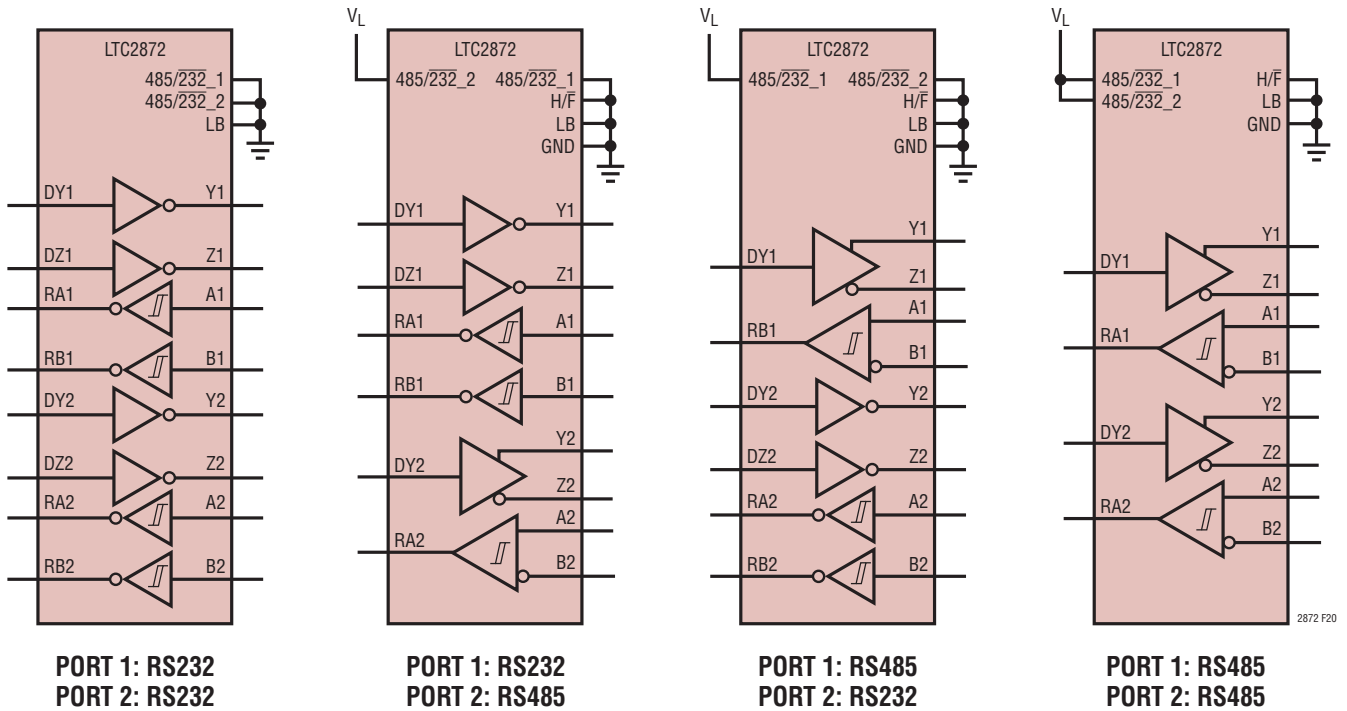


Figure 20. LTC2872 in Various Basic Port Configurations

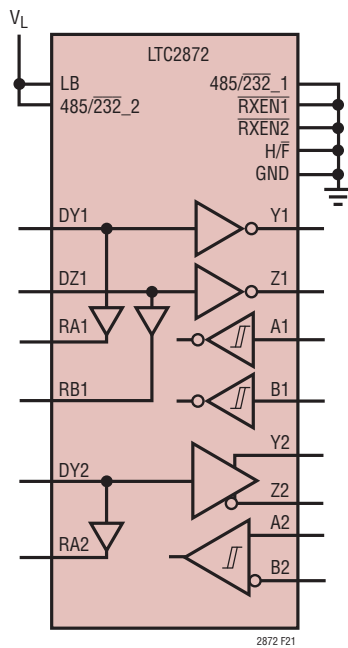


Figure 21. Loopback in RS232 and RS485 Modes

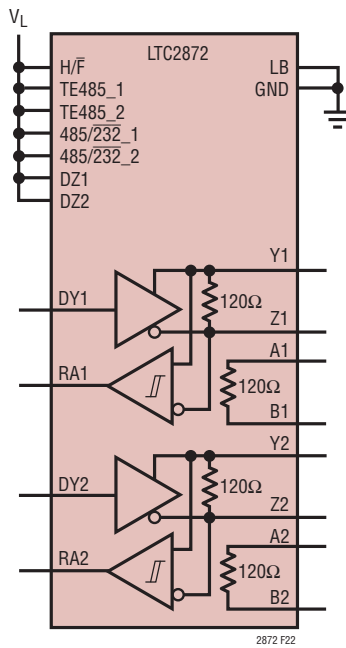


Figure 22. Half-Duplex RS485 Mode with Driver and Receiver Line Termination on Each Port

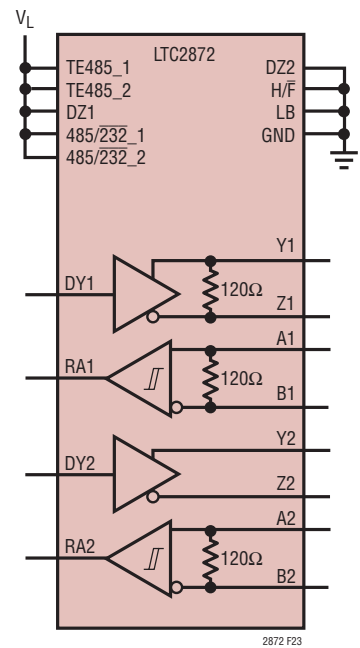


Figure 23. Full-Duplex RS485 Mode with Driver and Receiver Line Termination on Port 1, and Receiver-Only Termination on Port 2

**TYPICAL APPLICATIONS**  $V_{CC} = 3V$  to  $5.5V$ ,  $V_L = 1.7V$  to  $V_{CC}$ . Logic input pins not shown are tied to a valid logic state. External components necessary for operation are not shown.

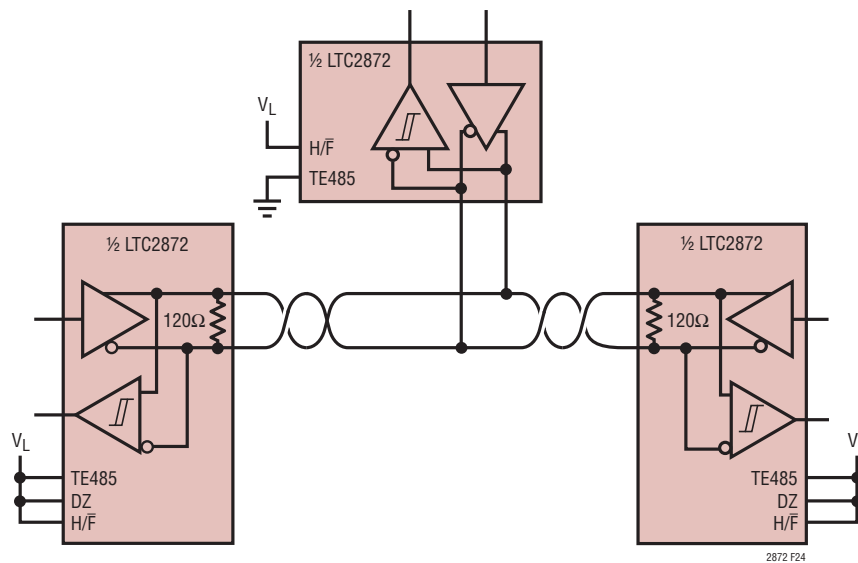


Figure 24. Typical RS485 Half Duplex Network

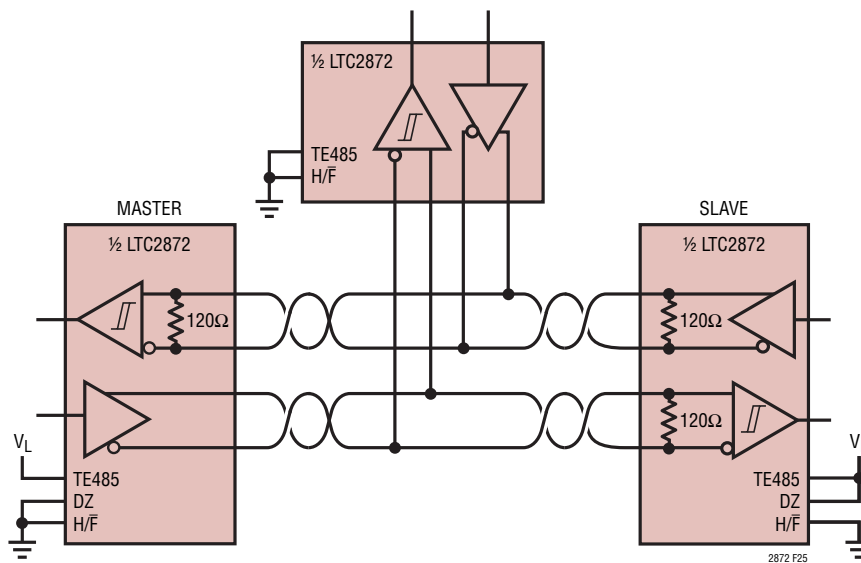
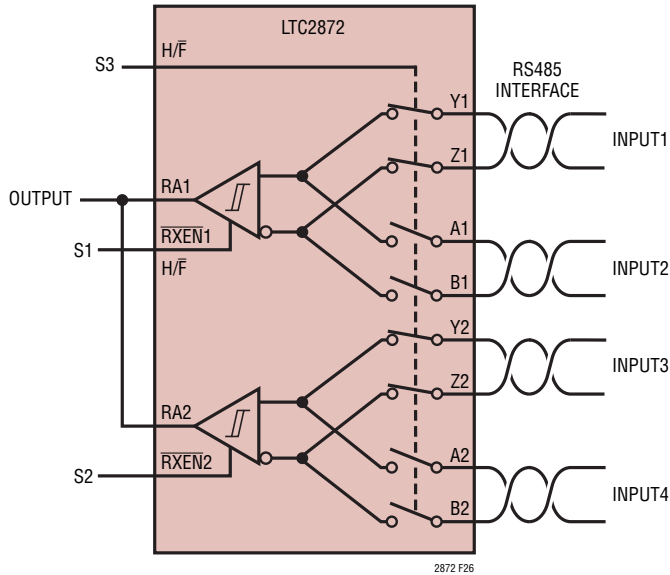


Figure 25. Typical RS485 Full Duplex Network

**TYPICAL APPLICATIONS**  $V_{CC} = 3V$  to  $5.5V$ ,  $V_L = 1.7V$  to  $V_{CC}$ . Logic input pins not shown are tied to a valid logic state. External components necessary for operation are not shown.

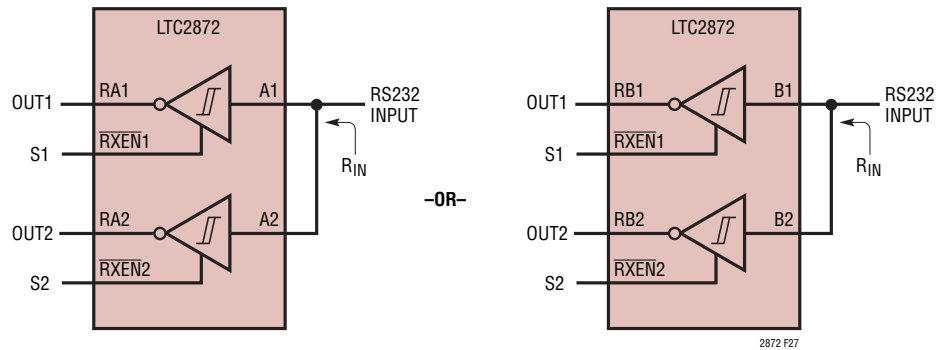


S1	S2	S3	SELECTED INPUT
0	1	1	INPUT1
0	1	0	INPUT2
1	0	1	INPUT3
1	0	0	INPUT4
1	1	X	NONE/HI-Z
0	0	X	INVALID

Figure 26. RS485 Receiver with 4-Way Selectable Inputs



**TYPICAL APPLICATIONS**  $V_{CC} = 3V$  to  $5.5V$ ,  $V_L = 1.7V$  to  $V_{CC}$ . Logic input pins not shown are tied to a valid logic state. External components necessary for operation are not shown.



S1	S2	$R_{IN}$	ACTIVE OUTPUT
0	1	5k	OUT1
1	0	5k	OUT2
1	1	62.5k	NONE (Hi-Z)
0	0	2.5k*	OUT1, OUT2

\* DOES NOT MEET RS232 SPECIFICATIONS

Figure 27. Sharing RS232 Receiver Inputs

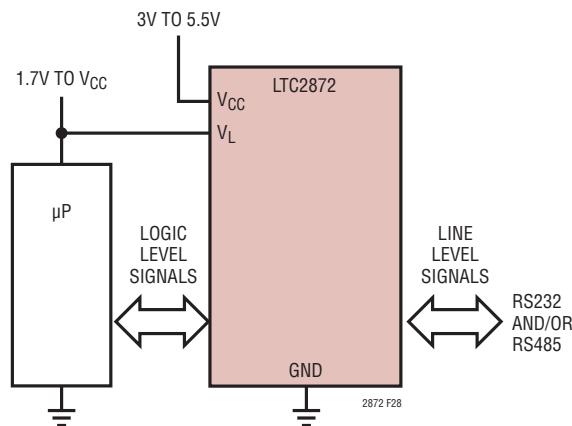


Figure 28. Low Voltage Microprocessor Interface

**TYPICAL APPLICATIONS**  $V_{CC} = 3V$  to  $5.5V$ ,  $V_L = 1.7V$  to  $V_{CC}$ . Logic input pins not shown are tied to a valid logic state. External components necessary for operation are not shown.

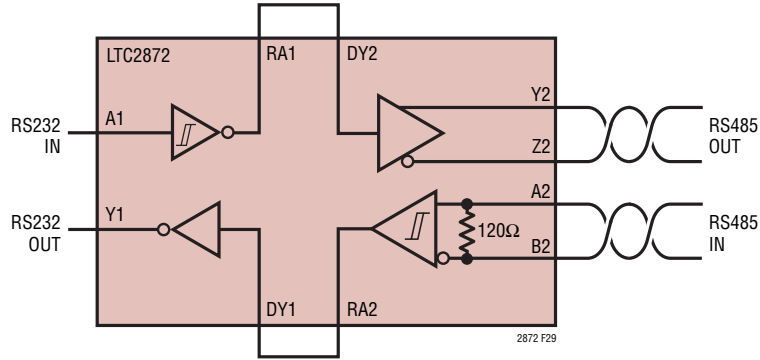


Figure 29. RS232 ↔ RS485 Conversion

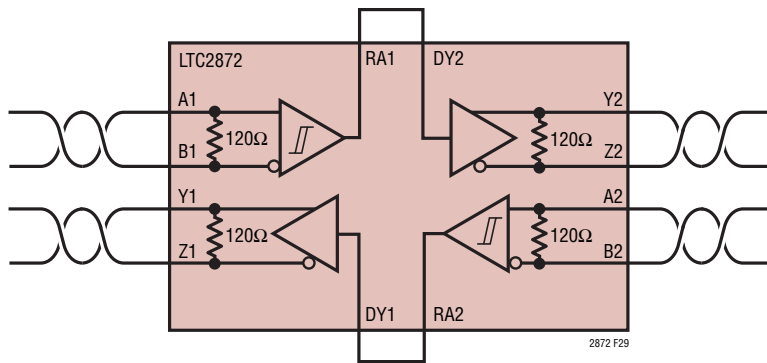
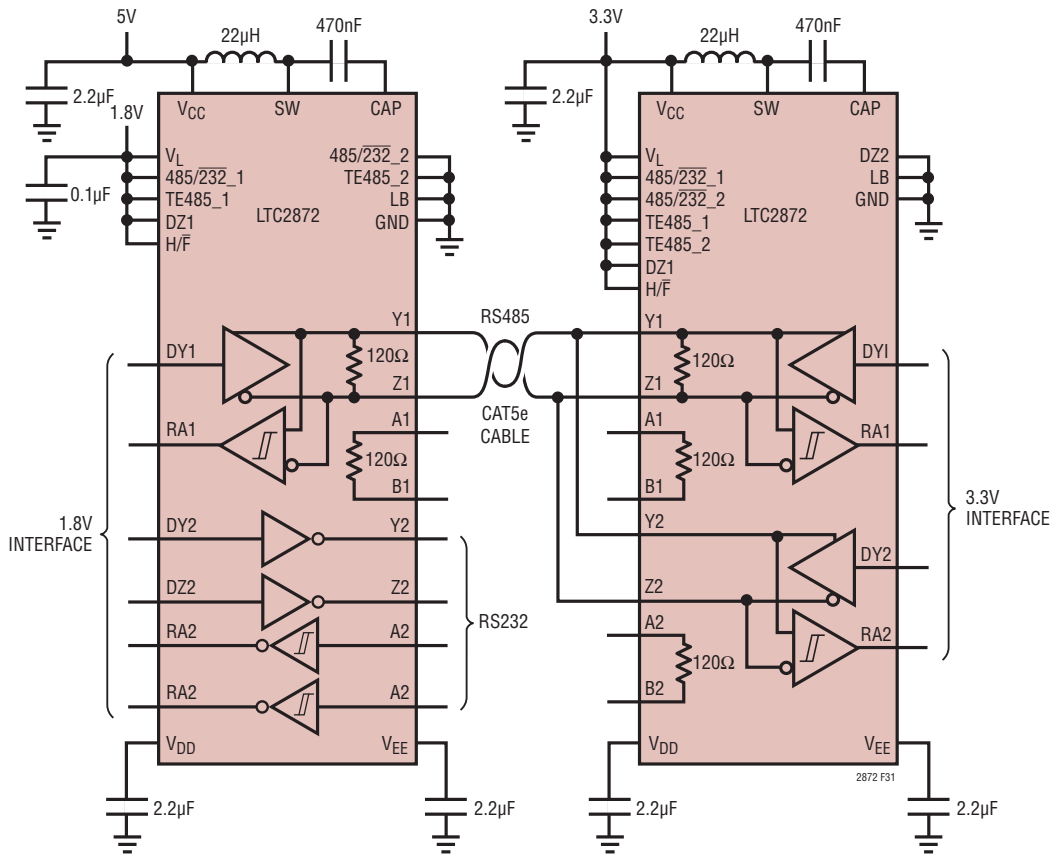


Figure 30. RS485 Repeater



## TYPICAL APPLICATION



**Figure 31. LTC2872 on Left: RS485 Half-Duplex and Terminated, Plus RS232. LTC2872 on Right: Dual RS485 Half-Duplex and Terminated. All External Components Shown**

## RELATED PARTS

PART NUMBER	DESCRIPTION	COMMENTS
LTC2870/LTC2871	RS232/RS485 Multiprotocol Transceivers with Integrated Termination	3V to 5.5V Supply, Automatic Selection of Termination Resistors, Duplex Control, Logic Supply Pin, ±26kV ESD
LTC1334	Single 5V RS232/RS485 Multiprotocol Transceiver	Dual Port, Single 5V Supply, Configurable, ±10kV ESD
LTC1387	Single 5V RS232/RS485 Multiprotocol Transceiver	Single Port, Configurable
LTC2801/LTC2802/ LTC2803/LTC2804	1.8V to 5.5V RS232 Single and Dual Transceivers	Up to 1Mbps, ±10kV ESD, Logic Supply Pin, Tiny DFN Packages
LTC2854/LTC2855	3.3V 20Mbps RS485 Transceiver with Integrated Switchable Termination	3.3V Supply, Integrated, Switchable, 120Ω Termination Resistor, ±25kV ESD
LTC2859/LTC2861	20Mbps RS485 Transceiver with Integrated Switchable Termination	5V Supply, Integrated, Switchable, 120Ω Termination Resistor, ±15kV ESD
LTM2881	Complete Isolated RS485/RS422 µModule® Transceiver + Power	20Mbps, 2500V <sub>RMS</sub> Isolation with Integrated DC/DC Converter, Integrated Switchable 120Ω Termination Resistor, ±15kV ESD
LTM2882	Dual Isolated RS232 µModule Transceiver + Power	1Mbps, 2500V <sub>RMS</sub> Isolation with Integrated DC/DC Converter, ±10kV ESD