

Si4133G Si4123G/22G/13G/12G

DUAL-BAND RF SYNTHESIZER WITH INTEGRATED VCOS FOR GSM AND GPRS WIRELESS COMMUNICATIONS

Features

- Dual-band RF Synthesizers • RF1: 900 MHz to 1.8 GHz
 - RF2: 750 MHz to 1.5 GHz
- IF synthesizer: 500 to 1000 MHz
- Integrated VCOs, loop filters, varactors, and resonators
- Minimal number of external components required
- Fast settling time: 140 µs
- GPRS Class 12 compliant
- Low phase noise
- Programmable powerdown modes
 - 1 µA standby current
 - 18 mA typical supply current
 - 2.7 to 3.6 V operation
- Packages: 24-pin TSSOP and 28-pin MLP

Applications

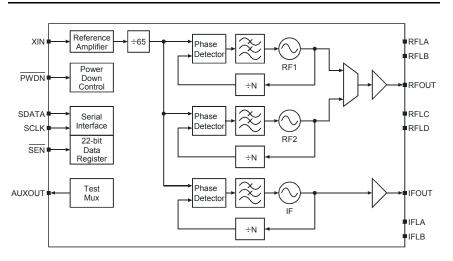
GSM 850, E-GSM 900, DCS 1800, and PCS 1900 cellular telephones

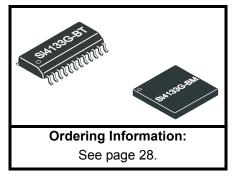
- GPRS data terminals
- HSCSD data terminals

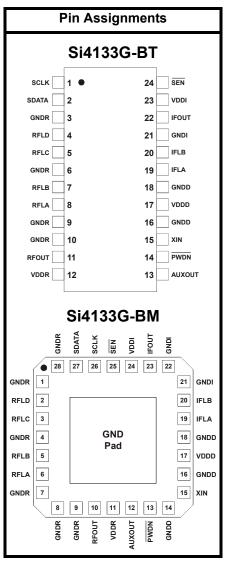
Description

The Si4133G is a monolithic integrated circuit that performs both IF and dual-band RF synthesis for GSM and GPRS wireless communications applications. The Si4133G includes three VCOs, loop filters, reference and VCO dividers, and phase detectors. Divider and powerdown settings are programmable with a three-wire serial interface.

Functional Block Diagram







Patents pending



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Electrical Specifications

Table 1. Recommended Operating Conditions

Parameter	Symbol	Test Condition	Min	Тур	Max	Unit							
Ambient Temperature	T _A		-20	25	85	°C							
Supply Voltage	V _{DD}		2.7	3.0	3.6	V							
Supply Voltages Difference	V_{Δ}	(V _{DDR} – V _{DDD}), (V _{DDI} – V _{DDD})	-0.3	_	0.3	V							
•													

Table 2. Absolute Maximum Ratings^{1,2}

Parameter	Symbol	Value	Unit
DC Supply Voltage	V _{DD}	-0.5 to 4.0	V
Input Current ³	I _{IN}	±10	mA
Input Voltage ³	V _{IN}	–0.3 to V _{DD} +0.3	V
Storage Temperature Range	T _{STG}	–55 to 150	°C

Notes:

1. Permanent device damage may occur if the above Absolute Maximum Ratings are exceeded. Functional operation should be restricted to the conditions as specified in the operational sections of this data sheet. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

2. This device is a high performance RF integrated circuit with an ESD rating of < 2 kV. Handling and assembly of this device should only be done at ESD-protected workstations.

3. For signals SCLK, SDATA, SEN, PWDN and XIN.



Table 3. DC Characteristics

(V_{DD} = 2.7 to 3.6 V, T_A = –20 to 85 °C)

Parameter	Symbol	Test Condition	Min	Тур	Max	Unit
Typical Supply Current ¹		RF1 and IF Operating	—	18	31	mA
RF1 Mode Supply Current ¹			_	13	17	mA
RF2 Mode Supply Current ¹				12	17	mA
IF Mode Supply Current ¹			_	10	14	mA
Standby Current		PWDN = 0	_	1		μA
High Level Input Voltage ²	V _{IH}		0.7 V _{DD}	_		V
Low Level Input Voltage ²	V _{IL}		_	_	$0.3 V_{\text{DD}}$	V
High Level Input Current ²	I _{IH}	V _{IH} = 3.6 V, V _{DD} = 3.6 V	-10	_	10	μA
Low Level Input Current ²	I _{IL}	V _{IL} = 0 V, V _{DD} = 3.6 V	-10	—	10	μA
High Level Output Voltage ³	V _{OH}	I _{OH} = –500 μA	V _{DD} -0.4	_		V
Low Level Output Voltage ³	V _{OL}	Ι _{ΟΗ} = 500 μΑ	_	—	0.4	V
Notes: 1. RF1 = 1.55 GHz, RF2 = 1.2 <u>GHz</u> , 2. For signals SCLK, SDATA, SEN, a					,	1

For signals SCLK, SI
 For signal AUXOUT.



Table 4. Serial Interface Timing

(V_{DD} = 2.7 to 3.6 V, T_A = -20 to 85 °C)

Parameter ¹	Symbol	Test Condition	Min	Тур	Мах	Unit
SCLK Cycle Time	t _{clk}	Figure 1	40	_		ns
SCLK Rise Time	t _r	Figure 1			50	ns
SCLK Fall Time	t _f	Figure 1			50	ns
SCLK High Time	t _h	Figure 1	10			ns
SCLK Low Time	tı	Figure 1	10			ns
SDATA Setup Time to SCLK \uparrow^2	t _{su}	Figure 2	5			ns
SDATA Hold Time from SCLK \uparrow^2	t _{hold}	Figure 2	0			ns
SEN↓ to SCLK↑ Delay Time ²	t _{en1}	Figure 2	10	_		ns
SCLK↑ to SEN↑ Delay Time ²	t _{en2}	Figure 2	12			ns
SEN [↑] to SCLK [↑] Delay Time ²	t _{en3}	Figure 2	12			ns
SEN Pulse Width	t _w	Figure 2	10	_		ns

Notes:

1. All timing is referenced to the 50% level of the waveform unless otherwise noted.

2. Timing is not referenced to 50% level of waveform. See Figure 2.

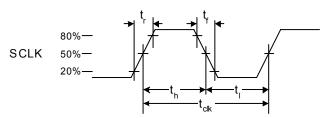


Figure 1. SCLK Timing Diagram



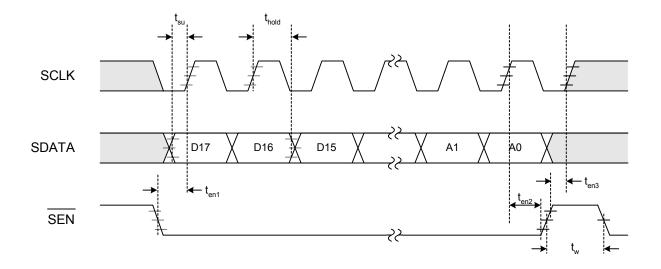


Figure 2. Serial Interface Timing Diagram

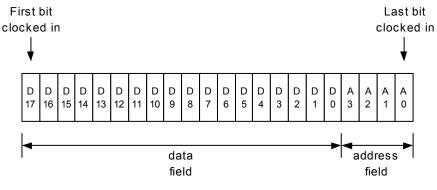


Figure 3. Serial Word Format



Table 5. RF and IF Synthesizer Characteristics

 $(V_{DD} = 2.7 \text{ to } 3.6 \text{ V}, \text{ T}_{A} = -20 \text{ to } 85 \text{ }^{\circ}\text{C})$

Parameter ¹	Symbol	Test Condition	Min	Тур	Мах	Unit
XIN Input Frequency	f _{REF}		_	13		MHz
Reference Amplifier Sensitivity	V _{REF}		0.5	_	V _{DD} +0.3	V _{PP}
Phase Detector Update Frequency	f_{ϕ}	$f_{\phi} = f_{REF}/R$		200		kHz
RF1 Center Frequency Range	f _{CEN}		947	—	1720	MHz
RF2 Center Frequency Range	f _{CEN}		789		1429	MHz
IF VCO Center Frequency Range	f _{CEN}		526	_	952	MHz
Tuning Range from f _{CEN}		Note: L _{EXT} ±10%	-5	_	5	%
RF1 VCO Pushing		Open loop		0.5		MHz/V
RF2 VCO Pushing				0.4		MHz/V
IF VCO Pushing				0.3		MHz/V
RF1 VCO Pulling		VSWR = 2:1, all		0.4		MHz _{PP}
RF2 VCO Pulling		phases, open loop		0.1		MHz _{PP}
IF VCO Pulling				0.1		MHz _{PP}
RF1 Phase Noise		1 MHz offset	_	-132		dBc/Hz
		3 MHz offset		-142		dBc/Hz
RF1 Integrated Phase Error		100 Hz to 100 kHz		0.9		deg rms
RF2 Phase Noise		1 MHz offset	—	-134		dBc/Hz
		3 MHz offset	_	-144	_	dBc/Hz
RF2 Integrated Phase Error		100 Hz to 100 kHz	—	0.7	—	deg rms
IF Phase Noise		100 kHz offset	—	-117	_	dBc/Hz
IF Integrated Phase Error		100 Hz to 100 kHz	—	0.4	_	deg rms
RF1 Harmonic Suppression		Second Harmonic	—	-26	—	dBc
RF2 Harmonic Suppression			—	-26	—	dBc
IF Harmonic Suppression			—	-26	—	dBc
RFOUT Power Level		Z _L = 50 Ω	-7	-2	1	dBm
IFOUT Power Level		Z _L = 50 Ω	-8	-6	-1	dBm
RF1 Reference Spurs		Offset = 200 kHz	—	-70	—	dBc
		Offset = 400 kHz		-75	—	dBc
		Offset = 600 kHz		-80		dBc
RF2 Reference Spurs		Offset = 200 kHz	—	-75	—	dBc
		Offset = 400 kHz		-80	—	dBc
		Offset = 600 kHz		-80	—	dBc
Powerup Request to Synthesizer Ready Time, RF1, RF2, IF ²	t _{pup}	Figures 4, 5	—	140	_	μS
Powerdown Request to Synthesizer Off Time ³	t _{pdn}	Figures 4, 5	_	—	100	ns

Notes:

1. RF1 = 1.55 GHz, RF2 = <u>1.2 GH</u>z, IF = <u>550 MHz</u> for all parameters unless otherwise noted.

From powerup request (PWDN[↑] or SEN[↑] during a write of 1 to bits PDIB and PDRB in Register 2) to RF and IF synthesizers ready (settled to within 0.1 ppm frequency error). Typical settling time to 5 degrees phase error is 120 µs.

3. From powerdown request (PWDN↓, or SEN↑ during a write of 0 to bits PDIB and PDRB in Register 2) to supply current equal to I_{PWDN}.



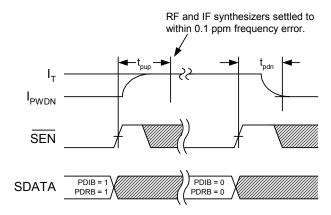


Figure 4. Software Power Management Timing Diagram

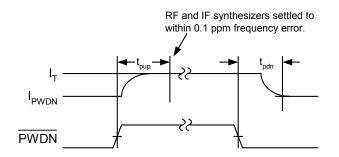


Figure 5. Hardware Power Management Timing Diagram



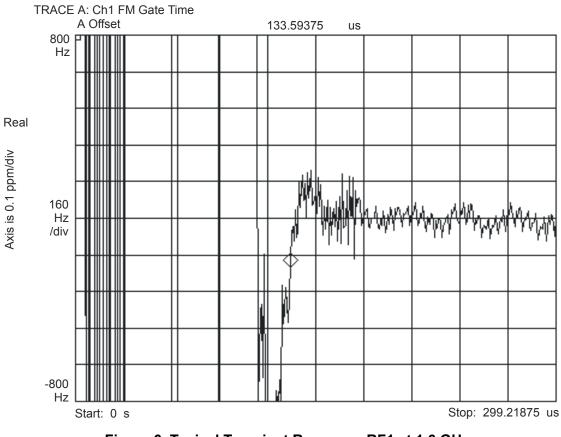
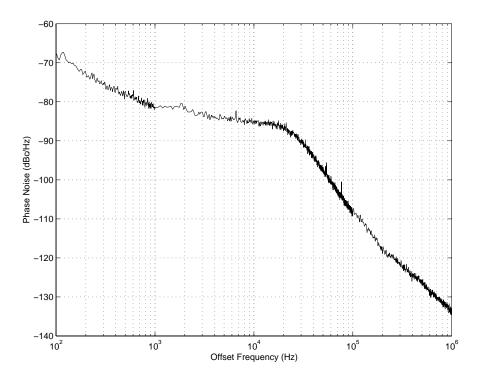


Figure 6. Typical Transient Response RF1 at 1.6 GHz with 200 kHz Phase Detector Update Frequency







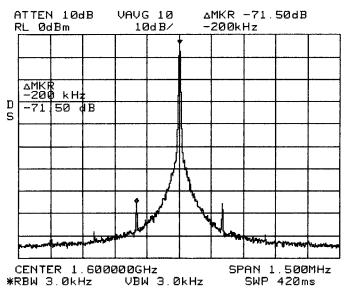
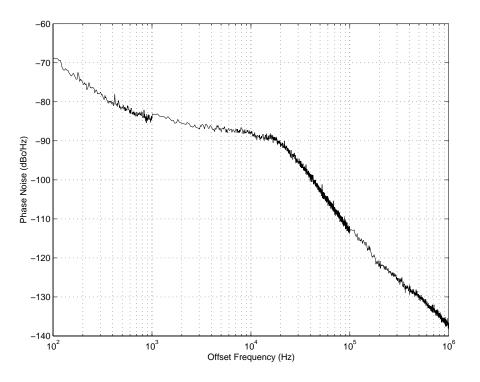


Figure 8. Typical RF1 Spurious Response at 1.6 GHz with 200 kHz Phase Detector Update Frequency







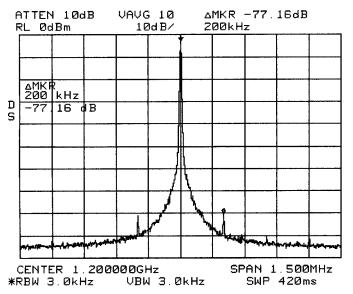
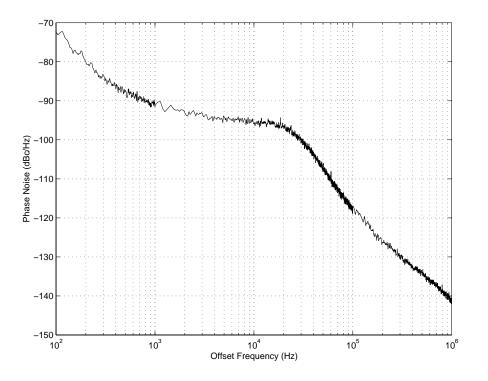


Figure 10. Typical RF2 Spurious Response at 1.2 GHz with 200 kHz Phase Detector Update Frequency







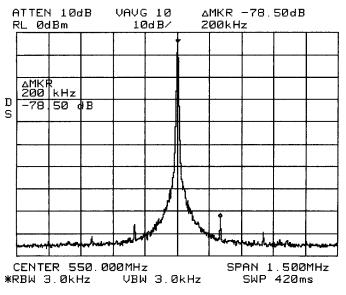
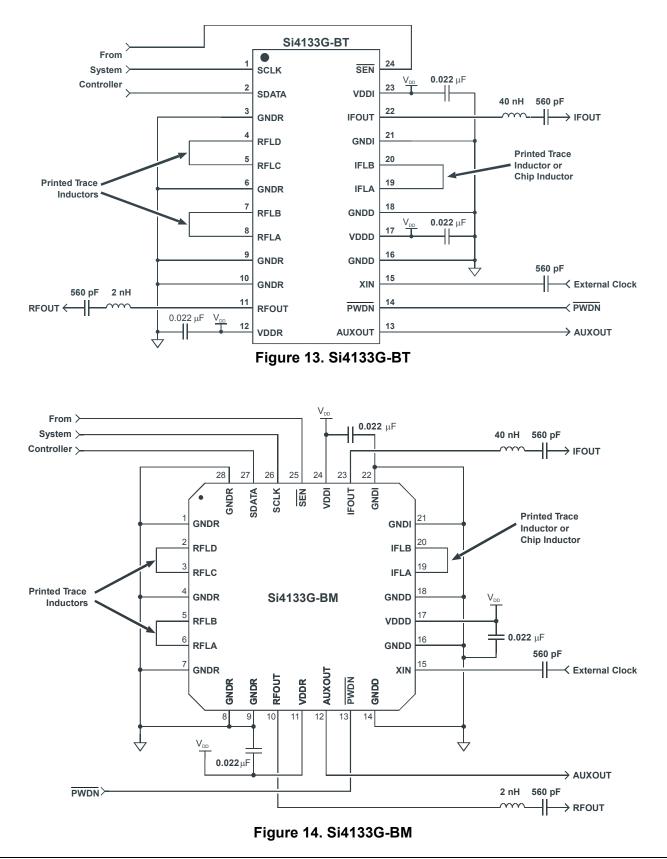


Figure 12. IF Spurious Response at 550 MHz with 200 kHz Phase Detector Update Frequency



Typical Application Circuits





Functional Description

The Si4133G is a monolithic integrated circuit that performs IF and dual-band RF synthesis for wireless applications such as GSM 850, E-GSM 900, DCS 1800, and PCS 1900. Its fast transient response also makes the Si4133G especially well suited to GPRS and HSCSD multislot applications where channel switching and settling times are critical. This integrated circuit (IC), with a minimal number of external components, completes the frequency synthesis function.

The Si4133G has three complete phase-locked loops (PLLs) with integrated voltage-controlled oscillators (VCOs). The low phase noise of the VCOs makes the Si4133G suitable for demanding wireless communications applications. Phase detectors, loop filters, and reference dividers are also integrated. The IC is programmed with a three-wire serial interface.

One PLL is provided for IF synthesis, and two PLLs are provided for dual-band RF synthesis. One RF VCO is optimized to have its center frequency set between 947 and 1720 MHz, whereas the second RF VCO is optimized to have its center frequency set between 789 and 1429 MHz. The IF VCO is optimized to have its center frequency set between 526 and 952 MHz. Each PLL can adjust its output frequency by \pm 5% relative to its VCO center frequency.

The center frequency of each VCO is set by connection of an external inductance. Inaccuracies in the value of the inductance are compensated for by the Si4133G's proprietary self-tuning algorithm. This algorithm is initiated each time the PLL is powered-up (by either the PWDN pin or by software) and/or each time a new output frequency is programmed.

The two RF PLLs share a common output pin, so only one PLL is active at a time. Because the two VCOs can be set to have widely separated center frequencies, the RF output can be programmed to service different frequency bands, thus the Si4133G is ideal for dualband cellular handsets.

The unique PLL architecture in the Si4133G produces a transient response that is superior in speed to fractional-N architectures without the high phase noise or spurious modulation effects often associated with those designs.

Serial Interface

A timing diagram for the serial interface is shown in Figure 2 on page 7. Figure 3 on page 7 shows the format of the serial word.

The Si4133G is programmed serially with 22-bit words comprised of 18-bit data fields and 4-bit address fields. When the serial interface is enabled (i.e., when SEN is low) data and address bits on the SDATA pin are clocked into an internal shift register on the rising edge of SCLK. Data in the shift register is then transferred on the rising edge of SEN to the internal data register identified in the address field. The serial interface is disabled when SEN is high.

Table 10 on page 20 summarizes the data register functions and addresses. The internal shift register ignores leading bits before the 22 required bits.

Setting the VCO Center Frequencies

The PLLs can adjust the IF and RF output frequencies $\pm 5\%$ with respect to their VCO center frequencies. Each center frequency is established by the value of an external inductance connected to the respective VCO. Manufacturing tolerances of $\pm 10\%$ for the external inductances are acceptable. The Si4133G compensates for inaccuracies in each inductance by executing a self-tuning algorithm after PLL powerup or after a change in the programmed output frequency.

Because the total tank inductance is in the low nH range, the inductance of the package must be considered when determining the correct external inductance. The total inductance (L_{TOT}) presented to each VCO is the sum of the external inductance (L_{EXT}) and the package inductance (L_{PKG}). Each VCO has a nominal capacitance (C_{NOM}) in parallel with the total inductance, and the center frequency is as follows:

$$f_{CEN} = \frac{1}{2\pi \sqrt{L_{TOT} \times C_{NOM}}}$$

or
$$f_{CEN} = \frac{1}{2\pi \sqrt{(L_{PKG} + L_{EXT}) \times C_{NOM}}}$$

Tables 6 and 7 summarize the characteristics of each VCO.



VCO	F _{CEN} F (M		C _{NOM} (pF)	L _{PKG} (nH)	L _{EXT} I (n	Range H)		
	Min Max				Min	Max		
RF1	947	1720	4.3	2.0	0.0	4.6		
RF2	789	1429	4.8	2.3	0.3	6.2		
IF	526 952		526 952		6.5	2.1	2.2	12.0

Table 6. Si4133G-BT VCO Characteristics

Table 7. Si4133G-BM VCO Characteristics

VCO	F _{CEN} Range (MHz)				C _{NOM} (pF)	L _{PKG} (nH)	L _{EXT} I (n	
	Min Max				Min	Max		
RF1	947	1720	4.3	1.5	0.5	5.1		
RF2	RF2 789		4.8	1.5	1.1	7.0		
IF	526 952		IF 526 9		6.5	1.6	2.7	12.5

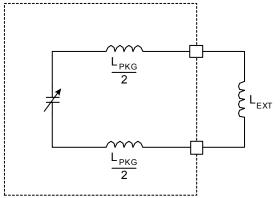


Figure 15. External Inductance Connection

As a design example, consider that the goal is to synthesize frequencies in a 25 MHz band between 1120 and 1145 MHz. The center frequency should be defined as midway between the two extremes, or 1132.5 MHz. The PLL can adjust the VCO output frequency $\pm 5\%$ of the center frequency, or ± 56.6 MHz of 1132.5 MHz (i.e., from approximately 1076 to 1189 MHz). The RF2 VCO has a C_{NOM} of 4.8 pF, and a 4.1 nH inductance in parallel with this capacitance yields the required center frequency. An external inductance of 1.8 nH should be connected between RFLC and RFLD as shown in Figure 15. This and 2.3 nH of L_{PKG} (Si4133G-BT), presents the correct total

inductance to the VCO. In manufacturing, the external inductance can vary $\pm 10\%$ of its nominal value and the Si4133G corrects for the variation with the self-tuning algorithm.

In most cases, particularly for the RF VCOs, the requisite value of the external inductance is small enough to utilize a PC board trace. During initial board layout, a length of trace approximating the required inductance can be used. For more information, refer to Application Note 31: Inductor Design for the Si41xx Synthesizer Family.

Self-Tuning Algorithm

The self-tuning algorithm is initiated immediately after powerup of a PLL or, if the PLL is already powered, after a change in its programmed output frequency. This algorithm attempts to tune the VCO so that its freerunning frequency is near the desired output frequency. In doing so, the algorithm compensates for manufacturing tolerance errors in the value of the external inductance connected to the VCO. It also reduces the frequency error for which the PLL must correct to get the precise desired output frequency. The self-tuning algorithm will leave the VCO oscillating at a frequency in error by less than 1% of the required output frequency.

After self-tuning, the PLL controls the VCO oscillation frequency. The PLL will complete frequency locking, eliminating any remaining frequency error. Thereafter, it will maintain frequency-lock and compensates for effects from temperature and supply voltage variations.

The Si4133G's self-tuning algorithm compensates for component value errors at any temperature within the specified temperature range. However, the ability of the PLL to compensate for drift in component values that occur *after* self-tuning is limited. For external inductances with temperature coefficients approximately $\pm 150 \text{ ppm}/^{\circ}$ C, the PLL can maintain lock for changes in temperature of approximately $\pm 30 \, ^{\circ}$ C.

Applications in which the PLL is regularly powered down (such as GSM) or switched between channels can minimize or eliminate the effects of temperature drift because the VCO is re-tuned when it is powered up or when a new frequency is programmed. Applications in which the ambient temperature can drift substantially after self-tuning, it might be necessary to monitor the LDETB (lock-detect bar) signal on the AUXOUT pin to determine the locking state of the PLL. See "Auxiliary Output (AUXOUT)" on page 18 for how to select LDETB.

The LDETB signal is normally low after self-tuning completes but rises to a logic high condition when the IF



or RF PLL nears the limit of its compensation range LDETB is also high when either PLL is executing the self-tuning algorithm. The output frequency is still locked when LDETB goes high, but the PLL eventually loses lock if the temperature continues to drift in the same direction. Therefore, if LDETB goes high, the IF and RF PLLs should be re-tuned promptly by initiating the self-tuning algorithm.

Output Frequencies

The IF and RF output frequencies are set by programming the N Divider registers. Each RF PLL has its own N register and can be programmed independently. All three PLL R-dividers are fixed at R = 65 to yield a 200 kHz phase detector update rate from a 13 MHz reference frequency. Programming the N Divider register for either RF1 or RF2 automatically selects the associated output.

The reference frequency on the XIN pin is divided by R and this signal is the input to the PLL's phase detector. The other input to the phase detector is the PLL's VCO output frequency divided by N. The PLL works to make these frequencies equal.

That is, after an initial transient:

$$\frac{f_{OUT}}{N} = \frac{f_{REF}}{65}$$
or
$$f_{OUT} = \frac{N}{65} \times f_{REF}$$

$$f_{OUT} = N \times 200 \text{ kHz}$$

The integer N is set by programming the RF1 N-Divider register (Register 3), the RF2 N-Divider register (Register 4), and the IF N-Divider register (Register 5).

Each N-divider is implemented as a conventional high speed divider. That is, it consists of a dual-modulus prescaler, a swallow counter, and a lower speed synchronous counter. However, these values are automatically calculated. Only the appropriate N value must be programmed.

PLL Loop Dynamics

The transient response for each PLL is optimized for a GSM application. VCO gain, phase detector gain, and loop filter characteristics are not programmable.

The settling time for each PLL is directly proportional to its phase detector update period T ϕ (T ϕ equals 1/f ϕ). For a GSM application with a 13 MHz reference frequency,

the RF and IF PLLs $T\phi = 5 \mu S$. During the first 6.5 update periods, the Si4133G executes the self-tuning algorithm. From then on the PLL controls the output frequency. Because of the unique architecture of the Si4133G PLLs, the time required to settle the output frequency to 0.1 ppm error is approximately 21 update periods. Total time after powerup or a change in programmed frequency until the synthesized frequency is settled (including time for self-tuning) is approximately 28 update periods or 140 μ S.

RF and IF Outputs (RFOUT and IFOUT)

The RFOUT pin is driven by an amplifier that buffers the output pin from the RF VCOs and must be coupled to its load through an ac coupling capacitor. The amplifier receives its input from the RF1 or RF2 VCO, depending on which N-Divider register was last written. For example, programming the N-Divider register for RF1 automatically selects the RF1 VCO output.

A matching network is required to maximize power delivered into a 50 Ω load. The network consists of a 2 nH series inductance, which can be realized with a PC board trace, connected between the RFOUT pin and the ac coupling capacitor. The network provides an adequate match for the RF1 and RF2 frequency bands and also filters the output signal to reduce harmonic distortion. A 50 Ω load is not required for proper operation of the Si4133G. Depending on transceiver requirements, the matching network might not be needed. See Figure 16.

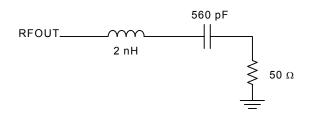
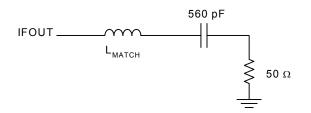


Figure 16. RFOUT 50 Ω Test Circuit

The IFOUT pin is driven by an amplifier that buffers the output pin from the IF VCO. The IFOUT pin must be coupled to its load through an ac coupling capacitor. A matching network is required to maximize power delivered into a 50 Ω load. See Figure 17.





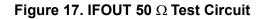


Table 8. L _{MATCH} Value	S
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Frequency	LMATCH
500–600 MHz	40 nH
600–800 MHz	27 nH
800–1 GHz	18 nH

The IF output level is dependent upon the load. Figure 18 displays the output level versus load resistance for a variety of output frequencies.

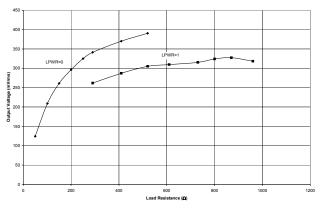


Figure 18. Typical IF Output Voltage vs. Load Resistance at 550 MHz

For resistive loads greater than 500 Ω the output level saturates and the bias currents in the IF output amplifier are higher than needed. The LPWR bit in the Main Configuration register (Register 0) can be set to 1 to reduce the bias currents and therefore reduce the power dissipated by the IF amplifier. For loads less than 500 Ω LPWR should be set to 0 to maximize the output level.

Reference Frequency Amplifier

The Si4133G provides a reference frequency amplifier. If the driving signal has CMOS levels it can be connected directly to the XIN pin. Otherwise, the reference frequency signal should be ac coupled to the XIN pin through a 560 pF capacitor.

Powerdown Modes

Table 9 summarizes the powerdown functionality. The Si4133G can be powered down by taking the PWDN pin low or by setting bits in the Powerdown register (Register 1). When the PWDN pin is low, the Si4133G will be powered down regardless of the Powerdown register settings. When the PWDN pin is high, power management is controlled by the Powerdown register bits.

The reference frequency amplifier, IF, and RF sections of the Si4133G circuitry can be individually powered down by setting the Powerdown register bits PDIB and PDRB low, respectively. The reference frequency amplifier is also powered up if the PDRB and PDIB bits are high. Also, setting the AUTOPDB bit to 1 in the Main Configuration register (Register 0) is equivalent to setting both bits in the Powerdown register to 1. The serial interface remains available and can be written in all powerdown modes.

Auxiliary Output (AUXOUT)

The signal appearing on AUXOUT is selected by setting the AUXSEL bits in the Main Configuration register (Register 0).

The LDETB signal can be selected by setting the AUXSEL bits to 11. This signal can indicate that the IF or RF PLL is going to lose lock due to excessive ambient temperature drift and should be re-tuned. The LDETB signal indicates a logical OR result if both IF and RF are simultaneously generating a signal.



PWDN Pin	AUTOPDB	PDIB	PDRB	IF Circuitry	RF Circuitry
PWDN = 0	x	x	x	OFF	OFF
	0	0	0	OFF	OFF
	0	0	1	OFF	ON
PWDN = 1	0	1	0	ON	OFF
	0	1	1	ON	ON
	1	x/	х	ON	ON

Table 9. Powerdown Configuration



Control Registers

Register	Name	Bit 17	Bit 16	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0	Main Configuration	0	0	0	0	AUX [1	(SEL :0]	0	0	0	0	0	0	LPWR	0	AUTO PDB	0	1	0
1	Reserved																		
2	Powerdown	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	PDIB	PDRB
3	RF1 N-Divider		N _{RF1} [17:0]																
4	RF2 N-Divider	0									N _F	_{RF} [16	6:0]						
5	IF N-Divider	0	0									N _{IF} [15:0]						
6	Reserved																		
		•	•		-		•						•					•	
•																			
•			1				1						1			1		1	1
15	Reserved																		

Table 10. Register Summary

Note: Registers 1 and 6–15 are reserved. Writes to these registers can result in unpredictable behavior. Registers not listed here are reserved and should not be written.



Register 0. Main Configuration Address Field = A[3:0] = 0000

Bit	D17	D16	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
Name	0	0	0	0	AUX [1:	SEL :0]	0	0	0	0	0	0	LPWR	0	AUTO PDB	0	1	0

Bit	Name	Function
17:14	Reserved	Program to zero.
13:12	AUXSEL [1:0]	Auxiliary Output Pin Definition.00= Reserved.01= Force output low.10= Reserved.11= Lock Detect—LDETB.
11:6	Reserved	Program to zero.
5	LPWR	Output Power-Level Settings for IF Synthesizer Circuit. $0 = R_{LOAD} < 500 \Omega$ —normal power mode. $1 = R_{LOAD} \ge 500 \Omega$ —low power mode.
4	Reserved	Program to zero.
3	AUTOPDB	 Auto Powerdown 0 = Software powerdown is controlled by Register 2. 1 = Equivalent to setting all bits in Register 2 = 1.
2	Reserved	Program to zero.
1	Reserved	Program to one .
0	Reserved	Program to zero.



Si4133G

Register 2. Powerdown Address Field (A[3:0]) = 0010

Bit	D17	D16	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
Name	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	PDIB	PDRB

Bit	Name	Function	
17:2	Reserved	Program to zero.	
1	PDIB	Powerdown IF Synthesizer. 0 = IF synthesizer powered down. 1 = IF synthesizer on. Note: Always program to 0 for Si4113G.	
0	PDRB	Powerdown RF Synthesizer. 0 = RF synthesizer powered down. 1 = RF synthesizer on.	

Register 3. RF1 N-Divider Address Field (A[3:0]) = 0011

Bit	D17	D16	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
Name		N _{RF1} [17:0]																

Bit	Name	Function
17:0	N _{RF1} [17:0]	N-Divider for RF1 Synthesizer.
		Register reserved for Si4122G. Writes to this register can result in unpredictable behavior.



Register 4. RF2 N-Divider Address Field = A[3:0] = 0100

Bit	D17	D16	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
Name	0		N _{RF2} [16:0]															

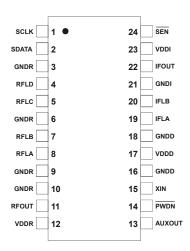
Bit	Name	Function
17	Reserved	Program to zero.
16:0	N _{RF2} [16:0]	N-Divider for RF2 Synthesizer.
		Register reserved for Si4123G. Writes to this register can result in unpredictable behavior.

Register 5. If	N-Divider	Address Field	(A[3:0]) = 0101
----------------	-----------	---------------	-----------------

Bit	D17	D16	D15	D15 D14 D13 D12 D11 D10 D9 D8 D7 D6 D5 D4 D3								D2	D1	D0					
Name	0	0		N _{IF} [15:0]									1						
Bit			Na	Name Function															
17:16	6		Rese	erved		Pro	Program to zero.												
15:0		N _{IF} [15:0]				Re	N-Divider for IF Synthesizer. Register reserved for Si4113G. Writes to this register can result in unpredictable behavior.												



Pin Descriptions: Si4133G-BT



Pin Number	Name	Description
1	SCLK	Serial clock input
2	SDATA	Serial data input
3	GNDR	Common ground for RF analog circuitry
4	RFLD	Pins for inductor connection to RF2 VCO
5	RFLC	Pins for inductor connection to RF2 VCO
6	GNDR	Common ground for RF analog circuitry
7	RFLB	Pins for inductor connection to RF1 VCO
8	RFLA	Pins for inductor connection to RF1 VCO
9	GNDR	Common ground for RF analog circuitry
10	GNDR	Common ground for RF analog circuitry
11	RFOUT	Radio frequency (RF) output of the selected RF VCO
12	VDDR	Supply voltage for the RF analog circuitry
13	AUXOUT	Auxiliary output
14	PWDN	Powerdown input pin
15	XIN	Reference frequency amplifier input
16	GNDD	Common ground for digital circuitry
17	VDDD	Supply voltage for digital circuitry
18	GNDD	Common ground for digital circuitry
19	IFLA	Pins for inductor connection to IF VCO
20	IFLB	Pins for inductor connection to IF VCO
21	GNDI	Common ground for IF analog circuitry
22	IFOUT	Intermediate frequency (IF) output of the IF VCO
23	VDDI	Supply voltage for IF analog circuitry
24	SEN	Enable serial port input

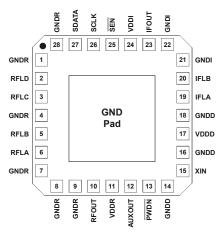


		Γ		
Pin Number	Si4133G-BT	Si4123G-BT	Si4122G-BT	Si4113G-BT
1	SCLK	SCLK	SCLK	SCLK
2	SDATA	SDATA	SDATA	SDATA
3	GNDR	GNDR	GNDR	GNDR
4	RFLD	GNDR	RFLD	RFLD
5	RFLC	GNDR	RFLC	RFLC
6	GNDR	GNDR	GNDR	GNDR
7	RFLB	RFLB	GNDR	RFLB
8	RFLA	RFLA	GNDR	RFLA
9	GNDR	GNDR	GNDR	GNDR
10	GNDR	GNDR	GNDR	GNDR
11	RFOUT	RFOUT	RFOUT	RFOUT
12	VDDR	VDDR	VDDR	VDDR
13	AUXOUT	AUXOUT	AUXOUT	AUXOUT
14	PWDN	PWDN	PWDN	PWDN
15	XIN	XIN	XIN	XIN
16	GNDD	GNDD	GNDD	GNDD
17	VDDD	VDDD	VDDD	VDDD
18	GNDD	GNDD	GNDD	GNDD
19	IFLA	IFLA	IFLA	GNDD
20	IFLB	IFLB	IFLB	GNDD
21	GNDI	GNDI	GNDI	GNDD
22	IFOUT	IFOUT	IFOUT	GNDD
23	VDDI	VDDI	VDDI	VDDD
24	SEN	SEN	SEN	SEN

 Table 11. Pin Descriptions for Si4133G Derivatives—TSSOP



Pin Descriptions: Si4133G-BM



Pin Number	Name	Description	
1	GNDR	Common ground for RF analog circuitry	
2	RFLD	Pins for inductor connection to RF2 VCO	
3	RFLC	Pins for inductor connection to RF2 VCO	
4	GNDR	Common ground for RF analog circuitry	
5	RFLB	Pins for inductor connection to RF1 VCO	
6	RFLA	Pins for inductor connection to RF1 VCO	
7	GNDR	Common ground for RF analog circuitry	
8	GNDR	Common ground for RF analog circuitry	
9	GNDR	Common ground for RF analog circuitry	
10	RFOUT	Radio frequency (RF) output of the selected RF VCO	
11	VDDR	Supply voltage for the RF analog circuitry	
12	AUXOUT	Auxiliary output	
13	PWDN	Powerdown input pin	
14	GNDD	Common ground for digital circuitry	
15	XIN	Reference frequency amplifier input	
16	GNDD	Common ground for digital circuitry	
17	VDDD	Supply voltage for digital circuitry	
18	GNDD	Common ground for digital circuitry	
19	IFLA	Pins for inductor connection to IF VCO	
20	IFLB	Pins for inductor connection to IF VCO	
21	GNDI	Common ground for IF analog circuitry	
22	GNDI	Common ground for IF analog circuitry	
23	IFOUT	Intermediate frequency (IF) output of the IF VCO	
24	VDDI	Supply voltage for IF analog circuitry	
25	SEN	Enable serial port input	
26	SCLK	Serial clock input	
27	SDATA	Serial data input	
28	GNDR	Common ground for RF analog circuitry	



Pin Number	Si4133G-BM	Si4123G-BM	Si4122G-BM	Si4113G-BM
1	GNDR	GNDR	GNDR	GNDR
2	RFLD	GNDR	RFLD	RFLD
3	RFLC	GNDR	RFLC	RFLC
4	GNDR	GNDR	GNDR	GNDR
5	RFLB	RFLB	GNDR	RFLB
6	RFLA	RFLA	GNDR	RFLA
7	GNDR	GNDR	GNDR	GNDR
8	GNDR	GNDR	GNDR	GNDR
9	GNDR	GNDR	GNDR	GNDR
10	RFOUT	RFOUT	RFOUT	RFOUT
11	VDDR	VDDR	VDDR	VDDR
12	AUXOUT	AUXOUT	AUXOUT	AUXOUT
13	PWDN	PWDN	PWDN	PWDN
14	GNDD	GNDD	GNDD	GNDD
15	XIN	XIN	XIN	XIN
16	GNDD	GNDD	GNDD	GNDD
17	VDDD	VDDD	VDDD	VDDD
18	GNDD	GNDD	GNDD	GNDD
19	IFLA	IFLA	IFLA	GNDD
20	IFLB	IFLB	IFLB	GNDD
21	GNDI	GNDI	GNDI	GNDD
22	GNDI	GNDI	GNDI	GNDD
23	IFOUT	IFOUT	IFOUT	GNDD
24	VDDI	VDDI	VDDI	VDDD
25	SEN	SEN	SEN	SEN
26	SCLK	SCLK	SCLK	SCLK
27	SDATA	SDATA	SDATA	SDATA
28	GNDR	GNDR	GNDR	GNDR

 Table 12. Pin Descriptions for Si4133G Derivatives—MLP



Ordering Guide

Ordering Part Number	Description	Operating Temperature	
Si4133G-BT* Si4133G-BM	RF1/RF2/IF	–20 to 85 °C	
Si4123G-BT* Si4123G-BM	RF1/IF	–20 to 85 [°] C	
Si4122G-BT* Si4122G-BM	RF2/IF	–20 to 85 [°] C	
Si4113G-BT* Si4113G-BM	RF1/RF2	–20 to 85 °C	
*Note: TSSOP not recommended for new designs.			

Si4133G Derivative Devices

The Si4133G performs both IF and dual-band RF frequency synthesis. The Si4113G, Si4122G, and the Si4123G are derivatives of this device. Table 13 outlines which synthesizers each derivative device features as well as which pins and registers coincide with each synthesizer.

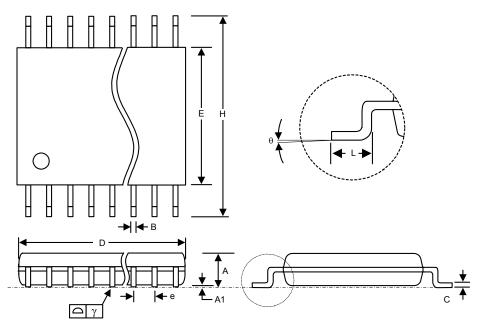
Table 13. S	i4133G Derivatives
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Name	Synthesizer	Pins	Registers
Si4113G	RF1, RF2	RFLA, RFLB, RFLC, RFLD	N_{RF1} , N_{RF2} , R_{RF1} , R_{RF2} , PDRB, AUTOPDB = 0, PDIB = 0
Si4122G	RF2, IF	RFLC, RFLD, IFLA, IFLB	N _{RF2} , R _{RF2} , PDRB, N _{IF} , R _{IF} , PDIB, LPWR
Si4123G	RF1, IF	RFLA, RFLB, IFLA, IFLB	N _{RF1} , R _{RF1} , PDRB, N _{IF} , R _{IF} , PDIB, LPWR
Si4133G	RF1, RF2, IF	RFLA, RFLB, RFLC, RFLD, IFLA, IFLB	N _{RF1} , N _{RF2} , R _{RF1} , R _{RF2} , PDRB, N _{IF} , R _{IF} , PDIB, LPWR



Package Outline: Si4133G-BT

Figure 19 illustrates the package details for the Si4133G-BT. Table 14 lists the values for the dimensions shown in the illustration.



Approximate device weight is 115.7 mg.



	Millim			
Symbol	Min	Мах	Typical*	
А	_	1.20	\checkmark	
A1	0.05	0.15	\checkmark	
В	0.19	0.30		
С	0.09	0.20	\checkmark	
D	7.70	7.90		
Е	4.30	4.50		
е	0.65 BSC			
Н	6.40			
L	0.45	0.75		
θ	0°	8°	\checkmark	
γ		0.10		
*Note: To guarantee coplanarity (γ), the parameters marked "Typical" may be exceeded.				

Table 14. Package Diagram Dimensions



Package Outline: Si4133G-BM

Figure 20 illustrates the package details for the Si4133G-BM. Table 15 lists the values for the dimensions shown in the illustration.

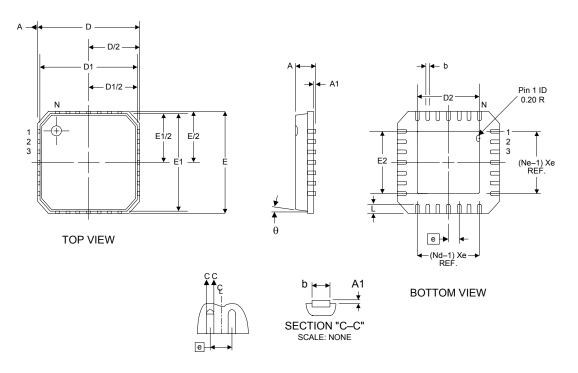


Figure 20. 28-Pin Micro Leadframe Package (MLP)

Symbol	Millimeters			
	Min	Nom	Max	
А		0.85	0.90	
A1	0.00	0.01	0.05	
b	0.18	0.23	0.30	
D, E	5.00 BSC			
D1, E1	4.75 BSC			
D2	2.55	2.70	2.85	
E2	2.55	2.70	2.85	
Ν	28			
Nd	7			
Ne	7			
е	0.50 BSC			
L	0.50	0.60	0.75	
θ			12°	

Table 15. Package Dimensions



Document Change List

Revision 1.3 to Revision 1.4

■ TSSOP outline updated.



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