SANYO *SANYO Semiconductors*

DATA SHEET

Monolithic Digital IC

LB11685VH — 3-phase sensor less Motor driver

Overview

The LB11685VH is a three-phase full-wave current-linear-drive motor driver IC. It adopts a sensor less control system without the use of a Hall Effect device. For quieter operation, the LB11685VH features a current soft switching circuit and be optimal for driving the cooling fan motors used in refrigerators, etc.

Functions

- Three-phase full-wave linear drive (Hall sensor-less method)
- Built-in three-phase output voltage control circuit
- Built-in current limiter circuit
- Built-in motor lock protection circuit
- Motor lock protection detection output
- FG output made by back EMF
- Built-in thermal shut down circuit
- Beat lock prevention circuit

Specifications

Maximum Ratings at Ta = 25°C

Parameter	Symbol	Conditions	Ratings	Unit
Maximum supply voltage	V_{CC} max		19	V
Input applied voltage	V_{IN} max		-0.3 to V_{CC} +0.3	V
Maximum output current	I_O max *1		1.2	A
Allowable power dissipation	Pd max	Mounted on a board *2	1.4	W
Operating temperature	Topr		-40 to 85	°C
Storage temperature	Tstg		-55 to 150	°C
Junction temperature	Tj max		150	°C

*1: The I_O is a peak value of motor-current.

*2: Specified board: 76.1mm × 114.3mm × 1.6mm, glass epoxy board.

LB11685VH

Recommended Operating Conditions at Ta = 25°C

Parameter	Symbol	Conditions	Ratings	Unit
Recommended Supply voltage	V_{CC}		12.0	V
Operating supply voltage	V_{CC} op		4.5 or 18.0	V

Electrical Characteristics at Ta = 25°C, V_{CC} = 5.0V

Parameter	Symbol	Conditions	Ratings			Unit
			min	typ	max	
Supply current	I_{CC}	FC1 = FC2 = 0V	5	10	20	mA
Internal regulate voltage	VREG		3.0	3.3	3.6	V
Output voltage (source)	VOSOUR	I_O = 0.8A *3		1.3	1.7	V
Output voltage (sink)	VOSINK	I_O = 0.8A *3		0.5	1.3	V
Current limiter	VOLIM		0.268	0.300	0.332	V
MCOM pin common-input voltage range	VINCOM		0		V_{CC} - 2	V
MCOM pin Source current for hysteresis	ICOM+	MCOM = 7V	30		80	μA
MCOM pin Sink current for hysteresis	ICOM-	MCOM = 7V	30		80	μA
MCOM pin hysteresis current ratio	RTCOM	RTCOM = ICOM+ / ICOM-	0.6		1.4	
VCO input bias current	I_{VCO}	V_{CO} = 2.3V			0.2	μA
VCO oscillation minimum frequency	f_{VCO}min	V_{CO} = 2.1V, CX = 0.015μF Design target *2		930		Hz
VCO oscillation maximum frequency	f_{VCO}max	V_{CO} = 2.7V, CX = 0.015μF Design target *2		8.6		kHz
CX charge / discharge current	I_{CX}	V_{CO} = 2.5V, CX = 1.6V	70	100	140	μA
CX hysteresis voltage	ΔVCX		0.35	0.55	0.75	
C1 (C2) charge current	IC1(2)+	V_{CO} = 2.5V, C1(2) = 1.3V	12	20	28	μA
C1 (C2) discharge current	IC1(2)-	V_{CO} = 2.5V, C1(2) = 1.3V	12	20	28	μA
C1 (C2) charge / discharge current ratio	RTC1(2)	RTC1(2) = IC1(2)+ / IC1(2)-	0.8	1.0	1.2	
C1/C2 charge current ratio	RTCCHG	RTCCHG = IC1+ / IC2+	0.8	1.0	1.2	
C1/C2 discharge current ratio	RTCDIS	RTCDIS = IC1- / IC2-	0.8	1.0	1.2	
C1 (C2) cramp voltage width	VCW1(2)		1.0	1.3	1.6	V
FG output low level voltage	VFGL	IFG = 3mA			0.5	V
RD output low level voltage	VRDL	IRD = 3mA			0.5	v
Thermal shut down operating temperature *1	TTSD	Junction temperature Design target *2	150	180		°C
Thermal shut down hysteresis temperature *1	ΔTTSD	Junction temperature Design target *2		15		°C

*1: The thermal shut down circuit is built-in for protection from damage of IC. But its operation is out of Topr. Design thermal calculation at normal operation.
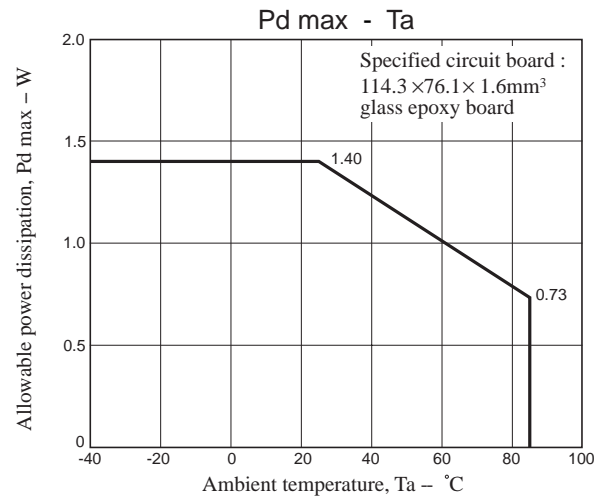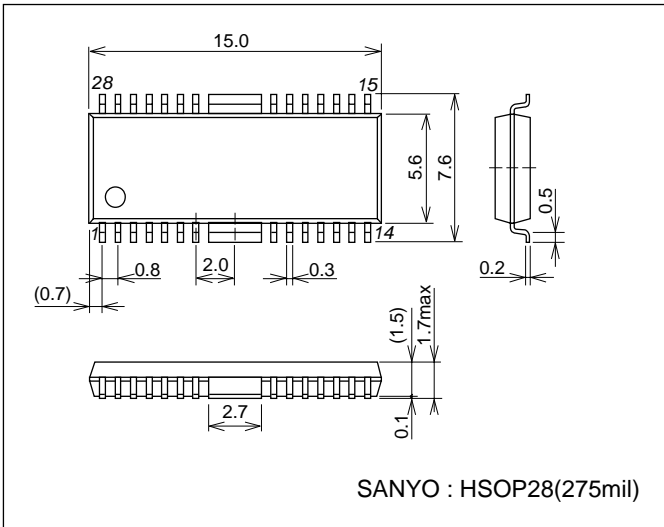
*2: Design target value and no measurement is made.
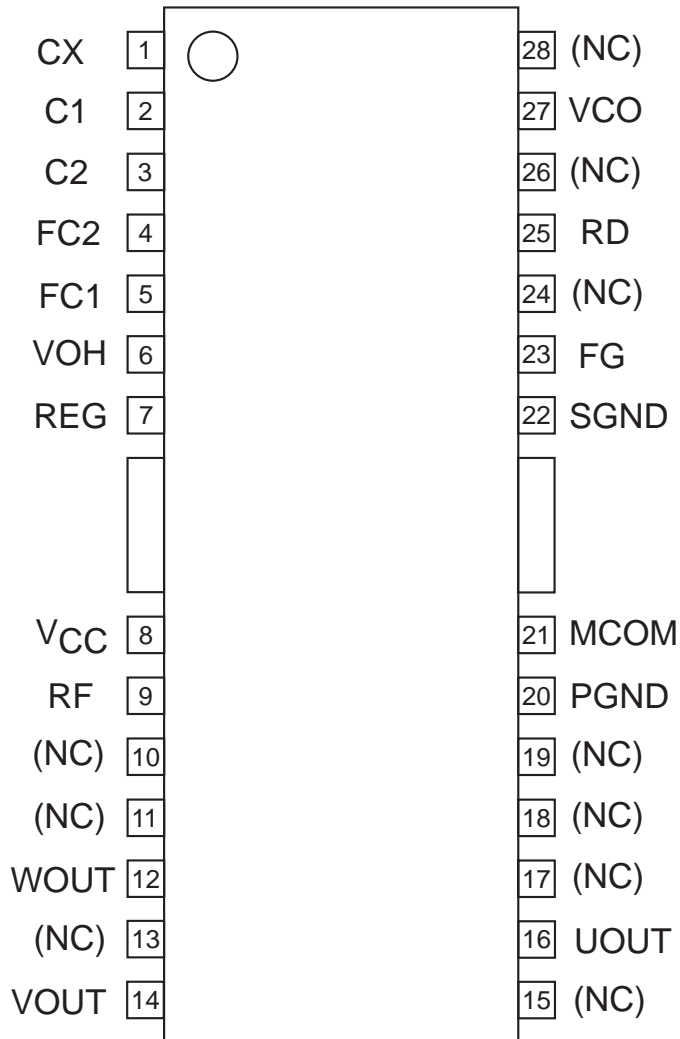
*3: The I_O is a peak value of motor-current.

Package Dimensions

unit : mm (typ)

3222A
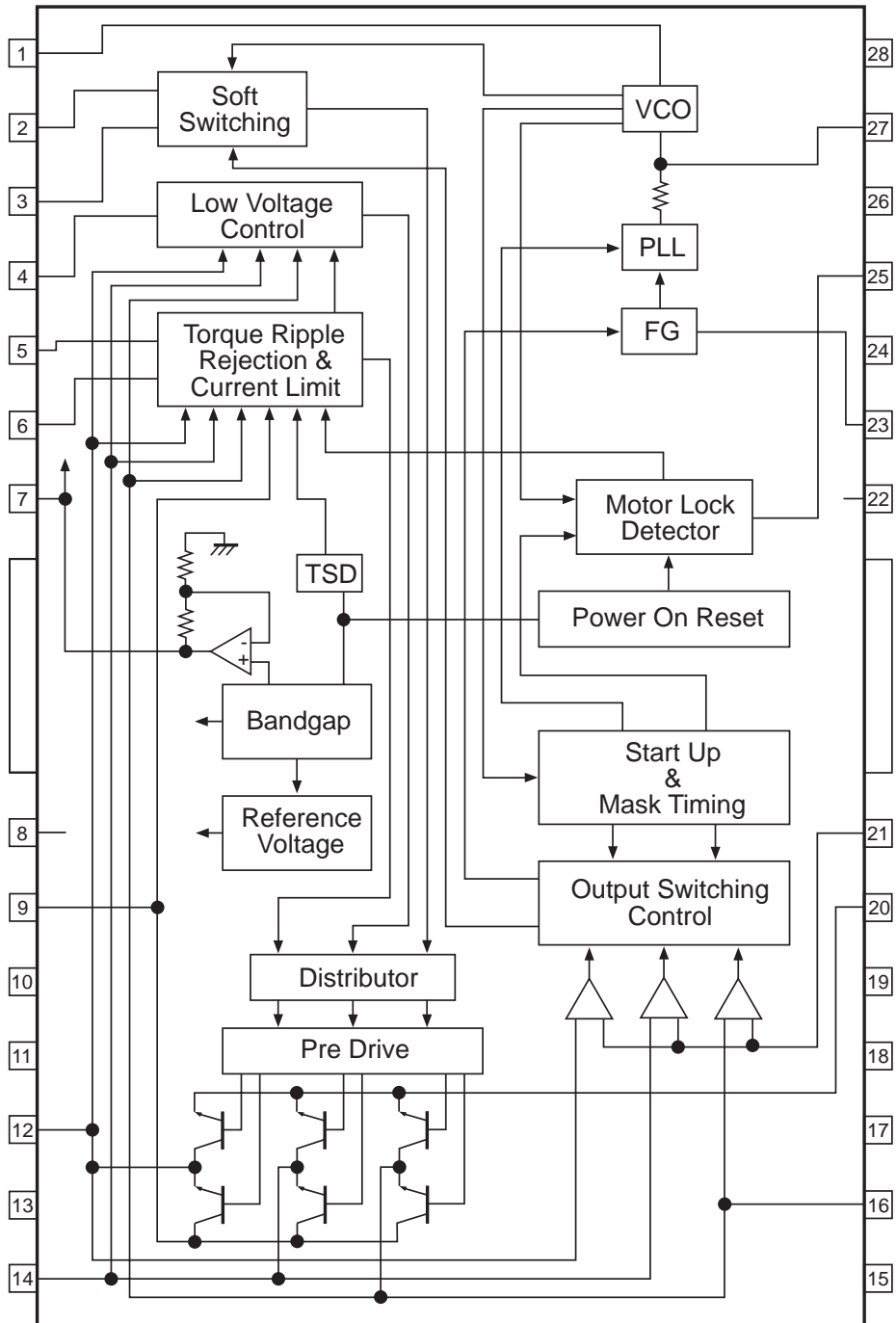
SANYO : HSOP28(275mil)

Pd max - Ta

Specified circuit board : 114.3 ×76.1× 1.6mm³ glass epoxy board

Allowable power dissipation, Pd max – W

Ambient temperature, Ta – ˚C

1.40

0.73

Pin Assignment

CX	1	28	(NC)
C1	2	27	VCO
C2	3	26	(NC)
FC2	4	25	RD
FC1	5	24	(NC)
VOH	6	23	FG
REG	7	22	SGND
V_{CC}	8	21	MCOM
RF	9	20	PGND
(NC)	10	19	(NC)
(NC)	11	18	(NC)
WOUT	12	17	(NC)
(NC)	13	16	UOUT
VOUT	14	15	(NC)

Block Diagram

Pin Function

Pin No.	Pin name	Function	Equivalent circuit
16 12 14	UOUT WOUT VOUT	Each output pin of three phases.	
20	PGND	GND pin in the output part. This pin is connected to GND. The SGND pin is also connected to GND	
9	RF	Pin to detect output current. By connecting a resistor between this pin and V_{CC}, the output current is detected as a voltage. The current limiter is operated by this voltage.	
21	MCOM	Motor coil midpoint input pin. The coil voltage waveform is detected based on this voltage.	
22	SGND	Ground pin (except the output part) This pin is connected to GND. The PGND pin is also connected to GND.	
23	FG	FG out made by back EMF pin. It synchronizes FG out with inverted V-phase. When don't use this function, open this pin.	
25	RD	Motor lock protection detection output pin. Output with L during rotation of motor. Open during lock protection of motor (High-impedance). When don't use this function, open this pin.	
27	VCO	PLL output pin and VCO input pin. To stabilize PLL output, connect a capacitor between this pin and GND.	
1	CX	VCO oscillation output pin. Operation frequency range and minimum frequency are determined by the capacity of the capacitor connected to this pin.	

Continue from the former page.
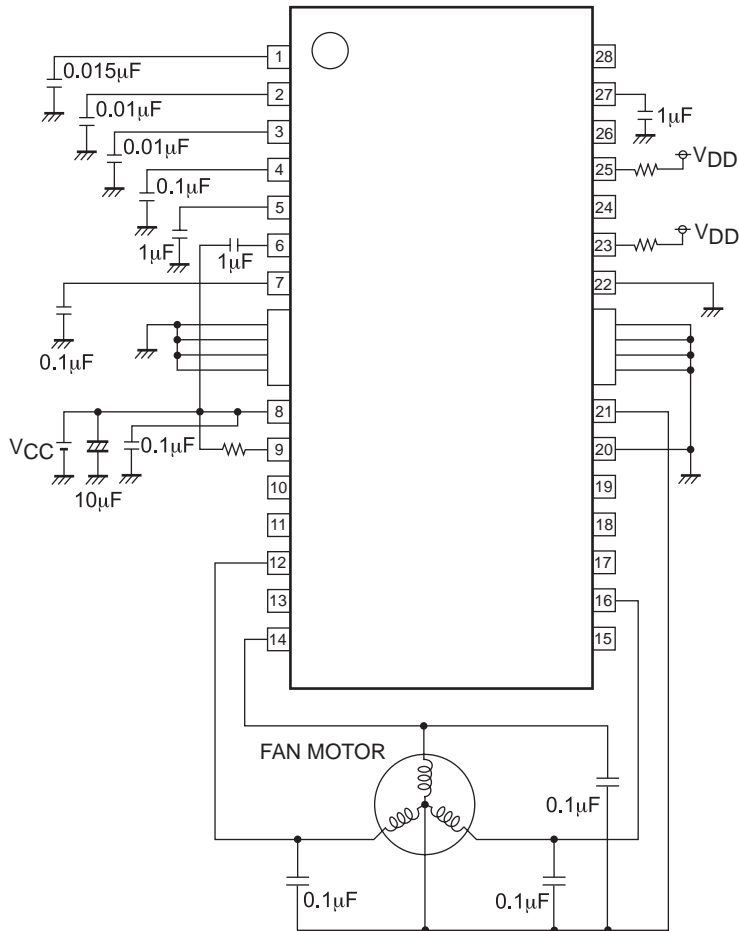
Pin No.	Pin name	Function	Equivalent circuit
2 3	C1 C2	Soft switching adjustment pin. The triangular wave from is form formed by connecting a capacitor with this pin. And, the switching of three-phase output is adjusted by the slope.	
4	FC2	Frequency characteristic correction pin 2. To suppress the oscillation of control system closed loop of sink-side, connect a capacitor between this pin and GND.	
5	FC1	Frequency characteristic correction pin 1. To suppress the oscillation of control system closed loop of source-side, connect a capacitor between this pin and GND.	
6	VOH	Three-phase output high level output pin. To stabilize the output voltage of this pin, connect a capacitor between this pin and the V_{CC} pin.	
7	VREG	DC voltage (3.3V) output pin. Connect a capacitor between this pin and GND for stabilization.	
19	VCC	Pin to supply power-supply voltage. To curb the influence of ripple and noise. The voltage should be stabilized.	

Application Circuit Example

* Each fixed number in the following FIG, is the referential value.

This catalog provides information as of June, 2010. Specifications and information herein are subject to change without notice.