# **Am50DL9608G**

Data Sheet



July 2003

The following document specifies Spansion memory products that are now offered by both Advanced Micro Devices and Fujitsu. Although the document is marked with the name of the company that originally developed the specification, these products will be offered to customers of both AMD and Fujitsu.

### **Continuity of Specifications**

There is no change to this datasheet as a result of offering the device as a Spansion product. Any changes that have been made are the result of normal datasheet improvement and are noted in the document revision summary, where supported. Future routine revisions will occur when appropriate, and changes will be noted in a revision summary.

# **Continuity of Ordering Part Numbers**

AMD and Fujitsu continue to support existing part numbers beginning with "Am" and "MBM". To order these products, please use only the Ordering Part Numbers listed in this document.

#### For More Information

Please contact your local AMD or Fujitsu sales office for additional information about Spansion memory solutions.







# Am50DL9608G

# Stacked Multi-Chip Package (MCP) Flash Memory and Pseudo SRAM 64 Megabit (4 M x 16-Bit) and 32 Megabit (2 M x 16-Bit) CMOS 3.0 Volt-only, Simultaneous Operation Flash Memories, and

8 Mbit (512 K x 16-Bit) Pseudo Static RAM

#### DISTINCTIVE CHARACTERISTICS

#### **MCP Features**

- Power supply voltage of 2.7 to 3.3 volt
- High performance
  - Flash access time as fast as 70 ns
  - Pseudo SRAM access time as fast as 55 ns
- Package
  - 73-Ball FBGA
- Operating Temperature
  - -40°C to +85°C

# Flash Memory Features (Am29DL640G/Am29DL320G)

Features apply to Am29DL640G and Am29DL320G independently.

#### **ARCHITECTURAL ADVANTAGES**

- Simultaneous Read/Write operations
  - Data can be continuously read from one bank while executing erase/program functions in another bank.
  - Zero latency between read and write operations
- Flexible Bank™ architecture
  - Read may occur in any of the three banks not being written or erased.
  - Four banks may be grouped by customer to achieve desired bank divisions.
- Manufactured on 0.17 µm process technology
- SecSi<sup>™</sup> (Secured Silicon) Sector
  - Extra 256 byte sector on Am29DL640G
  - Extra 256 byte sector on Am29DL320G
  - Factory locked and identifiable: 16 bytes available for secure, random factory Electronic Serial Number; verifiable as factory locked through autoselect function. ExpressFlash option allows entire sector to be available for factory-secured data
  - Customer lockable: Sector is one-time programmable.
     Once sector is locked, data cannot be changed.
- Zero Power Operation
  - Sophisticated power management circuits reduce power consumed during inactive periods to nearly zero.
- Boot sectors
  - Top and bottom boot sectors in Am29DL640G
  - Top or bottom boot options in Am29DL320G
- Compatible with JEDEC standards
  - Pinout and software compatible with single-power-supply flash standard

#### PERFORMANCE CHARACTERISTICS

High performance

- Access time as fast as 70 ns
- Program time: 4 μs/word typical utilizing Accelerate function

#### ■ Ultra low power consumption (typical values)

- 2 mA active read current at 1 MHz
- 10 mA active read current at 5 MHz
- 200 nA in standby or automatic sleep mode
- Minimum 1 million erase cycles guaranteed per sector
- 20 year data retention at 125°C
  - Reliable operation for the life of the system

#### **SOFTWARE FEATURES**

- Supports Common Flash Memory Interface (CFI)
- Program/Erase Suspend/Erase Resume
  - Suspends program/erase operations to allow programming/erasing in same bank
- Data# Polling and Toggle Bits
  - Provides a software method of detecting the status of program or erase cycles

#### HARDWARE FEATURES

- Any combination of sectors can be erased
- Ready/Busy# output (RY/BY#)
  - Hardware method for detecting program or erase cycle completion
- Hardware reset pin (RESET#)
  - Hardware method of resetting the internal state machine to the read mode
- **■** WP#/ACC input pin
  - Write protect (WP#) protects sectors 0, 1, 140, and 141 in Am29DL640G, and two outermost boot sectors in Am29DL320G
  - Acceleration (ACC) function accelerates program timing
- Sector protection
  - Hardware method of locking a sector, either in-system or using programming equipment, to prevent any program or erase operation within that sector
  - Temporary Sector Unprotect allows changing data in protected sectors in-system

#### **Pseudo SRAM Features**

- Power dissipation
  - Operating: 30 mA maximum
  - Standby: 60 μA maximum
- CE1s# and CE2s Chip Select
- Power down features using CE1s# and CE2s
- Data retention supply voltage: 2.7 to 3.3 volt
- Byte data control: LB#s (DQ7-DQ0), UB#s (DQ15-DQ8)

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#### **GENERAL DESCRIPTION**

The Am50DL9608G consists of two flash memory devices (one 64-Mbit Am29DL640G and one 32-Mbit Am29DL320G), and one 8 Mbit pseudo SRAM device.

#### Am29DL640G and Am29DL320G Features

Am29DL640G is a 64 megabit, 3.0 volt-only flash memory device, organized as 4,194,304 words. The Am29DL320G is a 32 megabit, 3.0 volt-only flash memory device, organized as 2,097,152 words. Word mode data appears on DQ15–DQ0. The device is designed to be programmed in-system with the standard 3.0 volt  $V_{\rm CC}$  supply, and can also be programmed in standard EPROM programmers.

The device is available with an access time of 70 or 85 ns and is offered in a 73-ball FBGA package. Standard control pins—chip enable (CE#fx), write enable (WE#), and output enable (OE#)—control normal read and write operations, and avoid bus contention issues.

The device requires only a **single 3.0 volt power sup- ply** for both read and write functions. Internally generated and regulated voltages are provided for the program and erase operations.

# Simultaneous Read/Write Operations with Zero Latency

The Simultaneous Read/Write architecture provides **simultaneous operation** by dividing the memory space into **four banks**. Sector addresses are fixed, system software can be used to form user-defined bank groups.

During an Erase/Program operation, any of the three non-busy banks may be read from. Note that only two banks can operate simultaneously. The device can improve overall system performance by allowing a host system to program or erase in one bank, then immediately and simultaneously read from the other bank, with zero latency. This releases the system from waiting for the completion of program or erase operations.

The Am29DL640G can be organized as both a top and bottom boot sector configuration.

Bank	Megabits	Sector Sizes
Bank 1	8 Mb	Eight 4 Kword, Fifteen 32 Kword
Bank 2	24 Mb	Forty-eight 32 Kword
Bank 3	24 Mb	Forty-eight 32 Kword
Bank 4	8 Mb	Eight 4 Kword, Fifteen 32 Kword

The Am29DL320G can be organized as either a top or bottom boot sector configuration. Top boot configuration is shown in the following table.

Bank	Megabits	Sector Sizes
Bank 1	4 Mb	Eight 4 Kword, Seven 32 Kword
Bank 2	12 Mb	Twenty-four 32 Kword
Bank 3	12 Mb	Twenty-four 32 Kword
Bank 4	4 Mb	Eight 32 Kword

Bottom boot configuration is shown in the following ta-

Bank	Megabits	Sector Sizes	
Bank 1	4 Mb	Eight 32 Kword	
Bank 2	12 Mb	Twenty-four 32 Kword	
Bank 3	12 Mb	Twenty-four 32 Kword	
Bank 4	4 Mb	Eight 4 Kword,	
Dailk 4	4 IVID	Seven 32 Kword	

Available on Am29DL640G and Am29DL320G, the SecSi™ (Secured Silicon) Sector is an extra 256 byte sector capable of being permanently locked by AMD or customers. The Secure SectorSecSi Indicator Bit (DQ7) is permanently set to a 1 if the part is factory locked, and set to a 0 if customer lockable. This way, customer lockable parts can never be used to replace a factory locked part.

Factory locked parts provide several options. The Secure SectorSecSi Sector may store a secure, random 16 byte ESN (Electronic Serial Number), customer code (programmed through AMD's ExpressFlash service), or both. Customer Lockable parts may utilize the Secure SectorSecSi Sector as a one-time programmable area.

The AMD **DMS** (**Data Management Software**) manages data programming, enables EEPROM emulation, and eases historical sector erase flash limitations. For more information on DMS or to obtain the software, contact AMD or an authorized representative.

The device offers complete compatibility with the JEDEC single-power-supply Flash command set standard. Commands are written to the command register using standard microprocessor write timings. Reading data out of the device is similar to reading from other Flash or EPROM devices.

The host system can detect whether a program or erase operation is complete by using the device **status bits:** RY/BY# pin, DQ7 (Data# Polling) and DQ6/DQ2 (toggle bits). After a program or erase cycle has been completed, the device automatically returns to the read mode.

The **sector erase architecture** allows memory sectors to be erased and reprogrammed without affecting the data contents of other sectors. The device is fully erased when shipped from the factory.

Hardware data protection measures include a low  $V_{CC}$  detector that automatically inhibits write operations during power transitions. The **hardware sector** protection feature disables both program and erase operations in any combination of the sectors of memory. This can be achieved in-system or via programming equipment.

The device offers two power-saving features. When addresses have been stable for a specified amount of time, the device enters the **automatic sleep mode**. The system can also place the device into the **standby mode**. Power consumption is greatly reduced in both modes.



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## PRELIMINARY

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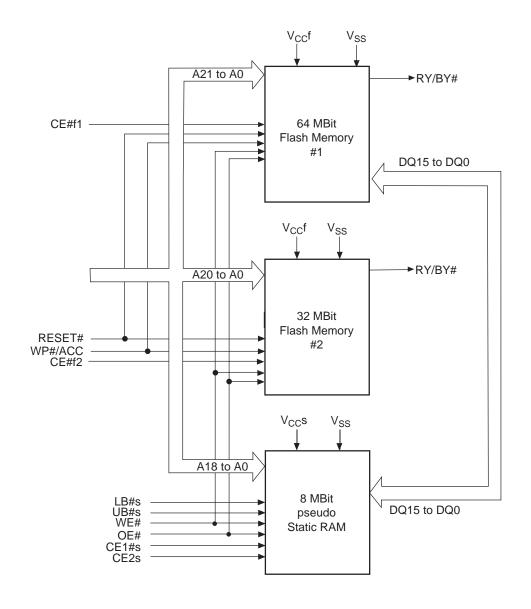
**Am50DL9608G** May 19, 2003



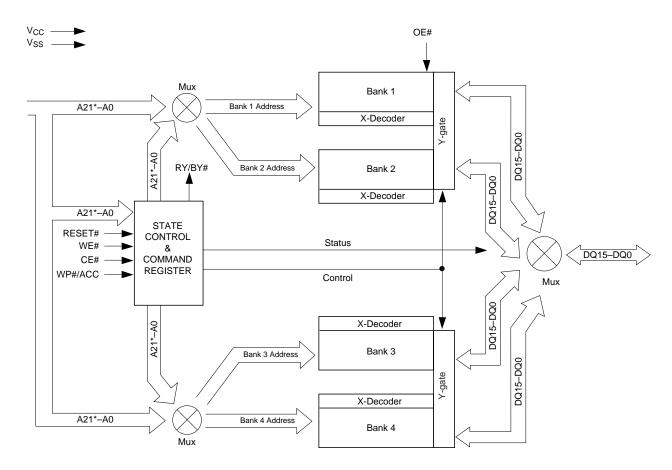
### PRODUCT SELECTOR GUIDE

Part Number		Am50DL9608G					
Speed	Standard Voltage Range:		Memory , Am29DL320G)	Pseudo SRAM			
Options	V <sub>CC</sub> = 2.7–3.3 V	75	70	75	70		
Max Access	Max Access Time (ns)		70	55	70		
CE# Access (ns)		70	70	55	70		
OE# Access (ns)		30	30	30	35		

### MCP BLOCK DIAGRAM



#### FLASH MEMORY BLOCK DIAGRAM

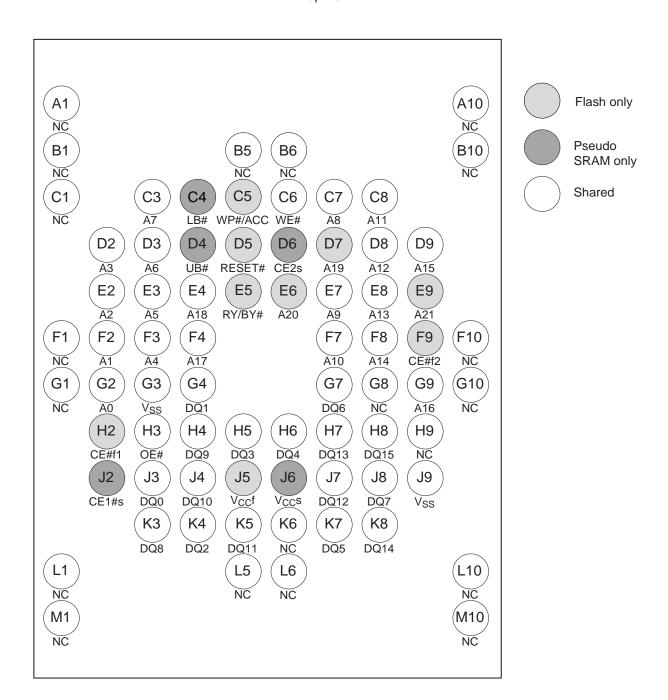


<sup>\*</sup> Addresses for Am29DL640G are A21-A0. Address for Am29DL320G are A20-A0.



#### **CONNECTION DIAGRAM**

# **73-Ball FBGA**Top View



# **Special Package Handling Instructions**

Special handling is required for Flash Memory products in molded packages (BGA). The package and/or data

integrity may be compromised if the package body is exposed to temperatures above 150°C for prolonged periods of time.

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#### PIN DESCRIPTION

A18-A0 = 19 Address Inputs (Common)

A21-A19, A-1 = 4 Address Inputs (Flash)

DQ15-DQ0 = 16 Data Inputs/Outputs (Common)

CE#f1 = Flash Chip Enable 1

(Am29DL640G)

CE#f2 = Flash Chip Enable 2

(Am29DL320G)

CE#1s = Pseudo SRAM Chip Enable 1

CE2s = Pseudo SRAM Chip Enable 2

OE# = Output Enable (Common)

WE# = Write Enable (Common)

RY/BY# = Ready/Busy Output

UB#s = Upper Byte Control (Pseudo SRAM)

LB#s = Lower Byte Control (Pseudo SRAM)

RESET# = Hardware Reset Pin, Active Low

WP#/ACC = Hardware Write Protect/

Acceleration Pin (Flash)

 $V_{CC}f$  = Flash 3.0 volt-only single power sup-

ply (see Product Selector Guide for speed options and voltage supply

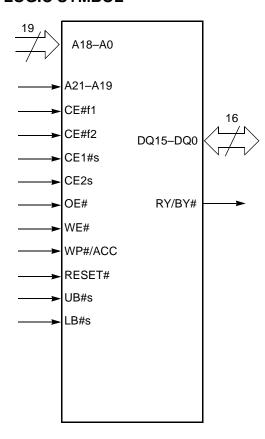
tolerances)

 $V_{CC}s$  = Pseudo SRAM Power Supply

V<sub>SS</sub> = Device Ground (Common)

NC = Pin Not Connected Internally

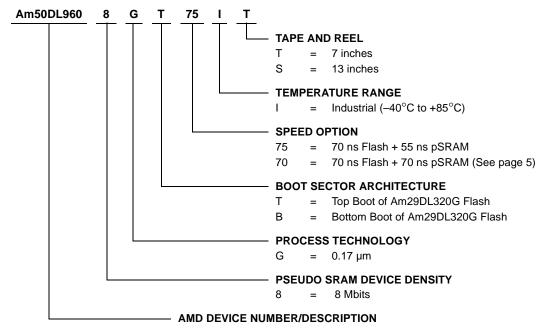
#### LOGIC SYMBOL





#### ORDERING INFORMATION

The order number (Valid Combination) is formed by the following:



Am50DL9608G Stacked Multi-Chip Package (MCP) Flash Memory and Pseudo SRAM Am29DL640G 64 Megabit (8/4 M x 16-Bit) and Am29DL320G 32 Megabit (4/2 M x 16-Bit) CMOS 3.0 Volt-only, Simultaneous Operation Flash Memory and 8 Mbit (152 K x 16-Bit) Pseudo Static RAM

#### **Valid Combinations**

Valid Combinations list configurations planned to be supported in volume for this device. Consult the local AMD sales office to confirm availability of specific valid combinations and to check on newly released combinations.

Valid Combinations							
Order Number Package Marking							
Am50DL9608GT70I Am50DL9608GB70I	T, S	M50000010 M50000011					
Am50DL9608GT75I Am50DL9608GB75I	T, S	M50000012 M50000013					

#### MCP DEVICE BUS OPERATIONS

This section describes the requirements and use of the device bus operations, which are initiated through the internal command register. The command register itself does not occupy any addressable memory location. The register is a latch used to store the commands, along with the address and data information needed to execute the command. The contents of the register serve as inputs to the internal state machine. The state machine outputs dictate the function of the device. Tables 1-2 lists the device bus operations, the inputs and control levels they require, and the resulting output. The following subsections describe each of these operations in further detail.

Table 1. Device Bus Operations—Flash Word Mode

Operation (Notes 1, 2)	CE#f1 CE#f2 (Note 7)	CE1#s (Note 8)	CE2s (Note 8)	OE#	WE#	Addr.	LB#s	UB#s	RESET#	WP#/ ACC (Note 4)	DQ7- DQ0	DQ15- DQ8
Read from Flash	L	H X	X L	L	Н	A <sub>IN</sub>	Х	Х	Н	L/H	D <sub>OUT</sub>	D <sub>OUT</sub>
Write to Flash	L	H X	X L	Н	L	A <sub>IN</sub>	Х	х	Н	(Note 4)	D <sub>IN</sub>	D <sub>IN</sub>
Standby	V <sub>CC</sub> ± 0.3 V	H X	X L	Х	Х	Х	Х	Х	V <sub>CC</sub> ± 0.3 V	Н	High-Z	High-Z
Output Disable	L	L	Н	H	H	X	L X	X L	Н	L/H	High-Z	High-Z
Flash Hardware Reset	Х	H X	X L	Х	Х	Х	Х	Х	L	L/H	High-Z	High-Z
Sector Protect (Note 5)	L	Х	X L	Н	L	SADD, A6 = L, A1 = H, A0 = L	х	х	V <sub>ID</sub>	L/H	D <sub>IN</sub>	Х
Sector Unprotect (Note 5)	L	H X	X L	Н	L	SADD, A6 = H, A1 = H, A0 = L	х	х	V <sub>ID</sub>	(Note 6)	D <sub>IN</sub>	Х
Temporary Sector Unprotect	Х	H X	X L	Х	х	Х	Х	Х	V <sub>ID</sub>	(Note 6)	D <sub>IN</sub>	High-Z
Read from Pseudo SRAM	Н	L	Н	L	Н	A <sub>IN</sub>	L H L	L L H	Н	Х	D <sub>OUT</sub> High-Z D <sub>OUT</sub>	D <sub>OUT</sub> D <sub>OUT</sub>
Write to Pseudo SRAM	Н	L	Н	х	L	A <sub>IN</sub>	L H L	L L H	Н	Х	D <sub>IN</sub> High-Z D <sub>IN</sub>	D <sub>IN</sub> D <sub>IN</sub> High-Z

**Legend:**  $L = Logic\ Low = V_{IL},\ H = Logic\ High = V_{IH},\ V_{ID} = 11.5-12.5\ V,\ V_{HH} = 9.0\pm0.5\ V,\ X = Don't\ Care,\ SADD = Flash\ Sector\ Address,\ A_{IN} = Address\ In,\ D_{IN} = Data\ In,\ D_{OUT} = Data\ Out$ 

#### Notes:

- 1. Other operations except for those indicated in this column are inhibited.
- 2. Do not apply  $CE\#x = V_{IL}$ ,  $CE1\#s = V_{IL}$  and  $CE2s = V_{IH}$  at the same time.
- 3. Don't care or open LB#s or UB#s.
- If WP#/ACC = V<sub>IL</sub>, the boot sectors will be protected. If WP#/ACC = V<sub>IH</sub> the boot sectors protection will be removed.
   If WP#/ACC = V<sub>ACC</sub> (9V), the program time will be reduced by 40%.
- 5. The sector protect and sector unprotect functions may also be implemented via programming equipment. See the "Sector/Sector Block Protection and Unprotection" section.
- If WP#/ACC = V<sub>IL</sub>, the two outermost boot sectors remain protected. If WP#/ACC = V<sub>IL</sub>, the two outermost boot sector protection depends on whether they were last protected or unprotected using the method described in "Sector/Sector Block Protection and Unprotection". If WP#/ACC = V<sub>ILL</sub> all sectors will be unprotected.
- Only one flash device should be accessed at a time. For Am29DL640G flash access, CE#f1 = V<sub>IL</sub>, CE#f2 = V<sub>IH</sub>. For Am29DL320G flash access, CE#f1 = V<sub>IH</sub>, CE#f2 = V<sub>IL</sub>.
- 8.  $CE\#1s=V_{IL}$ ,  $CE2s=V_{IH}$ ,  $CE\#1=V_{IH}$  and  $CE\#2=V_{IH}$  when accessing pseudo SRAM.

#### FLASH DEVICE BUS OPERATIONS

### **Requirements for Reading Array Data**

To read array data from the outputs, the system must drive the CE#f and OE# pins to  $V_{\rm IL}$ . CE#f is the power control and selects the device. OE# is the output control and gates array data to the output pins. WE# should remain at  $V_{\rm IH}$ .

The internal state machine is set for reading array data upon device power-up, or after a hardware reset. This ensures that no spurious alteration of the memory content occurs during the power transition. No command is necessary in this mode to obtain array data. Standard microprocessor read cycles that assert valid addresses on the device address inputs produce valid data on the device data outputs. Each bank remains enabled for read access until the command register contents are altered.

Refer to the AC Read-Only Operations table for timing specifications and to Figure 14 for the timing diagram.  $I_{CC1}$  in the DC Characteristics table represents the active current specification for reading array data.

#### Writing Commands/Command Sequences

To write a command or command sequence (which includes programming data to the device and erasing sectors of memory), the system must drive WE# and CE#f to  $V_{II}$ , and OE# to  $V_{IH}$ .

The device features an **Unlock Bypass** mode to facilitate faster programming. Once a bank enters the Unlock Bypass mode, only two write cycles are required to program a word or byte, instead of four. The "Byte/Word Program Command Sequence" section has details on programming data to the device using both standard and Unlock Bypass command sequences.

An erase operation can erase one sector, multiple sectors, or the entire device. Table 2 indicates the address space that each sector occupies. Similarly, a "sector address" is the address bits required to uniquely select a sector. The "Flash Command Definitions" section has details on erasing a sector or the entire chip, or suspending/resuming the erase operation.

The device address space is divided into four banks. A "bank address" is the address bits required to uniquely select a bank.

 $I_{\text{CC2}}$  in the DC Characteristics table represents the active current specification for the write mode. The Flash AC Characteristics section contains timing specification tables and timing diagrams for write operations.

#### **Accelerated Program Operation**

The device offers accelerated program operations through the ACC function. This is one of two functions

provided by the WP#/ACC pin. This function is primarily intended to allow faster manufacturing throughput at the factory.

If the system asserts  $V_{HH}$  on this pin, the device automatically enters the aforementioned Unlock Bypass mode, temporarily unprotects any protected sectors, and uses the higher voltage on the pin to reduce the time required for program operations. The system would use a two-cycle program command sequence as required by the Unlock Bypass mode. Removing  $V_{HH}$  from the WP#/ACC pin returns the device to normal operation. Note that  $V_{HH}$  must not be asserted on WP#/ACC for operations other than accelerated programming, or device damage may result. In addition, the WP#/ACC pin must not be left floating or unconnected; inconsistent behavior of the device may result. See "Write Protect (WP#)" on page 23 for related information.

#### **Autoselect Functions**

If the system writes the autoselect command sequence, the device enters the autoselect mode. The system can then read autoselect codes from the internal register (which is separate from the memory array) on DQ15–DQ0. Standard read cycle timings apply in this mode. Refer to the Sector/Sector Block Protection and Unprotection and Autoselect Command Sequence sections for more information.

# Simultaneous Read/Write Operations with Zero Latency

This device is capable of reading data from one bank of memory while programming or erasing in the other bank of memory. An erase operation may also be suspended to read from or program to another location within the same bank (except the sector being erased). Figure 19 shows how read and write cycles may be initiated for simultaneous operation with zero latency. I<sub>CC6</sub>f and I<sub>CC7</sub>f in the table represent the current specifications for read-while-program and read-while-erase, respectively.

### **Standby Mode**

When the system is not reading or writing to the device, it can place the device in the standby mode. In this mode, current consumption is greatly reduced, and the outputs are placed in the high impedance state, independent of the OE# input.

The device enters the CMOS standby mode when the CE#f and RESET# pins are both held at  $V_{CC} \pm 0.3~V.$  (Note that this is a more restricted voltage range than  $V_{IH}.)$  If CE#f and RESET# are held at  $V_{IH},$  but not within  $V_{CC} \pm 0.3~V,$  the device will be in the standby mode, but the standby current will be greater. The de-

vice requires standard access time ( $t_{CE}$ ) for read access when the device is in either of these standby modes, before it is ready to read data.

If the device is deselected during erasure or programming, the device draws active current until the operation is completed.

 $\ensuremath{I_{\text{CC3}}}\xspace f$  in the table represents the standby current specification.

### **Automatic Sleep Mode**

The automatic sleep mode minimizes Flash device energy consumption. The device automatically enables this mode when addresses remain stable for  $t_{\rm ACC}$  + 30 ns. The automatic sleep mode is independent of the CE#f, WE#, and OE# control signals. Standard address access timings provide new data when addresses are changed. While in sleep mode, output data is latched and always available to the system.  $I_{\rm CC5} f$  in the table represents the automatic sleep mode current specification.

#### **RESET#: Hardware Reset Pin**

The RESET# pin provides a hardware method of resetting the device to reading array data. When the RESET# pin is driven low for at least a period of  $t_{\rm RP}$ , the device immediately terminates any operation in progress, tristates all output pins, and ignores all read/write commands for the duration of the RESET# pulse. The device also resets the internal state machine to reading array data. The operation that was interrupted should be reinitiated once the device is

ready to accept another command sequence, to ensure data integrity.

Current is reduced for the duration of the RESET# pulse. When RESET# is held at  $V_{SS}\pm0.3$  V, the device draws CMOS standby current ( $I_{CC4}f$ ). If RESET# is held at  $V_{IL}$  but not within  $V_{SS}\pm0.3$  V, the standby current will be greater.

The RESET# pin may be tied to the system reset circuitry. A system reset would thus also reset the Flash memory, enabling the system to read the boot-up firmware from the Flash memory.

If RESET# is asserted during a program or erase operation, the RY/BY# pin remains a "0" (busy) until the internal reset operation is complete, which requires a time of  $t_{READY}$  (during Embedded Algorithms). The system can thus monitor RY/BY# to determine whether the reset operation is complete. If RESET# is asserted when a program or erase operation is not executing (RY/BY# pin is "1"), the reset operation is completed within a time of  $t_{READY}$  (not during Embedded Algorithms). The system can read data  $t_{RH}$  after the RESET# pin returns to  $V_{IH}$ .

Refer to the Flash AC Characteristics tables for RE-SET# parameters and to Figure 15 for the timing diagram.

### **Output Disable Mode**

When the OE# input is at  $V_{IH}$ , output from the device is disabled. The output pins are placed in the high impedance state.



Table 2. Am29DL640G Sector Architecture

Bank	Sector	Sector Address A21-A12	Sector Size (Kbytes/Kwords)	(x16) Address Range
	SA0	000000000	8/4	00000h-00FFFh
	SA1	000000001	8/4	01000h-01FFFh
	SA2	000000010	8/4	02000h-02FFFh
	SA3	000000011	8/4	03000h-03FFFh
	SA4	000000100	8/4	04000h-04FFFh
	SA5	000000101	8/4	05000h-05FFFh
	SA6	000000110	8/4	06000h-06FFFh
	SA7	000000111	8/4	07000h-07FFFh
	SA8	0000001xxx	64/32	08000h-0FFFFh
	SA9	0000010xxx	64/32	10000h-17FFFh
	SA10	0000011xxx	64/32	18000h-1FFFFh
Bank 1	SA11	0000100xxx	64/32	20000h-27FFFh
	SA12	0000101xxx	64/32	28000h-2FFFFh
	SA13	0000110xxx	64/32	30000h-37FFFh
	SA14	0000111xxx	64/32	38000h-3FFFFh
	SA15	0001000xxx	64/32	40000h-47FFFh
	SA16	0001001xxx	64/32	48000h-4FFFFh
	SA17	0001010xxx	64/32	50000h-57FFFh
	SA18	0001011xxx	64/32	58000h-5FFFFh
	SA19	0001100xxx	64/32	60000h-67FFFh
	SA20	0001101xxx	64/32	68000h-6FFFFh
	SA21	0001101xxx	64/32	70000h-77FFFh
	SA22	0001111xxx	64/32	78000h-7FFFFh

Table 2. Am29DL640G Sector Architecture (Continued)

Bank	Sector	Sector Address	Sector Size	(x16)	
Dank	Sector	A21-A12	(Kbytes/Kwords)	Address Range	
	SA23	0010000xxx	64/32	80000h-87FFFh	
	SA24	0010001xxx	64/32	88000h-8FFFFh	
	SA25	0010010xxx	64/32	90000h-97FFFh	
	SA26	0010011xxx	64/32	98000h-9FFFFh	
	SA27	0010100xxx	64/32	A0000h-A7FFFh	
	SA28	0010101xxx	64/32	A8000h-AFFFFh	
	SA29	0010110xxx	64/32	B0000h-B7FFFh	
	SA30	0010111xxx	64/32	B8000h-BFFFFh	
	SA31	0011000xxx	64/32	C0000h-C7FFFh	
	SA32	0011001xxx	64/32	C8000h-CFFFFh	
	SA33	0011010xxx	64/32	D0000h-D7FFFh	
	SA34	0011011xxx	64/32	D8000h-DFFFFh	
	SA35	0011000xxx	64/32	E0000h-E7FFFh	
	SA36	0011101xxx	64/32	E8000h-EFFFFh	
	SA37	0011110xxx	64/32	F0000h-F7FFFh	
	SA38	0011111xxx	64/32	F8000h-FFFFFh	
	SA39	0100000xxx	64/32	F9000h-107FFFh	
	SA40	0100001xxx	64/32	108000h-10FFFFh	
	SA41	0100010xxx	64/32	110000h-117FFFh	
	SA42	0101011xxx	64/32	118000h-11FFFFh	
	SA43	0100100xxx	64/32	120000h-127FFFh	
	SA44	0100101xxx	64/32	128000h-12FFFFh	
	SA45	0100110xxx	64/32	130000h-137FFFh	
Bank 2	SA46	0100111xxx	64/32	138000h-13FFFFh	
	SA47	0101000xxx	64/32	140000h-147FFFh	
	SA48	0101001xxx	64/32	148000h-14FFFFh	
	SA49	0101010xxx	64/32	150000h-157FFFh	
	SA50	0101011xxx	64/32	158000h-15FFFFh	
	SA51	0101100xxx	64/32	160000h-167FFFh	
	SA52	0101101xxx	64/32	168000h-16FFFFh	
	SA53	0101110xxx	64/32	170000h-177FFFh	
	SA54	0101111xxx	64/32	178000h-17FFFFh	
	SA55	0110000xxx	64/32	180000h-187FFFh	
	SA56	0110001xxx	64/32	188000h-18FFFFh	
	SA57	0110010xxx	64/32	190000h-197FFFh	
	SA58	0110011xxx	64/32	198000h-19FFFFh	
	SA59	0100100xxx	64/32	1A0000h-1A7FFFh	
	SA60	0110101xxx	64/32	1A8000h-1AFFFFh	
	SA61	0110110xxx	64/32	1B0000h-1B7FFFh	
	SA62	0110111xxx	64/32	1B8000h-1BFFFFh	
L	SA63	0111000xxx	64/32	1C0000h-1C7FFFh	
	SA64	0111001xxx	64/32	1C8000h-1CFFFFh	
	SA65	0111010xxx	64/32	1D0000h-1D7FFFh	
	SA66	0111011xxx	64/32	1D8000h-1DFFFFh	
	SA67	0111100xxx	64/32	1E0000h-1E7FFFh	
	SA68	0111101xxx	64/32	1E8000h-1EFFFFh	
	SA69	0111110xxx	64/32	1F0000h-1F7FFFh	
	SA70	0111111xxx	64/32	1F8000h-1FFFFFh	



Table 2. Am29DL640G Sector Architecture (Continued)

Bank	Sector	Sector Address A21–A12	Sector Size (Kbytes/Kwords)	(x16) Address Range	
	SA71	1000000xxx	64/32	200000h-207FFFh	
	SA72	1000001xxx	64/32	208000h-20FFFFh	
	SA73	1000010xxx	64/32	210000h-217FFFh	
	SA74	1000011xxx	64/32	218000h-21FFFFh	
	SA75	1000100xxx	64/32	220000h-227FFFh	
	SA76	1000101xxx	64/32	228000h-22FFFFh	
	SA77	1000110xxx	64/32	230000h-237FFFh	
	SA78	1000111xxx	64/32	238000h-23FFFFh	
	SA79	1001000xxx	64/32	240000h-247FFFh	
	SA80	1001001xxx	64/32	248000h-24FFFFh	
	SA81	1001010xxx	64/32	250000h-257FFFh	
	SA82	1001011xxx	64/32	258000h-25FFFFh	
	SA83	1001100xxx	64/32	260000h-267FFFh	
	SA84	1001101xxx	64/32	268000h-26FFFFh	
	SA85	1001110xxx	64/32	270000h-277FFFh	
	SA86	1001111xxx	64/32	278000h-27FFFh	
	SA87	1010000xxx	64/32	280000h-28FFFFh	
	SA88	1010001xxx	64/32	288000h-28FFFFh	
	SA89	1010010xxx	64/32	290000h-297FFFh	
	SA90	1010011xxx	64/32	298000h-29FFFFh	
	SA91	1010100xxx	64/32	2A0000h-2A7FFFh	
	SA92	1010101xxx	64/32	2A8000h–2AFFFFh	
	SA93	1010110xxx	64/32	2B0000h-2B7FFFh	
	SA94	1010111xxx	64/32	2B8000h–2BFFFFh	
Bank 3	SA95	1011000xxx	64/32	2C0000h-2C7FFh	
	SA96	1011001xxx	64/32	2C8000h–2CFFFFh	
	SA97	1011010xxx	64/32	2D0000h-2D7FFFh	
	SA98	1011011xxx	64/32	2D8000h–2DFFFFh	
	SA99	1011100xxx	64/32	2E0000h-2E7FFh	
	SA100	1011101xxx	64/32	2E8000h-2EFFFFh	
	SA101	1011110xxx	64/32	2F0000h-2FFFFh	
	SA102	1011111xxx	64/32	2F8000h–2FFFFFh	
	SA103	1100000xxx	64/32	300000h-307FFFh	
	SA104	1100001xxx	64/32	308000h-30FFFFh	
	SA105	1100010xxx	64/32	310000h–317FFFh	
	SA106	1100010xxx	64/32	318000h–31FFFFh	
	SA107	1100100xxx	64/32	320000h-327FFh	
	SA108	1100101xxx	64/32	328000h-32FFFFh	
	SA109	1100101xxx	64/32	330000h-337FFFh	
-	SA110	1100110xxx	64/32	338000h-33FFFFh	
-	SA111	1101111XX	64/32	340000h=347FFFh	
-	SA112	1101000xxx	64/32	348000h-34FFFh	
<u> </u>	SA113	1101001xxx	64/32	350000h-357FFFh	
<u> </u> -	SA114	1101010XXX	64/32	358000h-35FFFFh	
<u> </u> -	SA115	11011011XX	64/32	360000h-367FFFh	
<u> </u>	SA116	1101100xxx	64/32	368000h-36FFFFh	
<u> </u>		1101101xxx 1101110xxx			
<u> </u>	SA117		64/32	370000h_37FFFh	
	SA118	1101111xxx	64/32	378000h-37FFFFh	

Table 2. Am29DL640G Sector Architecture (Continued)

Bank	Sector	Sector Address A21–A12	Sector Size (Kbytes/Kwords)	(x16) Address Range
	SA119	1110000xxx	64/32	380000h-387FFh
	SA120	1110001xxx	64/32	388000h-38FFFFh
	SA121	1110010xxx	64/32	390000h-397FFFh
	SA122	1110011xxx	64/32	398000h-39FFFFh
	SA123	1110100xxx	64/32	3A0000h-3A7FFFh
	SA124	1110101xxx	64/32	3A8000h-3AFFFFh
	SA125	1110110xxx	64/32	3B0000h-3B7FFFh
	SA126	1110111xxx	64/32	3B8000h-3BFFFFh
	SA127	1111000xxx	64/32	3C0000h-3C7FFFh
	SA128	1111001xxx	64/32	3C8000h-3CFFFFh
	SA129	1111010xxx	64/32	3D0000h-3D7FFFh
Bank 4	SA130	1111011xxx	64/32	3D8000h-3DFFFFh
	SA131	1111100xxx	64/32	3E0000h-3E7FFFh
	SA132	1111101xxx	64/32	3E8000h-3EFFFFh
	SA133	1111110xxx	64/32	3F0000h-3F7FFFh
	SA134	1111111000	8/4	3F8000h-3F8FFFh
	SA135	1111111001	8/4	3F9000h-3F9FFFh
	SA136	1111111010	8/4	3FA000h-3FAFFFh
	SA137	1111111011	8/4	3FB000h-3FBFFFh
	SA138	1111111100	8/4	3FC000h-3FCFFFh
	SA139	111111101	8/4	3FD000h-3FDFFFh
	SA140	111111110	8/4	3FE000h-3FEFFFh
	SA141	111111111	8/4	3FF000h-3FFFFFh

Note: The address range is A21:A0

Table 3. Am29DL640G Bank Address

Bank	A21-A19
1	000
2	001, 010, 011
3	100, 101, 110
4	111

Table 4. Am29DL640G SecSi™ Sector Addresses

Device	Sector Size	(x16) Address Range
Am29DL640G	256 bytes	00000h-0007Fh



Table 5. Am29DL320G Top Boot Sector Addresses

	Sector	Sector Address	Sector Size	(x16)
	0.4.0	A20-A12	(Kbytes/Kwords)	Address Range
	SA0	000000xxx	64/32	000000h-07FFh
	SA1	000001xxx	64/32	008000h_0FFFFh
4	SA2	000010xxx	64/32	010000h_17FFFh
Bank 4	SA3	000011xxx	64/32	018000h-01FFFh
Ba	SA4	000100xxx	64/32	020000h-027FFFh
	SA5	000101xxx	64/32	028000h-02FFFFh
	SA6	000110xxx	64/32	030000h-037FFFh
	SA7	000111xxx	64/32	038000h-03FFFFh
	SA8	001000xxx	64/32	040000h-047FFFh
	SA9	001001xxx	64/32	048000h-04FFFFh
	SA10	001010xxx	64/32	050000h-057FFFh
	SA11	001011xxx	64/32	058000h-05FFFFh
	SA12	001100xxx	64/32	060000h-067FFFh
	SA13	001101xxx	64/32	068000h-06FFFFh
	SA14	001110xxx	64/32	070000h-077FFh
	SA15	001111xxx	64/32	078000h-07FFFh
	SA16	010000xxx	64/32	080000h-087FFFh
	SA17	010001xxx	64/32	088000h-08FFFFh
	SA18	010010xxx	64/32	090000h-097FFFh
Bank 3	SA19	010011xxx	64/32	098000h-09FFFFh
Ba	SA20	010100xxx	64/32	0A0000h-0A7FFFh
	SA21	010101xxx	64/32	0A8000h-0AFFFFh
	SA22	010110xxx	64/32	0B0000h-0B7FFFh
	SA23	010111xxx	64/32	0B8000h-0BFFFFh
	SA24	011000xxx	64/32	0C0000h-0C7FFFh
	SA25	011001xxx	64/32	0C8000h-0CFFFFh
	SA26	011010xxx	64/32	0D0000h-0D7FFFh
	SA27	011011xxx	64/32	0D8000h-0DFFFFh
	SA28	011100xxx	64/32	0E0000h-0E7FFFh
	SA29	011101xxx	64/32	0E8000h-0EFFFFh
	SA30	011110xxx	64/32	0F0000h-0F7FFFh
	SA31	011111xxx	64/32	0F8000h-0FFFFFh
	SA32	100000xxx	64/32	100000h-107FFFh
	SA33	100001xxx	64/32	108000h-10FFFFh
	SA34	100010xxx	64/32	110000h-117FFFh
	SA35	100011xxx	64/32	118000h-11FFFFh
	SA36	100100xxx	64/32	120000h-127FFFh
	SA37	100101xxx	64/32	128000h-12FFFFh
	SA38	100110xxx	64/32	130000h-137FFFh
Bank 2	SA39	100111xxx	64/32	138000h-13FFFFh
Ваі	SA40	101000xxx	64/32	140000h-147FFFh
	SA41	101001xxx	64/32	148000h-14FFFFh
	SA42	101010xxx	64/32	150000h-157FFFh
	SA43	101011xxx	64/32	158000h-15FFFFh
	SA44	101100xxx	64/32	160000h-167FFFh
	SA45	101101xxx	64/32	168000h-16FFFFh
	SA46	101110xxx	64/32	170000h-177FFFh
	SA47	101111xxx	64/32	178000h-17FFFFh

Table 5. Am29DL320G Top Boot Sector Addresses (Continued)

	Sector	Sector Address	Sector Size	(x16)
	Sector	A20-A12	(Kbytes/Kwords)	Address Range
	SA48	110000xxx	64/32	180000h-187FFFh
(pa	SA49	110001xxx	64/32	188000h-18FFFFh
ŭ L	SA50	110010xxx	64/32	190000h-197FFFh
(continued)	SA51	110011xxx	64/32	198000h-19FFFFh
	SA52	110100xxx	64/32	1A0000h-1A7FFFh
× 2	SA53	110101xxx	64/32	1A8000h-1AFFFFh
Bank	SA54	110110xxx	64/32	1B0000h-1B7FFFh
	SA55	110111xxx	64/32	1B8000h-1BFFFFh
	SA56	111000xxx	64/32	1C0000h-1C7FFFh
	SA57	111001xxx	64/32	1C8000h-1CFFFFh
	SA58	111010xxx	64/32	1D0000h-1D7FFFh
	SA59	111011xxx	64/32	1D8000h-1DFFFFh
	SA60	111100xxx	64/32	1E0000h-1E7FFFh
	SA61	111101xxx	64/32	1E8000h-1EFFFFh
-	SA62	111110xxx	64/32	1F0000h-1F7FFFh
Bank 1	SA63	111111000	8/4	1F8000h-1F8FFFh
B	SA64	111111001	8/4	1F9000h-1F9FFFh
	SA65	111111010	8/4	1FA000h-1FAFFFh
	SA66	111111011	8/4	1FB000h-1FBFFFh
	SA67	11111100	8/4	1FC000h-1FCFFFh
	SA68	11111101	8/4	1FD000h-1FDFFFh
	SA69	11111110	8/4	1FE000h-1FEFFFh
	SA70	11111111	8/4	1FF000h-1FFFFFh

Note: The address range is A20:A0.

Table 6. Am29DL320G Top Boot SecSi™ Sector Addresses

	Sector Address	Sector Size	(x16)
Device	A20-A12	(Bytes/Words)	Address Range
Am29DL320GT	111111xxx	256/128	1FF000h-1FF07Fh



Table 7. Am29DL320G Bottom Boot Sector Addresses

	Sector	Sector Address A20-A12	Sector Size (Kbytes/Kwords)	(x16) Address Range
	SA0	00000000	8/4	000000h-000FFFh
	SA1	00000001	8/4	001000h-001FFFh
	SA2	00000010	8/4	002000h-002FFFh
	SA3	00000011	8/4	003000h-003FFFh
	SA4	00000100	8/4	004000h-004FFFh
	SA5	00000101	8/4	005000h-005FFh
_ =	SA6	000000110	8/4	006000h-006FFh
Bank 1	SA7	000000111	8/4	007000h-007FFh
Ba	SA8	000001xxx	64/32	008000h-00FFFh
-	SA9	000010xxx	64/32	010000h-017FFh
<del> </del>	SA10	000011xxx	64/32	018000h-01FFFh
-	SA11	000100xxx	64/32	020000h-027FFFh
	SA12	000101xxx	64/32	028000h-02FFFh
	SA13	000110xxx	64/32	030000h-037FFFh
-	SA14	000111xxx	64/32	
	SA15	001000xxx	64/32	038000h-03FFFFh 040000h-047FFFh
<u> </u>	SA16	001000xxx	64/32	
<u> </u>	SA17	001001xxx	64/32	048000h_04FFFFh
<u> </u>	SA17	001010xxx	64/32	050000h-057FFFh
<u> </u>	SA19	001100xxx	64/32	058000h-05FFFFh
<u> </u>	SA19 SA20	001101xxx	64/32	060000h-067FFFh
<u> </u>	SA20 SA21	001101xxx	64/32	068000h-06FFFh
_	SA21 SA22		64/32	070000h-077FFFh
_	SA22 SA23	001111xxx	64/32	078000h-07FFFh
_		010000xxx		080000h-087FFFh
	SA24 SA25	010001xxx	64/32	088000h-08FFFFh
5		010010xxx	64/32	090000h-097FFh
Bank 2	SA26	010011xxx	64/32	098000h-09FFFh
	SA27	010100xxx	64/32	0A0000h-0A7FFFh
_	SA28	010101xxx	64/32	0A8000h-0AFFFFh
	SA29	010110xxx	64/32	0B0000h-0B7FFFh
_	SA30	010111xxx	64/32	0B8000h-0BFFFFh
_	SA31	011000xxx	64/32	0C0000h-0C7FFFh
_	SA32	011001xxx	64/32	0C8000h-0CFFFFh
<u> </u>	SA33	011010xxx	64/32	0D0000h-0D7FFFh
_	SA34	011011xxx	64/32	0D8000h-0DFFFFh
_	SA35	011100xxx	64/32	0E0000h-0E7FFh
_	SA36	011101xxx	64/32	0E8000h-0EFFFFh
	SA37	011110xxx	64/32	0F0000h-0F7FFFh
	SA38	011111xxx	64/32	0F8000h-0FFFFh
	SA39	100000xxx	64/32	100000h-107FFFh
	SA40	100001xxx	64/32	108000h-10FFFFh
<u> </u>	SA41 SA42	100010xxx 100011xxx	64/32 64/32	110000h-117FFFh 118000h-11FFFFh
Bank 3	SA42 SA43	100011xxx	64/32	120000h–117FFFh
Bar	SA43	100100xxx	64/32	128000h–12FFFh
	SA45	100101xxx	64/32	130000h-137FFh
-	SA46	100111xxx	64/32	138000h–13FFFFh
	SA47	101000xxx	64/32	140000h–147FFFh

Table 7. Am29DL320G Bottom Boot Sector Addresses (Continued)

	Sector	Sector Address A20-A12	Sector Size (Kbytes/Kwords)	(x16) Address Range
	SA48	101001xxx	64/32	148000h-14FFFFh
	SA49	101010xxx	64/32	150000h-157FFFh
	SA50	101011xxx	64/32	158000h-15FFFFh
	SA51	101100xxx	64/32	160000h-167FFFh
	SA52	101101xxx	64/32	168000h-16FFFFh
l en	SA53	101110xxx	64/32	170000h-177FFFh
(continued)	SA54	101111xxx	64/32	178000h-17FFFFh
00	SA55	111000xxx	64/32	180000h-187FFFh
3 (	SA56	110001xxx	64/32	188000h-18FFFFh
Bank 3	SA57	110010xxx	64/32	190000h-197FFFh
ä	SA58	110011xxx	64/32	198000h-19FFFFh
	SA59	110100xxx	64/32	1A0000h-1A7FFFh
	SA60	110101xxx	64/32	1A8000h-1AFFFFh
	SA61	110110xxx	64/32	1B0000h-1B7FFFh
	SA62	110111xxx	64/32	1B8000h-1BFFFFh
	SA63	111000xxx	64/32	1C0000h-1C7FFFh
	SA64	111001xxx	64/32	1C8000h-1CFFFFh
	SA65	111010xxx	64/32	1D0000h-1D7FFFh
Bank 4	SA66	111011xxx	64/32	1D8000h-1DFFFFh
San	SA67	111100xxx	64/32	1E0000h-1E7FFFh
	SA68	111101xxx	64/32	1E8000h-1EFFFFh
	SA69	111110xxx	64/32	1F0000h-1F7FFFh
	SA70	111111xxx	64/32	1F8000h-1FFFFFh

**Note:** The address range is A20:A0

Table 8. Am29DL320G Bottom Boot SecSi™ Sector Addresses

Device	Sector Address A20–A12	Sector Size (Bytes/Words)	(x16) Address Range
Am29DL320GB	000000xxx	256/128	00000h-00007Fh



# Sector/Sector Block Protection and Unprotection

(Note: For the following discussion, the term "sector" applies to both sectors and sector blocks. A sector block consists of two or more adjacent sectors that are protected or unprotected at the same time (see Table 9).

The hardware sector protection feature disables both program and erase operations in any sector. The hardware sector unprotection feature re-enables both program and erase operations in previously protected sectors. Sector protection/unprotection can be implemented via two methods.

Table 9. Am29DL640G Boot Sector/Sector Block Addresses for Protection/Unprotection

Sector	A21-A12	Sector/ Sector Block Size
SA0	000000000	8 Kbytes
SA1	000000001	8 Kbytes
SA2	000000010	8 Kbytes
SA3	000000011	8 Kbytes
SA4	000000100	8 Kbytes
SA5	000000101	8 Kbytes
SA6	000000110	8 Kbytes
SA7	0000000111	8 Kbytes
SA8-SA10	0000001XXX, 0000010XXX, 0000011XXX,	192 (3x64) Kbytes
SA11-SA14	00001XXXXX	256 (4x64) Kbytes
SA15-SA18	00010XXXXX	256 (4x64) Kbytes
SA19-SA22	00011XXXXX	256 (4x64) Kbytes
SA23-SA26	00100XXXXX	256 (4x64) Kbytes
SA27-SA30	00101XXXXX	256 (4x64) Kbytes
SA31-SA34	00110XXXXX	256 (4x64) Kbytes
SA35-SA38	00111XXXXX	256 (4x64) Kbytes

Sastan	A24 A42	Sector/
Sector	A21-A12	Sector Block Size
SA39-SA42	01000XXXXX	256 (4x64) Kbytes
SA43-SA46	01001XXXXX	256 (4x64) Kbytes
SA47-SA50	01010XXXXX	256 (4x64) Kbytes
SA51-SA54	01011XXXXX	256 (4x64) Kbytes
SA55-SA58	01100XXXXX	256 (4x64) Kbytes
SA59-SA62	01101XXXXX	256 (4x64) Kbytes
SA63-SA66	01110XXXXX	256 (4x64) Kbytes
SA67-SA70	01111XXXXX	256 (4x64) Kbytes
SA71-SA74	10000XXXXX	256 (4x64) Kbytes
SA75-SA78	10001XXXXX	256 (4x64) Kbytes
SA79-SA82	10010XXXXX	256 (4x64) Kbytes
SA83-SA86	10011XXXXX	256 (4x64) Kbytes
SA87-SA90	10100XXXXX	256 (4x64) Kbytes
SA91-SA94	10101XXXXX	256 (4x64) Kbytes
SA95-SA98	10110XXXXX	256 (4x64) Kbytes
SA99-SA102	10111XXXXX	256 (4x64) Kbytes
SA103-SA106	11000XXXXX	256 (4x64) Kbytes
SA107-SA110	11001XXXXX	256 (4x64) Kbytes
SA111-SA114	11010XXXXX	256 (4x64) Kbytes
SA115-SA118	11011XXXXX	256 (4x64) Kbytes
SA119-SA122	11100XXXXX	256 (4x64) Kbytes
SA123-SA126	11101XXXXX	256 (4x64) Kbytes
SA127-SA130	11110XXXXX	256 (4x64) Kbytes
SA131-SA133	1111100XXX, 1111101XXX, 1111110XXX	192 (3x64) Kbytes
SA134	1111111000	8 Kbytes
SA135	1111111001	8 Kbytes
SA136	1111111010	8 Kbytes
SA137	1111111011	8 Kbytes
SA138	1111111100	8 Kbytes
SA139	1111111101	8 Kbytes
SA140	1111111101	8 Kbytes
SA141	1111111111	8 Kbytes

Table 10. Am29DL320G Top Boot Sector/Sector Block Addresses for Protection/Unprotection

Sector	A20-A12	Sector/ Sector Block Size
SA0	000000XXX	64 Kbytes
SA1-SA3	000001XXX, 000010XXX 000011XXX	192 (3x64) Kbytes
SA4-SA7	0001XXXXX	256 (4x64) Kbytes
SA8-SA11	0010XXXXX	256 (4x64) Kbytes
SA12-SA15	0011XXXXX	256 (4x64) Kbytes
SA16-SA19	0100XXXXX	256 (4x64) Kbytes
SA20-SA23	0101XXXXX	256 (4x64) Kbytes
SA24-SA27	0110XXXXX	256 (4x64) Kbytes
SA28-SA31	0111XXXXX	256 (4x64) Kbytes
SA32-SA35	1000XXXXX	256 (4x64) Kbytes
SA36-SA39	1001XXXXX	256 (4x64) Kbytes
SA40-SA43	1010XXXXX	256 (4x64) Kbytes
SA44-SA47	1011XXXXX	256 (4x64) Kbytes
SA48-SA51	1100XXXXX	256 (4x64) Kbytes
SA52-SA55	1101XXXXX	256 (4x64) Kbytes
SA56-SA59	1110XXXXX	256 (4x64) Kbytes
SA60-SA62	111100XXX, 111101XXX, 111110XXX	192 (3x64) Kbytes
SA63	111111000	8 Kbytes
SA64	111111001	8 Kbytes
SA65	111111010	8 Kbytes
SA66	111111011	8 Kbytes
SA67	111111100	8 Kbytes
SA68	111111101	8 Kbytes
SA69	111111110	8 Kbytes
SA70	111111111	8 Kbytes

Table 11. Am29DL320G Bottom Boot Sector/Sector Block Addresses for Protection/Unprotection

Sector	A20-A12	Sector/Sector Block Size
SA70	111111XXX	64 Kbytes
SA69-SA67	111110XXX, 111101XXX, 111100XXX	192 (3x64) Kbytes
SA66-SA63	1110XXXXX	256 (4x64) Kbytes
SA62-SA59	1101XXXXX	256 (4x64) Kbytes
SA58-SA55	1100XXXXX	256 (4x64) Kbytes
SA54-SA51	1011XXXXX	256 (4x64) Kbytes
SA50-SA47	1010XXXXX	256 (4x64) Kbytes
SA46-SA43	1001XXXXX	256 (4x64) Kbytes
SA42-SA39	1000XXXXX	256 (4x64) Kbytes
SA38-SA35	0111XXXXX	256 (4x64) Kbytes
SA34-SA31	0110XXXXX	256 (4x64) Kbytes
SA30-SA27	0101XXXXX	256 (4x64) Kbytes
SA26-SA23	0100XXXXX	256 (4x64) Kbytes
SA22-SA19	0011XXXXX	256 (4x64) Kbytes
SA18-SA15	0010XXXXX	256 (4x64) Kbytes
SA14-SA11	0001XXXXX	256 (4x64) Kbytes
SA10-SA8	000011XXX, 000010XXX, 000001XXX	192 (3x64) Kbytes
SA7	000000111	8 Kbytes
SA6	000000110	8 Kbytes
SA5	000000101	8 Kbytes
SA4	000000100	8 Kbytes
SA3	000000011	8 Kbytes
SA2	00000010	8 Kbytes
SA1	00000001	8 Kbytes
SA0	000000000	8 Kbytes



Sector protection/unprotection requires V<sub>ID</sub> on the RE-SET# pin only, and can be implemented either in-system or via programming equipment. Figure 2 shows the algorithms and Figure 24 shows the timing diagram. For sector unprotect, all unprotected sectors must first be protected prior to the first sector unprotect write cycle. Note that the sector unprotect algorithm unprotects all sectors in parallel. All previously protected sectors must be individually re-protected. To change data in protected sectors efficiently, the temporary sector unprotect function is available. See "Temporary Sector Unprotect".

The device is shipped with all sectors unprotected. AMD offers the option of programming and protecting sectors at its factory prior to shipping the device through AMD's ExpressFlash™ Service. Contact an AMD representative for details.

It is possible to determine whether a sector is protected or unprotected. See the Sector/Sector Block Protection and Unprotection section for details.

### Write Protect (WP#)

The Write Protect function provides a hardware method of protecting without using  $V_{\rm ID}$ . This function is one of two provided by the WP#/ACC pin.

If the system asserts  $V_{\rm IL}$  on the WP#/ACC pin while the Am29DL640G is enabled (CE#f1), the device disables program and erase functions in sectors 0, 1, 140, and 141, independently of whether those sectors were protected or unprotected using the method described in "Sector/Sector Block Protection and Unprotection". Similarly, the two outermost boot sectors (SA0 and 1 on bottom boot devices or SA69 and 70 on top boot devices) on the Am29DL320G are protected when  $V_{\rm IL}$  is asserted on the WP#/ACC pin while the Am29DL320G is enabled (CE#f2).

If the system asserts  $V_{IH}$  on the WP#/ACC pin, the device reverts to whether the aforementioned sectors were last set to be protected or unprotected. That is, sector protection or unprotection for these sectors depends on whether they were last protected or unprotected using the method described in "Sector/Sector Block Protection and Unprotection".

Note that the WP#/ACC pin must not be left floating or unconnected; inconsistent behavior of the device may result.

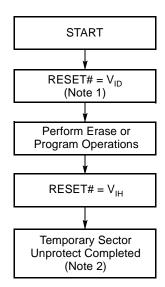
Table 12. WP#/ACC Modes

WP# Input Voltage	Am29DL640G	Am29DL320G		
V <sub>IL</sub>	Disables programming and erasing in SA0, SA1, SA140, and SA141	Disables programming and erasing in SA0 and SA1 or SA69 and SA70		
V <sub>IH</sub>	Enables programming and erasing in SA0, SA1, SA140, and SA141	Enables programming and erasing in SA0 and SA1 or SA60 and SA70		
V <sub>HH</sub>	Enables accelerated programming (ACC). See "Accelerated Program Operation" on page 11.			

### **Temporary Sector Unprotect**

(Note: For the following discussion, the term "sector" applies to both sectors and sector blocks. A sector block consists of two or more adjacent sectors that are protected or unprotected at the same time (see Table 9).

This feature allows temporary unprotection of previously protected sectors to change data in-system. The Sector Unprotect mode is activated by setting the RE-SET# pin to V<sub>ID</sub>. During this mode, formerly protected sectors can be programmed or erased by selecting the sector addresses. Once V<sub>ID</sub> is removed from the RE-SET# pin, all the previously protected sectors are protected again. Figure 1 shows the algorithm, and Figure 23 shows the timing diagrams, for this feature. If the WP#/ACC pin is at  $V_{\rm IL}$  while the Am29DL640G is enabled, sectors 0, 1, 140, and 141 of that device will remain protected during the Temporary sector Unprotect mode. Similarly, If the WP#/ACC pin is at V<sub>II</sub> while the Am29DL320G is enabled, the two outermost boot sectors (SA0 and 1 on bottom boot devices or SA69 and 70 on top boot devices) of that device will remain protected during the Temporary sector Unprotect mode.



#### Notes:

- 1. All protected sectors unprotected (If WP#/ACC =  $V_{lL}$ , the following sectors will remain protected: sectors 0, 1, 140, and 141 (Am29DL640G), sectors 0 and 1 (Am29DL320GB), or sectors 69 and 70 (Am29DL320GT).
- 2. All previously protected sectors are protected once again.

Figure 1. Temporary Sector Unprotect Operation



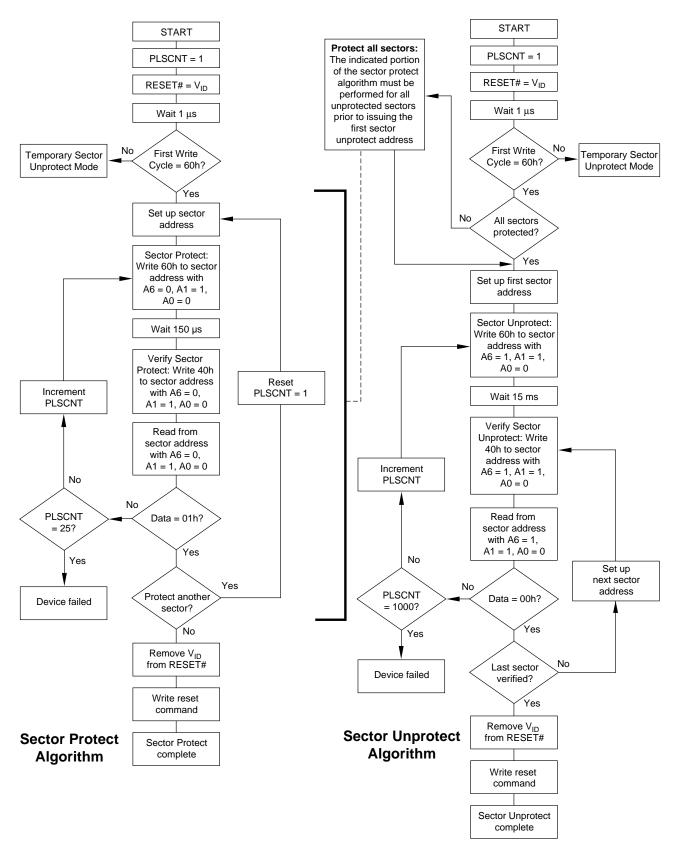


Figure 2. In-System Sector Protect/Unprotect Algorithms

### SecSi<sup>™</sup> (Secured Silicon) Sector SectorFlash Memory Region

The SecSi (Secured Silicon) Sector feature provides a Flash memory region that enables permanent part identification through an Electronic Serial Number (ESN). The SecSi Sector is 256 bytes in length, and uses a SecSi Sector Indicator Bit (DQ7) to indicate whether or not the SecSi Sector is locked when shipped from the factory. This bit is permanently set at the factory and cannot be changed, which prevents cloning of a factory locked part. This ensures the security of the ESN once the product is shipped to the field.

AMD offers the device with the SecSi Sector either factory locked or customer lockable. The factory-locked version is always protected when shipped from the factory, and has the SecSi (Secured Silicon) Sector Indicator Bit permanently set to a "1." The customer-lockable version is shipped with the SecSi Sector unprotected, allowing customers to utilize the that sector in any manner they choose. The customer-lockable version has the SecSi (Secured Silicon) Sector Indicator Bit permanently set to a "0." Thus, the SecSi Sector Indicator Bit prevents customer-lockable devices from being used to replace devices that are factory locked.

The system accesses the SecSi Sector Secure Sector through a command sequence (see "Enter SecSi™ Sector/Exit SecSi Sector Command Sequence"). After the system has written the Enter SecSi Sector command sequence, it may read the SecSi Sector by using the addresses normally occupied by the boot sectors. This mode of operation continues until the system issues the Exit SecSi Sector command sequence, or until power is removed from the device. Note that the ACC function and unlock bypass modes are not available when the SecSi Sector is enabled. On power-up, or following a hardware reset, the device reverts to sending commands to the first 256 bytes of Sector 0.

# Factory Locked: SecSi Sector Programmed and Protected At the Factory

In a factory locked device, the SecSi Sector is protected when the device is shipped from the factory. The SecSi Sector cannot be modified in any way. The device is preprogrammed with both a random number and secure ESNs. See Table 13 for address location details.

Table 13. SecSi Sector Programming

Device	Data	Word Mode	Byte Mode
Am29DL640G	Random	000000h–	000000h-
	number	000007h	00000Fh
AIII29DE040G	8-byte	000008h-	000010h–
	secure ESN	00000Fh	000020h
Am29DL320GB	16-byte secure	000000h-	000000h-
(Bottom boot)	ESN	000007h	00000Fh
Am29DL320GT	16-byte secure	1FF000h-	3FE000h-
(Top boot)	ESN	1FF007Fh	3FE0FFh

The device is available preprogrammed with one of the following:

- Random number and secure ESNs only
- Customer code through the ExpressFlash service
- Random number, secure ESNs, and customer code through the ExpressFlash service.

Customers may opt to have their code programmed by AMD through the AMD ExpressFlash service. AMD programs the customer's code, with or without the random ESN. The devices are then shipped from AMD's factory with the SecSi Sector permanently locked. Contact an AMD representative for details on using AMD's ExpressFlash service.

# Customer Lockable: SecSi Sector NOT Programmed or Protected At the Factory

If the security feature is not required, the SecSi Sector can be treated as an additional Flash memory space. The SecSi Sector can be read any number of times, but can be programmed and locked only once. Note that the accelerated programming (ACC) and unlock bypass functions are not available when programming the SecSi Sector.

The SecSi Sector area can be protected using one of the following procedures:

- Write the three-cycle Enter SecSi Sector Region command sequence, and then follow the in-system sector protect algorithm as shown in Figure 2, except that RESET# may be at either V<sub>IH</sub> or V<sub>ID</sub>. This allows in-system protection of the SecSi Sector Region without raising any device pin to a high voltage. Note that this method is only applicable to the SecSi Sector.
- To verify the protect/unprotect status of the SecSi Sector, follow the algorithm shown in Figure 3.

Once the SecSi Sector is locked and verified, the system must write the Exit SecSi Sector Region command sequence to return to reading and writing the remainder of the array.

The SecSi Sector lock must be used with caution since, once locked, there is no procedure available for unlocking the SecSi Sector area and none of the bits in the SecSi Sector memory space can be modified in any way.

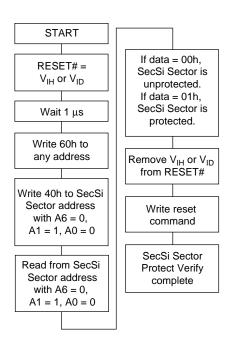


Figure 3. SecSi Sector Protect Verify

#### **Hardware Data Protection**

The command sequence requirement of unlock cycles for programming or erasing provides data protection against inadvertent writes (refer to Table 22 for command definitions). In addition, the following hardware data protection measures prevent accidental erasure or programming, which might otherwise be caused by spurious system level signals during  $V_{\rm CC}$  power-up and power-down transitions, or from system noise.

#### Low V<sub>CC</sub> Write Inhibit

When  $V_{CC}$  is less than  $V_{LKO}$ , the device does not accept any write cycles. This protects data during  $V_{CC}$  power-up and power-down. The command register and all internal program/erase circuits are disabled, and the device resets to the read mode. Subsequent writes are ignored until  $V_{CC}$  is greater than  $V_{LKO}$ . The system must provide the proper signals to the control pins to prevent unintentional writes when  $V_{CC}$  is greater than  $V_{LKO}$ .

#### Write Pulse "Glitch" Protection

Noise pulses of less than 5 ns (typical) on OE#, CE#f or WE# do not initiate a write cycle.

#### **Logical Inhibit**

Write cycles are inhibited by holding any one of OE# =  $V_{IL}$ , CE#f =  $V_{IH}$  or WE# =  $V_{IH}$ . To initiate a write cycle, CE#f and WE# must be a logical zero while OE# is a logical one.

#### **Power-Up Write Inhibit**

If WE# = CE#f =  $V_{IL}$  and OE# =  $V_{IH}$  during power up, the device does not accept commands on the rising edge of WE#. The internal state machine is automatically reset to the read mode on power-up.

# COMMON FLASH MEMORY INTERFACE (CFI)

The Common Flash Interface (CFI) specification outlines device and host system software interrogation handshake, which allows specific vendor-specified software algorithms to be used for entire families of devices. Software support can then be device-independent, JEDEC ID-independent, and forward- and backward-compatible for the specified flash device families. Flash vendors can standardize their existing interfaces for long-term compatibility.

This device enters the CFI Query mode when the system writes the CFI Query command, 98h, to address 55h in word mode (or address AAh in byte mode), any time the device is ready to read array data. The system can read CFI information at the addresses given in Tables 14–17. To terminate reading CFI data, the system must write the reset command. The CFI Query mode is not accessible when the device is executing an Embedded Program or embedded Erase algorithm.

The system can also write the CFI query command when the device is in the autoselect mode. The device enters the CFI query mode, and the system can read CFI data at the addresses given in Tables 14–17. The system must write the reset command to return the device to reading array data.

For further information, please refer to the CFI Specification and CFI Publication 100, available via the World Wide Web at http://www.amd.com/flash/cfi. Alternatively, contact an AMD representative for copies of these documents.

Table 14. Am29DL640G CFI Query Identification String

Addresses (Word Mode)	Addresses (Byte Mode)	Data	Description
10h	20h	0051h	Query Unique ASCII string "QRY"
11h	22h	0052h	
12h	24h	0059h	
13h	26h	0002h	Primary OEM Command Set
14h	28h	0000h	
15h	2Ah	0040h	Address for Primary Extended Table
16h	2Ch	0000h	
17h	2Eh	0000h	Alternate OEM Command Set (00h = none exists)
18h	30h	0000h	
19h	32h	0000h	Address for Alternate OEM Extended Table (00h = none exists)
1Ah	34h	0000h	

Table 15. Am29DL640G System Interface String

Addresses (Word Mode)	Addresses (Byte Mode)	Data	Description
1Bh	36h	0027h	V <sub>CC</sub> Min. (write/erase) D7–D4: volt, D3–D0: 100 millivolt
1Ch	38h	0036h	V <sub>CC</sub> Max. (write/erase) D7–D4: volt, D3–D0: 100 millivolt
1Dh	3Ah	0000h	V <sub>PP</sub> Min. voltage (00h = no V <sub>PP</sub> pin present)
1Eh	3Ch	0000h	V <sub>PP</sub> Max. voltage (00h = no V <sub>PP</sub> pin present)
1Fh	3Eh	0004h	Typical timeout per single byte/word write 2 <sup>N</sup> µs
20h	40h	0000h	Typical timeout for Min. size buffer write $2^{N}$ µs (00h = not supported)
21h	42h	000Ah	Typical timeout per individual block erase 2 <sup>N</sup> ms
22h	44h	0000h	Typical timeout for full chip erase 2 <sup>N</sup> ms (00h = not supported)
23h	46h	0005h	Max. timeout for byte/word write 2 <sup>N</sup> times typical
24h	48h	0000h	Max. timeout for buffer write 2 <sup>N</sup> times typical
25h	4Ah	0004h	Max. timeout per individual block erase 2 <sup>N</sup> times typical
26h	4Ch	0000h	Max. timeout for full chip erase 2 <sup>N</sup> times typical (00h = not supported)



Table 16. Am29DL640G Device Geometry Definition

Addresses (Word Mode)	Addresses (Byte Mode)	Data	Description
27h	4Eh	0017h	Device Size = 2 <sup>N</sup> byte
28h	50h	0002h	Flash Device Interface description (refer to CFI publication 100)
29h	52h	0000h	
2Ah	54h	0000h	Max. number of byte in multi-byte write = $2^N$ (00h = not supported)
2Bh	56h	0000h	
2Ch	58h	0003h	Number of Erase Block Regions within device
2Dh	5Ah	0007h	Erase Block Region 1 Information (refer to the CFI specification or CFI publication 100)
2Eh	5Ch	0000h	
2Fh	5Eh	0020h	
30h	60h	0000h	
31h	62h	007Dh	Erase Block Region 2 Information (refer to the CFI specification or CFI publication 100)
32h	64h	0000h	
33h	66h	0000h	
34h	68h	0001h	
35h	6Ah	0007h	Erase Block Region 3 Information (refer to the CFI specification or CFI publication 100)
36h	6Ch	0000h	
37h	6Eh	0020h	
38h	70h	0000h	
39h	72h	0000h	Erase Block Region 4 Information (refer to the CFI specification or CFI publication 100)
3Ah	74h	0000h	
3Bh	76h	0000h	
3Ch	78h	0000h	

# Table 17. Am29DL640G Primary Vendor-Specific Extended Query

Addresses (Word Mode)	Addresses (Byte Mode)	Data	Description
40h 41h 42h	80h 82h 84h	0050h 0052h 0049h	Query-unique ASCII string "PRI"
43h	86h	0031h	Major version number, ASCII (reflects modifications to the silicon)
44h	88h	0033h	Minor version number, ASCII (reflects modifications to the CFI table)
45h	8Ah	0004h	Address Sensitive Unlock (Bits 1-0) 0 = Required, 1 = Not Required Silicon Revision Number (Bits 7-2)
46h	8Ch	0002h	Erase Suspend 0 = Not Supported, 1 = To Read Only, 2 = To Read & Write
47h	8Eh	0001h	Sector Protect 0 = Not Supported, X = Number of sectors in per group
48h	90h	0001h	Sector Temporary Unprotect 00 = Not Supported, 01 = Supported
49h	92h	0004h	Sector Protect/Unprotect scheme 01 =29F040 mode, 02 = 29F016 mode, 03 = 29F400, 04 = 29LV800 mode
4Ah	94h	0077h	Simultaneous Operation 00 = Not Supported, X = Number of Sectors (excluding Bank 1)
4Bh	96h	0000h	Burst Mode Type 00 = Not Supported, 01 = Supported
4Ch	98h	0000h	Page Mode Type 00 = Not Supported, 01 = 4 Word Page, 02 = 8 Word Page
4Dh	9Ah	0085h	ACC (Acceleration) Supply Minimum  00h = Not Supported, D7-D4: Volt, D3-D0: 100 mV
4Eh	9Ch	0095h	ACC (Acceleration) Supply Maximum  00h = Not Supported, D7-D4: Volt, D3-D0: 100 mV
4Fh	9Eh	0001h	Top/Bottom Boot Sector Flag  00h = Uniform device, 01h = 8 x 8 Kbyte Sectors, Top And Bottom Boot with Write Protect, 02h = Bottom Boot Device, 03h = Top Boot Device, 04h = Both Top and Bottom
50h	A0h	0001h	Program Suspend 0 = Not supported, 1 = Supported
57h	AEh	0004h	Bank Organization 00 = Data at 4Ah is zero, X = Number of Banks
58h	B0h	0017h	Bank 1 Region Information  X = Number of Sectors in Bank 1
59h	B2h	0030h	Bank 2 Region Information  X = Number of Sectors in Bank 2
5Ah	B4h	0030h	Bank 3 Region Information  X = Number of Sectors in Bank 3



Addresses (Word Mode)	Addresses (Byte Mode)	Data	Description
5Bh	B6h	l 0017h	Bank 4 Region Information  X = Number of Sectors in Bank 4

# Table 18. Am29DL320G CFI Query Identification String

Addresses (Word Mode)	Addresses (Byte Mode)	Data	Description
10h	20h	0051h	Query Unique ASCII string "QRY"
11h	22h	0052h	
12h	24h	0059h	
13h	26h	0002h	Primary OEM Command Set
14h	28h	0000h	
15h	2Ah	0040h	Address for Primary Extended Table
16h	2Ch	0000h	
17h	2Eh	0000h	Alternate OEM Command Set (00h = none exists)
18h	30h	0000h	
19h	32h	0000h	Address for Alternate OEM Extended Table (00h = none exists)
1Ah	34h	0000h	

# Table 19. Am29DL320G System Interface String

Addresses (Word Mode)	Addresses (Byte Mode)	Data	Description
1Bh	36h	0027h	V <sub>CC</sub> Min. (write/erase) D7–D4: volt, D3–D0: 100 millivolt
1Ch	38h	0036h	V <sub>CC</sub> Max. (write/erase) D7–D4: volt, D3–D0: 100 millivolt
1Dh	3Ah	0000h	V <sub>PP</sub> Min. voltage (00h = no V <sub>PP</sub> pin present)
1Eh	3Ch	0000h	V <sub>PP</sub> Max. voltage (00h = no V <sub>PP</sub> pin present)
1Fh	3Eh	0004h	Typical timeout per single byte/word write 2 <sup>N</sup> µs
20h	40h	0000h	Typical timeout for Min. size buffer write 2 <sup>N</sup> µs (00h = not supported)
21h	42h	000Ah	Typical timeout per individual block erase 2 <sup>N</sup> ms
22h	44h	0000h	Typical timeout for full chip erase 2 <sup>N</sup> ms (00h = not supported)
23h	46h	0005h	Max. timeout for byte/word write 2 <sup>N</sup> times typical
24h	48h	0000h	Max. timeout for buffer write 2 <sup>N</sup> times typical
25h	4Ah	0004h	Max. timeout per individual block erase 2 <sup>N</sup> times typical
26h	4Ch	0000h	Max. timeout for full chip erase 2 <sup>N</sup> times typical (00h = not supported)

Table 20. Am29DL320G Device Geometry Definition

Addresses (Word Mode)	Addresses (Byte Mode)	Data	Description
27h	4Eh	0016h	Device Size = 2 <sup>N</sup> byte
28h	50h	0002h	Flash Device Interface description (refer to CFI publication 100)
29h	52h	0000h	
2Ah	54h	0000h	Max. number of bytes in multi-byte write = $2^N$ (00h = not supported)
2Bh	56h	0000h	
2Ch	58h	0002h	Number of Erase Block Regions within device
2Dh	5Ah	0007h	Erase Block Region 1 Information (refer to the CFI specification or CFI publication 100)
2Eh	5Ch	0000h	
2Fh	5Eh	0020h	
30h	60h	0000h	
31h	62h	003Eh	Erase Block Region 2 Information
32h	64h	0000h	
33h	66h	0000h	
34h	68h	0001h	
35h	6Ah	0000h	Erase Block Region 3 Information
36h	6Ch	0000h	
37h	6Eh	0000h	
38h	70h	0000h	
39h	72h	0000h	Erase Block Region 4 Information
3Ah	74h	0000h	
3Bh	76h	0000h	
3Ch	78h	0000h	



# Table 21. Am29DL320G Primary Vendor-Specific Extended Query

Addresses (Word Mode)	Addresses (Byte Mode)	Data	Description
40h 41h 42h	80h 82h 84h	0050h 0052h 0049h	Query-unique ASCII string "PRI"
43h	86h	0031h	Major version number, ASCII
44h	88h	0033h	Minor version number, ASCII
45h	8Ah	0001h	Silicon Revision Number 00h = 0.23 μm, 01h = 0.17 μm
46h	8Ch	0002h	Erase Suspend 0 = Not Supported, 1 = To Read Only, 2 = To Read & Write
47h	8Eh	0001h	Sector Protect 0 = Not Supported, X = Number of sectors in per group
48h	90h	0001h	Sector Temporary Unprotect 00 = Not Supported, 01 = Supported
49h	92h	0004h	Sector Protect/Unprotect scheme 04 = 29LV800 mode
4Ah	94h	0038h	Simultaneous Operation Number of Sectors (excluding Bank 1)
4Bh	96h	0000h	Burst Mode Type 00 = Not Supported, 01 = Supported
4Ch	98h	0000h	Page Mode Type 00 = Not Supported, 01 = 4 Word Page, 02 = 8 Word Page
4Dh	9Ah	0085h	ACC (Acceleration) Supply Minimum 00h = Not Supported, D7-D4: Volt, D3-D0: 100 mV
4Eh	9Ch	0095h	ACC (Acceleration) Supply Maximum 00h = Not Supported, D7-D4: Volt, D3-D0: 100 mV
4Fh	9Eh	000Xh	Top/Bottom Boot Sector Flag 02h = Bottom Boot Device, 03h = Top Boot Device

#### FLASH COMMAND DEFINITIONS

Writing specific address and data commands or sequences into the command register initiates device operations. Table 22 defines the valid register command sequences. Writing **incorrect address and data values** or writing them in the **improper sequence** may place the device in an unknown state. A reset command is then required to return the device to reading array data.

All addresses are latched on the falling edge of WE# or CE#f, whichever happens later. All data is latched on the rising edge of WE# or CE#f, whichever happens first. Refer to the Flash AC Characteristics section for timing diagrams.

### **Reading Array Data**

The device is automatically set to reading array data after device power-up. No commands are required to retrieve data. Each bank is ready to read array data after completing an Embedded Program or Embedded Erase algorithm.

After the device accepts an Erase Suspend command, the corresponding bank enters the erase-suspend-read mode, after which the system can read data from any non-erase-suspended sector within the same bank. The system can read array data using the standard read timing, except that if it reads at an address within erase-suspended sectors, the device outputs status data. After completing a programming operation in the Erase Suspend mode, the system may once again read array data with the same exception. See the Erase Suspend/Erase Resume Commands section for more information.

The system *must* issue the reset command to return a bank to the read (or erase-suspend-read) mode if DQ5 goes high during an active program or erase operation, or if the bank is in the autoselect mode. See the next section, Reset Command, for more information.

See also Requirements for Reading Array Data in the section for more information. The Read-Only Operations table provides the read parameters, and Figure 14 shows the timing diagram.

#### **Reset Command**

Writing the reset command resets the banks to the read or erase-suspend-read mode. Address bits are don't cares for this command.

The reset command may be written between the sequence cycles in an erase command sequence before erasing begins. This resets the bank to which the system was writing to the read mode. Once erasure begins, however, the device ignores reset commands until the operation is complete.

The reset command may be written between the sequence cycles in a program command sequence before programming begins. This resets the bank to which the system was writing to the read mode. If the program command sequence is written to a bank that is in the Erase Suspend mode, writing the reset command returns that bank to the erase-suspend-read mode. Once programming begins, however, the device ignores reset commands until the operation is complete.

The reset command may be written between the sequence cycles in an autoselect command sequence. Once in the autoselect mode, the reset command must be written to return to the read mode. If a bank entered the autoselect mode while in the Erase Suspend mode, writing the reset command returns that bank to the erase-suspend-read mode.

If DQ5 goes high during a program or erase operation, writing the reset command returns the banks to the read mode (or erase-suspend-read mode if that bank was in Erase Suspend).

### **Autoselect Command Sequence**

The autoselect command sequence allows the host system to access the manufacturer and device codes, and determine whether or not a sector is protected. The autoselect command sequence may be written to an address within a bank that is either in the read or erase-suspend-read mode. The autoselect command may not be written while the device is actively programming or erasing in the other bank.

The autoselect command sequence is initiated by first writing two unlock cycles. This is followed by a third write cycle that contains the bank address and the autoselect command. The bank then enters the autoselect mode. The system may read any number of autoselect codes without reinitiating the command sequence.

Table 22 shows the address and data requirements. To determine sector protection information, the system must write to the appropriate bank address (BA) and sector address (SADD). Table 2 shows the address range and bank number associated with each sector.

The system must write the reset command to return to the read mode (or erase-suspend-read mode if the bank was previously in Erase Suspend).

# Enter SecSi™ Sector/Exit SecSi Sector Command Sequence

The SecSi Sector region provides a secured data area containing a random, sixteen-byte electronic serial number (ESN). The system can access the SecSi Sector region by issuing the three-cycle Enter SecSi



Sector command sequence. The device continues to access the SecSi Sector region until the system issues the four-cycle Exit SecSi Sector command sequence. The Exit SecSi Sector command sequence returns the device to normal operation. The SecSi Sector is not accessible when the device is executing an Embedded Program or embedded Erase algorithm. Table 22 shows the address and data requirements for both command sequences. *Note that the ACC function and unlock bypass modes are not available when the SecSi sector is enabled.* See also "SecSi<sup>TM</sup> (Secured Silicon) Sector SectorFlash Memory Region" for further information.

### **Program Command Sequence**

Programming is a four-bus-cycle operation. The program command sequence is initiated by writing two unlock write cycles, followed by the program set-up command. The program address and data are written next, which in turn initiate the Embedded Program algorithm. The system is *not* required to provide further controls or timings. The device automatically provides internally generated program pulses and verifies the programmed cell margin. Table 22 shows the address and data requirements for the byte program command sequence. *Note that the SecSi Sector, autoselect, and CFI functions are unavailable when a program operation is in progress.* 

When the Embedded Program algorithm is complete, that bank then returns to the read mode and addresses are no longer latched. The system can determine the status of the program operation by using DQ7, DQ6, or RY/BY#. Refer to the Flash Write Operation Status section for information on these status bits.

Any commands written to the device during the Embedded Program Algorithm are ignored. Note that a hardware reset immediately terminates the program operation. The program command sequence should be reinitiated once that bank has returned to the read mode, to ensure data integrity.

Programming is allowed in any sequence and across sector boundaries. A bit cannot be programmed from "0" back to a "1." Attempting to do so may cause that bank to set DQ5 = 1, or cause the DQ7 and

DQ6 status bits to indicate the operation was successful. However, a succeeding read will show that the data is still "0." Only erase operations can convert a "0" to a "1."

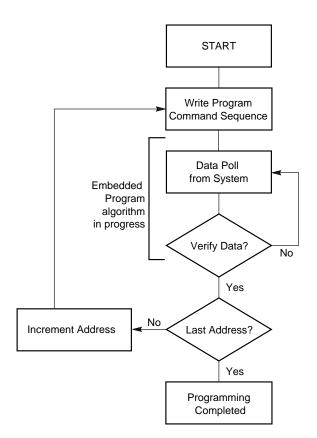
#### **Unlock Bypass Command Sequence**

The unlock bypass feature allows the system to program bytes or words to a bank faster than using the standard program command sequence. The unlock bypass command sequence is initiated by first writing two unlock cycles. This is followed by a third write cycle containing the unlock bypass command, 20h. That bank then enters the unlock bypass mode. A two-cycle unlock bypass program command sequence is all that is required to program in this mode. The first cycle in this sequence contains the unlock bypass program command, A0h; the second cycle contains the program address and data. Additional data is programmed in the same manner. This mode dispenses with the initial two unlock cycles required in the standard program command sequence, resulting in faster total programming time. Table 22 shows the requirements for the command sequence.

During the unlock bypass mode, only the Unlock Bypass Program and Unlock Bypass Reset commands are valid. To exit the unlock bypass mode, the system must issue the two-cycle unlock bypass reset command sequence (See Table 12).

The device offers accelerated program operations through the WP#/ACC pin. When the system asserts V<sub>HH</sub> on the WP#/ACC pin, the device automatically enters the Unlock Bypass mode. The system may then write the two-cycle Unlock Bypass program command sequence. The device uses the higher voltage on the WP#/ACC pin to accelerate the operation. Note that the WP#/ACC pin must not be at V<sub>HH</sub> any operation other than accelerated programming, or device damage may result. In addition, the WP#/ACC pin must not be left floating or unconnected; inconsistent behavior of the device may result.

Figure 3 illustrates the algorithm for the program operation. Refer to the Erase and Program Operations table in the AC Characteristics section for parameters, and Figure 16 for timing diagrams.



Note: See Table 22 for program command sequence.

Figure 4. Program Operation

## **Chip Erase Command Sequence**

Chip erase is a six bus cycle operation. The chip erase command sequence is initiated by writing two unlock cycles, followed by a set-up command. Two additional unlock write cycles are then followed by the chip erase command, which in turn invokes the Embedded Erase algorithm. The device does *not* require the system to preprogram prior to erase. The Embedded Erase algorithm automatically preprograms and verifies the entire memory for an all zero data pattern prior to electrical erase. The system is not required to provide any controls or timings during these operations. Table 22 shows the address and data requirements for the chip erase command sequence. *Note that the SecSi Sector, autoselect, and CFI functions are unavailable when a erase operation is in progress.* 

When the Embedded Erase algorithm is complete, that bank returns to the read mode and addresses are no longer latched. The system can determine the status of the erase operation by using DQ7, DQ6, DQ2, or RY/BY#. Refer to the Flash Write Operation Status section for information on these status bits.

Any commands written during the chip erase operation are ignored. However, note that a **hardware reset** immediately terminates the erase operation. If that occurs, the chip erase command sequence should be reinitiated once that bank has returned to reading array data, to ensure data integrity.

Figure 4 illustrates the algorithm for the erase operation. Refer to the Erase and Program Operations tables in the AC Characteristics section for parameters, and Figure 18 section for timing diagrams.

## **Sector Erase Command Sequence**

Sector erase is a six bus cycle operation. The sector erase command sequence is initiated by writing two unlock cycles, followed by a set-up command. Two additional unlock cycles are written, and are then followed by the address of the sector to be erased, and the sector erase command. Table 22 shows the address and data requirements for the sector erase command sequence. Note that the SecSi Sector, autoselect, and CFI functions are unavailable when a erase operation is in progress.

The device does *not* require the system to preprogram prior to erase. The Embedded Erase algorithm automatically programs and verifies the entire memory for an all zero data pattern prior to electrical erase. The system is not required to provide any controls or timings during these operations.

After the command sequence is written, a sector erase time-out of 80 µs occurs. During the time-out period, additional sector addresses and sector erase commands may be written. Loading the sector erase buffer may be done in any sequence, and the number of sectors may be from one sector to all sectors. The time between these additional cycles must be less than 80 us, otherwise erasure may begin. Any sector erase address and command following the exceeded time-out may or may not be accepted. It is recommended that processor interrupts be disabled during this time to ensure all commands are accepted. The interrupts can be re-enabled after the last Sector Erase command is written. Any command other than Sector Erase or Erase Suspend during the time-out period resets that bank to the read mode. The system must rewrite the command sequence and any additional addresses and commands.

The system can monitor DQ3 to determine if the sector erase timer has timed out (See the section on DQ3: Sector Erase Timer.). The time-out begins from the rising edge of the final WE# pulse in the command sequence.

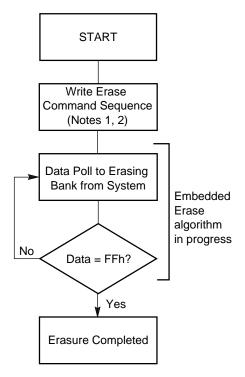
When the Embedded Erase algorithm is complete, the bank returns to reading array data and addresses are no longer latched. Note that while the Embedded Erase operation is in progress, the system can read



data from the non-erasing bank. The system can determine the status of the erase operation by reading DQ7, DQ6, DQ2, or RY/BY# in the erasing bank. Refer to the Flash Write Operation Status section for information on these status bits.

Once the sector erase operation has begun, only the Erase Suspend command is valid. All other commands are ignored. However, note that a **hardware reset** immediately terminates the erase operation. If that occurs, the sector erase command sequence should be reinitiated once that bank has returned to reading array data, to ensure data integrity.

Figure 4 illustrates the algorithm for the erase operation. Refer to the Erase and Program Operations tables in the AC Characteristics section for parameters, and Figure 18 section for timing diagrams.



#### Notes

- 1. See Table 22 for erase command sequence.
- See the section on DQ3 for information on the sector erase timer.

Figure 5. Erase Operation

## Erase Suspend/Erase Resume Commands

The Erase Suspend command, B0h, allows the system to interrupt a sector erase operation and then read data from, or program data to, any sector not selected for erasure. The bank address is required when writing this command. This command is valid only during the sector erase operation, including the 80 µs time-out period during the sector erase command sequence. The Erase Suspend command is ignored if written during the chip erase operation or Embedded Program algorithm.

When the Erase Suspend command is written during the sector erase operation, the device requires a maximum of 20 µs to suspend the erase operation. However, when the Erase Suspend command is written during the sector erase time-out, the device immediately terminates the time-out period and suspends the erase operation. Addresses are "don't-cares" when writing the Erase suspend command.

After the erase operation has been suspended, the bank enters the erase-suspend-read mode. The system can read data from or program data to any sector not selected for erasure. (The device "erase suspends" all sectors selected for erasure.) Reading at any address within erase-suspended sectors produces status information on DQ7–DQ0. The system can use DQ7, or DQ6 and DQ2 together, to determine if a sector is actively erasing or is erase-suspended. Refer to the Flash Write Operation Status section for information on these status bits.

After an erase-suspended program operation is complete, the bank returns to the erase-suspend-read mode. The system can determine the status of the program operation using the DQ7 or DQ6 status bits, just as in the standard Byte Program operation. Refer to the Flash Write Operation Status section for more information.

In the erase-suspend-read mode, the system can also issue the autoselect command sequence. The device allows reading autoselect codes even at addresses within erasing sectors, since the codes are not stored in the memory array. When the device exits the autoselect mode, the device reverts to the Erase Suspend mode, and is ready for another valid operation. Refer to the Sector/Sector Block Protection and Unprotection and Autoselect Command Sequence sections for details.

To resume the sector erase operation, the system must write the Erase Resume command (address bits are don't care). The bank address of the erase-suspended bank is required when writing this command. Further writes of the Resume command are ignored. Another Erase Suspend command can be written after the chip has resumed erasing.

Table 22. Am29DL640G and Am29DL320G Command Definitions

	Command		Ś	Bus Cycles (Notes 2-5)											
	Sequence		Cycles	Fir	st	Sec	ond	Thire	d	Four	th	Fiftl	า	Sixt	h
	(Note 1)		ડ	Addr	Data	Addr	Data	Addr	Data	Addr	Data	Addr	Data	Addr	Data
Re	Read (Note 6)		1	RA	RD										
Re	set (Note 7)		1	XXX	F0										
(8	Manufacturer ID	Word	4	555	AA	2AA	55	(BA)555	90	(BA)X00	01				
(Note	Device ID (Note 9)	Word	6	555	AA	2AA	55	(BA)555	90	(BA)X01	7E	(BA)X0E	02/0A	(BA)X0F	00/01
elect (N	SecSi Sector Factory Protect (Note 10)	Word	4	555	AA	2AA	55	(BA)555	90	(BA)X03	80/00				
Autoselect	Sector/Sector Block Protect Verify (Note 11)	Word	4	555	AA	2AA	55	(BA)555	90	(SADD) X02	00/01				
Ent	Enter SecSi Sector Region V		3	555	AA	2AA	55	555	88						
Exi	t SecSi Sector Region	Word	4	555	AA	2AA	55	555	90	XXX	00				
Pro	ogram	Word	4	555	AA	2AA	55	555	A0	PA	PD				
Un	lock Bypass	Word	3	555	AA	2AA	55	555	20						
Un	lock Bypass Program (No	te 12)	2	XXX	A0	PA	PD								
Un	lock Bypass Reset (Note	13)	2	XXX	90	XXX	00								
Chi	ip Erase	Word	6	555	AA	2AA	55	555	80	555	AA	2AA	55	555	10
Se	Sector Erase Word		6	555	AA	2AA	55	555	80	555	AA	2AA	55	SADD	30
Erase Suspend (Note 14)			1	BA	B0										
Erase Resume (Note 15)			1	BA	30										
CF	I Query (Note 16)	Word	1	55	98										

#### Legend:

X = Don't care

RA = Address of the memory location to be read.

RD = Data read from location RA during read operation.

PA = Address of the memory location to be programmed. Addresses latch on the falling edge of the WE# or CE#f pulse, whichever happens later.

PD = Data to be programmed at location PA. Data latches on the rising edge of WE# or CE#f pulse, whichever happens first.

SADD = Address of the sector to be verified (in autoselect mode) or erased. Address bits A21–A12 uniquely select any sector. Refer to Table 2 for information on sector addresses.

BA = Address of the bank that is being switched to autoselect mode, is in bypass mode, or is being erased. Address bits A21–A19 select a bank. Refer to Table 3 for information on sector addresses.

- 1. See Tables 1 to 2 for description of bus operations.
- 2. All values are in hexadecimal.
- Except for the read cycle and the fourth cycle of the autoselect command sequence, all bus cycles are write cycles.
- Data bits DQ15–DQ8 are don't care in command sequences, except for RD and PD.
- Unless otherwise noted, address bits A21–A12 are don't cares for unlock and command cycles, unless SADD or PA is required.
- No unlock or command cycles required when bank is reading array data.
- The Reset command is required to return to the read mode (or to the erase-suspend-read mode if previously in Erase Suspend) when a bank is in the autoselect mode, or if DQ5 goes high (while the bank is providing status information).
- The fourth cycle of the autoselect command sequence is a read cycle. The system must provide the bank address to obtain the manufacturer ID, device ID, or SecSi Sector factory protect information. Data bits DQ15–DQ8 are don't care. See the Autoselect Command Sequence section for more information.
- The device ID must be read across the fourth, fifth, and sixth cycles. At address x0E, the data is 02h for Am29DL640G and 0Ah for Am29DL320G. At address x0F, the data is 01h for

- Am29DL640G and Am29DL320G (top boot) and 00h for Am29DL320G (bottom boot).
- For Am29DL640G, the data is 80h for factory locked and 00h for not factory locked. For Am29DL320G, they are 81H and 01h respectively.
- The data is 00h for an unprotected sector/sector block and 01h for a protected sector/sector block.
- 12. The Unlock Bypass command is required prior to the Unlock Bypass Program command.
- 13. The Unlock Bypass Reset command is required to return to the read mode when the bank is in the unlock bypass mode.
- 14. The system may read and program in non-erasing sectors, or enter the autoselect mode, when in the Erase Suspend mode. The Erase Suspend command is valid only during a sector erase operation, and requires the bank address.
- 15. The Erase Resume command is valid only during the Erase Suspend mode, and requires the bank address.
- Command is valid when device is ready to read array data or when device is in autoselect mode.



#### FLASH WRITE OPERATION STATUS

The device provides several bits to determine the status of a program or erase operation: DQ2, DQ3, DQ5, DQ6, and DQ7. Table 23 and the following subsections describe the function of these bits. DQ7 and DQ6 each offer a method for determining whether a program or erase operation is complete or in progress. The device also provides a hardware-based output signal, RY/BY#, to determine whether an Embedded Program or Erase operation is in progress or has been completed.

## **DQ7: Data# Polling**

The Data# Polling bit, DQ7, indicates to the host system whether an Embedded Program or Erase algorithm is in progress or completed, or whether a bank is in Erase Suspend. Data# Polling is valid after the rising edge of the final WE# pulse in the command sequence.

During the Embedded Program algorithm, the device outputs on DQ7 the complement of the datum programmed to DQ7. This DQ7 status also applies to programming during Erase Suspend. When the Embedded Program algorithm is complete, the device outputs the datum programmed to DQ7. The system must provide the program address to read valid status information on DQ7. If a program address falls within a protected sector, Data# Polling on DQ7 is active for approximately 1 µs, then that bank returns to the read mode.

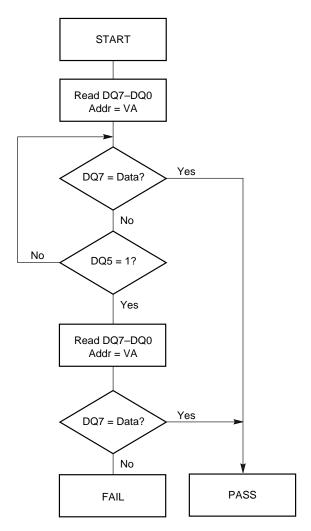
During the Embedded Erase algorithm, Data# Polling produces a "0" on DQ7. When the Embedded Erase algorithm is complete, or if the bank enters the Erase Suspend mode, Data# Polling produces a "1" on DQ7. The system must provide an address within any of the sectors selected for erasure to read valid status information on DQ7.

After an erase command sequence is written, if all sectors selected for erasing are protected, Data# Polling on DQ7 is active for approximately 100  $\mu$ s, then the bank returns to the read mode. If not all selected sectors are protected, the Embedded Erase algorithm erases the unprotected sectors, and ignores the selected sectors that are protected. However, if the system reads DQ7 at an address within a protected sector, the status may not be valid.

When the system detects DQ7 has changed from the complement to true data, it can read valid data at DQ15–DQ0 (or DQ7–DQ0 for byte mode) on the *following* read cycles. Just prior to the completion of an Embedded Program or Erase operation, DQ7 may change asynchronously with DQ15–DQ8 (DQ7–DQ0 in byte mode) while Output Enable (OE#) is asserted low. That is, the device may change from providing status information to valid data on DQ7. Depending on when the system samples the DQ7 output, it may read the status or valid data. Even if the device has com-

pleted the program or erase operation and DQ7 has valid data, the data outputs on DQ15–DQ0 may be still invalid. Valid data on DQ15–DQ0 (or DQ7–DQ0 for byte mode) will appear on successive read cycles.

Table 23 shows the outputs for Data# Polling on DQ7. Figure 5 shows the Data# Polling algorithm. Figure 20 in the Flash AC Characteristics section shows the Data# Polling timing diagram.



- VA = Valid address for programming. During a sector erase operation, a valid address is any sector address within the sector being erased. During chip erase, a valid address is any non-protected sector address.
- DQ7 should be rechecked even if DQ5 = "1" because DQ7 may change simultaneously with DQ5.

Figure 6. Data# Polling Algorithm

## RY/BY#: Ready/Busy#

The RY/BY# is a dedicated, open-drain output pin which indicates whether an Embedded Algorithm is in progress or complete. The RY/BY# status is valid after the rising edge of the final WE# pulse in the command sequence. Since RY/BY# is an open-drain output, several RY/BY# pins can be tied together in parallel with a pull-up resistor to  $V_{\rm CC}$ .

If the output is low (Busy), the device is actively erasing or programming. (This includes programming in the Erase Suspend mode.) If the output is high (Ready), the device is in the read mode, the standby mode, or one of the banks is in the erase-suspend-read mode.

Table 23 shows the outputs for RY/BY#.

## DQ6: Toggle Bit I

Toggle Bit I on DQ6 indicates whether an Embedded Program or Erase algorithm is in progress or complete, or whether the device has entered the Erase Suspend mode. Toggle Bit I may be read at any address, and is valid after the rising edge of the final WE# pulse in the command sequence (prior to the program or erase operation), and during the sector erase time-out.

During an Embedded Program or Erase algorithm operation, successive read cycles to any address cause DQ6 to toggle. The system may use either OE# or CE#f to control the read cycles. When the operation is complete, DQ6 stops toggling.

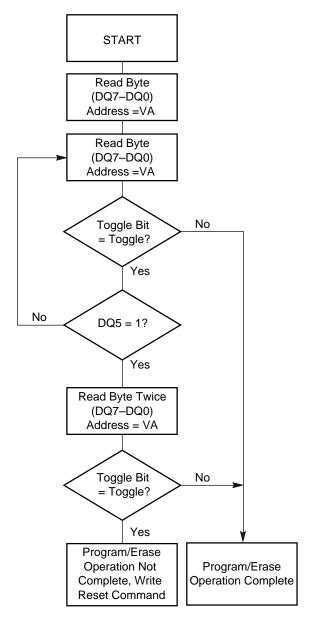
After an erase command sequence is written, if all sectors selected for erasing are protected, DQ6 toggles for approximately 100  $\mu$ s, then returns to reading array data. If not all selected sectors are protected, the Embedded Erase algorithm erases the unprotected sectors, and ignores the selected sectors that are protected.

The system can use DQ6 and DQ2 together to determine whether a sector is actively erasing or is erase-suspended. When the device is actively erasing (that is, the Embedded Erase algorithm is in progress), DQ6 toggles. When the device enters the Erase Suspend mode, DQ6 stops toggling. However, the system must also use DQ2 to determine which sectors are erasing or erase-suspended. Alternatively, the system can use DQ7 (see the subsection on DQ7: Data# Polling).

If a program address falls within a protected sector, DQ6 toggles for approximately 1 µs after the program command sequence is written, then returns to reading array data.

DQ6 also toggles during the erase-suspend-program mode, and stops toggling once the Embedded Program algorithm is complete.

Table 23 shows the outputs for Toggle Bit I on DQ6. Figure 6 shows the toggle bit algorithm. Figure 21 in the "Flash AC Characteristics" section shows the toggle bit timing diagrams. Figure 22 shows the differences between DQ2 and DQ6 in graphical form. See also the subsection on DQ2: Toggle Bit II.



**Note:** The system should recheck the toggle bit even if DQ5 = "1" because the toggle bit may stop toggling as DQ5 changes to "1." See the subsections on DQ6 and DQ2 for more information.

Figure 7. Toggle Bit Algorithm



## DQ2: Toggle Bit II

The "Toggle Bit II" on DQ2, when used with DQ6, indicates whether a particular sector is actively erasing (that is, the Embedded Erase algorithm is in progress), or whether that sector is erase-suspended. Toggle Bit II is valid after the rising edge of the final WE# pulse in the command sequence.

DQ2 toggles when the system reads at addresses within those sectors that have been selected for erasure. (The system may use either OE# or CE#f to control the read cycles.) But DQ2 cannot distinguish whether the sector is actively erasing or is erase-suspended. DQ6, by comparison, indicates whether the device is actively erasing, or is in Erase Suspend, but cannot distinguish which sectors are selected for erasure. Thus, both status bits are required for sector and mode information. Refer to Table 23 to compare outputs for DQ2 and DQ6.

Figure 6 shows the toggle bit algorithm in flowchart form, and the section "DQ2: Toggle Bit II" explains the algorithm. See also the DQ6: Toggle Bit I subsection. Figure 21 shows the toggle bit timing diagram. Figure 22 shows the differences between DQ2 and DQ6 in graphical form.

## Reading Toggle Bits DQ6/DQ2

Refer to Figure 6 for the following discussion. Whenever the system initially begins reading toggle bit status, it must read DQ15–DQ0 (or DQ7–DQ0 for byte mode) at least twice in a row to determine whether a toggle bit is toggling. Typically, the system would note and store the value of the toggle bit after the first read. After the second read, the system would compare the new value of the toggle bit with the first. If the toggle bit is not toggling, the device has completed the program or erase operation. The system can read array data on DQ15–DQ0 (or DQ7–DQ0 for byte mode) on the following read cycle.

However, if after the initial two read cycles, the system determines that the toggle bit is still toggling, the system also should note whether the value of DQ5 is high (see the section on DQ5). If it is, the system should then determine again whether the toggle bit is toggling, since the toggle bit may have stopped toggling just as DQ5 went high. If the toggle bit is no longer toggling, the device has successfully completed the program or erase operation. If it is still toggling, the device did not completed the operation successfully, and the system must write the reset command to return to reading array data.

The remaining scenario is that the system initially determines that the toggle bit is toggling and DQ5 has

not gone high. The system may continue to monitor the toggle bit and DQ5 through successive read cycles, determining the status as described in the previous paragraph. Alternatively, it may choose to perform other system tasks. In this case, the system must start at the beginning of the algorithm when it returns to determine the status of the operation (top of Figure 6).

## **DQ5: Exceeded Timing Limits**

DQ5 indicates whether the program or erase time has exceeded a specified internal pulse count limit. Under these conditions DQ5 produces a "1," indicating that the program or erase cycle was not successfully completed.

The device may output a "1" on DQ5 if the system tries to program a "1" to a location that was previously programmed to "0." **Only an erase operation can change a "0" back to a "1."** Under this condition, the device halts the operation, and when the timing limit has been exceeded, DQ5 produces a "1."

Under both these conditions, the system must write the reset command to return to the read mode (or to the erase-suspend-read mode if a bank was previously in the erase-suspend-program mode).

## **DQ3: Sector Erase Timer**

After writing a sector erase command sequence, the system may read DQ3 to determine whether or not erasure has begun. (The sector erase timer does not apply to the chip erase command.) If additional sectors are selected for erasure, the entire time-out also applies after each additional sector erase command. When the time-out period is complete, DQ3 switches from a "0" to a "1." If the time between additional sector erase commands from the system can be assumed to be less than 50  $\mu s$ , the system need not monitor DQ3. See also the Sector Erase Command Sequence section.

After the sector erase command is written, the system should read the status of DQ7 (Data# Polling) or DQ6 (Toggle Bit I) to ensure that the device has accepted the command sequence, and then read DQ3. If DQ3 is "1," the Embedded Erase algorithm has begun; all further commands (except Erase Suspend) are ignored until the erase operation is complete. If DQ3 is "0," the device will accept additional sector erase commands. To ensure the command has been accepted, the system software should check the status of DQ3 prior to and following each subsequent sector erase command. If DQ3 is high on the second status check, the last command might not have been accepted.

Table 23 shows the status of DQ3 relative to the other status bits.

## Table 23. Write Operation Status

	Status		DQ7 (Note 2)	DQ6	DQ5 (Note 1)	DQ3	DQ2 (Note 2)	RY/BY#
Standard	Embedded Program Algorithm		DQ7#	Toggle	0	N/A	No toggle	0
Mode	Embedded Erase Algorithm		0	Toggle	0	1	Toggle	0
Erase	Erase-Suspend-	Erase Suspended Sector	1	No toggle	0	N/A	Toggle	1
Suspend Mode	Read	Non-Erase Suspended Sector	Data	Data	Data	Data	Data	1
	Erase-Suspend-Program		DQ7#	Toggle	0	N/A	N/A	0

- 1. DQ5 switches to '1' when an Embedded Program or Embedded Erase operation has exceeded the maximum timing limits. Refer to the section on DQ5 for more information.
- 2. DQ7 and DQ2 require a valid address when reading status information. Refer to the appropriate subsection for further details.
- 3. When reading write operation status bits, the system must always provide the bank address where the Embedded Algorithm is in progress. The device outputs array data if the system addresses a non-busy bank.



## **ABSOLUTE MAXIMUM RATINGS**

Storage Temperature Plastic Packages55°C to +125°C
Ambient Temperature with Power Applied
Voltage with Respect to Ground
V <sub>CC</sub> (Note 1)0.5 V to +4.0 V
RESET# (Note 2)0.5 V to +12.5 V
WP#/ACC0.5 V to +10.5 V
All other pins (Note 1)0.5 V to V <sub>CC</sub> +0.5 V
Output Short Circuit Current (Note 3) 200 mA
Notes:

- Minimum DC voltage on input or I/O pins is -0.5 V. During voltage transitions, input or I/O pins may overshoot V<sub>SS</sub> to -2.0 V for periods of up to 20 ns. Maximum DC voltage on input or I/O pins is V<sub>CC</sub> +0.5 V. See Figure 7. During voltage transitions, input or I/O pins may overshoot to V<sub>CC</sub> +2.0 V for periods up to 20 ns. See Figure 8.
- Minimum DC input voltage on pins RESET#, and WP#/ACC is −0.5 V. During voltage transitions, WP#/ACC, and RESET# may overshoot V<sub>SS</sub> to −2.0 V for periods of up to 20 ns. See Figure 7. Maximum DC input voltage on pin RESET# is +12.5 V which may overshoot to +14.0 V for periods up to 20 ns. Maximum DC input voltage on WP#/ACC is +9.5 V which may overshoot to +12.0 V for periods up to 20 ns.
- No more than one output may be shorted to ground at a time. Duration of the short circuit should not be greater than one second.

Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational sections of this data sheet is not implied. Exposure of the device to absolute maximum rating conditions for extended periods may affect device reliability.

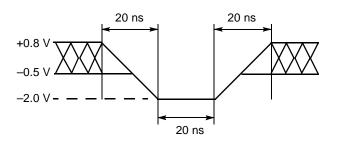


Figure 8. Maximum Negative Overshoot Waveform

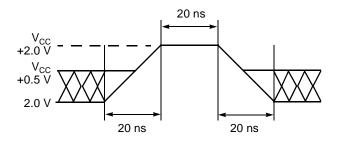


Figure 9. Maximum Positive Overshoot Waveform

## **OPERATING RANGES**

## Industrial (I) Devices

Ambient Temperature (T<sub>A</sub>) . . . . . . . . -40°C to +85°C

## V<sub>CC</sub>f/V<sub>CC</sub>s Supply Voltages

 $V_{CC}f/V_{CC}s$  for standard voltage range . .2.7 V to 3.3 V Operating ranges define those limits between which the functionality of the device is guaranteed.

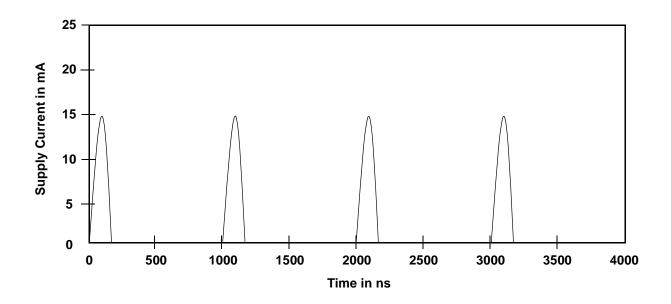
## **CMOS Compatible**

Parameter Symbol	Parameter Description	Test Conditions		Min	Тур	Max	Unit
l <sub>LI</sub>	Input Load Current	$V_{IN} = V_{SS}$ to $V_{CC}$ , $V_{CC} = V_{CC \text{ max}}$				±1.0	μΑ
I <sub>LIT</sub>	RESET# Input Load Current	V <sub>CC</sub> = V <sub>CC max</sub> ; RESET# = 12	.5 V			35	μA
I <sub>LO</sub>	Output Leakage Current	$V_{OUT} = V_{SS}$ to $V_{CC}$ , $V_{CC} = V_{CC \text{ max}}$				±1.0	μΑ
I <sub>LR</sub>	Reset Leakage Current	$V_{CC} = V_{CC \text{ max}}$ ; RESET# = 12	.5 V			35	μA
I <sub>LIA</sub>	ACC Input Leakage Current	V <sub>CC</sub> = V <sub>CC max</sub> , WP#/ACC = \	ACC max			35	μA
I <sub>CC1</sub> f	Flash V <sub>CC</sub> Active Read Current (Notes 1, 2)	CE#f = V <sub>IL</sub> , OE# = V <sub>IH</sub> , Word Mode	5 MHz 1 MHz		10 2	16 4	mA
I <sub>CC2</sub> f	Flash V <sub>CC</sub> Active Write Current (Notes 2, 3)	CE#f = V <sub>IL</sub> , OE# = V <sub>IH</sub> , WE# :	= V <sub>II</sub>		15	30	mA
I <sub>CC3</sub> f	Flash V <sub>CC</sub> Standby Current (Note 2)	$V_{CC}f = V_{CC \text{ max}}$ , CE#f, RESET#,  WP#/ACC = $V_{CC}f \pm 0.3 \text{ V}$			0.2	10	μA
I <sub>CC4</sub> f	Flash V <sub>CC</sub> Reset Current (Note 2)	$V_{\rm CC}$ f = $V_{\rm CC~max}$ , RESET# = $V_{\rm SS}\pm0.3$ V, WP#/ACC = $V_{\rm CC}$ f $\pm0.3$ V			0.2	10	μΑ
I <sub>CC5</sub> f	Flash V <sub>CC</sub> Current Automatic Sleep Mode (Notes 2, 4)	$V_{CC}f = V_{CC \text{ max}}, V_{IH} = V_{CC} \pm 0.3 \text{ V};$ $V_{IL} = V_{SS} \pm 0.3 \text{ V}$			0.2	10	μΑ
I <sub>CC6</sub> f	Flash V <sub>CC</sub> Active Read-While-Program Current (Notes 1, 2)	CE#f = V <sub>IL</sub> , OE# = V <sub>IH</sub>			21	45	mA
I <sub>CC7</sub> f	Flash V <sub>CC</sub> Active Read-While-Erase Current (Notes 1, 2)	CE#f = V <sub>IL</sub> , OE# = V <sub>IH</sub>			21	45	mA
I <sub>CC8</sub> f	Flash V <sub>CC</sub> Active Program-While-Erase-Suspended Current (Notes 2, 5)	CE#f = V <sub>IL</sub> , OE#f = V <sub>IH</sub>			17	35	mA
$V_{IL}$	Input Low Voltage			-0.2		0.8	V
V <sub>IH</sub>	Input High Voltage			2.4		V <sub>CC</sub> + 0.2	V
V <sub>HH</sub>	Voltage for WP#/ACC Program Acceleration and Sector Protection/Unprotection			8.5		9.5	V
V <sub>ID</sub>	Voltage for Sector Protection, Autoselect and Temporary Sector Unprotect			11.5		12.5	V
V <sub>OL</sub>	Output Low Voltage	$I_{OL} = 4.0 \text{ mA}, V_{CC}f = V_{CC}s = 100 \text{ mA}$	V <sub>CC min</sub>			0.45	V
V <sub>OH1</sub>	Output High Voltage	$I_{OH} = -2.0 \text{ mA}, V_{CC}f = V_{CC}s = V_{CC \text{ min}}$		0.85 x V <sub>CC</sub>			V
V <sub>OH2</sub>	<u> </u>	$I_{OH} = -100 \mu A$ , $V_{CC} = V_{CC min}$		V <sub>CC</sub> -0.4			
$V_{LKO}$	Flash Low V <sub>CC</sub> Lock-Out Voltage (Note 5)			2.3		2.5	V

- 1. The  $I_{CC}$  current listed is typically less than 2 mA/MHz, with OE# at  $V_{vv}$ .
- 2. Maximum  $I_{CC}$  specifications are tested with  $V_{CC} = V_{CC} max$ .
- 3.  $I_{CC}$  active while Embedded Erase or Embedded Program is in progress.
- Automatic sleep mode enables the low power mode when addresses remain stable for t<sub>ACC</sub> + 30 ns. Typical sleep mode current is 200 nA.
- 5. Not 100% tested.
- 6. 2 Flash stack together  $\rightarrow$  double the current limit from 5  $\rightarrow$  10  $\mu A$

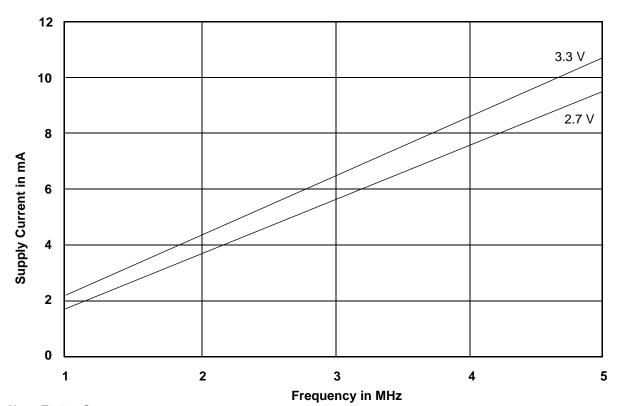


## **Zero-Power Flash**



Note: Addresses are switching at 1 MHz

Figure 10. I<sub>CC1</sub> Current vs. Time (Showing Active and Automatic Sleep Currents)



**Note:**  $T = 25 \,^{\circ}C$ 

Figure 11. Typical  $I_{CC1}$  vs. Frequency

7.

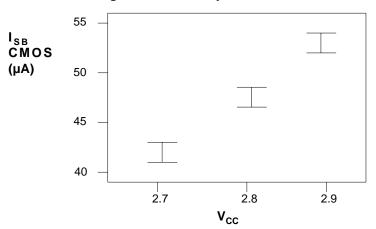
## PSEUDO SRAM DC AND OPERATING CHARACTERISTICS

Parameter Symbol	Parameter Description	Test Conditions	Min	Тур	Max	Unit
ILI	Input Leakage Current	$V_{IN} = V_{SS}$ to $V_{CC}$	-1.0		1.0	μA
I <sub>LO</sub>	Output Leakage Current	CE1#s = $V_{IH}$ , CE2s = $V_{IL}$ or OE# = $V_{IH}$ or WE# = $V_{IL}$ , $V_{IO}$ = $V_{SS}$ to $V_{CC}$	-1.0		1.0	μΑ
I <sub>CC1</sub> s	Average Operating Current	$ \begin{aligned} & \text{Cycle time} = 1  \mu\text{s}, \ 100\% \ \text{duty,} \\ & I_{\text{IO}} = 0  \text{mA, CE1\#s} \leq 0.2 \text{ V,} \\ & \text{CE2} \geq V_{\text{CC}} - 0.2 \text{ V, V}_{\text{IN}} \leq 0.2 \text{ V or} \\ & V_{\text{IN}} \geq V_{\text{CC}} - 0.2 \text{ V} \end{aligned} $		3	5	mA
I <sub>CC2</sub> s	Average Operating Current			12	25	mA
V <sub>IL</sub>	Input Low Voltage		-0.2 (Note 3)		0.4	V
V <sub>IH</sub>	Input High Voltage		2.2		V <sub>CC</sub> +0.2 (Note 2)	V
V <sub>OL</sub>	Output Low Voltage	I <sub>OL</sub> = 2.0 mA			0.4	V
V <sub>OH</sub>	Output High Voltage	$I_{OH} = -1.0 \text{ mA}$	2.2			V
I <sub>SB</sub>	Standby Current (TTL)	CE1#s = $V_{IH}$ , CE2 = $V_{IL}$ , Other inputs = $V_{IH}$ or $V_{IL}$			0.3	mA
I <sub>SB1</sub>	Standby Current (CMOS)	$ \begin{aligned} \text{CE1\#s=V}_{\text{IH}}, \text{CE2=V}_{\text{IL:}} \\ \text{Other inputs = V}_{\text{IH}} \text{ or V}_{\text{IL:}} \\ t_{\text{A}} = 85^{\circ}\text{C}, \text{V}_{\text{CC}} = 3.0 \text{ V} \end{aligned} $			60	μA
I <sub>SB2</sub>	Standby Current (CMOS)	CE1#s= $V_{IH}$ , CE2= $V_{IL}$ : Other inputs = $V_{IH}$ or $V_{IL}$ : $t_A = 85^{\circ}\text{C}$ , $V_{CC} = 3.3 \text{ V}$			85	μA

## Notes:

- 1.  $T_A = -40^{\circ}$  to  $85^{\circ}$ C, otherwise specified.
- 2. Overshoot:  $V_{CC}$ +1.0V if pulse width  $\leq$  20 ns.
- 3. Undershoot: -1.0V if pulse width  $\leq 20$  ns.
- 4. Overshoot and undershoot are sampled, not 100% tested.
- 5. Stable power supply required 200 µs before device operation.

Figure 12. Standby Current ISB CMOS



- 1. At 70°, for reference only
- 2. Not 100% tested
- 3. Sample Size of 5



## **TEST CONDITIONS**

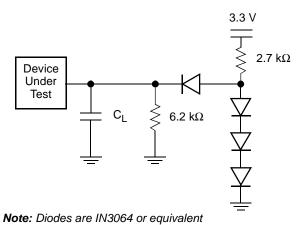


Figure 13. Test Setup

Table 24. Test Specifications

Test Condition	All Speed Options	Unit
Output Load	1 TTL gate	
Output Load Capacitance, C <sub>L</sub> (including jig capacitance)	30	pF
Input Rise and Fall Times	5	ns
Input Pulse Levels	0.0–3.0	V
Input timing measurement reference levels	1.5	V
Output timing measurement reference levels	1.5	V

## **KEY TO SWITCHING WAVEFORMS**

WAVEFORM	INPUTS	OUTPUTS				
		Steady				
	Cha	Changing from H to L				
	Cha	anging from L to H				
	Don't Care, Any Change Permitted	Changing, State Unknown				
$\longrightarrow$	Does Not Apply	Center Line is High Impedance State (High Z)				

KS000010-PAL

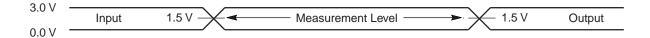


Figure 14. Input Waveforms and Measurement Levels

## **Pseudo SRAM CE#s Timing**

Paran	neter		Tost Sotum		AllSpeeds	Unit
JEDEC	Std	Description	Test Setup		Allopeeus	Offic
_	t <sub>CCR</sub>	CE#s Recover Time	_	Min	0	ns

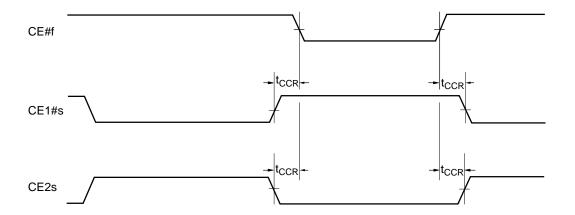


Figure 15. Timing Diagram for Alternating Between Pseudo SRAM to Flash

## **Read-Only Operations**

Param	neter					All Speed	
JEDEC	Std.	Description		Test Setup		Options	Unit
t <sub>AVAV</sub>	t <sub>RC</sub>	Read Cycle Time (Note 1)			Min	70	ns
t <sub>AVQV</sub>	t <sub>ACC</sub>	Address to Output Delay	CE#f, OE# = V <sub>IL</sub>	Max	70	ns	
t <sub>ELQV</sub>	t <sub>CE</sub>	Chip Enable to Output Delay	OE# = V <sub>IL</sub>	Max	70	ns	
t <sub>GLQV</sub>	t <sub>OE</sub>	Output Enable to Output Del		Max	30	ns	
t <sub>EHQZ</sub>	t <sub>DF</sub>	Chip Enable to Output High 2	Chip Enable to Output High Z (Notes 1, 3)			16	ns
t <sub>GHQZ</sub>	t <sub>DF</sub>	Output Enable to Output Hig	h Z (Notes 1, 3)		Max	16	ns
t <sub>AXQX</sub>	t <sub>OH</sub>	Output Hold Time From Addresses, CE#f or OE#, Whichever Occurs First			Min	0	ns
		0	Read		Min	0	ns
	t <sub>OEH</sub>	Output Enable Hold Time (Note 1)	Toggle and Data# Polling		Min	10	ns

- 1. Not 100% tested.
- 2. See Figure 11 and Table 24 for test specifications
- 3. Measurements performed by placing a  $50\Omega$  termination on the data pin with a bias of  $V_{CC}/2$ . The time from OE# high to the data bus driven to  $V_{CC}/2$  is taken as  $t_{DF}$

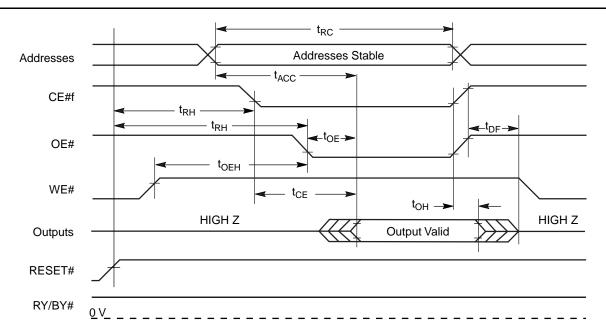
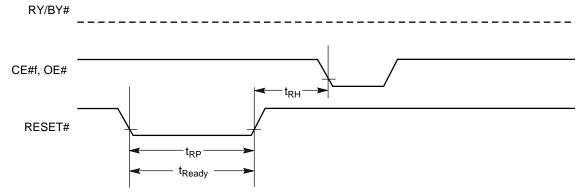


Figure 16. Read Operation Timings

## **Hardware Reset (RESET#)**

Parameter					
JEDEC	Std	Description	Description		Unit
	t <sub>Ready</sub>	RESET# Pin Low (During Embedded Algorithms) to Read Mode (See Note)	Max	20	μs
	t <sub>Ready</sub>	RESET# Pin Low (NOT During Embedded Algorithms) to Read Mode (See Note)	Max	500	ns
	t <sub>RP</sub>	RESET# Pulse Width	Min	500	ns
	t <sub>RH</sub>	Reset High Time Before Read (See Note)	Min	50	ns
	t <sub>RPD</sub>	RESET# Low to Standby Mode	Min	20	μs
	t <sub>RB</sub>	RY/BY# Recovery Time	Min	0	ns

Note: Not 100% tested.



Reset Timings NOT during Embedded Algorithms

## **Reset Timings during Embedded Algorithms**

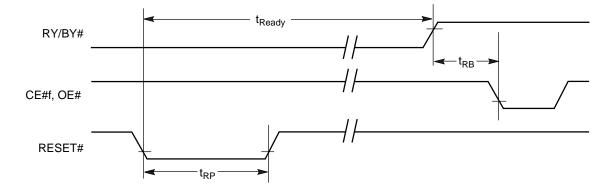


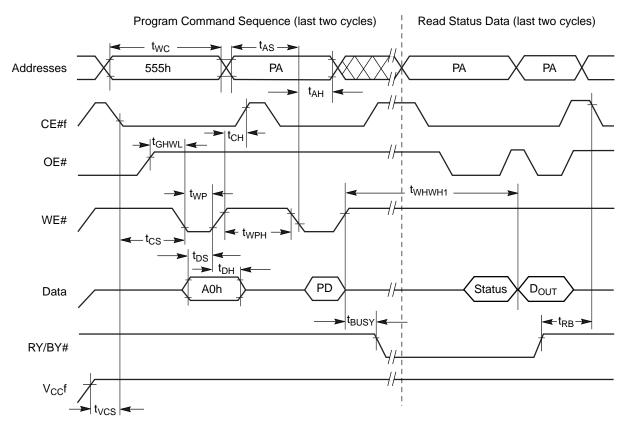
Figure 17. Reset Timings



## **Erase and Program Operations**

Parar	neter					
JEDEC	Std	Description			All Speed Options	Unit
t <sub>AVAV</sub>	t <sub>WC</sub>	Write Cycle Time (Note 1)		Min	70	ns
t <sub>AVWL</sub>	t <sub>AS</sub>	Address Setup Time		Min	0	ns
	t <sub>ASO</sub>	Address Setup Time to OE# low during tog	gle bit polling	Min	15	ns
+		Address Hold Time	Am29DL640G	Min	40	ns
$t_{WLAX}$	t <sub>AH</sub>	Address Floid Time	Am29DL320G	IVIIII	45	115
	t <sub>AHT</sub>	Address Hold Time From CE#f or OE# high during toggle bit polling	ו	Min	0	ns
		Data Satura Tima	Am29DL640G	Min	40	
t <sub>DVWH</sub>	t <sub>DS</sub>	Data Setup Time	Am29DL320G	Min	35	ns
t <sub>WHDX</sub>	t <sub>DH</sub>	Data Hold Time		Min	0	ns
	t <sub>OEPH</sub>	Output Enable High during toggle bit polling	g	Min	20	ns
t <sub>GHWL</sub>	t <sub>GHWL</sub>	Read Recovery Time Before Write (OE# High to WE# Low)		Min	0	ns
t <sub>WLEL</sub>	t <sub>WS</sub>	WE# Setup Time (CE#f to WE#)		Min	0	ns
t <sub>ELWL</sub>	t <sub>CS</sub>	CE#f Setup Time		Min	0	ns
t <sub>EHWH</sub>	t <sub>WH</sub>	WE# Hold Time (CE#f to WE#)		Min	0	ns
t <sub>WHEH</sub>	t <sub>CH</sub>	CE#f Hold Time		Min	0	ns
t <sub>WLWH</sub>	t <sub>WP</sub>	Write Pulse Width		Min	30	ns
t <sub>WHDL</sub>	t <sub>WPH</sub>	Write Pulse Width High		Min	30	ns
	t <sub>SR/W</sub>	Latency Between Read and Write Operation	ns	Min	0	ns
t <sub>WHWH1</sub>	t <sub>WHWH1</sub>	Programming Operation (Note 2)		Тур	7	μs
t <sub>WHWH1</sub>	t <sub>WHWH1</sub>	Accelerated Programming Operation, Word or Byte (Note 2)		Тур	4	μs
t <sub>WHWH2</sub>	t <sub>WHWH2</sub>	Sector Erase Operation (Note 2)		Тур	0.4	sec
	t <sub>VCS</sub>	V <sub>CC</sub> Setup Time (Note 1)		Min	50	μs
	t <sub>RB</sub>	Write Recovery Time from RY/BY#		Min	0	ns
	t <sub>BUSY</sub>	Program/Erase Valid to RY/BY# Delay		Max	90	ns

- 1. Not 100% tested.
- 2. See the "Flash Erase And Programming Performance" section for more information.



- 1.  $PA = program \ address, \ PD = program \ data, \ D_{OUT}$  is the true data at the program address.
- 2. Illustration shows device in word mode.

Figure 18. Program Operation Timings

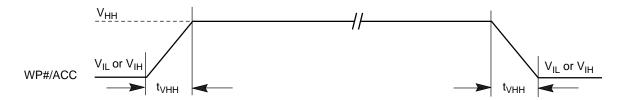
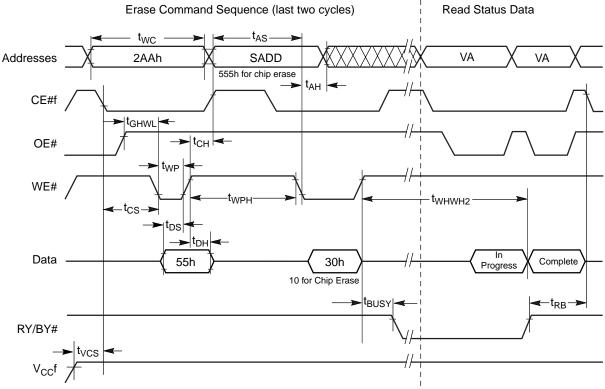


Figure 19. Accelerated Program Timing Diagram





- 1. SADD = sector address (for Sector Erase), VA = Valid Address for reading status data (see "Flash Write Operation Status".
- 2. These waveforms are for the word mode.

Figure 20. Chip/Sector Erase Operation Timings

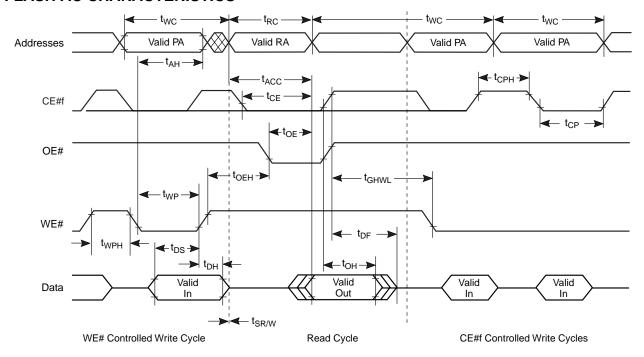
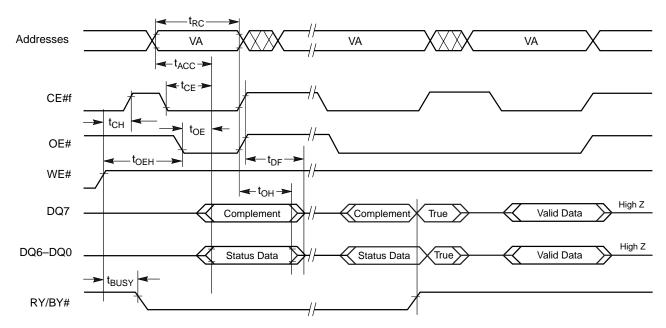


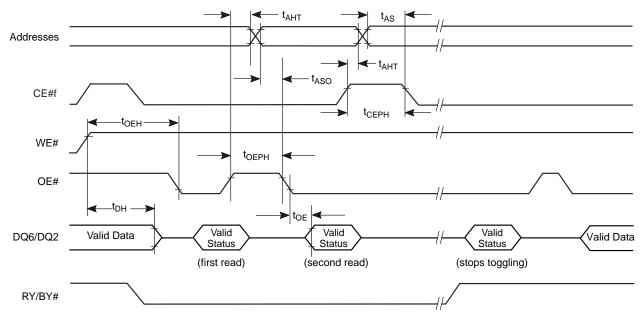
Figure 21. Back-to-back Read/Write Cycle Timings



**Note:** VA = Valid address. Illustration shows first status cycle after command sequence, last status read cycle, and array data read cycle.

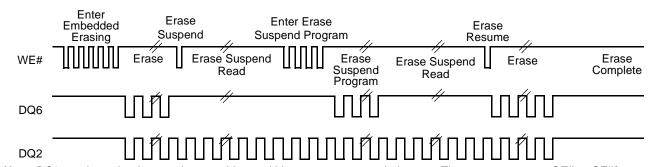
Figure 22. Data# Polling Timings (During Embedded Algorithms)





**Note:** VA = Valid address; not required for DQ6. Illustration shows first two status cycle after command sequence, last status read cycle, and array data read cycle.

Figure 23. Toggle Bit Timings (During Embedded Algorithms)



**Note:** DQ2 toggles only when read at an address within an erase-suspended sector. The system may use OE# or CE#f to toggle DQ2 and DQ6.

Figure 24. DQ2 vs. DQ6

## **Temporary Sector Unprotect**

Parameter					
JEDEC	DEC Std Description			All Speed Options	Unit
	t <sub>VIDR</sub>	V <sub>ID</sub> Rise and Fall Time (See Note)	Min	500	ns
	t <sub>VHH</sub>	V <sub>HH</sub> Rise and Fall Time (See Note)	Min	250	ns
	t <sub>RSP</sub>	RESET# Setup Time for Temporary Sector Unprotect	Min	4	μs
	t <sub>RRB</sub>	RESET# Hold Time from RY/BY# High for Temporary Sector Unprotect	Min	4	μs

Note: Not 100% tested.

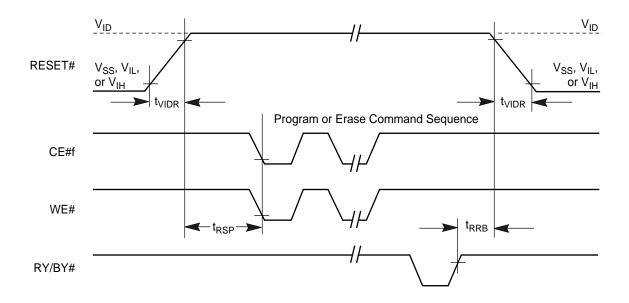
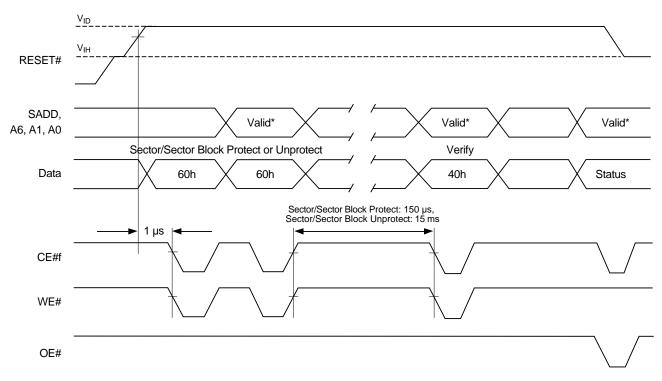


Figure 25. Temporary Sector Unprotect Timing Diagram





<sup>\*</sup> For sector protect, A6 = 0, A1 = 1, A0 = 0. For sector unprotect, A6 = 1, A1 = 1, A0 = 0, SADD = Sector Address.

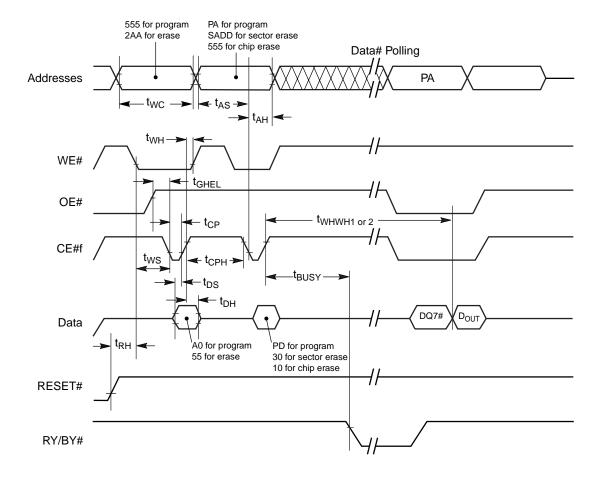
Figure 26. Sector/Sector Block Protect and Unprotect Timing Diagram

## **Alternate CE#f Controlled Erase and Program Operations**

Parar	meter			All Speed	
JEDEC	Std	Description		Options	Unit
t <sub>AVAV</sub>	t <sub>WC</sub>	Write Cycle Time (Note 1)	Min	70	ns
t <sub>AVWL</sub>	t <sub>AS</sub>	Address Setup Time	Min	0	ns
t <sub>ELAX</sub>	t <sub>AH</sub>	Address Hold Time	Min	40	ns
t <sub>DVEH</sub>	t <sub>DS</sub>	Data Setup Time	Min	40	ns
t <sub>EHDX</sub>	t <sub>DH</sub>	Data Hold Time	Min	0	ns
t <sub>GHEL</sub>	t <sub>GHEL</sub>	Read Recovery Time Before Write (OE# High to WE# Low)	Min	0	ns
t <sub>WLEL</sub>	t <sub>WS</sub>	WE# Setup Time	Min	0	ns
t <sub>EHWH</sub>	t <sub>WH</sub>	WE# Hold Time	Min	0	ns
t <sub>ELEH</sub>	t <sub>CP</sub>	CE#f Pulse Width	Min	40	ns
t <sub>EHEL</sub>	t <sub>CPH</sub>	CE#f Pulse Width High	Min	30	ns
t <sub>WHWH1</sub>	t <sub>WHWH1</sub>	Programming Operation (Note 2)	Тур	7	μs
t <sub>WHWH1</sub>	t <sub>WHWH1</sub>	Accelerated Programming Operation, Word or Byte (Note 2)	Тур	4	μs
t <sub>WHWH2</sub>	t <sub>WHWH2</sub>	Sector Erase Operation (Note 2)	Тур	0.4	sec

- 1. Not 100% tested.
- 2. See the "Flash Erase And Programming Performance" section for more information.





- 1. Figure indicates last two bus cycles of a program or erase operation.
- 2. PA = program address, SADD = sector address, PD = program data.
- 3. DQ7# is the complement of the data written to the device.  $D_{OUT}$  is the data written to the device.
- 4. Waveforms are for the word mode.

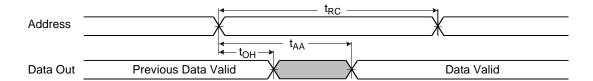
Figure 27. Flash Alternate CE#f Controlled Write (Erase/Program) Operation Timings

## **Power Up Time**

When powering up the SRAM, maintain  $V_{CC}s$  for 100  $\mu s$  minimum with CE#1s at  $V_{IH}$ .

## **Read Cycle**

Parameter	Description		Spe	eed	1114
Symbol	Description	55	70	Unit	
t <sub>RC</sub>	Read Cycle Time	Min	55	70	ns
t <sub>AA</sub>	Address Access Time	Max	55	70	ns
t <sub>CO1</sub> , t <sub>CO2</sub>	Chip Enable to Output	Max	55	70	ns
t <sub>OE</sub>	Output Enable Access Time	Max	30	35	ns
t <sub>BA</sub>	LB#s, UB#s to Access Time	Max	55	70	ns
t <sub>LZ1</sub> , t <sub>LZ2</sub>	Chip Enable (CE1#s Low and CE2s High) to Low-Z Output	Min	5		ns
t <sub>BLZ</sub>	UB#, LB# Enable to Low-Z Output	Min	5		ns
t <sub>OLZ</sub>	Output Enable to Low-Z Output	Min	5		ns
t <sub>HZ1</sub> , t <sub>HZ2</sub>	Chip Disable to High-Z Output	Max	20	25	ns
t <sub>BHZ</sub>	UB#s, LB#s Disable to High-Z Output	Max	20	25	ns
t <sub>OHZ</sub>	Output Disable to High-Z Output	Max	20	25	ns
t <sub>OH</sub>	Output Data Hold from Address Change	Min	Min 10		ns

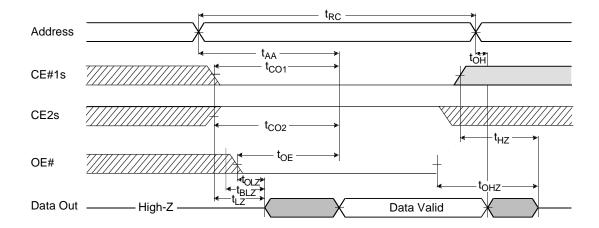


- 1.  $CE1\#s = OE\# = V_{IL}$ ,  $CE2s = WE\# = V_{IH}$ , UB#s and/or  $LB\#s = V_{IL}$
- 2. Do not access device with cycle timing shorter than  $t_{RC}$  for continuous periods < 10  $\mu$ s.

Figure 28. Pseudo SRAM Read Cycle—Address Controlled



## PSEUDO SRAM AC CHARACTERISTICS Read Cycle

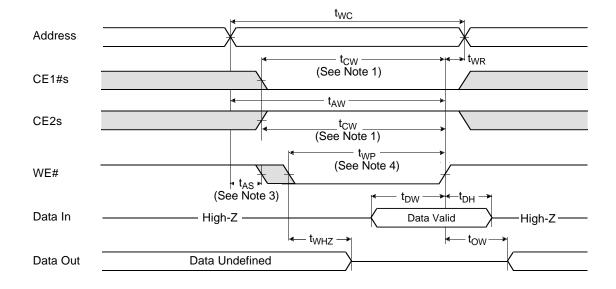


- 1.  $WE# = V_{IH}$ .
- t<sub>HZ</sub> and t<sub>OHZ</sub> are defined as the time at which the outputs achieve the open circuit conditions and are not referenced to output voltage levels.
- 3. At any given temperature and voltage condition,  $t_{HZ}$  (Max.) is less than  $t_{LZ}$  (Min.) both for a given device and from device to device interconnection.
- 4. Do not access device with cycle timing shorter than  $t_{RC}$  for continuous periods < 10  $\mu$ s.

Figure 29. Pseudo SRAM Read Cycle

## **Write Cycle**

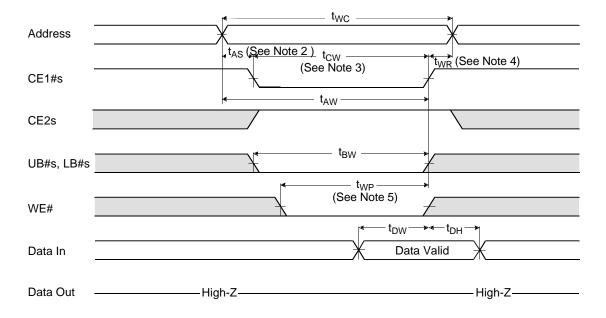
Parameter	December 1		Speed		1114
Symbol	Description		55	70	Unit
t <sub>WC</sub>	Write Cycle Time	rcle Time Min 55 70		ns	
t <sub>Cw</sub>	Chip Enable to End of Write	Min	45	55	ns
t <sub>AS</sub>	Address Setup Time	Min	(	)	ns
t <sub>AW</sub>	Address Valid to End of Write	Min	45 55		ns
t <sub>BW</sub>	UB#s, LB#s to End of Write	Min	45 55		ns
t <sub>WP</sub>	Write Pulse Time	Min	45	55	ns
t <sub>WR</sub>	Write Recovery Time	Min	0		ns
	Write to Output High 7	Min	(	)	
$t_{WHZ}$	Write to Output High-Z	Max	2	5	ns
t <sub>DW</sub>	Data to Write Time Overlap	Min	40		ns
t <sub>DH</sub>	Data Hold from Write Time	Min	0		ns
t <sub>ow</sub>	End Write to Output Low-Z	Min	5		ns



- 1. WE# controlled.
- 2.  $t_{CW}$  is measured from CE1#s going low to the end of write.
- 3.  $t_{WR}$  is measured from the end of write to the address change.  $t_{WR}$  applied in case a write ends as CE1#s or WE# going high.
- 4.  $t_{AS}$  is measured from the address valid to the beginning of write.
- 5. A write occurs during the overlap ( $t_{WP}$ ) of low CE#1 and low WE#. A write begins when CE1#s goes low and WE# goes low when asserting UB#s or LB#s for a single byte operation or simultaneously asserting UB#s and LB#s for a double byte operation. A write ends at the earliest transition when CE1#s goes high and WE# goes high. The  $t_{WP}$  is measured from the beginning of write to the end of write.

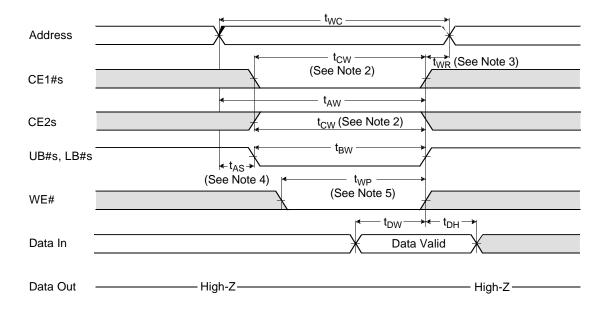
Figure 30. Pseudo SRAM Write Cycle—WE# Control





- 1. CE1#s controlled.
- 2. t<sub>CW</sub> is measured from CE1#s going low to the end of write.
- 3. t<sub>WR</sub> is measured from the end of write to the address change. t<sub>WR</sub> applied in case a write ends as CE1#s or WE# going high.
- 4.  $t_{AS}$  is measured from the address valid to the beginning of write.
- 5. A write occurs during the overlap (t<sub>WP</sub>) of low CE1#s and low WE#. A write begins when CE1#s goes low and WE# goes low when asserting UB#s or LB#s for a single byte operation or simultaneously asserting UB#s and LB#s for a double byte operation. A write ends at the earliest transition when CE1#s goes high and WE# goes high. The t<sub>WP</sub> is measured from the beginning of write to the end of write.

Figure 31. Pseudo SRAM Write Cycle—CE1#s Control



- 1. UB#s and LB#s controlled.
- 2.  $t_{CW}$  is measured from CE1#s going low to the end of write.
- 3.  $t_{WR}$  is measured from the end of write to the address change.  $t_{WR}$  applied in case a write ends as CE1#s or WE# going high.
- 4.  $t_{AS}$  is measured from the address valid to the beginning of write.
- 5. A write occurs during the overlap (t<sub>WP</sub>) of low CE#1s and low WE#. A write begins when CE1#s goes low and WE# goes low when asserting UB#s or LB#s for a single byte operation or simultaneously asserting UB#s and LB#s for a double byte operation. A write ends at the earliest transition when CE1#s goes high and WE# goes high. The t<sub>WP</sub> is measured from the beginning of write to the end of write.

Figure 32. Pseudo SRAM Write Cycle— UB#s and LB#s Control



## FLASH ERASE AND PROGRAMMING PERFORMANCE

Parameter	Typ (Note 1)	Max (Note 2)	Unit	Comments		
Sector Erase Time		0.4	5	sec	Excludes 00h	
Chin Erasa Tima	Am29DL640G	56		200	programming	
Chip Erase Time	Am29DL320G	28		sec	prior to erasure (Note 4)	
Accelerated Word Progra	m Time	4	120	μs		
Word Program Time		7	210	μs	Excludes system level	
Chip Program Time	Am29DL640G	28	84		overhead (Note 5)	
(Note 3)	Am29DL320G	14	42	sec		

#### Notes:

- Typical program and erase times assume the following conditions: 25°C, 3.0 V V<sub>CC</sub>, 1,000,000 cycles. Additionally, programming typicals assume checkerboard pattern.
- 2. Under worst case conditions of  $90^{\circ}$ C,  $V_{CC} = 2.7$  V, 1,000,000 cycles.
- 3. The typical chip programming time is considerably less than the maximum chip programming time listed, since most bytes program faster than the maximum program times listed.
- 4. In the pre-programming step of the Embedded Erase algorithm, all bytes are programmed to 00h before erasure.
- 5. System-level overhead is the time required to execute the two- or four-bus-cycle sequence for the program command. See Table 22 for further information on command definitions.
- 6. The device has a minimum erase and program cycle endurance of 1,000,000 cycles.

## LATCHUP CHARACTERISTICS

Description	Min	Max
Input voltage with respect to $V_{\rm SS}$ on all pins except I/O pins (including A9, OE#, and RESET#)	-1.0 V	12.5 V
Input voltage with respect to V <sub>SS</sub> on all I/O pins	-1.0 V	V <sub>CC</sub> + 1.0 V
V <sub>CC</sub> Current	-100 mA	+100 mA

**Note:** Includes all pins except  $V_{CC}$ . Test conditions:  $V_{CC} = 3.0 \text{ V}$ , one pin at a time.

## **BGA PACKAGE CAPACITANCE**

Parameter Symbol	Parameter Description	Test Setup	Тур	Max	Unit
C <sub>IN</sub>	Input Capacitance	V <sub>IN</sub> = 0	11	14	pF
C <sub>OUT</sub>	Output Capacitance	V <sub>OUT</sub> = 0	12	16	pF
C <sub>IN2</sub>	Control Pin Capacitance	V <sub>IN</sub> = 0	14	16	pF
C <sub>IN3</sub>	WP#/ACC Pin Capacitance	V <sub>IN</sub> = 0	17	20	pF

#### Notes:

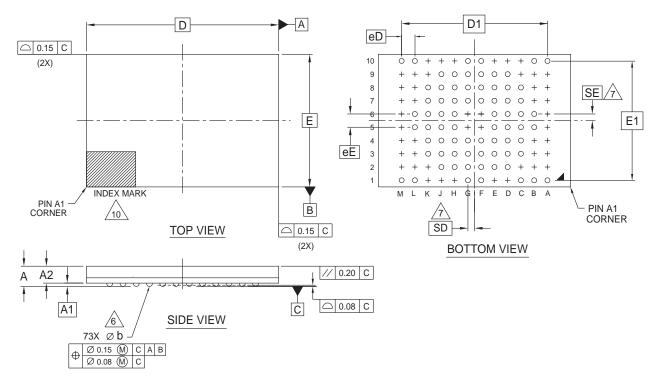
- 1. Sampled, not 100% tested.
- 2. Test conditions  $T_A = 25$ °C, f = 1.0 MHz.

## **FLASH DATA RETENTION**

Parameter Description	Test Conditions	Min	Unit
Minimum Pattern Data Retention Time	150°C	10	Years
Millimum Pattern Data Retention Time	125°C	20	Years

## PHYSICAL DIMENSIONS

## FTA073—73-Ball Fine-Pitch Grid Array 8 x 11.6 mm



PACKAGE		FTA 073		
JEDEC		N/A		NOTE
	11.60 mm x 8.00 mr PACKAGE		mm	NOTE
SYMBOL	MIN.	NOM.	MAX.	
Α			1.40	PROFILE
A1	0.25			BALL HEIGHT
A2	1.00		1.11	BODY THICKNESS
D		11.60 BSC.		BODY SIZE
Е		8.00 BSC.		BODY SIZE
D1		8.80 BSC.		MATRIX FOOTPRINT
E1		7.20 BSC.		MATRIX FOOTPRINT
MD		12		MATRIX SIZE D DIRECTION
ME		10		MATRIX SIZE E DIRECTION
n		73		BALL COUNT
Øb	0.30	0.35	0.40	BALL DIAMETER
еE		0.80 BSC		BALL PITCH
eD		0.80 BSC		BALL PITCH
SD/SE		0.40 BSC		SOLDER BALL PLACEMENT
	B2,B3,B4 D1,D10 H1.H10	,A4,A5,A6,A 4,B7,B8,B9, ,E1,E10,F5, ,J1,J10,K1,k ,L3,L4,L7,L M4,M5,M6,N	C2,C9,C10 F6,G5,G6 (2,K9,K10	DEPOPULATED SOLDER BALL

#### NOTES:

- DIMENSIONING AND TOLERANCING METHODS PER ASME Y14.5M-1994.
- ALL DIMENSIONS ARE IN MILLIMETERS.
- BALL POSITION DESIGNATION PER JESD 95-1, SPP-010.
- e REPRESENTS THE SOLDER BALL GRID PITCH.
- SYMBOL "MD" IS THE BALL MATRIX SIZE IN THE "D" DIRECTION.

SYMBOL "ME" IS THE BALL MATRIX SIZE IN THE "E" DIRECTION.

n IS THE NUMBER OF POPULTED SOLDER BALL POSITIONS FOR MATRIX SIZE MD X ME.



6 DIMENSION "b" IS MEASURED AT THE MAXIMUM BALL DIAMETER IN A PLANE PARALLEL TO DATUM C.



/T SD AND SE ARE MEASURED WITH RESPECT TO DATUMS A AND B AND DEFINE THE POSITION OF THE CENTER SOLDER BALL IN THE OUTER ROW.

WHEN THERE IS AN ODD NUMBER OF SOLDER BALLS IN THE OUTER ROW SD OR SE = 0.000.

WHEN THERE IS AN EVEN NUMBER OF SOLDER BALLS IN THE OUTER ROW, SD OR SE = e/2

"+" INDICATES THE THEORETICAL CENTER OF DEPOPULATED 8. BALLS.

1 A1 CORNER TO BE IDENTIFIED BY CHAMFER, LASER OR INK MARK, METALLIZED MARK INDENTION OR OTHER MEANS.

3159\38 14h



#### **REVISION SUMMARY**

## Revision A (October 7, 2002)

Initial release.

## Revision A+1 (October 14, 2002)

#### Flash DC Characteristics

Added CMOS compatible table.

## Revision A+2 (November 5, 2002)

#### **Distinctive Characteristics**

Added Pseudo SRAM access time.

Changed power dissipation standby from 70  $\mu A$  maximum to 60  $\mu A$ .

Changed wording from 1 million write cycles to 1 million erase cycles.

## **Product Selector Guide**

Removed the 85 ns speed options.

Added a 75 ns speed option.

Removed a f from CE# Access.

#### **Special Package Handling Instructions**

Modified wording.

## **Ordering Information**

Modified order numbers and package markings to reflect new speed option.

## **Pseudo SRAM and Operating Characteristics**

Changed the typical and maximum of the Average Operating Current ( $I_{CC1}$ s and  $I_{CC2}$ s).

Changed the maximum of the Standby Current (CMOS) to 70 µA.

## Customer Lockable: SecSi Sector NOT Programmed or Protected at the factory.

Added second bullet, SecSi sector-protect verify text and figure 3.

# SecSi Sector Flash Memory Region, and Enter SecSi Sector/Exit SecSi Sector Command Sequence

Added notes, "Note that the ACC function and unlock bypass modes are not available when the SecSi sector is enabled."

# Byte/Word Program Command Sequence, Sector Erase Command Sequence, and Chip Erase Command Sequence

Added "Note that the SecSi Sector, autoselect, and CFI functions are unavailable when a [program/erase] operation is in progress."

## **Common Flash Memory Interface (CFI)**

Changed wording in last sentence of third paragraph from, "...the autoselect mode." to "...reading array data."

Changed CFI website address.

#### **Command Definitions**

Changed wording in last sentence of first paragraph from, "...resets the device to reading array data." to ... "may place the device to an unknown state. A reset command is then required to return the device to reading array data."

#### Table 12. Am29DL640G Command Definitions

Changed the first address of the unlock bypass reset command sequence from BA to XXX.

## **CMOS Compatible**

Added I<sub>LR</sub> parameter to table.

Deleted I<sub>ACC</sub> parameter from table.

Changed the maximums of  $I_{CC}3f$ ,  $I_{CC}4f$ , and  $I_{CC}5f$  from 5  $\mu A$  to 10  $\mu A$ .

Added Note #6.

## **Pseudo SRAM DC and Operating Characteristics**

Changed the test conditions and maximum for  $I_{SB1}$  and added the  $I_{SB2}$  parameter symbol.

## Figure 12. Standby Current I<sub>SB</sub> CMOS

Added figure.

## Revision A+3 (January 2, 2003)

#### **Pseudo SRAM AC Characteristics**

Write Cycle table: Changed t<sub>DW</sub> to 40 ns.

## **Physical Dimensions**

Deleted A1 specification from table.

## Revision A+4 (May 19, 2003)

# pSRAM Data Retention, Figure 33. CE#1 Controlled Data Retention Mode, and Figure 34. CE2s Controlled Data Retention Mode

Removed table and figures from data sheet.

## **Pseudo SRAM and Operating Characteristics**

Changed the Max value for the Average operating current and Standby current (CMOS) to 85  $\mu s$ .

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