CSM\_K3HB-V\_DS\_E\_8\_1

® **71**° (€

### An Ideal Indicator for OK/NG Judgements in Automated and Picking Machines, Measuring Factors such as Pressure, Load, Torque, and Weight Using Load Cell Signal Input.

- Easy recognition of judgement results using color display that can be switched between red and green. \*
- Equipped with a position meter for monitoring operating status trends.
- External event input allows use in various measurement and discrimination applications.
- Input 0.001 mVDC or higher (0.000 to 19.999 mV range supported). External power takeoff of 100 mA at 10 VDC provided. (Models with 5-VDC power takeoff also available.)
- Series expanded to include DeviceNet models.
- Short body with depth of only 95 mm (from behind the front panel), or 97 mm for DeviceNet models.
- UL certification approval (Certification Mark License).
- CE Marking conformance by third party assessment body.
- Water-resistant enclosure conforms to NEMA 4X (equivalent to IP66).
- Capable of high-speed sampling at 50 times per second (20 ms)
- · Easy-to-set two-point scaling allows conversion and display of any user-set values.
- \* Visual confirmation of judgement results is not supported on models that do not have an output or models that do not support DeviceNet. You can change the display color by setting it, but you cannot switch it based on the judgement results.



For the most recent information on models that have been certified for safety standards, refer to your OMRON website.



Refer to Safety Precautions for All Digital Panel Meters.

# Model Number Structure

## ■ Model Number Legend

Base Units and Optional Boards can be ordered individually or as sets.

#### **Base Units**

K3HB-V

1. Input Sensor Code

LC: Load cell input (DC low-voltage input)

5. Supply Voltage

100-240 VAC: 100 to 240 VAC 24 VAC/VDC: 24 VAC/VDC

### **Base Units with Optional Boards**

K3HB-V --1 2 3 4

#### 2. Sensor Power Supply/Output Type Code

L1B:

Relay output (PASS: SPDT) + Sensor power supply

L2B:

None
Relay output (PASS: SPDT) + Sensor power supply
(10 VDC +/-5%, 100 mA) (See note 1.)
Linear current output (0 to 20 or 4 to 20 mA DC) + Sensor power
supply (10 VDC +/-5%, 100 mA) (See note 2.)
Linear voltage output (0 to 5, 1 to 5, or 0 to 10 VDC) + Sensor
power supply (10 VDC +/-5%, 100 mA) (See note 2.)
Sensor power supply (10 VDC +/-5%, 100 mA)
Communications (RS-232C) + Sensor power supply
(10 VDC +/-5%, 100 mA) (See note 2.)
Communications (RS-485) + Sensor power supply
(10 VDC +/-5%, 100 mA) (See note 2.)
Relay output (PASS: SPDT) + Sensor power supply
(5 VDC +/-5%, 100 mA) (See note 1.)
Linear current output (DC0(4) -20 mA) + Sensor power supply
(5 VDC +/-5%, 100 mA) (See note 2.)
Linear voltage output (DC0(1) -5 V, 0-10 V)+ Sensor power
supply (5 VDC +/-5%, 100 mA) (See note 2.)
Sensor power supply (5 VDC +/-5%, 100 mA)
Communications (RS-232C) + Sensor power supply
(5 VDC +/-5%, 100 mA) (See note 2.)
Communications RS-485) + Sensor power supply
(5 VDC +/-5%, 100 mA) (See note 2.)
Communications RS-485) + Sensor power supply
(5 VDC +/-5%, 100 mA) (See note 2.) FLK1B:

FLK3B:

CPE:

L1E:

L2E:

FLK1E:

FLK3E:

#### Optional Boards

Sensor Power Supply/Output Boards

K33-∟

Relay/Transistor Output Boards

**Event Input Boards** 

K35-L

# 3. Relay/Transistor Output Type Code

None: None

C1: Relay contact (H/L: SPDT each)
C2: Relay contact (HH/H/LL/L: SPST-NO each)

T1: Transistor (NPN open collector: HH/H/PASS/L/LL)
T2: Transistor (PNP open collector: HH/H/PASS/L/LL)
BCD \*: BCD output + transistor output (NPN open collector: HH/H/PASS/L/LL) DRT: DeviceNet (See note 2.)

\* A Special BCD Output Cable (sold separately) is required.

#### 4. Event Input Type Code

None: None

1: 5 inputs (M3 terminal blocks), NPN open collector 2: 8 inputs (10-pin MIL connector), NPN open collector 3: 5 inputs (M3 terminal blocks), PNP open collector

4: 8 inputs (10-pin MIL connector), PNP open collector

### Note: 1. CPB, CPE can be combined with relay outputs only. 2. Only one of the following can be used by each Digital Indicator: RS-232C/RS-485 communications, a linear output, or DeviceNet communications. Rubber Packing Accessories (Sold Separately)

K32-DICN: Special Cable (for event inputs, with 8-pin connector) K32-BCD: Special BCD Output Cable

ITUDDCI	i acking	
	Model	
K00 D4		

Note: Rubber packing is provided with the Controller.

# **Specifications**

# **■** Ratings

	100 to 240 VAC (50/60 Hz), 24 VAC/VDC, DeviceNet power supply: 24 VDC		
oltage range	85% to 110% of the rated power supply voltage, DeviceNet power supply: 11 to 25 VDC		
	100 to 240 V: 18 VA max. (max. load) 24 VAC/DC: 11 VA/7 W max. (max. load)		
	DeviceNet power supply: 50 mA max. (24 VDC)		
	DC voltage		
	Delta-Sigma method		
	10 VDC ±5%, 100 mA (models with external power supply only) or 5 VDC, 100 mA (models with external power supply only)		
Timing input	NPN open collector or no-voltage contact signal ON residual voltage: 3 V max. ON current at 0 $\Omega$ : 17 mA max. Max. applied voltage: 30 VDC max. OFF leakage current: 1.5 mA max.		
Startup compensation timer input	NPN open collector or no-voltage contact signal ON residual voltage: 2 V max.		
Hold input	ON current at 0 Ω: 4 mA max.		
Reset input	Max. applied voltage: 30 VDC max. OFF leakage current: 0.1 mA max.		
Forced-zero input	or ounage contain or minimum		
Bank input			
Relay output	250 VAC, 30 VDC, 5 A (resistive load) Mechanical life expectancy: 5,000,000 operations, Electrical life expectancy: 100,000 operations		
Transistor output	Maximum load voltage: 24 VDC, Maximum load current: 50 mA, Leakage current: 100 μA max.		
Linear output	Linear output 0 to 20 mA DC, 4 to 20 mA DC: Load: 500 $\Omega$ max, Resolution: Approx. 10,000, Output error: $\pm 0.5\%$ FS Linear output 0 to 5 VDC, 0 to 5 VDC, 0 to 10 VDC: Load: 5 $k\Omega$ max, Resolution: Approx. 10,000, Output error: $\pm 0.5\%$ FS (1 V or less: $\pm 0.15$ V; no output for 0 V or less)		
	Negative LCD (backlit LED) display 7-segment digital display (Character height: PV: 14.2 mm (green/red); SV: 4.9 mm (green)		
	Scaling function, measurement operation selection, averaging, previous average value comparison, forced zero, zero-limit, output hysteresis, output OFF delay, output test, teaching, display value selection, display color selection, key protection, bank selection, display refresh period, maximum/minimum hold, reset		
rature	−10 to 55°C (with no icing or condensation)		
ity	25% to 85%		
	−25 to 65°C (with no icing or condensation)		
	2,000 m max.		
	Watertight packing, 2 fixtures, terminal cover, unit stickers, operation manual. DeviceNet models also include a DeviceNet connector (Hirose HR31-5.08P-5SC(01)) and crimp terminals (Hirose HR31-SC-121) (See note 3.)		
	Startup compensation timer input Hold input Reset input Forced-zero input Bank input Relay output Transistor output		

DC power supply models require a control power supply capacity of approximately 1 A per Unit when power is turned ON. Particular attention is required when using two or more DC power supply models. The OMRON S8VS-series DC Power Supply Unit is recommended.
 PNP input types are also available.
 For K3HB-series DeviceNet models, use only the DeviceNet Connector included with the product. The crimp terminals provided are for Thin Cables.

# **■** Characteristics

Display range		-19,999 to 99,999			
Sampling perio	d	20 ms (50 times/second)			
Comparative ou	utput response time	100 ms max.			
Linear output re	esponse time	150 ms max.			
Insulation resis	tance	20 M $\Omega$ min. (at 500 VDC)			
Dielectric stren	gth	2,300 VAC for 1 min between external terminals and case			
Noise immunity		100 to 240 VAC models: ±1,500 V at power supply terminals in normal or common mode (waveform with 1-ns rising edge and pulse width of 1 μs/100 ns) 24 VAC/VDC models: ±1,500 V at power supply terminals in normal or common mode (waveform with 1-ns rising edge and pulse width of 1 μs/100 ns)			
Vibration resist	ance	Frequency: 10 to 55 Hz; Acceleration: 50 m/s², 10 sweeps of 5 min each in X, Y, and Z directions			
Shock resistant	се	150 m/s² (100 m/s² for relay outputs) 3 times each in 3 axes, 6 directions			
Weight		Approx. 300 g (Base Unit only)			
Degree of	Front panel	Conforms to NEMA 4X for indoor use (equivalent to IP66)			
protection	Rear case	IP20			
	Terminals	IP00 + finger protection (VDE0106/100)			
Memory protect	tion	EEPROM (non-volatile memory) Number of rewrites: 100,000			
Applicable stan	dards	UL61010-1, CSA C22.2 No. 61010-1-04 EN61010-1 (IEC61010-1): Pollution degree 2/Overvoltage category II EN61326-1			
EMC		EMI: EN61326 industrial applications Electromagnetic radiation interference CISPR 11 Group 1, Class A  Terminal interference voltage CISPR 11 Group 1, Class A  EMS: EN61326 industrial applications Electrostatic Discharge Immunity EN61000-4-2: 4 kV (contact), 8 kV (in air) Radiated Electromagnetic Field Immunity EN61000-4-3: 10 V/m 1 kHz sine wave amplitude modulation (80 MHz to 1 GHz, 1.4 to 2 GHz) Electrical Fast Transient/Burst Immunity EN61000-4-4: 2 kV (power line), 1 kV (I/O signal line) Surge Immunity EN61000-4-5: 1 kV with line (power line), 2 kV with ground (power line) Conducted Disturbance Immunity EN61000-4-6: 3 V (0.15 to 80 MHz) Power Frequency Magnetic Immunity EN61000-4-8: 30 A/m (50 Hz) continuous time Voltage Dips and Interruptions Immunity EN61000-4-11: 0.5 cycle, 0°/180°, 100% (rated voltage)			

# ■ Input Ranges (Measurement Range and Accuracy)

Input type	Range	Set value	Measurement range	Input impedance	Accuracy	Allowable instantaneous overload (30 s)
K3HB-VLC	Α	R LC	0.00 to 199.99 mV	1 MΩ min.	±0.1% rdg ±1 digit max.	±200 V
Load Cell, mV	В	P TE	0.000 to 19.999 mV		±0.1% rdg ±5 digits max.	
	С	E LE	±100.00 mV		±0.1% rdg ±3 digits max.	
	D	d LE	±199.99 mV		±0.1% rdg ±1 digit max.	

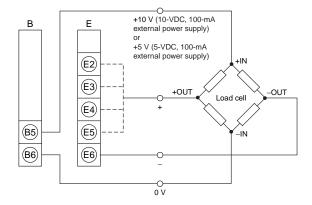
Note: 1. The accuracy is for an ambient temperature of 23±5°C. For all ranges,10% or less of max. input ±0.1% FS.

2. The letters "rdg" mean "reading."

Input type	A TE	PTE	[ L[	d LE	
Connected terminals		<b>(E3)</b> – <b>(E6)</b>	<b>E</b> 4 – <b>E</b> 6	Œ5 - Œ6	
(mV) 200.000	199.99			199.99	
150.000			100.00		
100.000 50.000		19.999			
0.00		0.000			
-50.00		0.000			
-100.00 -150.00			-100.00		
-200.00				100.00	
				-199.99	
Maximum measurement range	-19.99 to 219.99 mV	-1.999 to 21.999 mV	-110.00 to 110.00 mV	-199.99 to 219.99 mV	

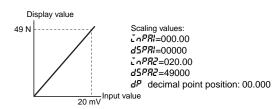
The area shown in dark shading indicates the factory setting.

# **■ Load Cell Wiring Example**



# ■ Scaling Example Using Range A

Indicated on the K3HB-V as 0 to 49N in the load cell specifications (rated load 49N, recommended applied voltage 10 V, rated output 2 mV/V) (See note.)



Note: "2 mV/V" indicates a load cell output of 2 mV for 1 V applied voltage for the rated load (when using a load of 1 N). When the applied voltage is 10 V, the load cell output is 20 mV (2 mV x 10).

The precision can be increased by entering the A1 and A2 input values by teaching, and then scaling the results.

# **Common Specifications**

# **■** Event Input Ratings

Input type	S-TMR, HOLD, RESET, ZERO, BANK1, BANK2, BANK4	TIMING
Contact	ON: 1 k $\Omega$ max., OFF: 100 k $\Omega$ min.	
No-contact	Load current: 4 mA max.	ON residual voltage: 3 V max. OFF leakage current: 1.5 mA max. Load current: 17 mA max. Maximum applied voltage: 30 VDC max.

# **■** Output Ratings

### **Contact Output**

Item	Resistive loads (250 VAC, cosφ=1; 30 VDC, L/R=0 ms)	Inductive loads (250 VAC, closed circuit, cos∳=0.4; 30 VDC, L/R=7 ms)
Rated load	5 A at 250 VAC 5 A at 30 VDC	1 A at 250 VAC 1 A at 30 VDC
Rated through current	5A	
Mechanical life expectancy	5,000,000 operations	
Electrical life expectancy	100,000 operations	

## **Transistor Output**

Maximum load voltage	24 VDC
Maximum load current	50 mA
Leakage current	100 μA max.

### **Linear Output**

Item	0 to 20 mA	4 to 20 mA	0 to 5 V	1 to 5 V	0 to 10 V
Allowable load impedance	500 $\Omega$ max.	5 k $Ω$ min.			
Resolution	Approx. 10,000				
Output error	±0.5%FS		±0.5%FS (1 V or les	ss: no output for ±0.	15 V; 0 V or less)

# **Serial Communications Output**

Item	RS-232C, RS-485
Communications method	Half duplex
Synchronization method	Start-stop synchronization
Baud rate	9,600, 19,200, or 38,400 bps
Transmission code	ASCII
Data length	7 bits or 8 bits
Stop bit length	2 bits or 1 bit
Error detection	Vertical parity and FCS
Parity check	Odd, even

Note: For details on serial and DeviceNet communications, refer to the *Digital Indicator K3HB Communications User's Manual* (Cat.No. N129).

# BCD Output I/O Ratings (Input Signal Logic: Negative)

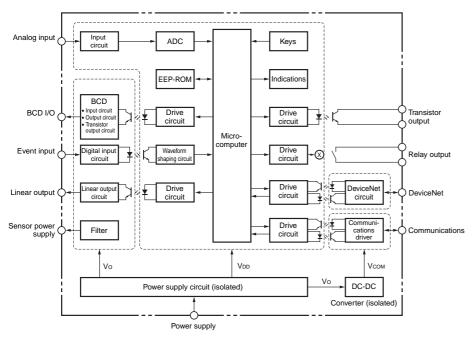
	I/O signal name		Item	Rating
Inputs	REQUEST HOLD MAX MIN	Input signal		No-voltage contact input
		Input current for no-voltage input		10 mA
	RESET	Signal	ON voltage	1.5 V max.
		level	OFF voltage	3 V min.
Outputs	DATA POLARITY OVER DATA VALID RUN	Maximum load voltage		24 VDC
		Maximum load current		10 mA
		Leakage current		100 μA max.
	HH H	Maximum load voltage		24 VDC
	PASS L LL	Maximum load current		50 mA
		Leakage current		100 μA max.

Note: For details on serial and DeviceNet communications, refer to the *Digital Indicator K3HB Communications User's Manual* (Cat.No. N129).

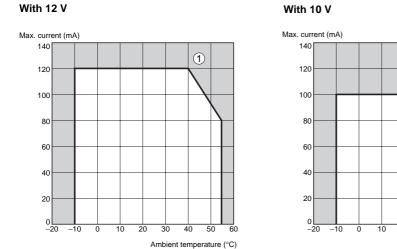
# **DeviceNet Communications**

Communications prot	ocol	Conforms to DeviceNet					
Supported communications	Remote I/O communications	Master-Slave connection (polling, bit-strobe, COS, cyclic) Conforms to DeviceNet communications standards.					
	I/O allocations	ΑI	locate any I/O data	using the Configurat	or.		
		Allocate any data, such as DeviceNet-specific parameters and variable area for Digita Indicators.					
		Input area: 2 blocks, 60 words max.					
			utput area: 1 block,				
		(T	he first word in the a	rea is always allocate	ed for the Output Exe	cution Enabled Flags.)	
	Message communications		plicit message com				
			ompoWay/F commu mmunications)	nications commands	s can be executed (u	sing explicit message	
Connection methods Combination of multi-drop and T-branch connections (for trunk and drop			and drop lines)				
Baud rate	DeviceNet: 500, 250, or 125 Kbps (automatic follow-up)						
Communications med	ia	Sp	pecial 5-wire cable (	2 signal lines, 2 pow	er supply lines, 1 sh	ield line)	
Communications dista	ance						
			Baud rate	Network length (max.)	Drop line length (max.)	Total drop line length (max.)	
			500 Kbps	100 m (100 m)	6 m	39 m	
			250 Kbps	100 m (250 m)	6 m	78 m	
			125 Kbps	100 m (500 m)	6 m	156 m	
			The values in pare	ntheses are for Thic	k Cable.	<u> </u>	
Communications pow	er supply	24	-VDC DeviceNet po	ower supply			
Allowable voltage fluc	tuation range	11	to 25-VDC Device	Net power supply			
<b>Current consumption</b>		50 mA max. (24 VDC)					
Maximum number of r	nodes	64 (DeviceNet Configurator is counted as one node when connected)			nected)		
Maximum number of slaves			63				
Error control checks		CRC errors					
DeviceNet power supp	oly	Supplied from DeviceNet communications connector					

# ■ Internal Block Diagram



# ■ Power Supply Derating Curve for Sensor (Reference Value)



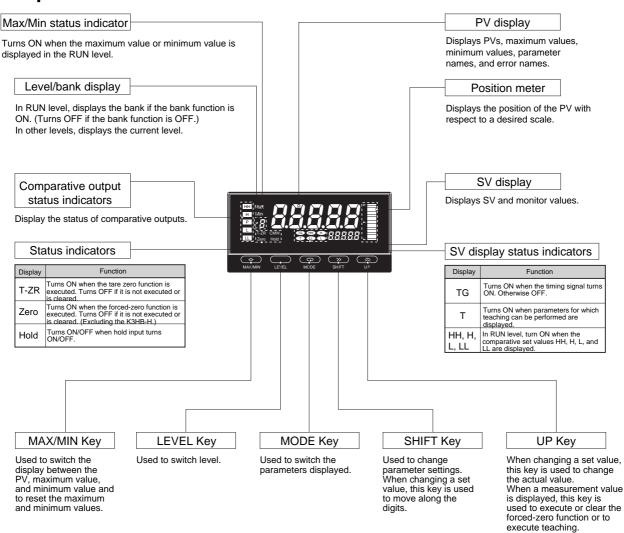
- Note: 1. The above values are for standard mounting. The derating curve differs depending on the mounting conditions.
  - 2. Do not use the Sensor outside of the derating area (i.e., do not use it in the area labeled ① in the above graphics). Doing so may occasionally cause deterioration or damage to internal components.

30

Ambient temperature (°C)

(1)

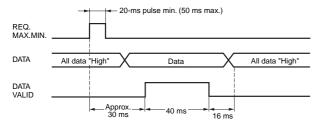
# **■** Component Names and Functions



# **■ BCD Output Timing Chart**

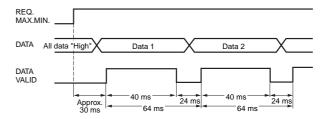
A REQUEST signal from a Programmable Controller or other external device is required to read BCD data.

### **Single Sampling Data Output**



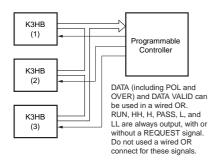
The data is set in approximately 30 ms from the rising edge of the REQUEST signal and the DATA VALID signal is output. When reading the data from a Programmable Controller, start reading the data when the DATA VALID signal turns ON. The DATA VALID signal will turn OFF 40 ms later, and the data will turn OFF 16 ms after that.

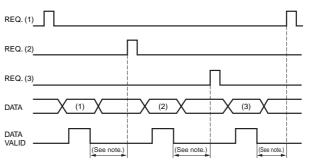
### **Continuous Data Output**



Measurement data is output every 64 ms while the REQUEST signal remains ON.

Note: If HOLD is executed when switching between data 1 and data 2, either data 1 or data 2 is output depending on the timing of the hold signal. The data will not go LOW.

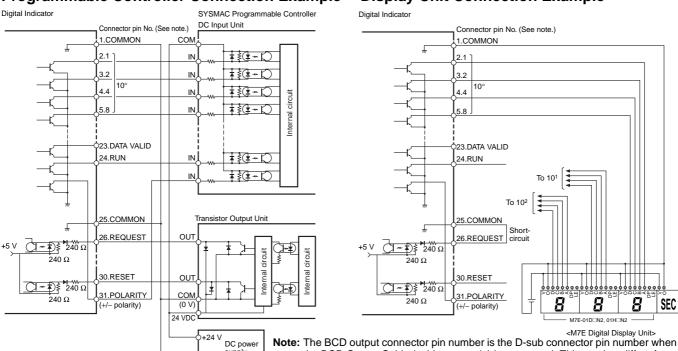




Note: Leave 20 ms min. between DATA VALID turning OFF and the REQUEST signal.

## **Programmable Controller Connection Example**

### **Display Unit Connection Example**



the BCD output connector pin number is the D-sub connector pin number when the BCD Output Cable (sold separately) is connected. This number differs from the pin number for the Digital Indicator narrow pitch connector (manufactured by Honda Tsushin Kogyo Co., Ltd.).

Refer to the following User's Manual for application precautions and other information required when using the Digital Indicator: K3HB-S/-X/-V/-H Digital Indicator User's Manual (Cat. No. N128)

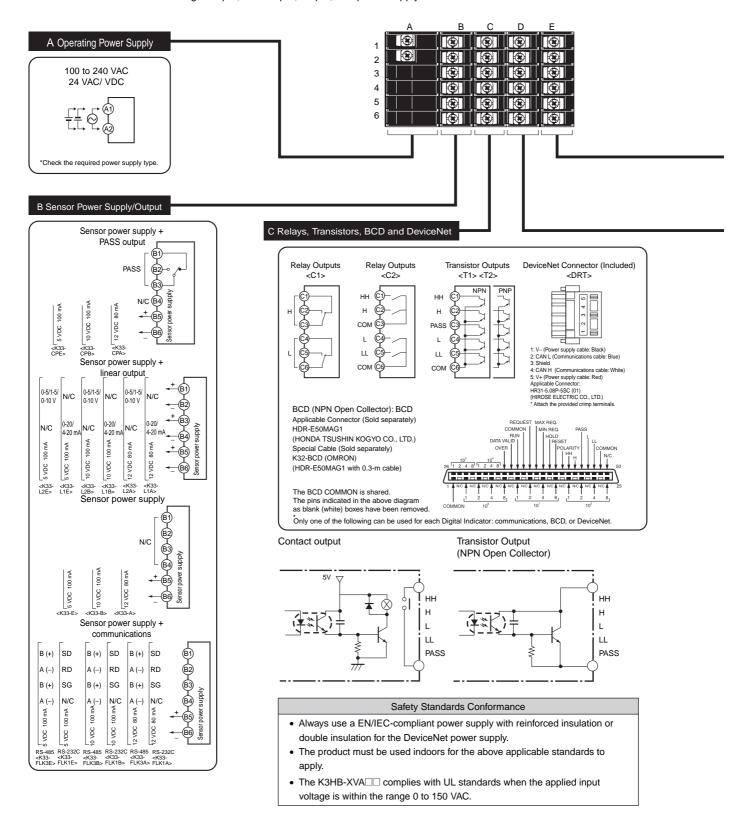
The manual can be downloaded from the following site in PDF format: OMRON Industrial Web http://www.fa.omron.co.jp

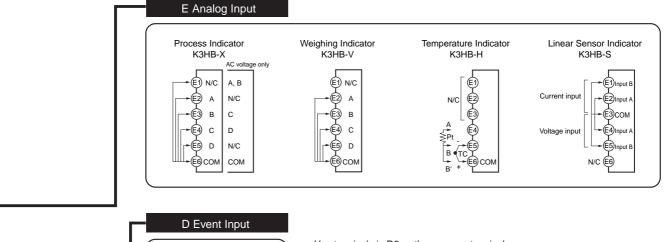
# K3HB-V

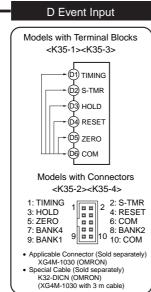
### **■** Connections

### **Terminal Arrangement**

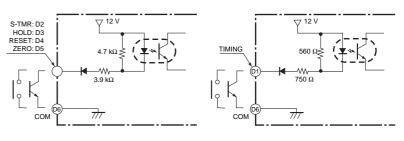
Note: Insulation is used between signal input, event input, output, and power supply terminals.



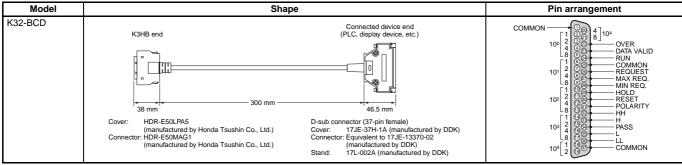




- Use terminal pin D6 as the common terminal.
- Use NPN open collector or no-voltage contacts for event input.
   PNP types are also available.



# **BCD Output Cable**



Note: The BCD Output Cable has a D-sub plug. Cover: 17JE-37H-1A (manufactured by DDK); Connector: equivalent to 17JE-23370-02 (D1) (manufactured by DDK)

# **Special Cable (for Event Inputs with 8-pin Connector)**

Model	Appearance		Wiring		
K32-DICN	9 10 2 3,000 mm	<b>•</b>	Pin No.  1 2 3 4 5 6 7 8 9	Signal name N/C S-TMR HOLD RESET N/C COM BANK4 BANK2 BANK1 COM	

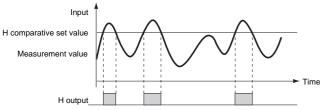
# **■ Main Functions**

### Measurement

### Timing Hold

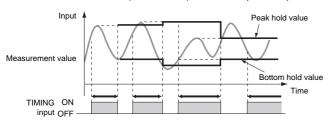
#### **Normal**

 Continuously performs measurement and always outputs based on comparative results.



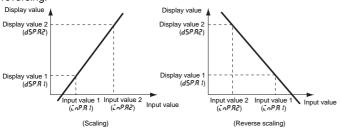
### **Peak Hold/Bottom Hold**

• Measures the maximum (or minimum) value in a specified period.



#### Scaling

Scaling converts input signals in any way required before displaying them. The values can be manipulated by shifting, inverting, or +/- reversing.



#### **Teaching**

Settings for scaling can be made using the present measurement values instead of inputting values with the SHIFT and UP Keys. This is a convenient function for making settings while monitoring the operating status, for calculating amounts by tare reduction (to measure only the contents), or when the result should be zero but the display is not zero for some reason.

### Standby Sequence

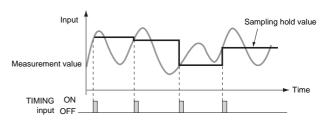
Turns the comparative output OFF until the measurement value enters the PASS range.

### Average Processing

Average processing of input signals with extreme changes or noise smooths out the display and makes control stable.

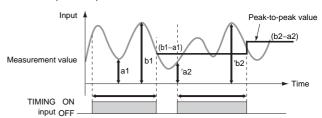
### Sampling Hold

• Holds the measurement at the rising edge of the TIMING signal.



#### Peak-to-peak Hold

Measures the difference between the maximum and minimum values in a specified period.



### Previous Average Value Comparison

Slight changes can be removed from input signals to detect only extreme changes.

# ■ Input Compensation/Display

#### Forced-zero

Forces the present value to 0. (Convenient for setting reference values or deducting tares for weight measurement.)

#### **Tare Zero**

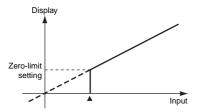
Shifts the current value measured with a forced zero to 0 again. It is possible to measure two or more compounds separately and then, by releasing the tare zero and forced-zero, measure the combined total.

#### **Zero-trimming**

Compensates for mild fluctuations in input signals due to factors such as sensor temperature drift, based on OK (PASS) data at measurement. (This function can be used with sampling hold, peak hold, or bottom hold.)

#### Zero-limit

Changes the display value to 0 for input values less than the set value. It is enabled in normal mode only. (This function can be used, for example, to stop negative values being displayed or to eliminate flickering and minor inconsistencies near 0.)



#### **Interruption Memory**

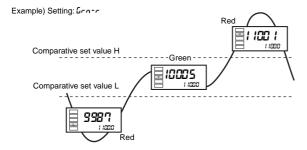
- The minimum and maximum values when the power supply is turned OFF can be saved if interruption memory is turned ON.
- If interruption memory is ON, the maximum and minimum values after the last resetting will be displayed.
- If interruption memory is OFF, the maximum and minimum values will be displayed after the power supply is turned ON (or after the reset input is performed).

#### **Display Refresh Period**

The display refresh period can be lengthened to reduce flickering and thereby make the display easier to read.

#### **Display Color Selection**

Values can be displayed in either red or green. With comparative output models, the display color can also be set to change according to the status of comparative outputs (e.g., green to red or red to green).



#### **Display Value Selection**

The current display value can be selected from the present value, the maximum value, and the minimum value.

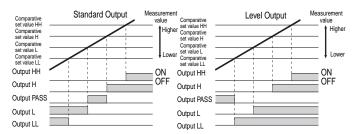
#### Step Value

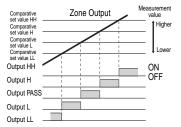
It is possible to specify (i.e., restrict) the values that the smallest displayed digit can change by. For example, if the setting is 2, the smallest digit will only take the values 0, 2, 4, 6, or 8 and if the setting is 5, it will only take the values 0 or 5. If the setting is 10, it will only take the value of 0.

# **■** Output

#### **Comparative Output Pattern**

The output pattern for comparative outputs can be selected. In addition to high/low comparison with set values, output based on level changes is also possible. (Use the type of output pattern appropriate for the application.)





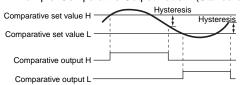
#### **Output Logic**

Reverses the output operation of comparative outputs for compara-

#### **Hysteresis**

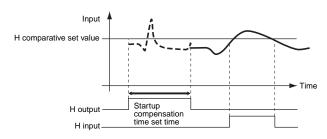
Prevents comparative output chattering when the measurement value fluctuates slightly near the set value.

Example: Comparative Output Pattern (Standard Output)



#### **Startup Compensation Timer**

Measurement can be stopped for a set time using external input.

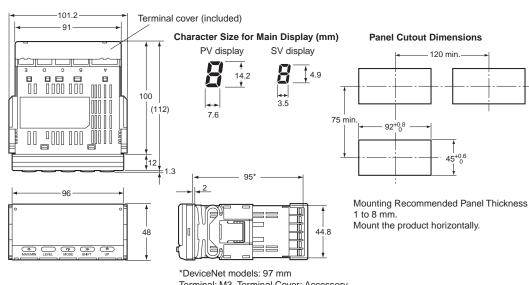


### PASS Output Change

Comparative results other than PASS and error signals can be output from the PASS output terminal.

### ■ Dimensions





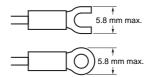
Terminal: M3, Terminal Cover: Accessory

# **■** Wiring Precautions

- For terminal blocks, use the crimp terminals suitable for M3 screws.
- Tighten the terminal screws to the recommended tightening torque of approx. 0.5 N·m.
- To prevent inductive noise, separate the wiring for signal lines from that for power lines.

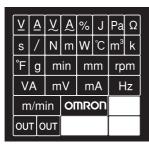
### Wiring

• Use the crimp terminals suitable for M3 screws shown below.



### **Unit Stickers**

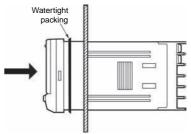
• Select the appropriate units from the unit sticker sheets provided and attach the sticker to the Indicator.



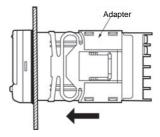
**Note:** When using for meters, such as weighing meters, use the units specified by regulations on weights and measures.

# **■** Mounting Method

- 1. Insert the K3HB into the mounting cutout in the panel.
- Insert watertight packing around the Unit to make the mounting watertight.

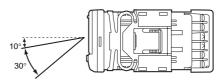


Insert the adapter into the grooves on the left and right sides of the rear case and push until it reaches the panel and is fixed in place.



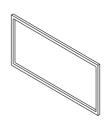
### **■ LCD Field of Vision**

The K3HB is designed to have the best visibility at the angles shown in the following diagram.



# ■ Rubber Packing (Sold Separately)

K32-P1



If the rubber packing is lost or damaged, it can be ordered using the following model number: K32-P1

(Depending on the operating environment deterioration, contraction, or hardening of the rubber packing may occur and so, in order to ensure the level of waterproofing specified in NEMA4, periodic replacement is recommended.)

**Note:** Rubber packing is provided with the Controller.

ALL DIMENSIONS SHOWN ARE IN MILLIMETERS.

To convert millimeters into inches, multiply by 0.03937. To convert grams into ounces, multiply by 0.03527.

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Please know and observe all prohibitions of use applicable to the products.

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### **DIMENSIONS AND WEIGHTS**

Dimensions and weights are nominal and are not to be used for manufacturing purposes, even when tolerances are shown.

#### PERFORMANCE DATA

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In the interest of product improvement, specifications are subject to change without notice.

